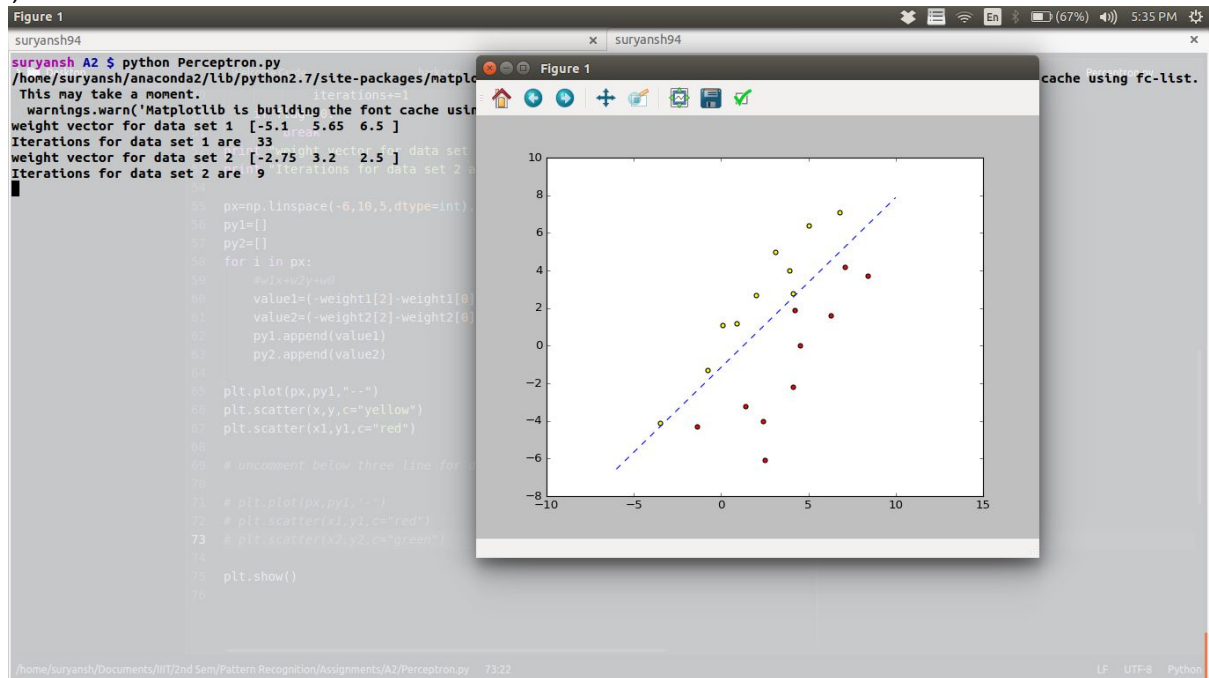


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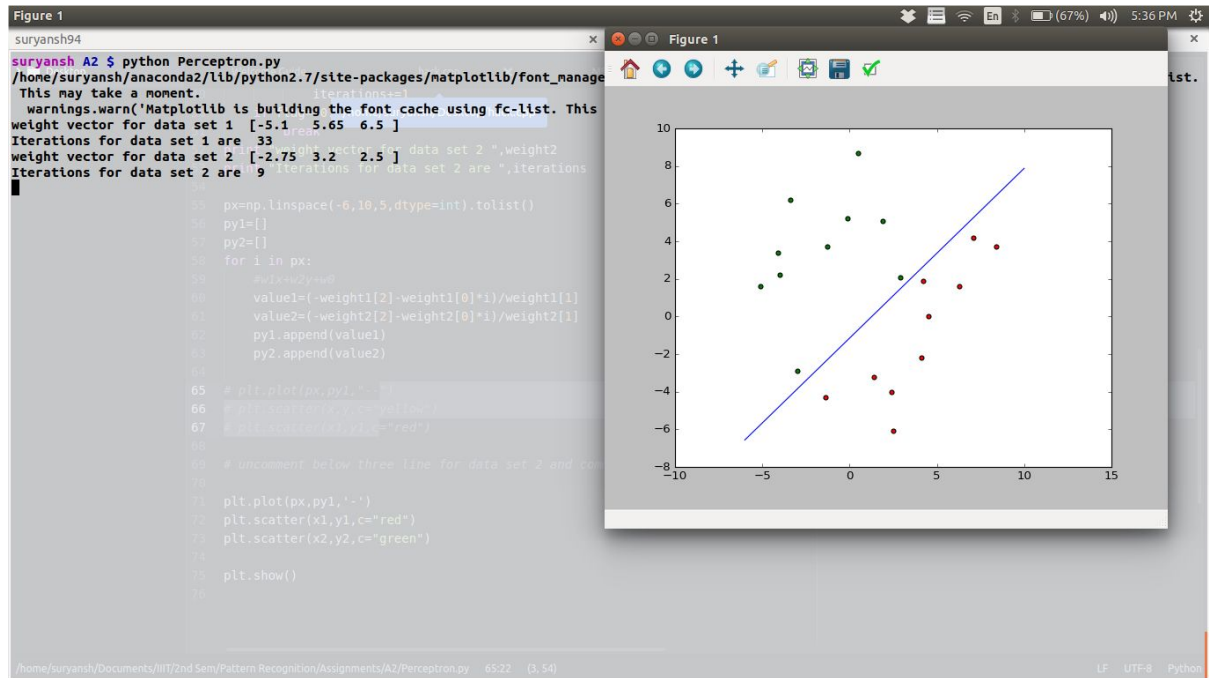
1) Perceptron

