

PRECISION MODE:

The major limitation of ordinary diode is that it cannot rectify voltages below  $V_f$  ( $\approx 0.6V$ ), the cut-in voltage of the diode. A circuit that acts like an ideal diode can be designed by placing a diode in the feedback loop of an op-amp.

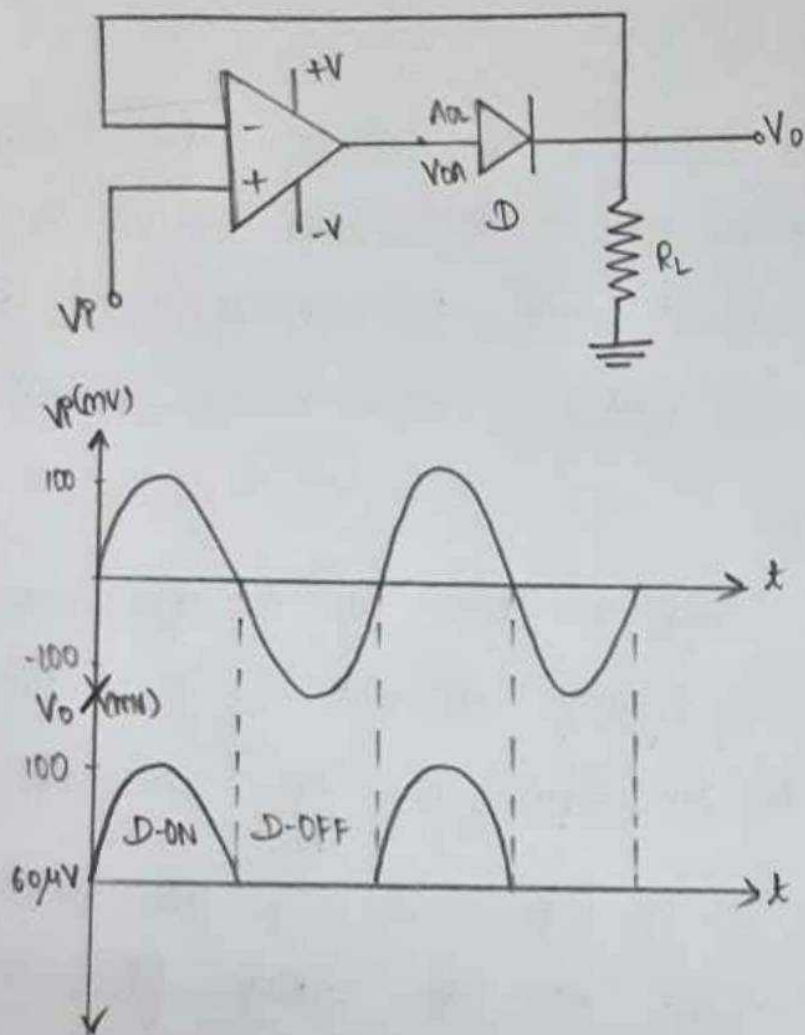
Here, the cut-in voltage is divided by the open loop gain  $A_{OL}$  ( $\approx 10^4$ ) of the op-amp so that  $V_f$  is virtually eliminated. When the input  $V_i > \frac{V_f}{A_{OL}}$ , then  $V_{out}$

the output of the op-amp exceeds  $V_f$  and diode  $D$  conducts. Then circuit acts like voltage follower.

When  $V_i$  is negative or  $V_i < \frac{V_f}{A_{OL}}$  then diode  $D$  is off and no current is delivered to load  $R_L$  except for small bias current of op-amp and reverse saturation current of the diode. This circuit is called precision diode and is capable of rectifying input signals of the order of mV.

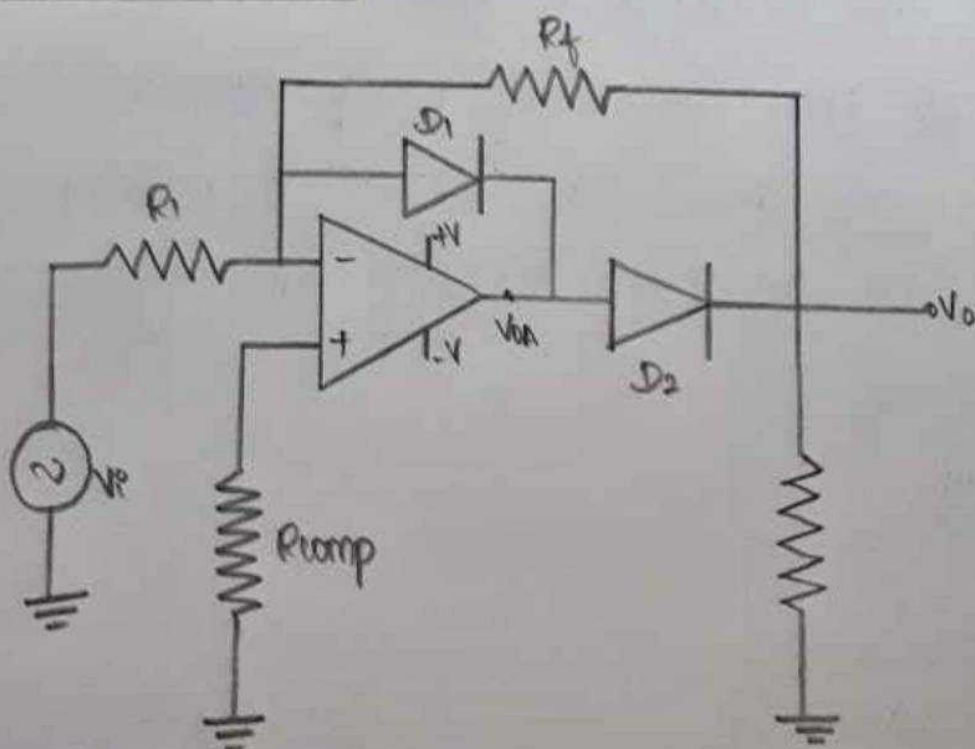
APPLICATIONS:

- \* Half-wave rectifier
- \* Full-wave rectifier
- \* Peak-value detector
- \* Clipper and clamper.



$$\frac{V_Y}{A_{OL}} = \frac{0.6}{10^4} = 60 \mu V$$

### HALF WAVE RECTIFIER::

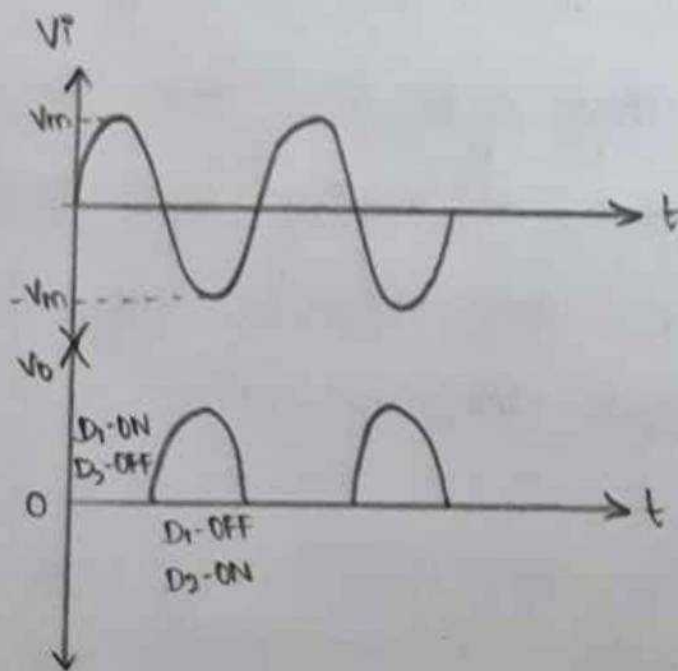




An Inverting amplifier can be converted into an ideal half wave rectifier by adding two diodes.

