Backpropagation in RNNs

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Review: Questions

Questions

• Can RNNs have more than one hidden layer?

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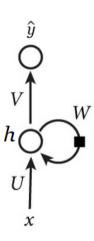
- Can RNNs have more than one hidden layer? Yes! You can also have multiple RNN blocks - these are called stacked RNNs
- The state (h_t) of an RNN records information from all previous time steps. At each new timestep, the old information gets *morphed* slightly by the current input. What would happen if we *morphed* the state too much?

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- The state (h_t) of an RNN records information from all previous time steps. At each new timestep, the old information gets *morphed* slightly by the current input. What would happen if we *morphed* the state too much? **Effect of previous time-steps will be reduced, may not be desirable for sequence learning problems**

RNNs: Forward Pass

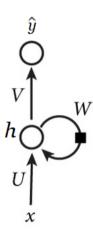


• Forward pass equations:

$$h_t = \tanh(Ux_t + Wh_{t-1})$$
$$\hat{y}_t = \text{softmax}(Vh_t)$$

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RNNs: Forward Pass



Forward pass equations:

$$h_t = \tanh(Ux_t + Wh_{t-1})$$
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Loss function e.g., Cross Entropy loss:

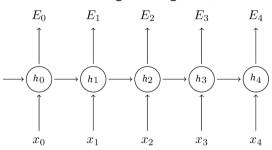
$$E_t(y_t, \hat{y}_t) = -y_t \log \hat{y}_t$$

$$E(y_t, \hat{y}_t) = \sum_t E_t(y_t, \hat{y}_t)$$

$$= -\sum_t y_t \log \hat{y}_t$$

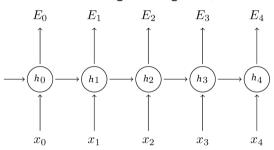
Backpropagation: How?

- Goal: Calculate gradients of error E w.r.t. weights U, V, W
- These gradients will be used to learn weights using SGD; how?



Backpropagation: How?

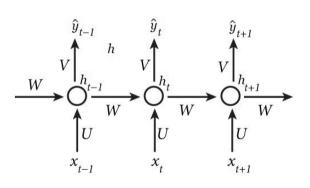
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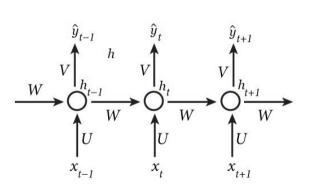
• Backpropagation Through Time (BPTT): We sum up gradients at each time step for one training example: $\frac{\partial E}{\partial W} = \sum_t \frac{\partial E_t}{\partial W}$

Credit: Denny Britz, WildML RNN Tutorial

Vineeth N B (IIT-H) §8.2 Backprop in RNNs 4/13

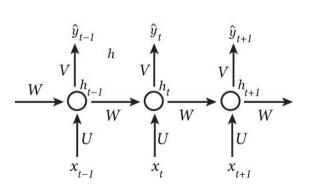


• Consider error at one time step: E_3 ; let us calculate the gradient $\partial E_3/\partial V$



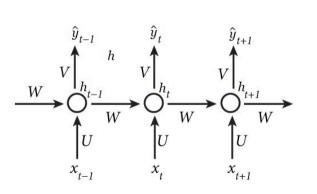
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- Writing $z_3 = Vh_3$, gradient can be calculated as:

$$\frac{\partial E_3}{\partial V} = \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial V}$$



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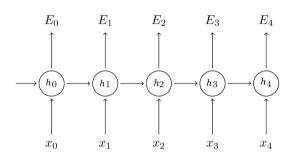
$$\begin{split} \frac{\partial E_3}{\partial V} &= \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial V} \\ &= \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial z_3} \frac{\partial z_3}{\partial V} \end{split}$$



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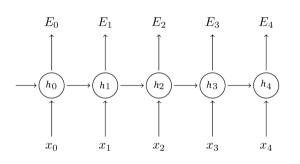
$$\frac{\partial E_3}{\partial V} = \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial V}$$
$$= \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial z_3} \frac{\partial z_3}{\partial V}$$
$$= (\hat{y}_3 - y_3) \otimes h_3$$

where \otimes is outer product



- How about $\partial E_3/\partial W$?
- Can we write it as:

$$\frac{\partial E_3}{\partial W} = \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial W}$$



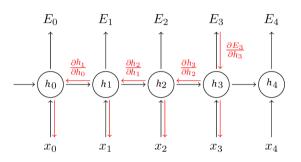
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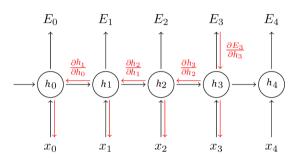
ullet It's not complete, since h_3 depends on W.

$$h_3 = tanh(Ux_2 + Wh_2)$$

Chain rule needs to be applied again!