i) Number of iterations for data set 1 are 33.



ii)

Number of iteration for data set 2 are 9.



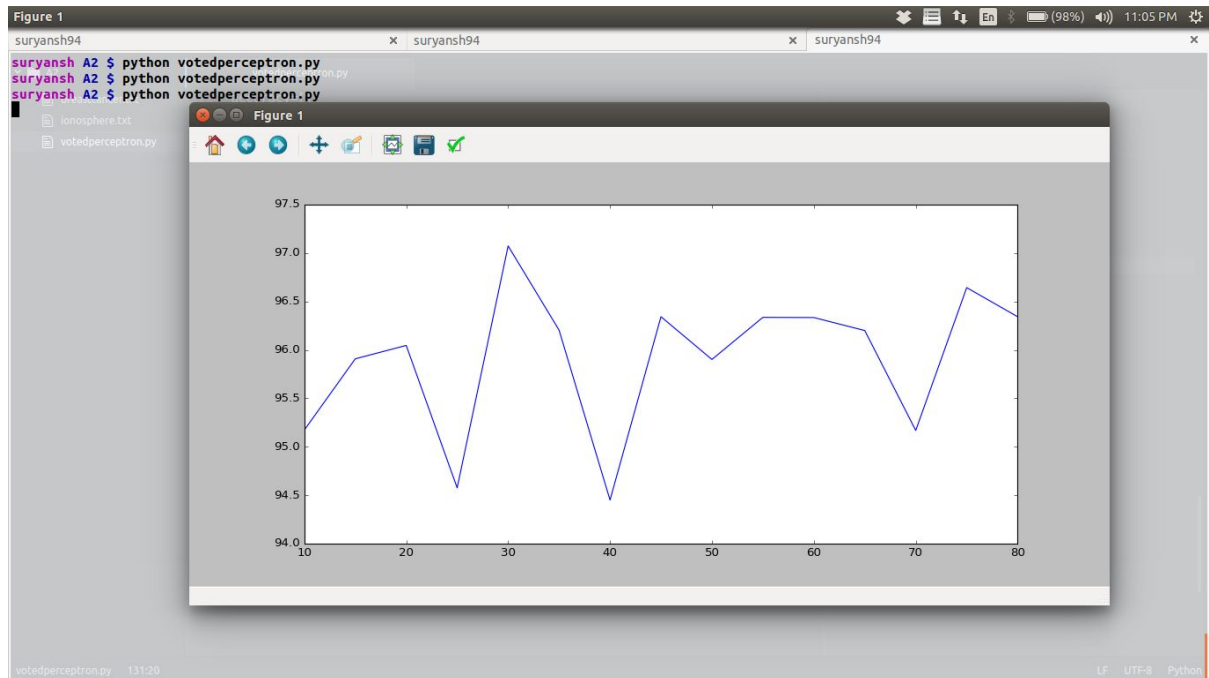
iii)