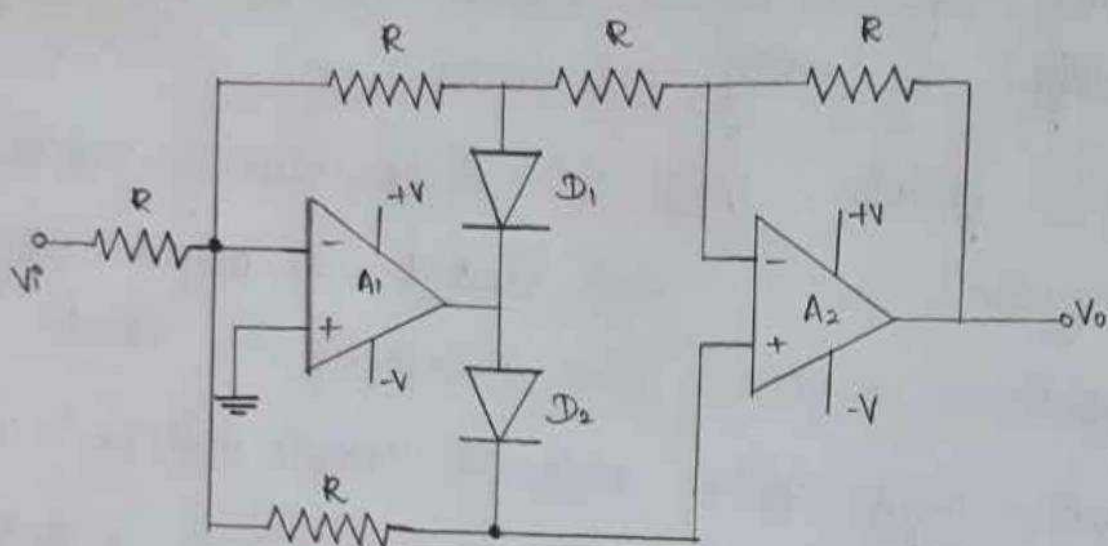
When  $V_i$  is positive, diode  $D_1$  conducts causing  $V_{OA}$  to go to negative.  $D_2$  is reverse biased. The output voltage  $V_o$  is zero, so no current flows through  $R_f$ ,  $D_1$  conducts.

For negative input  $V_i < 0$ , diode  $D_2$  conducts and  $D_1$  is off. The negative input  $V_i$  forces the op-amp output  $V_{OA}$  positive and causes  $D_2$  to conduct. The circuit acts like inverter for  $R_f = R_1$  and  $V_o$  is positive.



### FULL-WAVE RECTIFIER:-

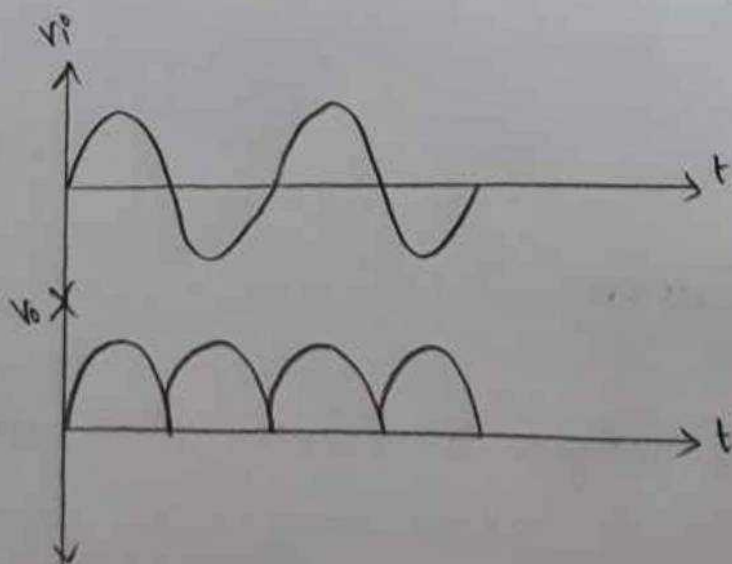
A full wave rectifier or absolute value circuit



For positive input,  $V_i > 0$ , diode  $D_1$  is ON and  $D_2$  is OFF. Both the op-amps  $A_1$  and  $A_2$  act as inverters.

For negative input  $V_i < 0$  diode  $D_1$  is OFF and  $D_2$  is ON.

Let the output voltage of  $A_1$  be  $V$ . Since the differential input to  $A_2$  is zero the inverting input terminal is also at voltage  $V$ . When  $V_i < 0$ , the output is positive. The input and output waveforms are.

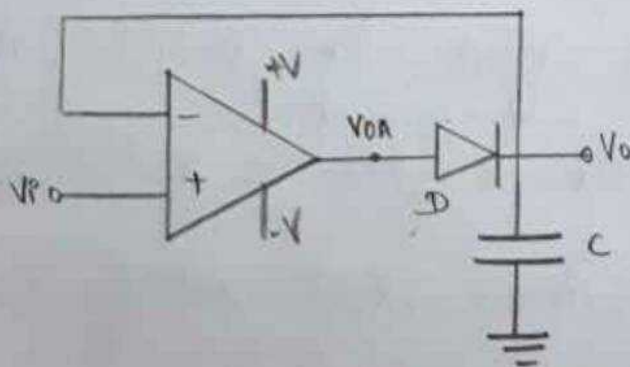




This circuit is called absolute value circuit as output is positive even when input is negative.

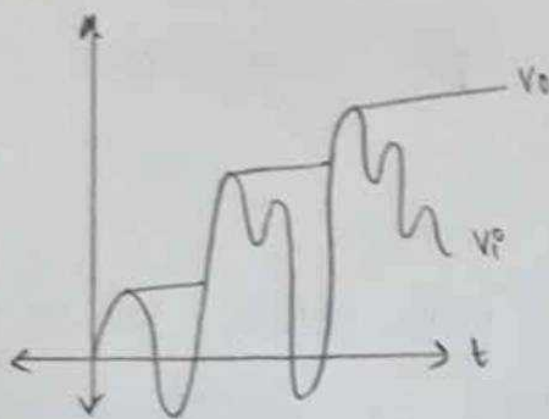
### PEAK DETECTOR:-

The function of a peak detector is to compute the peak value of the input. The circuit follows the voltage peaks of a signal and stores the highest value on a capacitor. If a higher peak signal value comes along, this new value is stored. The highest peak value is stored until the capacitor is discharged.



When input  $V_p > V_c$  (voltage across capacitor), D is forward biased and circuit becomes voltage follower. The output voltage  $V_o$  follows  $V_p$  till  $V_p$  exceeds  $V_c$ .

When  $V_p < V_c$ , D is reverse biased, and capacitor holds charge till  $V_p$  again attains value greater than  $V_c$ .



Peak detectors find application in test and measurement instrumentation as well as in amplitude modulation (AM) communication.

### OSCILLATOR:

Oscillators can generate output signal without any AC input signal. It generates different frequency. Positive feedback is given to oscillators.

An oscillator circuit should satisfy Barkhausen criterion.

The conditions are:

(i)  $|A\beta| = 1$

where  $A \rightarrow$  loop gain

$\rightarrow \beta$  is feedback factor (transfer ratio)

