ScaRC is ready for use in FDS

Alternative solver for the FDS pressure equation

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Agenda

1 2 3 4

Pressure equation ScaRC solver Solver



FDS pressure Poisson equation Different discretization types



Elliptic partial differential equation of "Poisson" type

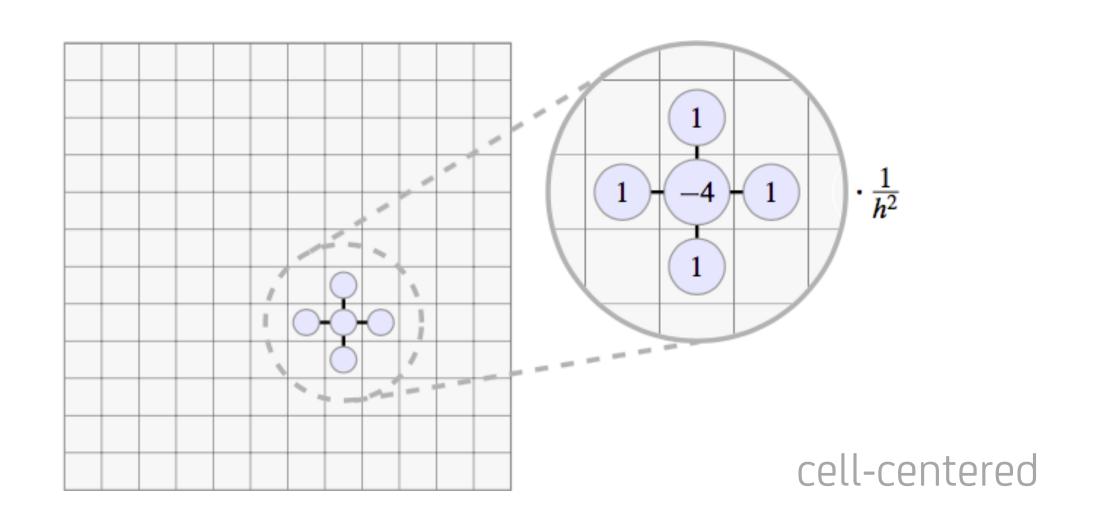
$$abla^2\mathcal{H} = -rac{\partial (
abla\cdot \mathbf{u})}{\partial t} -
abla\cdot \mathbf{F}$$
 + boundary conditions

Strongly coupled with velocity field, to be solved at least twice per time step

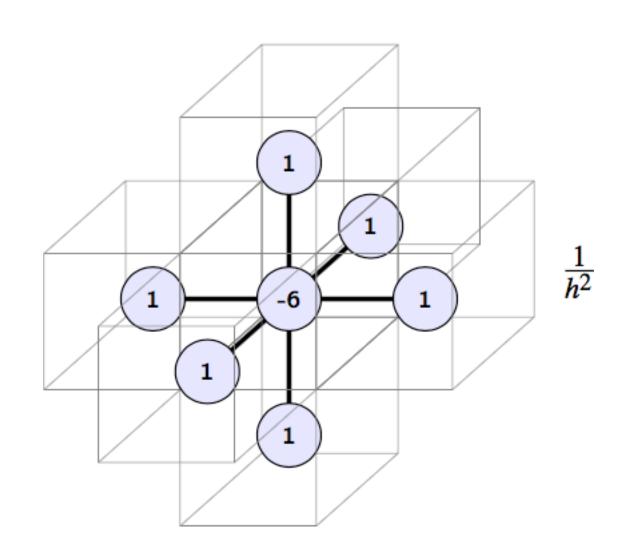
Source terms of previous time step. e.g. radiation, combustion pyrolysis, ...

Key feature: Local information is spread immediately over whole domain!