No of iterations required in the first case is 33 iterations whereas in the second case, 9 iterations are required. Learning rate is both in the same case. The main reason for the difference between number of iterations is because of the data points. In first case the data points are close and that why weight vector(if the point is misclassified) is updated by a small margin and so moving the weight vector in the solution region takes more time as compared to second case where the data is scattered far away and so the weight vector is updated by more margin.

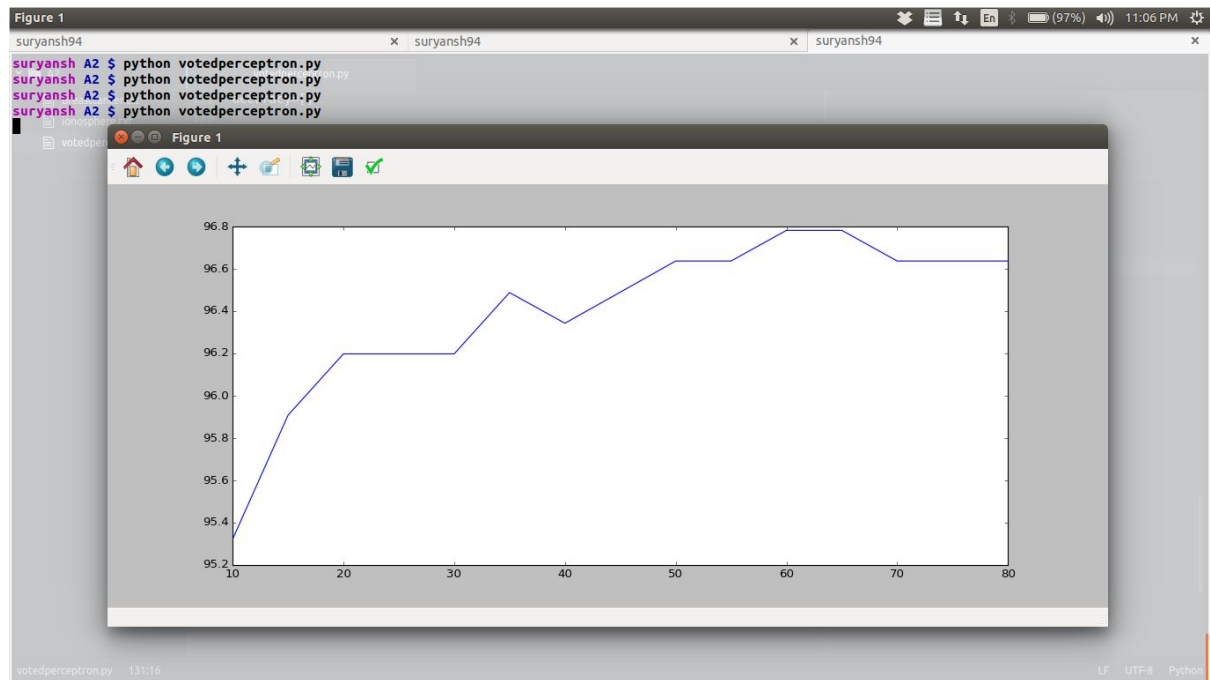
2)