(ii) The total phase shift of ~~the network~~ around the loop is  $0^\circ$

$$\theta = 360^\circ \text{ (or) } 0^\circ$$



## TYPES OF OSCILLATOR:

\* Low frequency oscillator

(i) RC phase shift oscillator

(ii) Wien Bridge oscillator

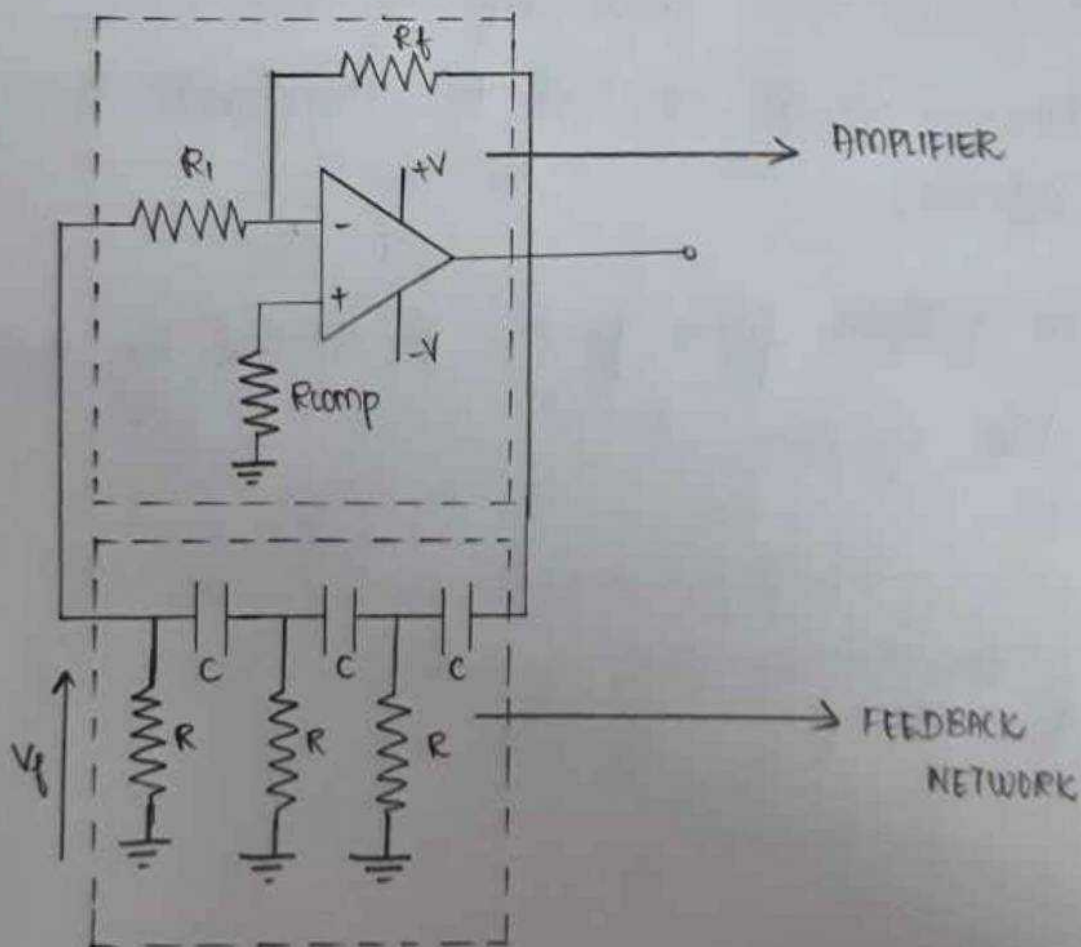
\* High frequency oscillator

(i) Hartley oscillator

(ii) Colpitts oscillator.

## RC - PHASE SHIFT OSCILLATOR:

The circuit of an RC-phase shift oscillator



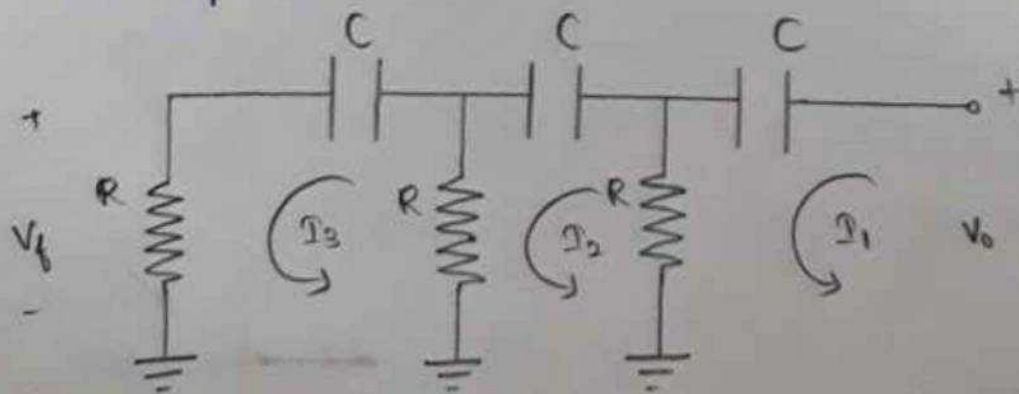
The op-amp is used in inverting mode and therefore provides  $180^\circ$  phase shift. The additional phase of  $180^\circ$  is provided by the RC feedback network to obtain a total phase shift of  $360^\circ$ .

The feedback network consists of three identical RC stages. Each of the RC stages provides  $60^\circ$  phase shift so the total phase shift due to feedback network is  $180^\circ$ .

It is not necessary to use identical RC sections, even if non-identical sections of RC are used it is possible to obtain total phase shift of  $180^\circ$ .

This phenomenon can lead to undesirable inter-modal oscillations.

The feedback factor  $\beta$  can be obtained by applying KVL equations:





$$I_1 \left( R + \frac{1}{sC} \right) - I_2 R = 0 \longrightarrow \textcircled{1}$$

$$I_2 \left( 2R + \frac{1}{sC} \right) - I_1 R - I_3 R = 0 \longrightarrow \textcircled{2}$$

$$I_3 \left( 2R + \frac{1}{sC} \right) - I_2 R = 6 \longrightarrow \textcircled{3}$$

$$V_f = I_3 R \longrightarrow \textcircled{4}$$

By solving  $\textcircled{1}$ ,  $\textcircled{2}$  and  $\textcircled{3}$  equations

$$I_3 = \frac{V_0 R^2 s^3 C^3}{1 + 5sRC + 6s^2 C^2 R^2 + s^3 R^3 C^3}$$

substitute  $I_3$  in  $\textcircled{4}$ ,

$$V_f = \frac{V_0 R^3 s^3 C^3}{1 + 5sRC + 6s^2 R^2 C^2 + s^3 R^3 C^3}$$

WKT,

$$\beta = \frac{V_f}{V_0}$$

$$\beta = \frac{R^3 s^3 C^3}{1 + 5sRC + 6s^2 R^2 C^2 + s^3 R^3 C^3}$$

Divide  $R^3 s^3 C^3$  on both numerator and denominator

$$\beta = \frac{1}{\frac{1}{R^3 s^3 C^3} + \frac{5}{sRC} + \frac{6}{s^2 R^2 C^2} + 1}$$

In steady state,  $s = j\omega$

$$\beta = \frac{1}{\frac{1}{R^3 \omega^3 C^3} + \frac{5}{j^2 \omega^2 R^2 C^2} + \frac{6}{j \omega R C} + 1}$$

$$j^2 = -1 ; j^3 = -j$$

$$\beta = \frac{1}{\frac{-1}{j R^3 \omega^3 C^3} - \frac{5}{\omega^2 R^2 C^2} + \frac{6}{j \omega R C} + 1}$$

$$\text{Take } \alpha = \frac{1}{\omega R C}$$

$$\beta = \frac{1}{\frac{-\alpha^3}{j} - 5\alpha^2 + \frac{6\alpha}{j} + 1}$$

$$= \frac{1}{1 - 6\alpha j - 5\alpha^2 + \alpha^3 j}$$

$$\beta = \frac{1}{(1 - 5\alpha^2) + \alpha j(\alpha^2 - 6)}$$

For  $A\beta = 1$  ;  $\beta$  should be real, (i.e): Imaginary term = 0;