5-point stencil in 2D



7-point stencil in 3D

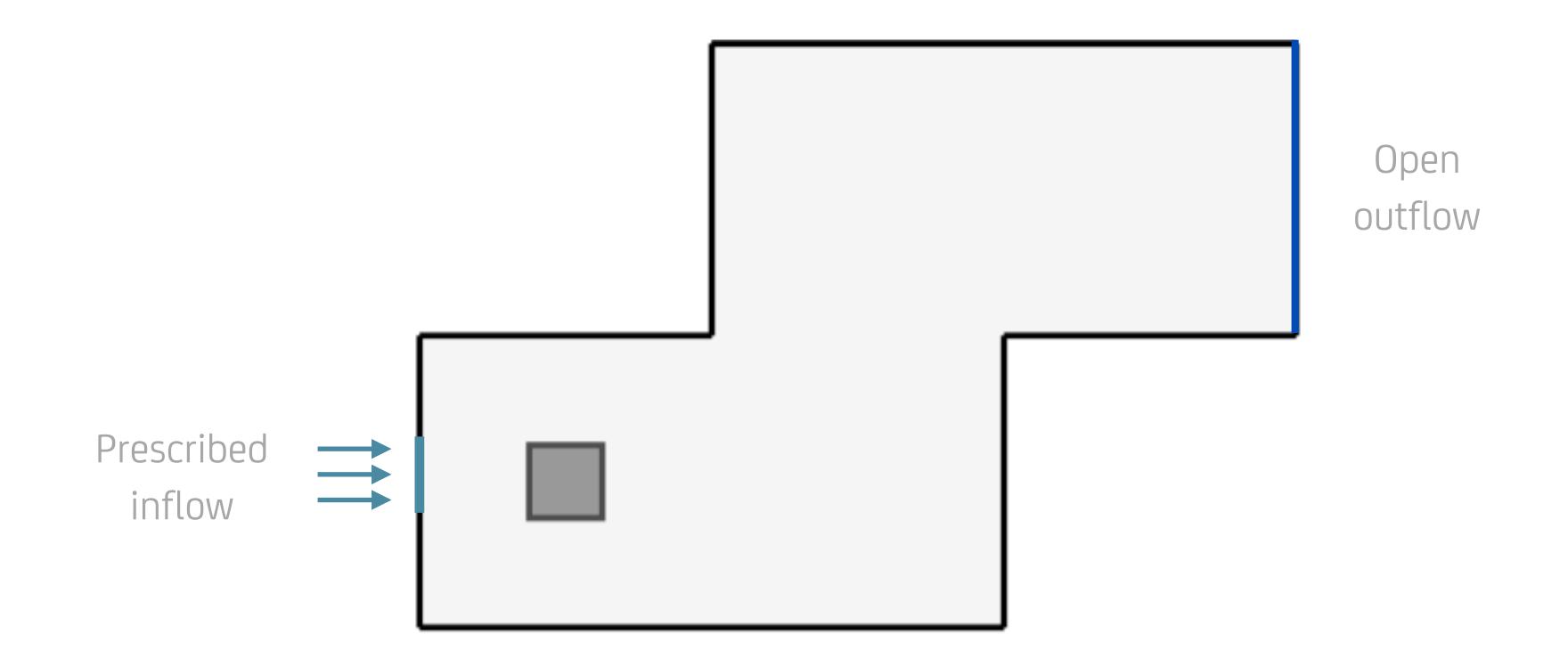


Specifies physical relations between grid cells according to elliptic equation



Demo-case, 2D-pipe with obstruction'

