August 31, 2021.

Determinants.

example.

$$f: \mathbb{R}^{n \times n} \longrightarrow \mathbb{R}$$

Let A be an nxn matrix [aij]. Let Aij denote the (n-1) x(n-1) matrix obtained by removing the jth row and the jth column of A. Then

$$\det(A) = a_{11} \det A_{11} - a_{21} \det A_{21} + \cdots + a_{n1} \det A_{n1}.$$

$$df(A)$$

$$df(A)$$

$$\left[\text{Exprension by minors along first column} \right]$$

Note that the definition above is recursive in nature.

Moreover one may define det(A) using expansion

by minors on other rows and on columns.

(1). Observe that
$$d_f(I_n) = 1$$
.

Let Ri denote the row vector, it row of the motrix.
Then

$$A = \begin{cases} -R_1 - \\ \vdots \\ -R_n - \end{cases}$$
 (in terms of row vector)

d is linear means

$$\frac{d}{dt} \left[-R+S - \right] \qquad \left[\begin{array}{c} Here & R \text{ and } S \text{ are row} \\ Vertors & of A, for some i \end{array} \right]$$

$$= d_f \left[\begin{array}{c} \vdots \\ -R \end{array} \right] + d_f \left[\begin{array}{c} \vdots \\ -S \end{array} \right] ,$$

and

$$d_{f}\left(-cR-\right) = c d_{f}\left(-R-\right)$$

dy linear function

If two adjacent rows of a matrix A are equal Any nxn moleix then $d_f(A) = 0$. $A = \begin{cases} a & b & c \\ a & b & c \\ d & e & f \end{cases}$ $\operatorname{det}(A) = a \cdot \operatorname{old}(b) - a \cdot \operatorname{det}(b) + d \cdot \operatorname{old}(b)$

We prove this by induction on n. Assume that rows j and j+1 are equal.

Using Induction

Then Ail (motrix obtained as minor by removing 1st column and ith row

"Proof by induction on n".

Let
$$n = 2$$
. $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{11} & a_{12} \end{bmatrix}$

Two adjocent rows of A ore equal.

$$d_{f}(A) = a_{11} \cdot \det(a_{12}) - a_{11} \cdot \det(a_{12})$$

$$= a_{11} \cdot a_{12} - a_{11} \cdot a_{12}$$

$$= 0$$

Let us try for n=3.

Assume that
$$A = \begin{cases} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{cases}$$
 equal

$$A = \begin{cases} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{21} & a_{22} & a_{23} \end{cases}$$

$$d_{f}(A) = a_{11} \cdot d_{f} \begin{bmatrix} a_{22} & a_{23} \\ a_{21} & a_{23} \end{bmatrix} - a_{21} \cdot d_{f} \begin{bmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{bmatrix}$$

$$= 0 + a_{21} \cdot d_{f} \begin{bmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{bmatrix}$$

In other words,

$$d_f(A) = a_{11} \cdot d_f(A_{11}) - a_{21} \cdot d_f(A_{21}) + a_{21} \cdot d_f(A_{31})$$

formal proof by induction.

Step 1. (Bose cose). Let n=2, then $d_f(A)=0$.

Step 2. (Induction hypothesis).

Assume that for all square motrices of size less than or equal to K, whenever two adjacent rows are equal, then $d_f(A) = 0$

$$A = \left[\begin{array}{c} a_{ij} \end{array} \right]_{(k+1) \times (lc+1)}$$
, claim. $d_f(A) = 0$

Suppose that rows j and j+1 are equal.

Consider the motrices Ai, ; i=1,2,..., K+1.

Note that Ai, will have two equal rows except Thus $d_f(A_{ii}) = 0$, whenever $i \neq j$, $i \neq j+1$. when i=j or i=j+1. Also observe that for i=j and i=j+1, we have $A_{j,l} = A_{j+l,l}$ and $a_{j,l} = a_{j+l,l}$ Thus $d_f(A) = \underbrace{\qquad \pm a_{j,l} d_f(A_{j,l})}_{a_{j+l,l}} \mp a_{d_f}(A_{j+l,l}) \pm \cdots$

 $= \pm a_{ji} d_f(A_{ji}) \mp a_{ji} d_f(A_{ji})$ = 0

Hence if two adjacent rows of ony square motrix A are equal, then $d_f(A) = 0$.

and the the same the same of the same to be a second

1) If a multiple of one row is added to an adjacent row, the determinant is unchanged.

$$d_{f} \begin{pmatrix} \vdots \\ -R - \\ -s + cR - \end{pmatrix} = d_{f} \begin{pmatrix} \vdots \\ -R - \\ -s - \end{pmatrix} + c d_{f} \begin{pmatrix} -R - \\ -R - \end{pmatrix}$$

$$= d_{f} \begin{pmatrix} \vdots \\ -R - \\ -s - \end{pmatrix}$$

$$= d_{f} \begin{pmatrix} \vdots \\ -R - \\ -s - \end{pmatrix}$$

5). If two adjacent rows are interchanged, then determinant is multiplied by -1.