Data Set of Breast Cancer

Epoch vs Accuracy (vanilla)

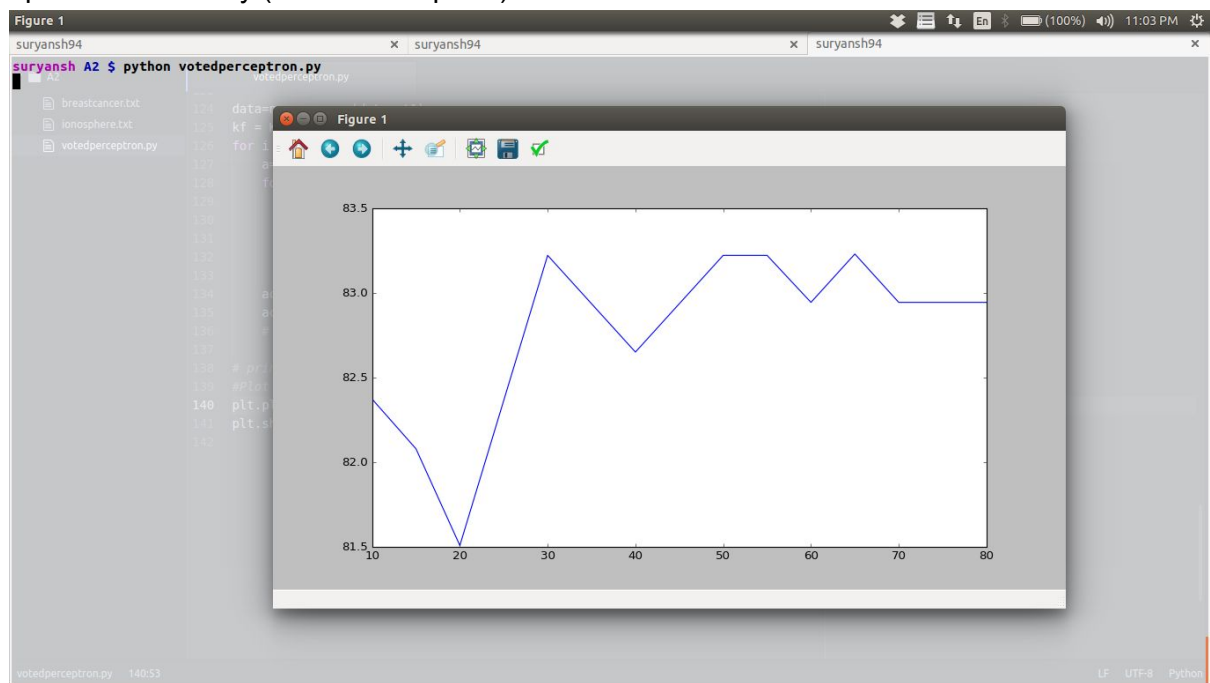


Epoch vs Accuracy (Voted Perceptron)