Simple example to explain the concepts

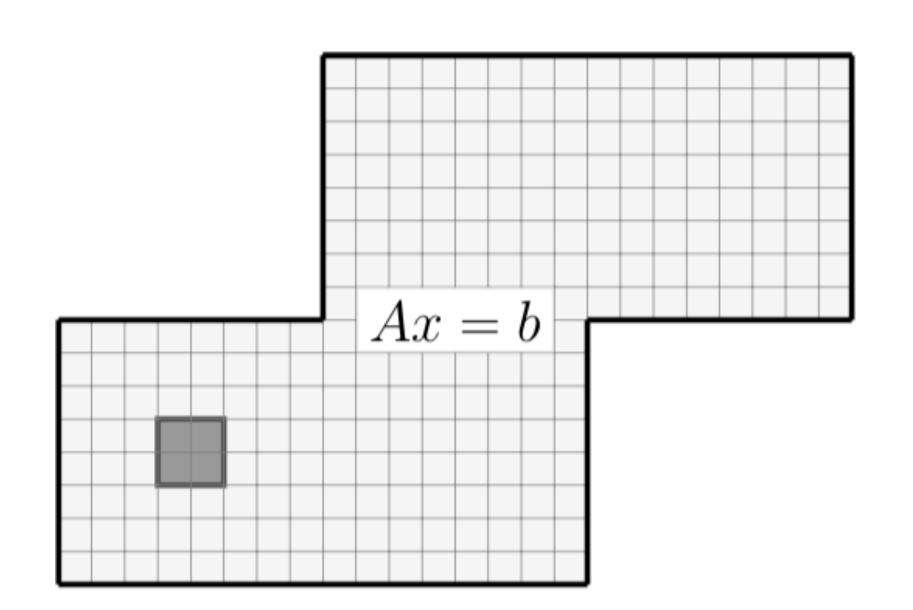


Pressure equation



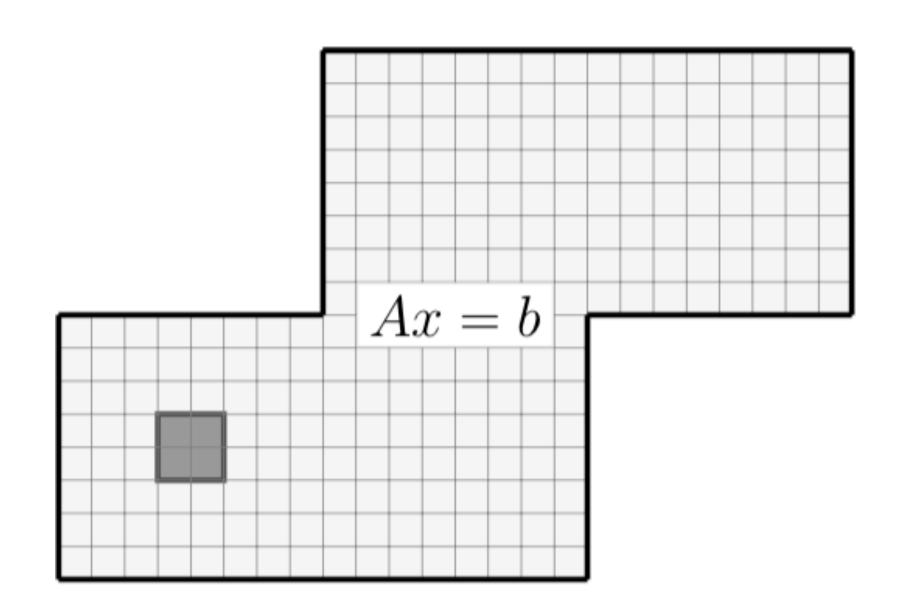
Global discretization

1 global matrix, 1 global right hand side vector



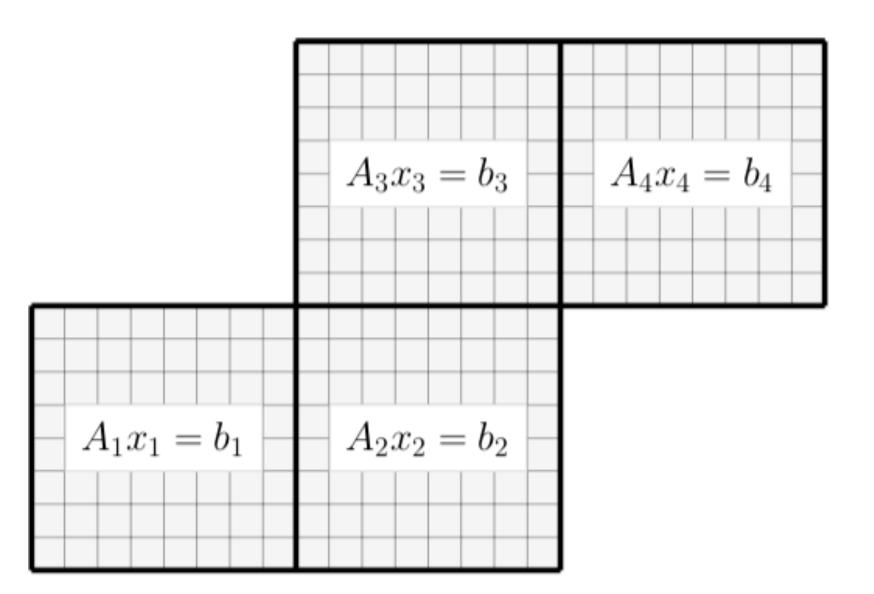
Global discretization

1 global matrix, 1 global right hand side vector



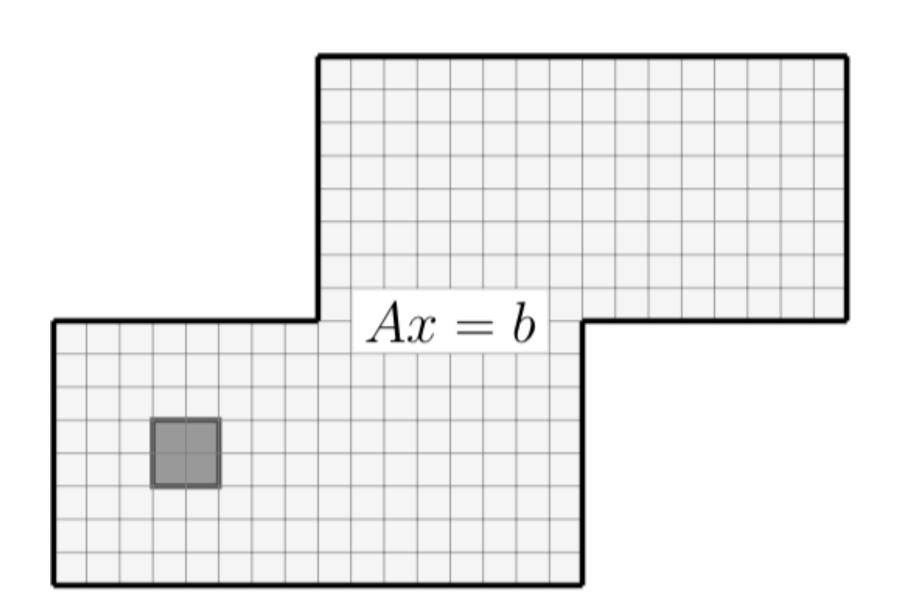