$$\alpha(6 + \alpha^2) = 0$$

$$\alpha^2 - 6 = 0$$

$$\alpha^2 = 6$$

$$\therefore \alpha = \sqrt{6}$$

$$\text{That is } \frac{1}{\omega R C} = \sqrt{6}$$



The frequency of oscillation,  $f_0$  is

$$f_0 = \frac{1}{2\pi RC\sqrt{6}}$$

On equating real part to zero,  $\beta$  is

$$[\alpha = \sqrt{6}]$$

$$\beta = \frac{1}{1 - 5\alpha^2} = \frac{1}{1 - 5(\sqrt{6})^2}$$

$$= \frac{1}{1 - 5(6)} = \frac{1}{1 - 30}$$

$$\therefore \beta = \frac{-1}{29}$$

The negative sign indicates feedback network produces  $180^\circ$  phase shift

$$|\beta| = \frac{1}{29}$$

$$|A\beta| \geq 1$$

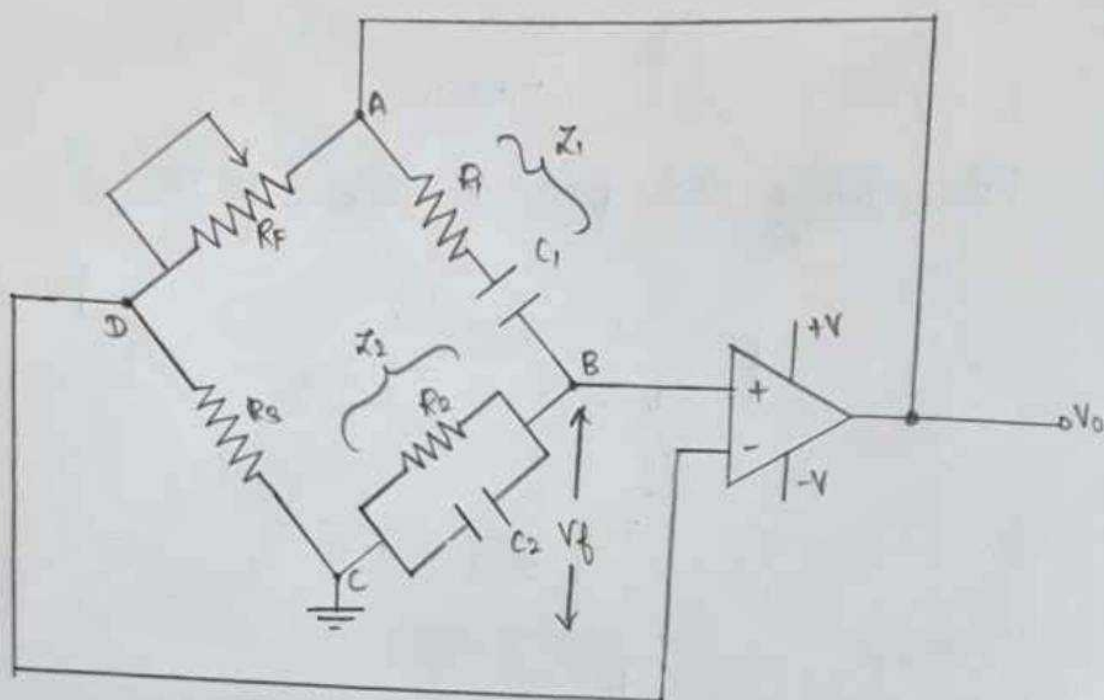
$$\underline{\underline{|A| \geq 29}}$$

The gain of inverting op-amp should be atleast 29 (or)  $R_f = 29k$ . The gain  $A_v$  is kept greater than 29 to ensure that variations in circuit parameters will not make  $|A_v\beta| < 1$ , otherwise oscillations will die out.

### WEIN BRIDGE OSCILLATION:

Another commonly used audio frequency oscillator is a

Wien Bridge oscillator.



It may be noted that the feedback signal in this circuit is connected to the non-inverting (+) input terminal so that the op-amp is working as non-inverting amplifier. Therefore, the feedback network need not provide any phase shift.

The circuit has series RC in one arm and parallel RC in adjoining arm. Resistors  $R_1$  and  $R_F$  are connected in remaining two arms.

The condition of zero phase shift around the circuit is achieved by balancing the bridge.

The feedback signal  $V_f$  across parallel combination  $R_3C_2$  is applied to non-inverting input terminal of the op-amp.



The gain A is,

$$A = 1 + \frac{R_F}{R_g}$$

feedback factor,  $\beta$  is

$$\beta = \frac{V_f}{V_o} = \frac{Z_2}{Z_1 + Z_2} \rightarrow \textcircled{1}$$

$$Z_1 = R_1 + \frac{1}{sC_1}$$

$$Z_1 = \frac{R_1 s C_1 + 1}{s C_1}$$

$$Z_2 = R_2 \parallel \frac{1}{sC_2} = \frac{R_2 \times \frac{1}{sC_2}}{R_2 + \frac{1}{sC_2}}$$

$$Z_2 = \frac{R_2}{1 + R_2 s C_2}$$

sub  $Z_1, Z_2$  in  $\textcircled{1}$ ,

$$\begin{aligned} \beta &= \frac{\frac{R_2}{1 + R_2 s C_2}}{\frac{1 + R_1 s C_1}{s C_1} + \frac{R_2}{1 + R_2 s C_2}} = \frac{\frac{R_2}{(1 + R_2 s C_2)}}{\frac{(1 + R_1 s C_1)(1 + R_2 s C_2) + R_2 s C_1}{(s C_1)(1 + R_2 s C_2)}} \\ &= \frac{R_2 s C_1}{R_2 s C_1 + (1 + R_1 s C_1)(1 + R_2 s C_2)} \\ &= \frac{R_2 s C_1}{R_2 s C_1 + 1 + R_2 s C_2 + R_1 s C_1 + s^2 R_1 R_2 C_1 C_2} \end{aligned}$$

In steady state,  $s = j\omega$

$$\beta = \frac{j\omega R_2 C_1}{R_1 j\omega C_1 + 1 + R_2 j\omega C_2 + R_1 j\omega C_1 + j^2 \omega^2 R_1 R_2 C_1 C_2}$$

WKT,  $j^2 = -1$

$$= \frac{j\omega R_2 C_1}{1 + j\omega(R_1 C_1 + R_2 C_2 + R_2 C_1) - \omega^2(R_1 R_2 C_1 C_2)}$$

$$\beta = \frac{j\omega R_2 C_1}{(1 - \omega^2(R_1 R_2 C_1 C_2)) + j\omega(R_1 C_1 + R_2 C_2 + R_2 C_1)}$$

In order  $\beta$  to be a real quantity,

$$1 - \omega^2(R_1 R_2 C_1 C_2) = 0$$

Thus the frequency of oscillation,  $f_0$  is

$$1 = \omega^2(R_1 R_2 C_1 C_2)$$

$$\omega = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}$$

$$f_0 = \frac{1}{2\pi \sqrt{R_1 R_2 C_1 C_2}}$$

If  $R_1 = R_2 = R$  and  $C_1 = C_2 = C$

$$f_0 = \frac{1}{2\pi \sqrt{R^2 C^2}}$$

$$\therefore f_0 = \frac{1}{2\pi RC}$$



On equating imaginary to zero,  $\beta$  is

$$\beta = \frac{\omega R_2 C_1}{\omega(R_1 C_1 + R_2 C_2 + R_2 C_1)}$$

when  $R_1 = R_2 = R$  and  $C_1 = C_2 = C$

$$\beta = \frac{RC}{RC + RC + RC}$$

$$= \frac{RC}{3RC}$$

$$\boxed{\beta = \frac{1}{3}}$$

WKT,

$$|\beta| = 1$$

$$\underline{\underline{|\beta| \geq 3}}$$

$$A = 1 + \frac{R_f}{R_3} \Rightarrow 3 = 1 + \frac{R_f}{R_3}$$

$$\therefore R_f = 2R_3$$

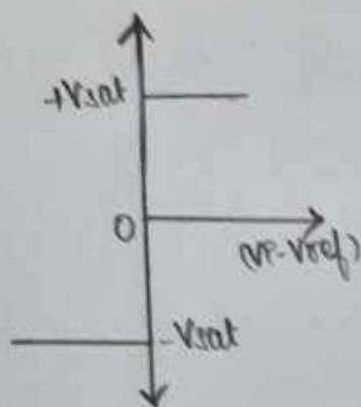
### COMPARATOR:

A comparator is a circuit which compares a signal voltage applied at one input of an op-amp with a known reference voltage at the other input.

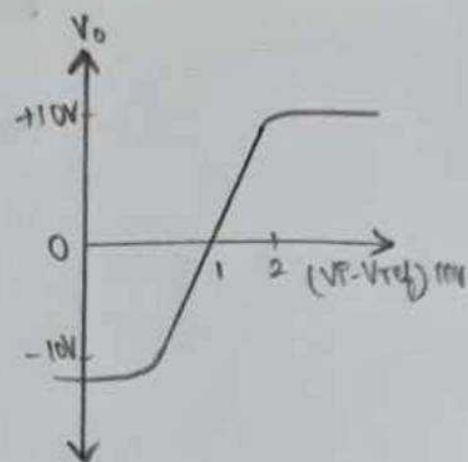
It is basically an open-loop op-amp with output  $\pm V_{sat}$  ( $= V_{cc}$ ).

The transfer characteristics of

(i) Ideal comparator



(ii) Practical comparator



It may be seen that the change in the output state takes place with an increment in input  $V_i$  of only 2mV. This is uncertainty region, where output cannot be directly defined. This region is due to input offset voltage and offset null compensating techniques can be used to eliminate this.