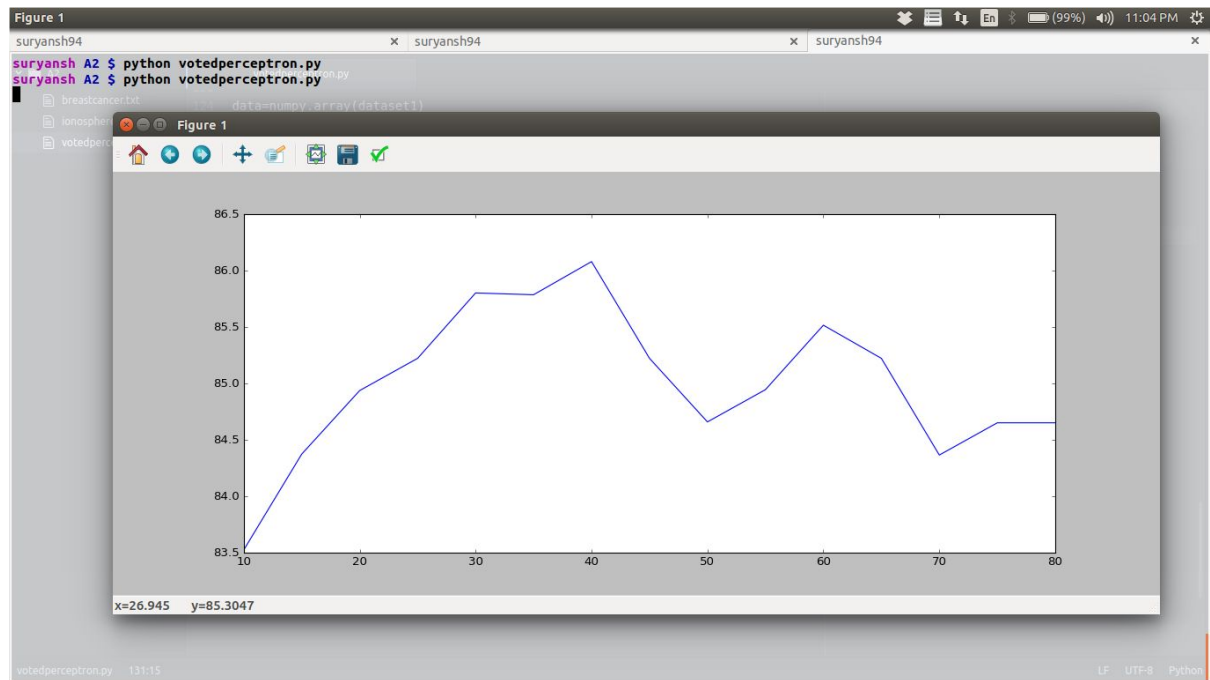


Data set of Ionosphere

Epoch vs Accuracy (Voted Perceptron)



Epoch vs Accuracy (vanilla)