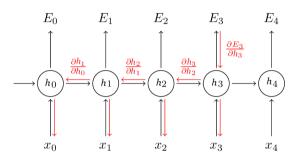


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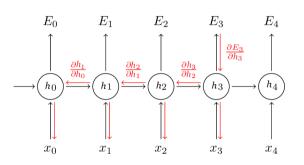
$$\frac{\partial E_3}{\partial W} = \sum_{k=0}^{3} \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \frac{\partial h_3}{\partial h_k} \frac{\partial h_k}{\partial W}$$



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• How about $\partial E_3/\partial U$?



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- How about $\partial E_3/\partial U$? Similar to $\partial E_3/\partial W$
 - Homework!

• Observe that $\partial h_3/\partial h_k$, when k=1, will be further expanded, using chain rule, as:

$$\frac{\partial h_3}{\partial h_1} = \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial h_1}$$

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$$\frac{\partial h_3}{\partial h_1} = \frac{\partial h_3}{\partial h_2} \frac{\partial h_2}{\partial h_1}$$

• Consequently, gradient $\partial E_3/\partial W$ can be written as:

$$\frac{\partial E_3}{\partial W} = \sum_{k=0}^{3} \frac{\partial E_3}{\partial \hat{y}_3} \frac{\partial \hat{y}_3}{\partial h_3} \left(\prod_{j=k+1}^{3} \frac{\partial h_j}{h_{j-1}} \right) \frac{\partial h_k}{\partial W}$$

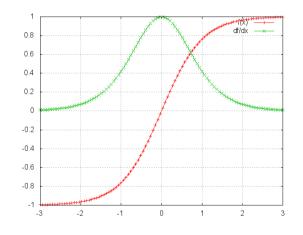
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Do you see any problem?

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Sequences (sentences) can be quite long, perhaps 20 words or more - need to backpropagate through many layers! \implies Vanishing Gradient Problem!

Vanishing Gradient Problem

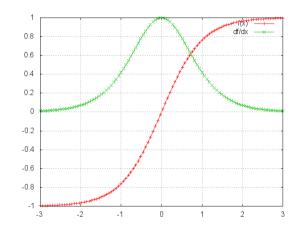


Observe the equation:

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 For sigmoid activations, gradient is upper bounded by 1; what does this tell us?

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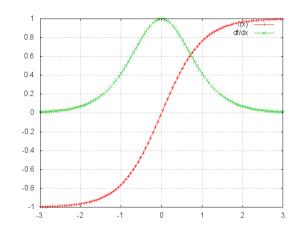


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- Gradients will vanish over time, and long-range dependencies will not contribute at all! How to combat?

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- Gradients will vanish over time, and long-range dependencies will not contribute at all! How to combat? We'll see in the next lecture

Exploding Gradients Problem

• What if weights are high?

Exploding Gradients Problem

- What if weights are high?
- Could lead to the exploding gradients problem
- This, however, is not much of a problem; why?

Exploding Gradients Problem

- What if weights are high?
- Could lead to the exploding gradients problem
- This, however, is not much of a problem; why?
 - Will show up as NaN during implementation
 - Gradient clipping works!

Homework

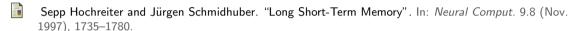
Readings

- Chapter 10 of Deep Learning Book (Goodfellow et al)
- Part 3, Denny Britz, WildML Recurrent Neural Networks Tutorial

Question

• In the next lecture, we'll see architectures that tackle the vanishing gradient problem reasonably well; meanwhile, can you think of simpler solutions (preferably those which don't change the RNN architecture)?

References



- Razvan Pascanu, Tomas Mikolov, and Yoshua Bengio. "On the difficulty of training recurrent neural networks". In: *ICML*, 2013.
- Kyunghyun Cho et al. "On the Properties of Neural Machine Translation: Encoder-Decoder Approaches". In: SSST@EMNLP. 2014.
- lan Goodfellow, Yoshua Bengio, and Aaron Courville. Deep Learning. MIT Press, 2016.