Set of local discretizations

M local matrices, M local right hand side vectors



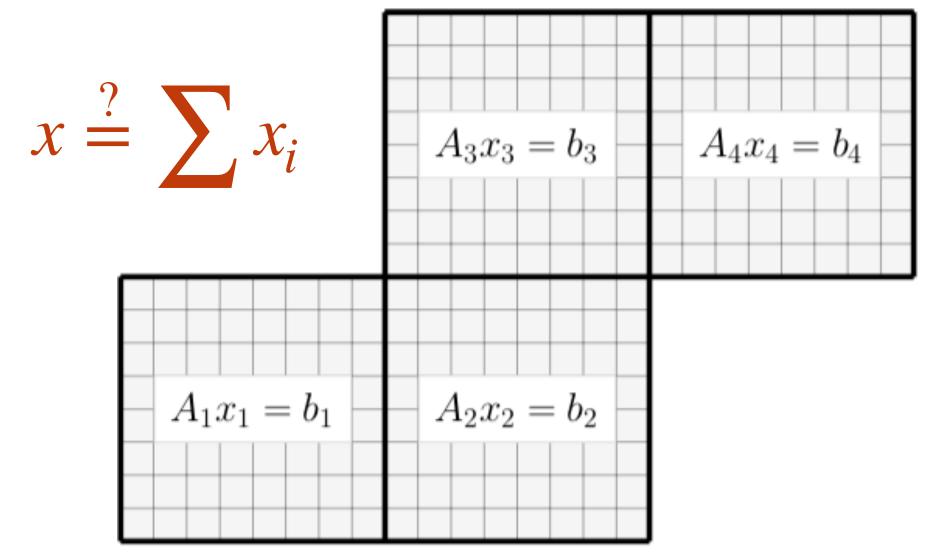
Global discretization

1 global matrix, 1 global right hand side vector



Set of local discretizations

M local matrices, M local right hand side vectors



Pressure equation

Mesh 3 Mesh 4

There are different possibilities to discretize ...