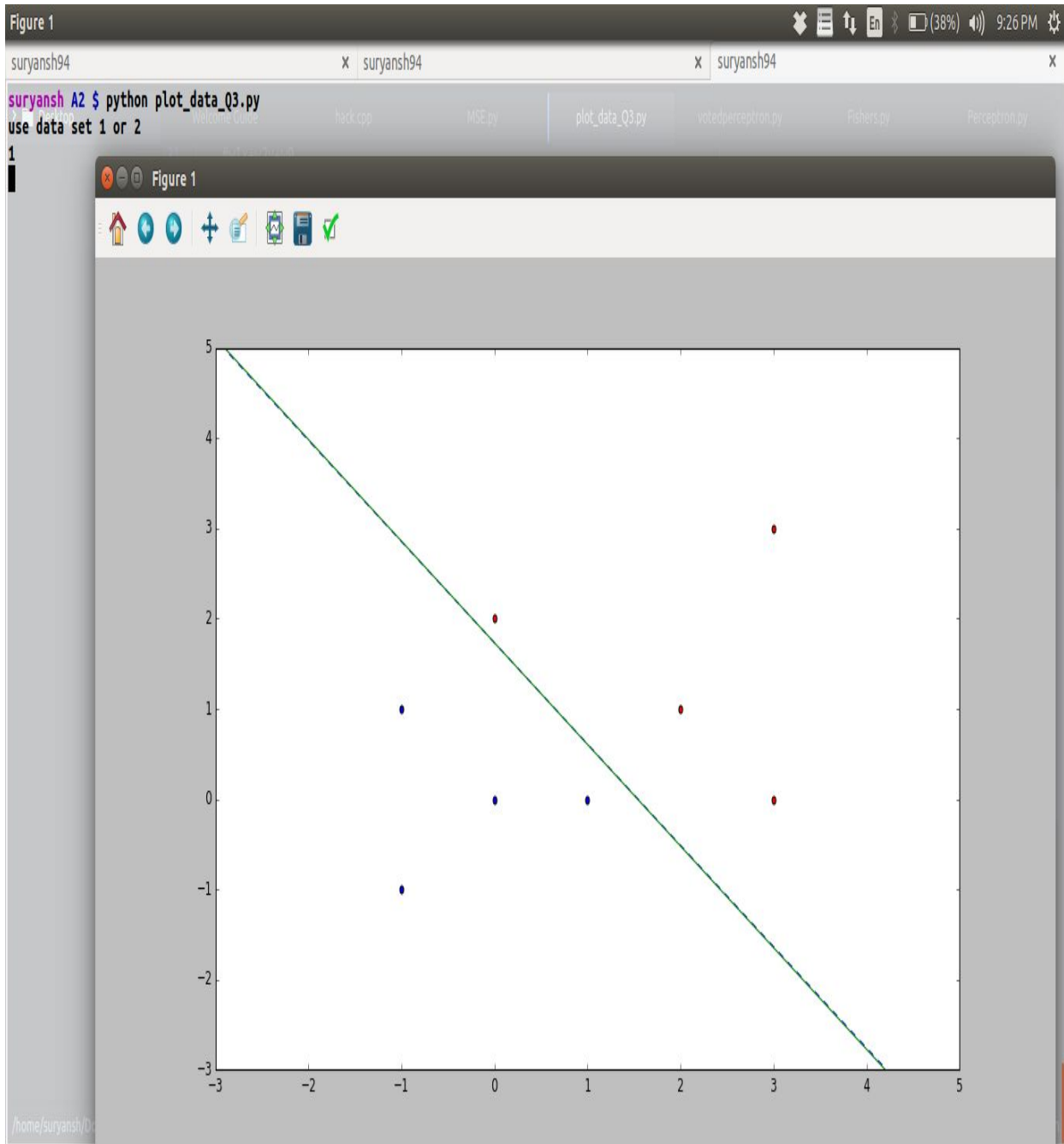


Voted Perceptron takes into account the cumulative effect of all the weight vectors generated during the learning phase whereas Vanilla Perceptron runs until all the samples are classified by one weight vector.