Types of comparators:

- \* Non Inverting comparator
- \* Inverting comparator

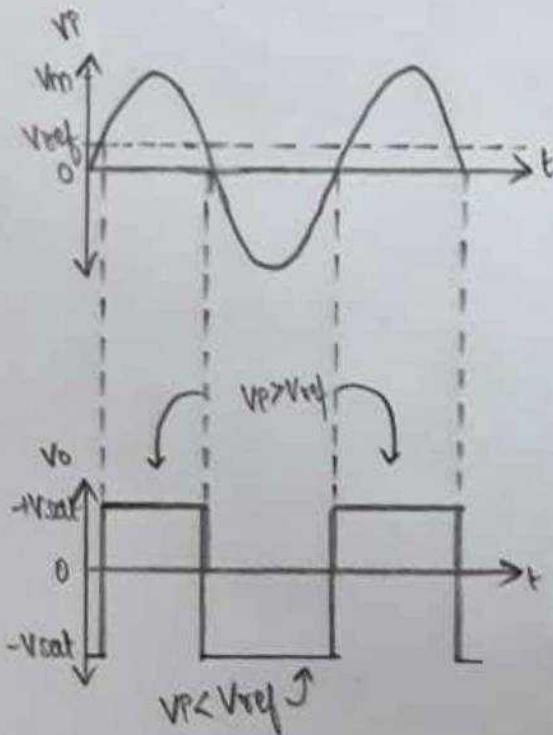
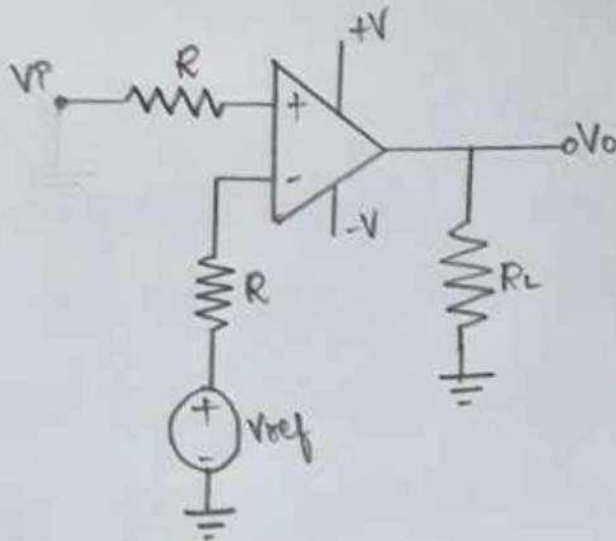
Non-Inverting Comparator:

A fixed reference voltage  $V_{ref}$  is applied to (-) input and a time varying signal  $V_i$  applied to (+) input. The output voltage is at  $-V_{sat}$  for  $V_i < V_{ref}$ . And  $V_o$  goes to  $+V_{sat}$

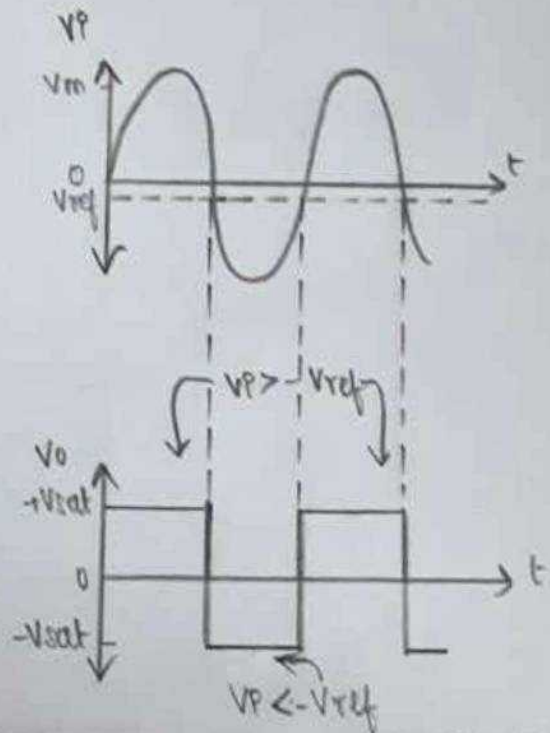


for  $V_i > V_{ref}$

The non-inverting comparator circuit and output waveforms.



$V_{ref}$  is positive



$V_{ref}$  is negative

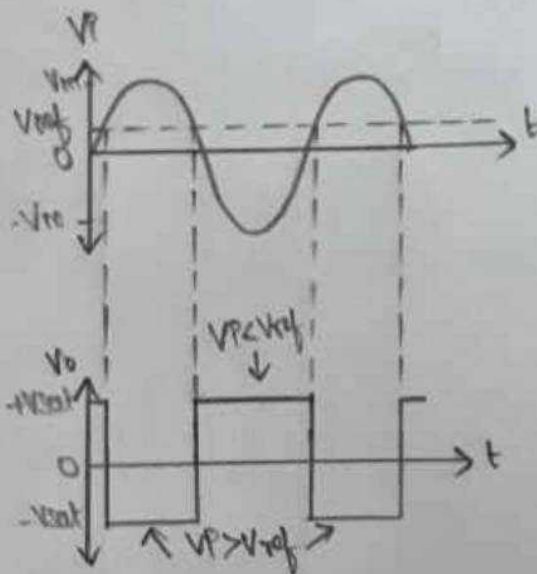
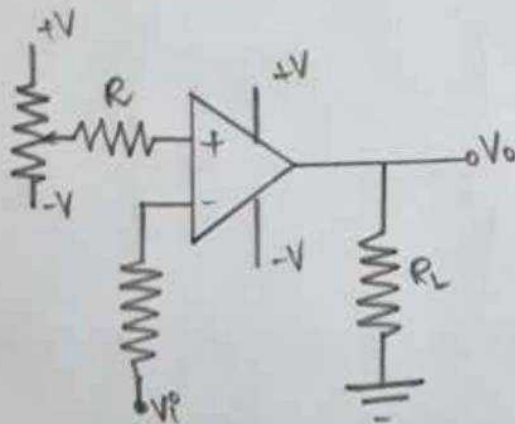
Inverting Amplifier:

The reference voltage  $V_{ref}$  is applied to (+) input and  $V_i$  is applied to (-) input. The output voltage is at  $-V_{sat}$

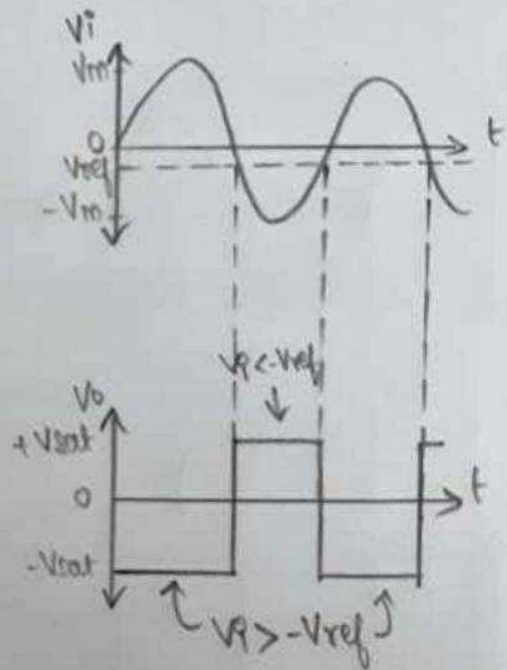
for  $V_i > V_{ref}$  and  $V_o$  goes to  $+V_{sat}$  for  $V_i < V_{ref}$

$V_{ref}$  is obtained by connecting a potentiometer to (+) Input.

The Inverting comparator circuit and output waveforms are.



$V_{ref} > 0$



$V_{ref} < 0$

### APPLICATIONS OF COMPARATOR.

Some important applications of comparator are:

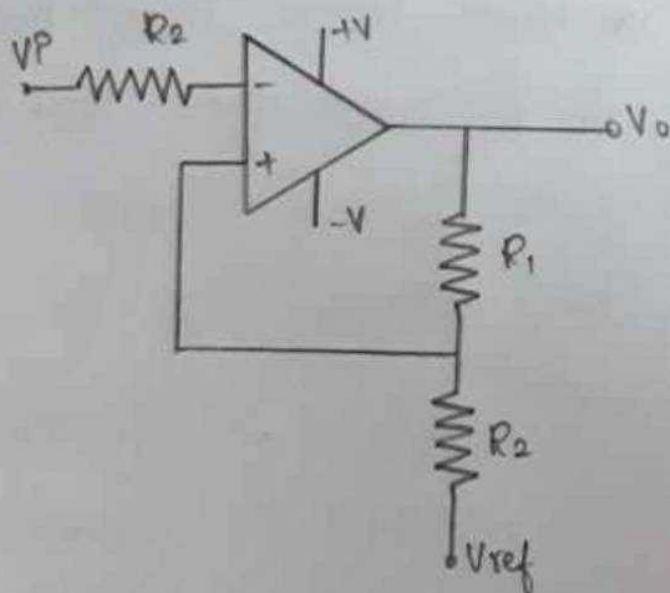
- \* Zero crossing detector
- \* Window detector
- \* Time marker generator
- \* Phase meter.



