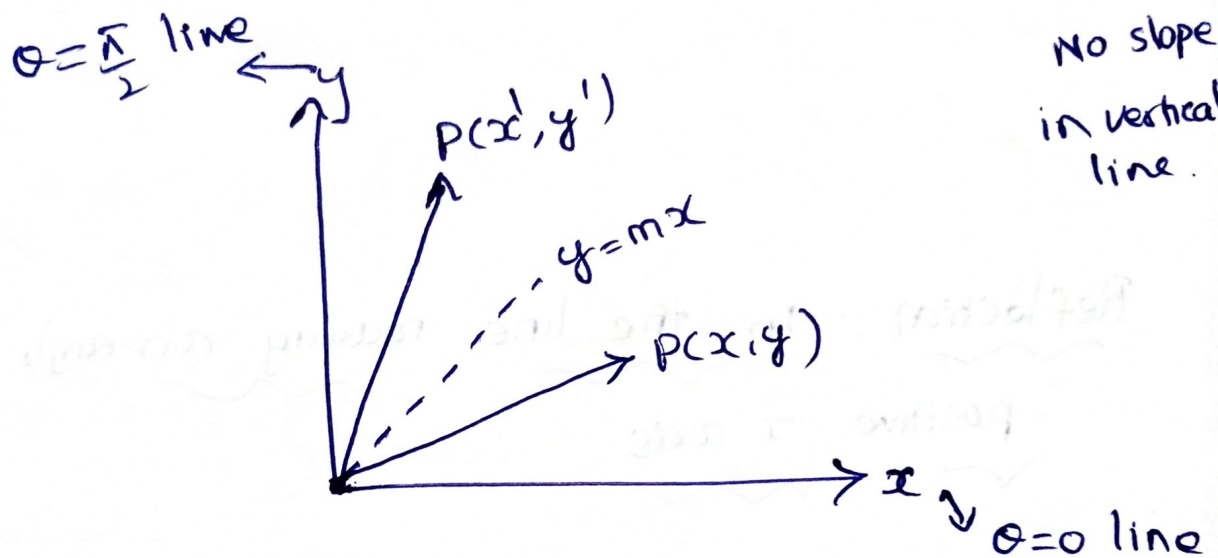


Matrix transformation:

Reflection about line $y = mx$

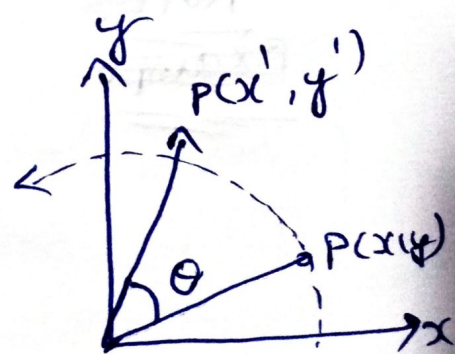
$$\text{Matrix} = \frac{1}{1+m^2} \begin{bmatrix} 1-m^2 & 2m \\ 2m & m^2-1 \end{bmatrix}$$

→ NOTE
Not suitable
for y -axis
ie $x=0$
No slope
in vertical
line.



Rotation in Counter clock wise direction with angle θ :

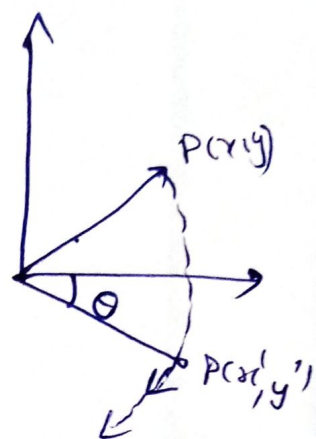
$$\text{Matrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$



Rotation in clockwise direction with an angle θ

$$\text{Matrix} = \begin{bmatrix} \cos(-\theta) & -\sin(-\theta) \\ \sin(-\theta) & \cos(-\theta) \end{bmatrix}$$

$$\text{Matrix} = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$$



Reflection in the line making an angle θ with the positive x-axis

$$\text{Matrix} = \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}$$

NOTE:

Example:

Reflection in the y-axis, i.e. $x=0$

Then $\frac{1}{1+m^2} \begin{bmatrix} 1-m^2 & 2m \\ 2m & m^2-1 \end{bmatrix}$ not suitable

Using $\theta = \frac{\pi}{2}$, Reflection matrix

$$\begin{bmatrix} \cos(\pi) & \sin(\pi) \\ \sin(\pi) & -\cos(\pi) \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

problem Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be rotation through $-\frac{\pi}{2}$

followed by reflection in the y-axis

what is the resultant matrix?

Given

Sol:

$$\theta = -\frac{\pi}{2} \text{ (clockwise)}$$

$$\text{matrix} = \begin{bmatrix} \cos(-\frac{\pi}{2}) & -\sin(-\frac{\pi}{2}) \\ \sin(-\frac{\pi}{2}) & \cos(-\frac{\pi}{2}) \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

Reflection on y-axis

ie y-axis $\Rightarrow x=0$

\therefore ie slope $m=0$

$$\text{from matrix} \Rightarrow \frac{1}{1+m^2} \begin{bmatrix} 1-m^2 & 2m \\ 2m & m^2-1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

problem

Find the matrix of linear transformation which is obtained by first rotating all vectors through angle $\frac{\pi}{6}$ and then reflecting through x-axis

Sol: T_1 : Rotation with $\theta = \pi/6$

$$\text{Rotation matrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

$$= \begin{bmatrix} \cos \frac{\pi}{6} & -\sin \frac{\pi}{6} \\ \sin \frac{\pi}{6} & \cos \frac{\pi}{6} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