$$d_{f} \begin{bmatrix} \vdots \\ -R - \\ -S \end{bmatrix} = d_{f} \begin{bmatrix} \vdots \\ -R - \\ -(S-R) - \end{bmatrix}$$

$$= df \begin{cases} \frac{i \ln r \sigma}{R} + (S - R) - \frac{i \ln r \sigma}{R} \\ \frac{i \ln r \sigma}{R} + (S - R) - \frac{i \ln r \sigma}{R} \end{cases}$$

$$= d_{f} \left[\begin{array}{c} \vdots \\ -(s-R) \\ - \end{array} \right]$$

$$= d_{f} \left[\begin{array}{c} \vdots \\ - S - \\ - (-R) - \end{array} \right]$$

$$= - d_f \left[\begin{array}{c} -s \\ -R \end{array} \right]$$

(6). If two rows of a matrix A are equal, then $d_f(A) = 0$.

A rows finitely many on equal bimes:
$$d_f(A) = \pm d_f(A') = 0$$

1. If a multiple of one row is added to onother row, the determinant is unchanged.

$$d_f(E_{ij}(\lambda)\cdot A) = d_f(A)$$

2. If two rows are interchanged, the determinant

is multiplied by -1.

$$d_f(P_{ij}\cdot A) = -d_f(A)$$

3. By linearity property of df, we have

$$d_f(E_i(\lambda)\cdot A) = \lambda \cdot d_f(A)$$

Special coses: A = I

(a)
$$d_f(\varepsilon_{ij}(\lambda)) = 1$$

(c)
$$d_f(E_i(x)) = \lambda \qquad (\lambda \neq 0)$$

4. Let E be an elementary motrix and let A be arbitrary square motrix. Then
$$d_{f}(E \cdot A) = d_{f}(E) \cdot d_{f}(A).$$

Question. How to compute determinant of (A)?

$$d_{f}(A') = d_{f}(\underbrace{\varepsilon_{K} \cdots \varepsilon_{2}}, \underbrace{\varepsilon_{1} A}) d_{f}(\varepsilon_{1}) d(A)$$

$$|| Inductively$$

$$= d_{f}(\varepsilon_{K}) \cdots d_{f}(\varepsilon_{1}) \cdot d_{f}(A)$$

Thus $d_f(A) = \frac{1}{d_f(E_K) \cdots d_f(E_f)} \cdot d_f(A')$ $d_f(A) = \frac{1}{d_f(E_K) \cdots d_f(E_f)} \cdot d_f(A')$ $d_f(A) = \frac{1}{d_f(E_K) \cdots d_f(E_f)} \cdot d_f(A')$

Theorem. (Axiomatic Characterization of the Determinent):

The determinant function (given by expansion by minors on the first column,

det A = a11 det A11 - a21 det A2,+, ..., ± an, det An1)

is the only one satisfying rules *, , * 2, and *3.

dj:=det

*,: det(I) = 1

*2: det(A) is linear in the rows of the matrix

*3 14 two adjoient rows of A are equal, then $\det(A) = 0$.

Proof.

Recall,

$$d(A') = d_f(E_K) \cdot \cdot \cdot \cdot d_f(E_f) \cdot d_f(A)$$

Using *, *, and *, we have determined $d_f(E_k)$,...
, $d_f(E_f)$. In thus $d_f(A')$.

D

Notation.

 $d_f(A) := det(A)$

Corollery. A square matrix A is invertible if and only if det A = 0.

$$\mathcal{E}_{\kappa} \cdots \mathcal{E}_{1} A = A$$

Theorem. Let A, B be any two $n \times n$ matrices, then $\det(AB) = (\det A) \cdot (\det B)$.

Shoot.

Proof. Recall, $\det(E \cdot B) = \det(E) \det(B)$ where E is elementary matrix.

We divide the proof in two coses:

(ose 1. Assume that A is invertible.

then $A = E_K \cdots E_1 \cdot \blacksquare$ (product of elementory) motrices

Thus $\det(A) = \det(E_{ik} \cdots E_{i})$ $= \det(E_{ik}) \cdots \det(E_{i})$

NOW,

$$det(AB) = det(E_{K} \cdots E_{i} \cdot B)$$

$$= det(E_{K}) \cdots det(E_{i}) \cdot (detB)$$

$$= det(A) \cdot detB$$

Cose 2. Assume that A is not invertible, then det (A)=0 Enough to prove that det (AB) = 0.

$$A \longrightarrow E_{\Lambda} \longrightarrow \dots \longrightarrow E_{K} E_{K-1} \dots E_{\Lambda} = A'$$

$$det(A'B) = det(E_K \cdots E_f \cdot A'B)$$

$$= det(E_K) \cdots \frac{det(E_f) \cdot (det(A'B))}{df}$$

$$= \frac{det(E_K) \cdots \frac{det(E_f) \cdot (det(A'B))}{df}$$

Since det (Ei) to for any i

Corollory. If A is invertible matrix, then

det
$$(A^{-1}) = \frac{1}{\det(A)}$$
.

Discussion on Problems, Please see the recording.