## REGENERATIVE COMPARATOR (SCHMITT TRIGGER)

If positive feedback added to comparator circuit, gain can be increased greatly. It may not be possible to maintain loop gain exactly equal to unity for a long time because of supply voltage and temperature variations, in practical circuits. So value greater than unity is chosen. It also gives output waveform virtually discontinuous at comparison voltage. This circuit exhibits phenomenon called hysteresis or backlash.

### Regenerative comparator:



The input is applied to (-) terminal and feedback voltage to (+) terminal.  $V_P$  triggers  $V_o$  every time it exceeds upper threshold voltage ( $V_{UT}$ ) and lower threshold

voltage ( $V_{LT}$ ). The hysteresis width is difference between these two threshold voltages.

when  $V_P < V_{UT}$ :  $V_H = V_{UT} - V_{LT}$

Upper threshold voltage,  $V_{UT}$  is

$V_O = +V_{sat}$

$$V_{UT} = \frac{V_{ref} R_1}{R_1 + R_2} + \frac{R_2 V_{sat}}{R_1 + R_2}$$

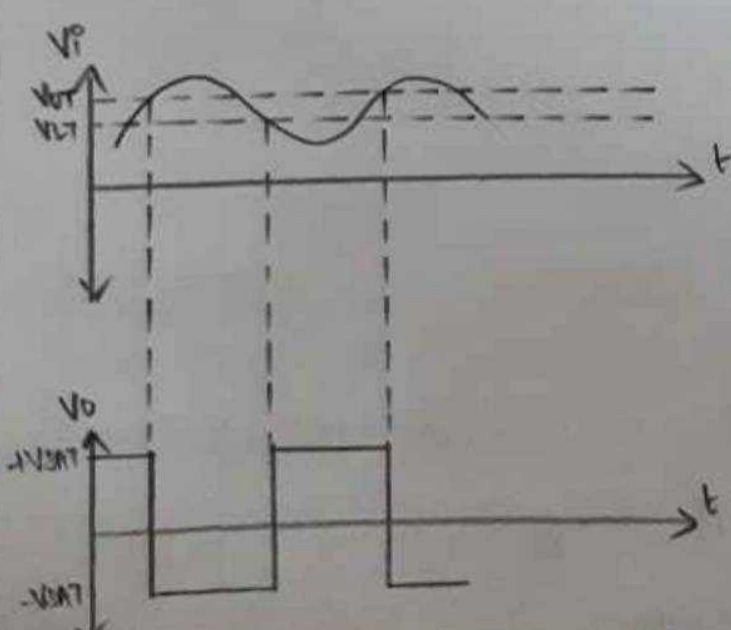
when  $V_P > V_{UT}$ :

$V_O = -V_{sat}$

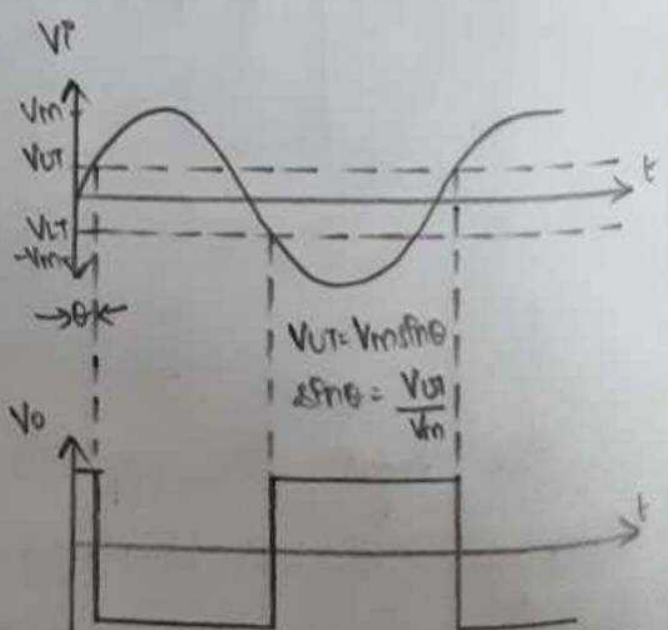
Lower threshold voltage,  $V_{LT}$  is

$$V_{LT} = \frac{V_{ref} R_1}{R_1 + R_2} - \frac{R_2 V_{sat}}{R_1 + R_2}$$

The input voltage  $V_P$  must become lesser than  $V_{LT}$  in order to cause  $V_O$  to switch from  $-V_{sat}$  to  $+V_{sat}$



Simple trigger used as square wave



Shift in output for  $V_{UT} = -V_{LT}$



Hysteresis width is,

$$V_H = V_{UT} - V_{LT} = \frac{V_{ref} R_1}{R_1 + R_2} + \frac{R_2 V_{sat}}{R_1 + R_2} - \frac{V_{ref} R_1}{R_1 + R_2} + \frac{R_2 V_{sat}}{R_1 + R_2}$$

$$V_H = \frac{2 R_2 V_{sat}}{R_1 + R_2}$$

Because of hysteresis, the circuit triggers at a higher voltage for increasing signals than decreasing.

If  $V_i < V_H$ , then transition in one direction will never reset itself.

If  $V_{ref} = 0$ , then

$$V_{UT} = -V_{LT} = \frac{R_2 V_{sat}}{R_1 + R_2}$$

The most important application of Schmitt trigger circuit is to convert a very slowly varying input voltage into a square wave output.

### MULTIVIBRATOR:

Multivibrator is a wave shaping circuit.

The output of the multivibrator is a square wave.

### Types of Multivibrator:

(1) Astable Multivibrator

- also called as free running oscillator

- has two quasi stable states

(ii) monostable multivibrator:

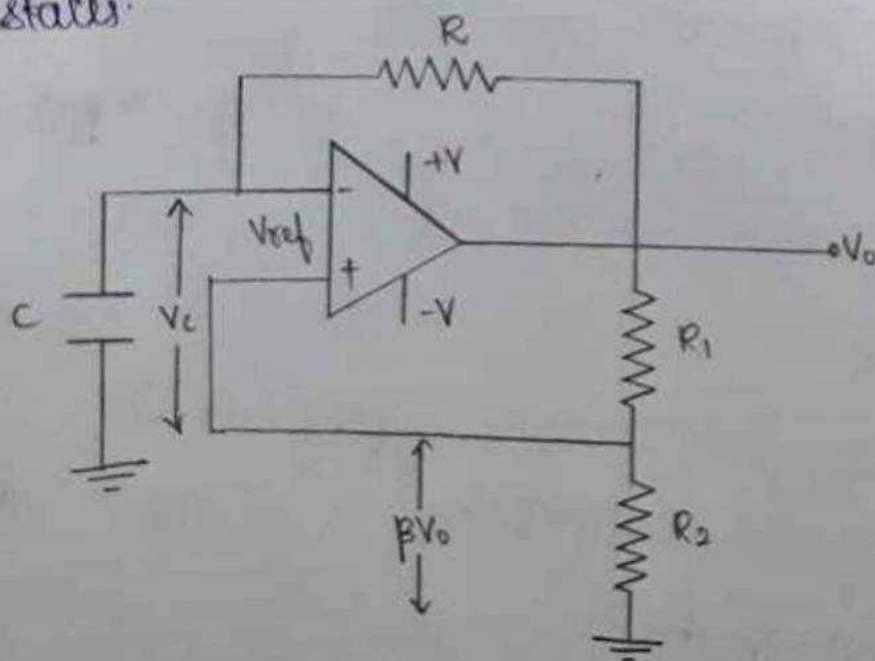
- also called One shot multivibrator
- has one stable and one quasi stable state

(iii) Bistable multivibrator:

- has two stable states
- its applications are flip flops.