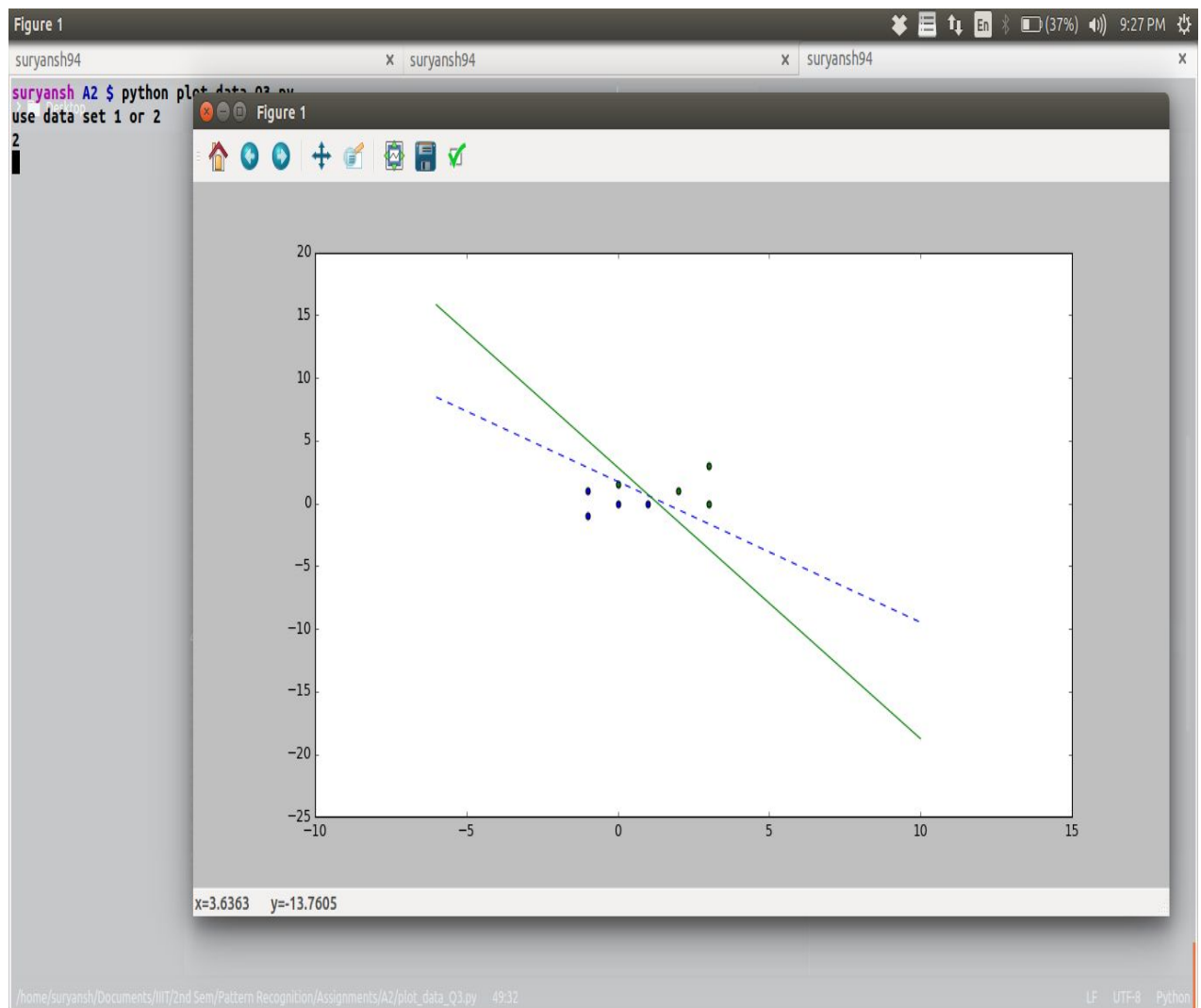
Voted Perceptron has more accuracy and efficiency due to the reason stated above. Although it is efficient, Voted Perceptron has more space complexity than Vanilla Perceptron as we have to store all the weight vectors and their counts generated during the running of algorithm. As we can see from the graphs that the plot is a stabilized one for Voted after a certain number of epochs and not so for Vanilla Perceptron. This is because Voted takes into account all the W 's generated and after certain number of epochs the W changes rarely.

3)

Plot for data set 1 , dotted line represent Fishers Classifiers and other represents LMS.
Both lines are almost overlapping with each other



Plot for data set 2 , dotted line represent Fishers Classifiers and other represents LMS



As it can be seen Fisher has correctly classified the sample in both the cases but the least square classifier has not correctly classified data points in second case. The reason behind this is that least square classifies the point on the basis of the distance between the point and the plane and it tries to minimize the sum of square errors. But the Fisher discriminant focuses on finding weight vector that minimizes the misclassification errors. This is achieved by projecting the input vector onto a new subspace, where the classes are best separated.

4)

④ Relation b/w Least Square & Fisher's Discriminant
 let $S = \{(x_1, y_1), (x_2, y_2) \dots (x_m, y_m)\}$ be m points
 in class c_1 & m_2 be the No of points in class c_2 .
 m_1 of which are in subset D_1 labelled w_1 , & m_2 of
 which are in subset D_2 labelled as w_2

We assume that sample z_i is formed from x_i
 by adding a threshold component $x_0 = 1$ to make an
 augmented pattern vector with no loss in generality
 we can assume that the first m_1 sample
 are labelled w_1 & second m_2 are w_2 , The data
 is normalised if it $\in w_2$.

$$Z = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \end{bmatrix}$$

where 1_i is column vector of m_i ones & x_i is $m_i \times d$
 matrix whose rows are the sample labelled w_i .