Pressure equation

Mesh 3 Mesh 4

... at cells inside and around a solid obstruction

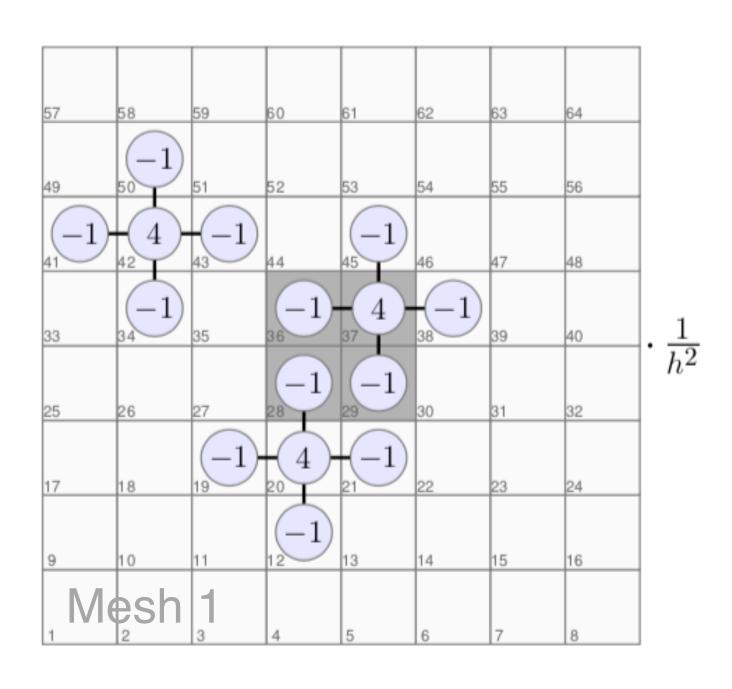
Structured versus unstructured discretizations

1

Pressure equation

Structured

Regular matrix stencils



8x8 cells

Cells inside obstructions are included



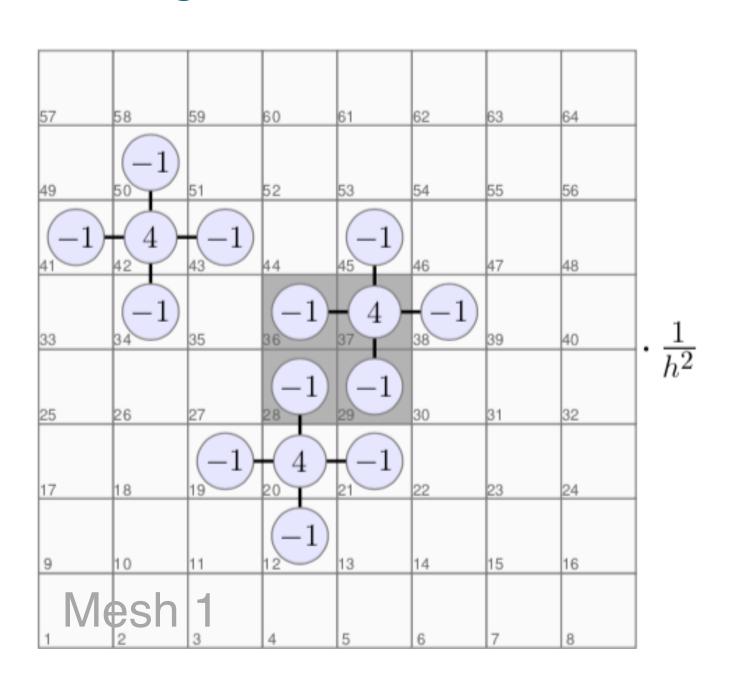
Structured versus unstructured discretizations

