

### Tutorial 3

1) Pseudo code for linear search

```
for (i=0 to n)
{
    if (arr[i] == value)
        // element found
}
```

2) void insertion (int arr[], int n)

```
{
    if (n <= 1)
        return;
    insertion (arr, n-1);
    int nth = arr[n-1];
    int j = n-2;
    while (j >= 0 && arr[j] > nth)
    {
        arr[j+1] = arr[j];
        j--;
    }
    arr[j+1] = nth;
}
```

for (i=1 to n) // iterative

```
{
    key ← arr[i]
    j ← i-1
    while (j >= 0 and arr[j] > key)
    {
        arr[j+1] ← arr[j]
    }
}
```

Insertion Sort is online sorting because it doesn't know the whole input, more input can be inserted with the insertion sorting is running.

Q3 Complexity

Name	Best	Worst	Average
• Selection Sorting	$O(n^2)$	$O(n^2)$	$O(n^2)$
• Bubble Sorting	$O(n^2)$	$O(n^2)$	$O(n^2)$
• Insertion Sorting	$O(n)$	$O(n^2)$	$O(n^2)$
• Heap Sorting	$O(n \log n)$	$O(n \log n)$	$O(n \log n)$
• Quick Sorting	$O(n \log n)$	$O(n^2)$	$O(n \log n)$
• Merge Sorting	$O(n \log n)$	$O(n \log n)$	$O(n \log n)$

Q4)

Inplace Sorting	Stable Sorting	Online Sorting
Bubble	Merge Sort	Insertion
Selection	Bubble	
Insertion	Insertion	
Quick Sort	Count	
Heap Sort		

Q5)

```

int binary (int arr[], int l, int r, int n)
{
    if (l >= r)
    {
        int mid = l * (r - l) / 2
        if (arr[mid] == n)
            return mid;
        else if (arr[mid] > n)
            return binary(arr, l, mid - 1, n);
    }
}

```

SA



else

return binary (arr, mid+1, s, n);

}

return -1;

}

int binary (int arr[], int l, int r, int n)

{ while (l <= r)

{ int m = l + (r-l)/2

if (arr[m] == n)

return m;

else if (arr[m] > n)

r = m-1;

else

l = m+1;

return -1;

}

Time complexity of binary search  $\Rightarrow O(\log n)$

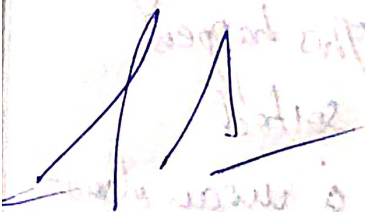
linear search  $\Rightarrow O(n)$

6) Recursive relation for binary recursive search

sol)  $T(n) = T(n/2) + 1$

where  $T(n)$  is the time required for binary

search in an array of size  $n$ .



Q7) int find (A[], n, k)

```

{
    sort (A, n)
    for (i = 0 to n-1)
    {
        n = binary search (A, v, n-1, k - A[i])
        if (n)
            return 1
    }
    return -1
}

```

$$\text{Time complexity} = O(n \log n) + n \cdot O(\log n)$$

$$= O(n \log n)$$

8) Quick Sort is the fastest general purpose sort. In most practical situations, quick sort is the method of choice. If stability is important and space is available, merge sort might be best.

9) A pair  $(a[i], a[j])$  is said to be inversion if  $a[i] > a[j]$

In an  $A = \{7, 21, 31, 8, 10, 1, 20, 6, 7, 5\}$

total no of inversion are 31 using merge sort.

10) The worst case time complexity of quick sort is  $O(n^2)$ . This case occurs when the picked pivot is always an extreme (smallest or largest) element. This happens when input array is sorted or reverse sorted.

The best case is when we select pivot as a mean element



iii) Recurrence relation of  
Merge sort  $\Rightarrow T(n) = 2T(n/2) + n$   
Quick sort  $\Rightarrow T(n) = 2T(n/2) + n$

- Merge sort is more efficient than quick sort in case of larger array size or datasets.
- Worst case complexity for quick sort is  $O(n^2)$  whereas  $O(n \log n)$  for merge sort.

12) Stable selection sort

```
void stable selection (int a[], int n)
{
    for (int i = 0; i < n-1; i++)
    {
        int min = i;
        for (int j = i+1; j < n; j++)
        {
            if (a[min] > a[j])
                min = j;
        }
        int key = a[min];
        while (min > i)
        {
            a[min] = a[min-1];
            min--;
        }
        a[i] = key;
    }
}
```

13) Modified Bubble sorting

```
void bubble (int a[], int n)
{
    for (int i = 0; i < n; i++)
    {
        int swaps = 0
```

```
for (int j=0; j<n-1; j++)
```

```
{ if (a[j] > a[j+1])
```

```
{
```

```
    int t = a[j];
```

```
    a[j] = a[j+1];
```

```
    a[j+1] = t;
```

```
    swaps++;
```

```
}
```

```
}
```

```
if (swaps == 0)
```

```
    break;
```

```
}
```

```
}
```