### ASTABLE MULTIVIBRATOR

A simple op-amp square wave generator. Also called free running oscillator, the principle of generation of square wave output is to force an op-amp to operate in saturation region. In astable multivibrator, both are quasi stable states.



consider an instant of time when output is at  $+V_{sat}$ . The capacitor now charges from  $-V_{sat}$  through resistor R and



reaches  $+ \beta V_{sat}$ .

When  $V_P > V_{ref}$  transition takes place, therefore the capacitor voltage,  $V_C > V_{ref}$  then transition takes place from  $+V_{sat}$  to  $-V_{sat}$ .

Now the output voltage,  $V_O = -V_{sat}$  then the capacitor discharges from  $+ \beta V_{sat}$  and reaches  $- \beta V_{sat}$ . The voltage again switches from  $-V_{sat}$  to  $+V_{sat}$ .

$V_C \rightarrow$  causes exponentially increasing and decreasing output voltage,  $V_O$ .

The voltage across capacitor  $V_C(t) = V_f + (V_P - V_f) e^{-t/RC}$

$$V_f = +V_{sat}$$

$$V_P = -\beta V_{sat}$$

$$V_C(t) = V_{sat} + (-\beta V_{sat} - V_{sat}) e^{-t/RC}$$

$$\beta V_{sat} = V_{sat} + V_{sat} (-\beta - 1) e^{-t/RC}$$

At  $t = T_1$ ;

$$\beta V_{sat} = V_{sat} [1 + (-1 - \beta) e^{-t/RC}]$$

$$\beta = 1 - (1 + \beta) e^{-t/RC}$$

$$(1 + \beta) e^{-t/RC} = 1 - \beta$$

$$e^{-t/RC} = \frac{1 - \beta}{1 + \beta}$$

$$\frac{1}{e^{T_1/RC}} = \frac{1-\beta}{1+\beta}$$

$$e^{T_1/RC} = \frac{1+\beta}{1-\beta}$$

Take  $\ln$  on both sides,

$$\frac{T_1}{RC} = \ln \left( \frac{1+\beta}{1-\beta} \right)$$

$$T_1 = RC \ln \left( \frac{1+\beta}{1-\beta} \right)$$

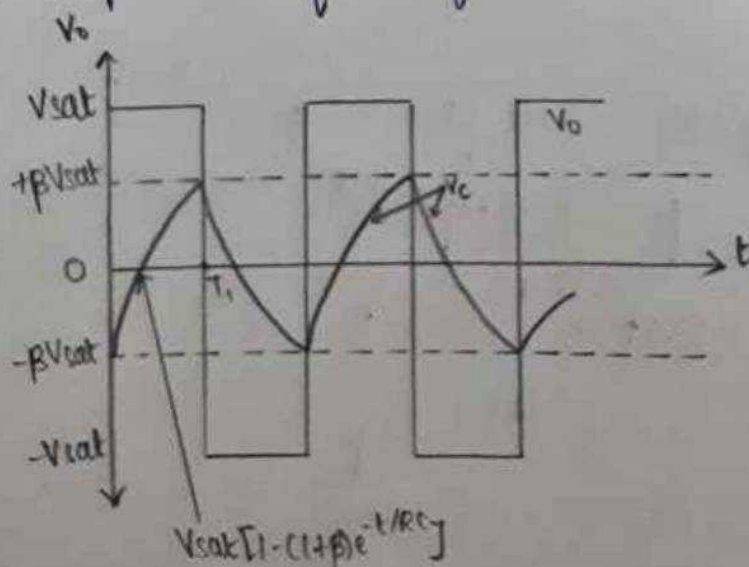
Total time period :

$$T = T_1 + T_2$$

$$T_1 = T_2 = RC \ln \left( \frac{1+\beta}{1-\beta} \right)$$

$$T = 2RC \ln \left( \frac{1+\beta}{1-\beta} \right)$$

The output waveforms of Astable Multivibrator.





## ACTIVE FILTERS:

A frequency selective electronic circuit that passes electronic signals of specific band of frequencies and attenuates the signals of frequencies outside the band is called an electronic filter. The active filters use op-amp as the active element and resistor and capacitor as passive element.

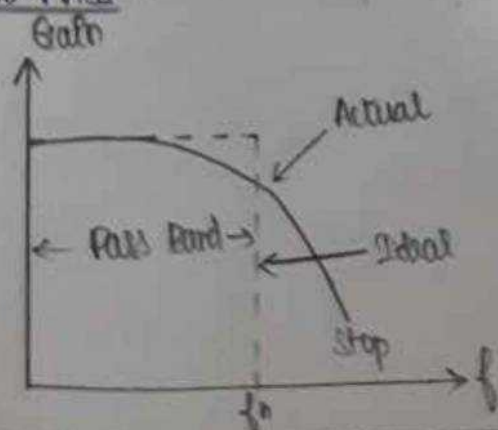
### The advantages of using Op-Amp:

- \* provides gain
- \* Input signal is not attenuated
- \* high input impedance
- \* low output impedance
- \* Improves load drive capacity.

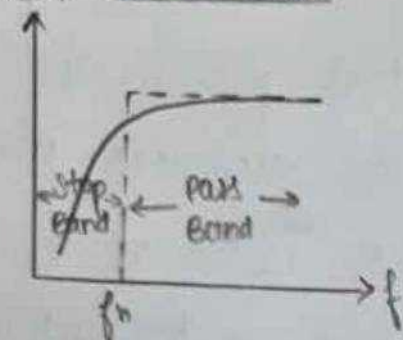
### The most commonly used filters are:

- \* Low Pass Filter (LPF)
- \* High Pass Filter (HPF)
- \* Band Pass Filter (BPF)
- \* Band Reject Filter - also called Band Stop Filter (BSF)

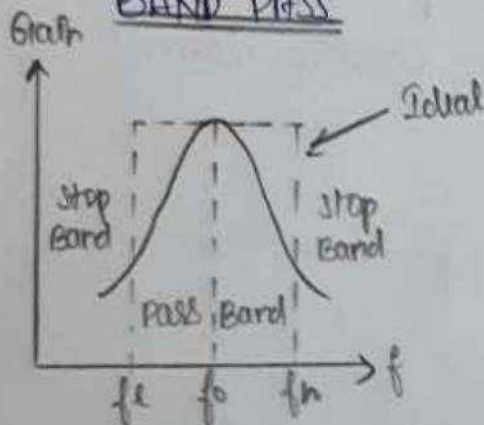
### LOW PASS:



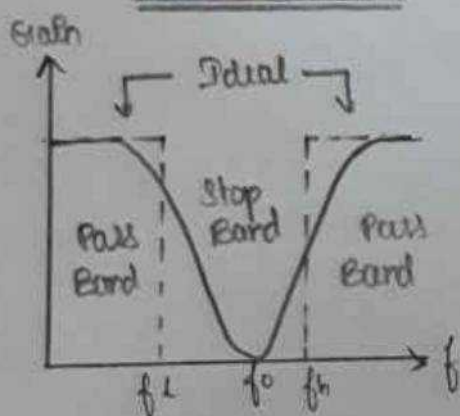
### HIGH PASS



### BAND PASS

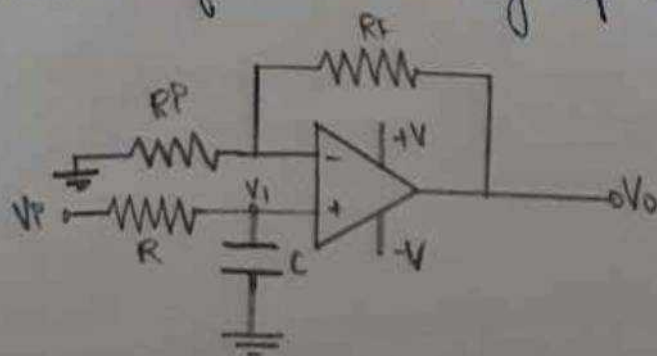


### BAND REJECT

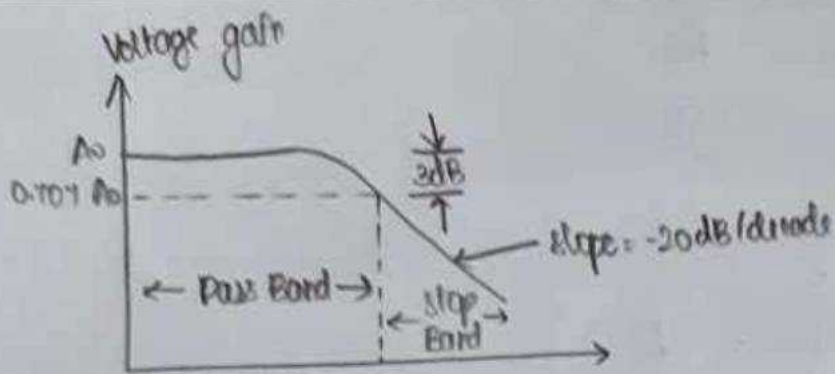


### FIRST ORDER LOW PASS FILTER:

This circuit consists of single RC network connected to (+) terminal of non-inverting op-amp.