T_2 : Reflection about x-axis $\theta = 0$ line i.e. $y = 0$

$$\begin{aligned} &\therefore \text{slope } m = 0 \\ &\text{form matrix } \frac{1}{1+m^2} \begin{bmatrix} 1-m^2 & 2m \\ 2m & m^2-1 \end{bmatrix} \quad \left. \begin{array}{l} \text{(OR)} \\ \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix} \\ \text{with } \theta = 0 \end{array} \right\} \\ &\text{put } m = 0 \\ &= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad \left. \begin{array}{l} \\ \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \end{array} \right\} \end{aligned}$$

∴ ~~Reflection~~ Rotation followed by reflection

T_1 followed by T_2

$$\Rightarrow \cancel{T_1(T_2)} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

$$= \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{\sqrt{3}}{2} \end{bmatrix}$$

Reflection followed by a rotation:

ie 1st Reflection Then Rotation.

R_θ — indicates rotation through angle θ .

R_ϕ — indicates reflection with angle ϕ
through origin

Then

$$\text{Matrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{bmatrix}$$

Rotation followed by reflection

ie First Rotation Then reflection

$$\begin{bmatrix} \cos 2\phi & \sin 2\phi \\ \sin 2\phi & -\cos 2\phi \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

Rotation followed by Rotation:

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

problem

Find matrix for $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ ~~first~~ which rotates
vectors through $-\frac{3\pi}{4}$ Then reflects
through horizontal axis. (x-axis)
 $\rightarrow \phi = 0$ line

Sol:

Given $\theta = -\frac{3\pi}{4}$, $\phi = 0$

$$\text{Matrix} = \begin{bmatrix} \cos 0 & \sin 0 \\ \sin 0 & \cos 0 \end{bmatrix} \begin{bmatrix} \cos(-\frac{3\pi}{4}) & -\sin(-\frac{3\pi}{4}) \\ \sin(-\frac{3\pi}{4}) & \cos(-\frac{3\pi}{4}) \end{bmatrix}$$

Ex (1) Let $P(3, 2)$ after rotation of 90°

New point = ?

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos 90 & -\sin 90 \\ \sin 90 & \cos 90 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

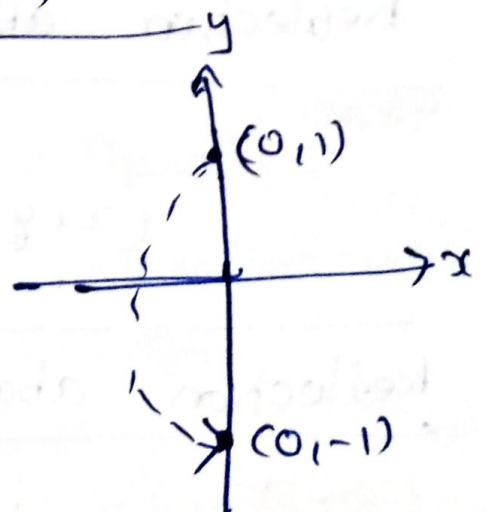
$$= \begin{bmatrix} -2 \\ 3 \end{bmatrix}$$

3

Reflection through x-axis (or) 0° -line

$$\text{matrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\text{ie } (x, y) \rightarrow (x, -y)$$



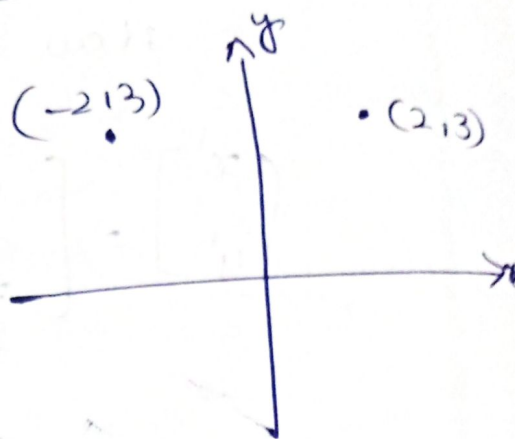
y becomes $-y$

iii

Reflection in y-axis (or) 90° -line

(x, y) becomes $(-x, y)$

$$\text{matrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$



Reflection about $y=x$ (or) 45° -line

$$\text{matrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

(x, y) becomes (y, x)

Reflection about $y=-x$ (or) 135° line

$$\text{matrix} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

(x, y) becomes $(-y, -x)$

Reflection about line $y=kx$ (or) line with slope $=k$

$$\text{matrix} = \frac{1}{1+k^2} \begin{bmatrix} 1-k^2 & 2k \\ 2k & k^2-1 \end{bmatrix}$$

* Rotation followed by a rotation

Let A_{θ_1} is matrix which rotates vectors

through angle θ_1 i.e. $A_{\theta_1} = \begin{bmatrix} \cos \theta_1 & -\sin \theta_1 \\ \sin \theta_1 & \cos \theta_1 \end{bmatrix}$

A_{θ_2} is matrix which rotates vectors

through angle θ_2 i.e. $A_{\theta_2} = \begin{bmatrix} \cos \theta_2 & -\sin \theta_2 \\ \sin \theta_2 & \cos \theta_2 \end{bmatrix}$

Then if we apply these two rotations

in Succession Then

$$\text{matrix} = \begin{bmatrix} \cos(\theta_1 + \theta_2) & -\sin(\theta_1 + \theta_2) \\ \sin(\theta_1 + \theta_2) & \cos(\theta_1 + \theta_2) \end{bmatrix}$$