We partition a & y_i correspondingly

$$a = \begin{bmatrix} w_0 \\ w_0 \end{bmatrix}$$

$$y_i = \begin{cases} m/m_1 & \text{if } x_i \in w_1 \\ -m/m_2 & \text{if } x_i \in w_2 \end{cases} \quad \text{--- (1)}$$

Choosing the label class as defined in eq (1)
 links the Least Square to Fisher discriminant.

For Least Square error method we know

$$Z^T Z a = Z^T y \quad \text{where } y \text{ is label class}$$

--- (2)

Writing eq (1) in form of partitioned matrix

$$\begin{bmatrix} 1_1^t & 1_2^t \\ x_1^t & -x_2^t \end{bmatrix} \begin{bmatrix} 1 & x_1 \\ -1_2 & -x_2 \end{bmatrix} \begin{bmatrix} w_0 \\ w \end{bmatrix} = \begin{bmatrix} 1_1^t & -1_2^t \\ x_1^t & -x_2^t \end{bmatrix} \begin{bmatrix} \frac{m}{m_1} & 1_1 \\ -\frac{m}{m_2} & 1_2 \end{bmatrix} \quad (2)$$

We know sample mean \bar{u}_i & the pooled scatter matrix S_w are given as

$$\bar{u}_i = \frac{1}{n_i} \sum_{x \in D_i} x \quad i=1, 2, \dots$$

$$\& S_w = \sum_{i=1}^2 \sum_{x \in D_i} (x - \bar{u}_i)(x - \bar{u}_i)^t$$

We can multiply eq (2) matrices

$$\begin{bmatrix} m & (m_1 \bar{u}_1 + m_2 \bar{u}_2)^t \\ (m_1 \bar{u}_1 + m_2 \bar{u}_2) & (S_w + m_1 \bar{u}_1 \bar{u}_1^t + m_2 \bar{u}_2 \bar{u}_2^t) \end{bmatrix} \begin{bmatrix} w_0 \\ w \end{bmatrix} = \begin{bmatrix} 0 \\ m(\bar{u}_1 - \bar{u}_2) \end{bmatrix}$$

This can be viewed as a pair of equations, the first of which can be solved for w_0 in terms of w

$$w_0 = -\bar{u}^t w \quad (4)$$

$\bar{u} \rightarrow$ mean of all sample

Substituting in eq (2) obtained from matrix & few algebraic manipulation

$$\left[\frac{1}{m} S_w + \frac{m_1 m_2}{n_2} (\bar{u}_1 - \bar{u}_2)(\bar{u}_1 - \bar{u}_2)^t \right] w = \bar{u}_1 - \bar{u}_2 \quad (5)$$

because the vector $(\bar{u}_1 - \bar{u}_2)(\bar{u}_1 - \bar{u}_2)^t$ is the direction of $(\bar{u}_1 - \bar{u}_2)$ for any value of w , we can

write $\frac{m_1 m_2}{m_2} (\bar{u}_1 - \bar{u}_2)(\bar{u}_1 - \bar{u}_2)^t w = (1-\alpha)(\bar{u}_1 - \bar{u}_2)$

where α is some scalar

then eq (5) yields

$$w \propto m S_w^{-1} (\bar{u}_1 - \bar{u}_2) \quad (6)$$

eg ⑥ except for an ~~unimportant~~ scale factors
 is identical to the solution for Fisher's
 Linear Discriminant. In addition, we obtain
 the threshold weight w_0 & decision rule:

$$\begin{cases} w_1, & \text{if } w^T \frac{(x - \mu)}{\sqrt{\frac{1}{2}(\Sigma_1 + \Sigma_2)}} > 0 \\ w_2, & \text{otherwise} \end{cases}$$

————— x ————— y —————