voltage across capacitor

$$V_i(s) = \frac{\frac{1}{sC} \cdot V_P(s)}{R + \frac{1}{sC}} = \frac{\frac{V_P(s)}{sC}}{\frac{1 + R s C}{sC}}$$

$$V_i(s) = \frac{V_P(s)}{1 + R s C}$$

$$\frac{V_i(s)}{V_P(s)} = \frac{1}{1 + R s C} \rightarrow \textcircled{1}$$

also, Gain,  $A = \frac{V_o}{V_{in}}$

closed loop gain:

$$A_0 = \left( 1 + \frac{R_f}{R_i} \right) = \frac{V_o(s)}{V_i(s)} \rightarrow \textcircled{2}$$

Transfer function =  $\frac{V_o(s)}{V_P(s)}$

$$H_{LP}(s) = \frac{V_o(s)}{V_P(s)} = \frac{V_o(s)}{V_i(s)} \cdot \frac{V_i(s)}{V_P(s)} \rightarrow \textcircled{3}$$

sub  $\textcircled{1}$  &  $\textcircled{2}$  in  $\textcircled{3}$

$$H_{LP}(s) = \frac{A_0}{1 + sRC}$$

when  $s = j\omega$

$$H_{LP}(j\omega) = \frac{A_0}{1 + j\omega RC}$$

WKT,  $\omega = 2\pi f$

$$= \frac{A_0}{1 + j2\pi f RC}$$

Take  $f_h = \frac{1}{2\pi RC}$

$$H_{LP}(j\omega) = \frac{A_0}{1 + j\left(\frac{f}{f_h}\right)}$$

Magnitude of transfer function is,

$$|H_{LP}(j\omega)| = \frac{A_0}{\sqrt{1 + (f/f_h)^2}}$$

case (i):

when  $f \ll f_h$

$$|H_{LP}(j\omega)| = A_0$$

case (ii):

when  $f = f_h$

$$|H_{LP}(j\omega)| = \frac{A_0}{\sqrt{2}} = 0.707 A_0$$

case (iii):

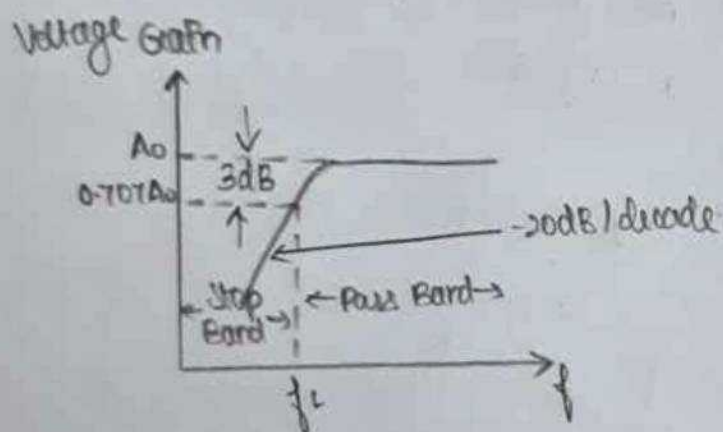
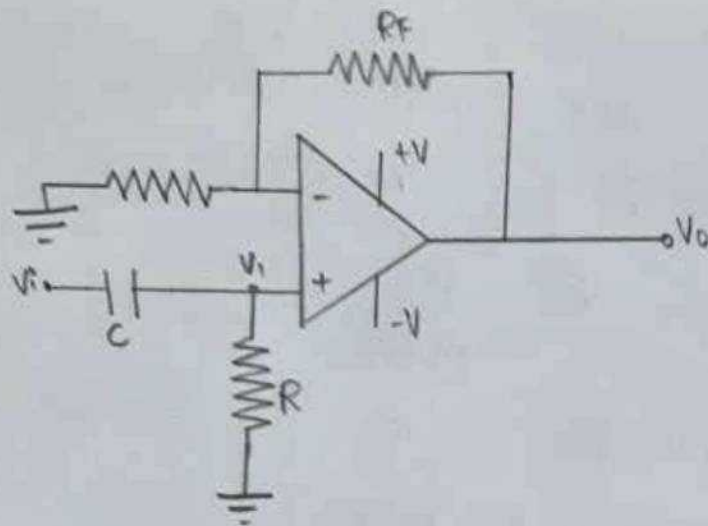
when  $f \gg f_h$

$$|H_{LP}(j\omega)| = 0$$



## HIGH PASS FILTER:

A high pass filter is a complement of low pass filter and can be obtained by interchanging R and C.



Voltage across capacitor,

$$V_i(s) = \frac{V_p(s) \times R}{R + \frac{1}{sC}} = \frac{V_p(s) \times R}{R s C + 1}$$

$$V_i(s) = \frac{V_p(s) R s C}{1 + R s C}$$

$$\boxed{\frac{V_i(s)}{V_p(s)} = \frac{R s C}{1 + R s C}} \quad \rightarrow \textcircled{1}$$

closed loop gain  $A_o$  is

$$A_o = \left( 1 + \frac{R_f}{R_i} \right) = \frac{V_o(s)}{V_i(s)} \rightarrow \textcircled{2}$$

Transfer function  $H_{HP}(s)$  is

$$H_{HP}(s) = \frac{V_o(s)}{V_i(s)} = \frac{V_o(s)}{V_i(s)} \cdot \frac{V_i(s)}{V_p(s)} \rightarrow \textcircled{3}$$

Sub  $\textcircled{1}$ ,  $\textcircled{2}$  in  $\textcircled{3}$ ,

$$H_{HP}(s) = A_o \cdot \frac{R_i C s}{1 + R_i C s}$$

when  $s = j\omega$

$$H_{HP}(j\omega) = \frac{A_o \cdot R_i j\omega C}{1 + j\omega R_i C}$$

where,  $\omega = 2\pi f$

$$H_{HP}(j\omega) = \frac{A_o \cdot j 2\pi f R_i C}{1 + j 2\pi f R_i C}$$

$$\text{Let } f_L = \frac{1}{2\pi R_i C}$$

$$H_{HP}(j\omega) = \frac{A_o \cdot j (f/f_L)}{1 + j (f/f_L)}$$

Divide by  $f/f_L$  on numerator and denominator

$$= \frac{A_o \cdot j}{\frac{1}{f/f_L} + j(1)} = \frac{j \cdot A_o}{\frac{f_L}{f} + j}$$

Magnitude of transfer function is

$$|H_{HP}(j\omega)| = \frac{A_o}{\sqrt{1 + \left(\frac{f_L}{f}\right)^2}}$$



Case (i):

when  $f < f_L$

$$|H_{HP}(j\omega)| = 0$$

Case (ii)

when  $f = f_L$

$$|H_{HP}(j\omega)| = \frac{A_0}{\sqrt{2}} = 0.707 A_0$$

Case (iii)

when  $f > f_L$

$$|H_{HP}(j\omega)| = A_0$$

BAND PASS FILTER:

It allows only a particular range of frequency

It is of two types:

\* Narrow Band Pass Filter

$$Q\text{-factor} > 10$$

\* Wide Band Pass Filter

$$Q\text{-factor} < 10$$

$$\text{where, } Q\text{ factor} = \frac{f_0}{BW}$$

Depending on band width  $Q$ -factor is altered.

BAND REJECT FILTER:

It rejects the particular range of frequencies.

It is of two types:

\* Narrow Band Reject filter / Notch filter.

\* Wide Band Reject filter.

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