1

Pressure equation

Structured

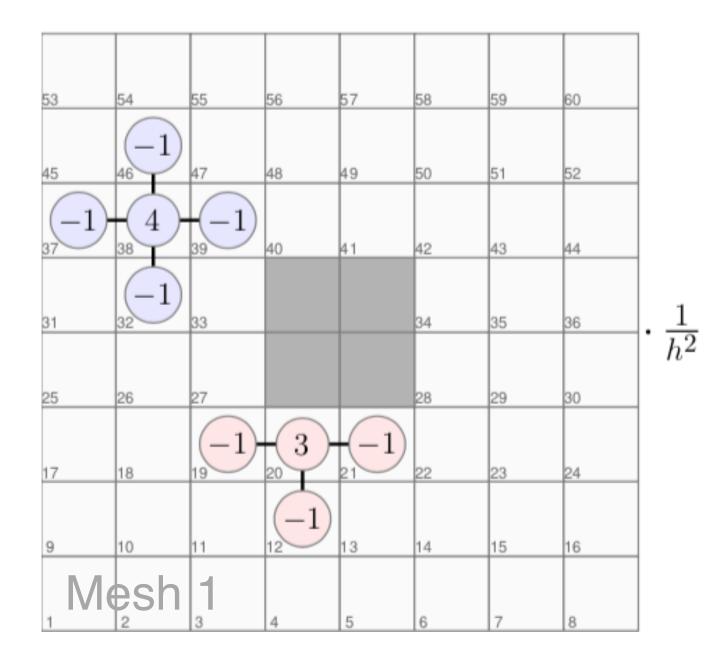
Regular matrix stencils



8x8 cells

Unstructured

Irregular matrix stencils



Cells inside obstructions are **included**

Cells inside obstructions are excluded



8x8 cells

Sparsity

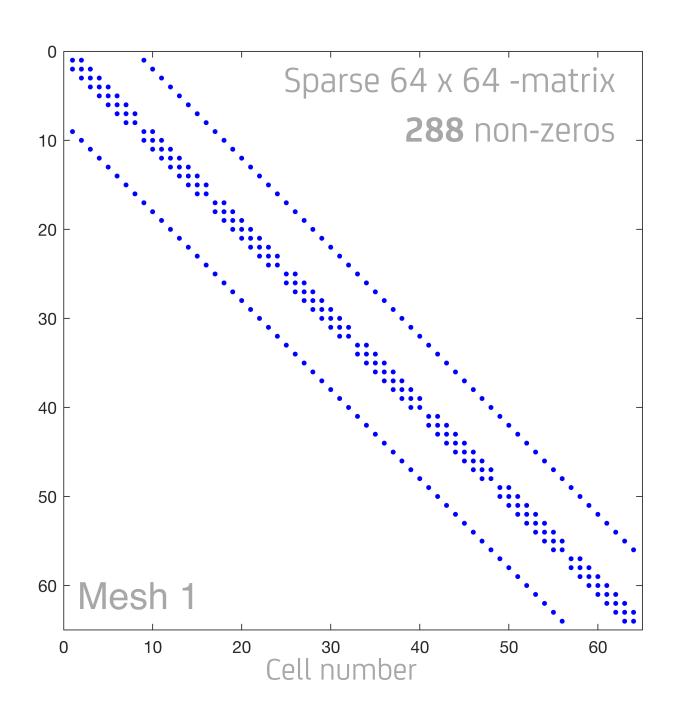
patterns

1

Pressure equation

Structured

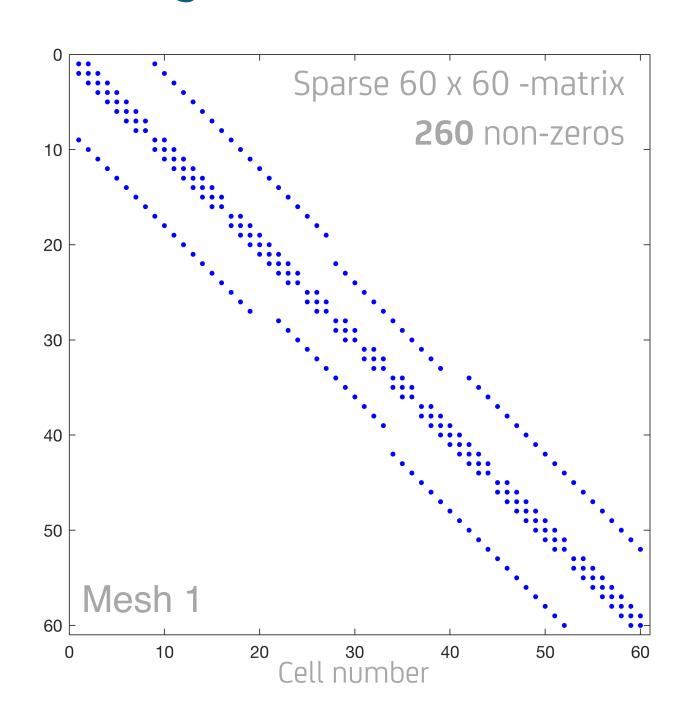
Highly regular Poisson matrix A



Highly optimized solvers usable (fast!)

Unstructured

Irregular Poisson matrix A



Need of more robust solvers (slower!)



8x8 cells

Sparsity

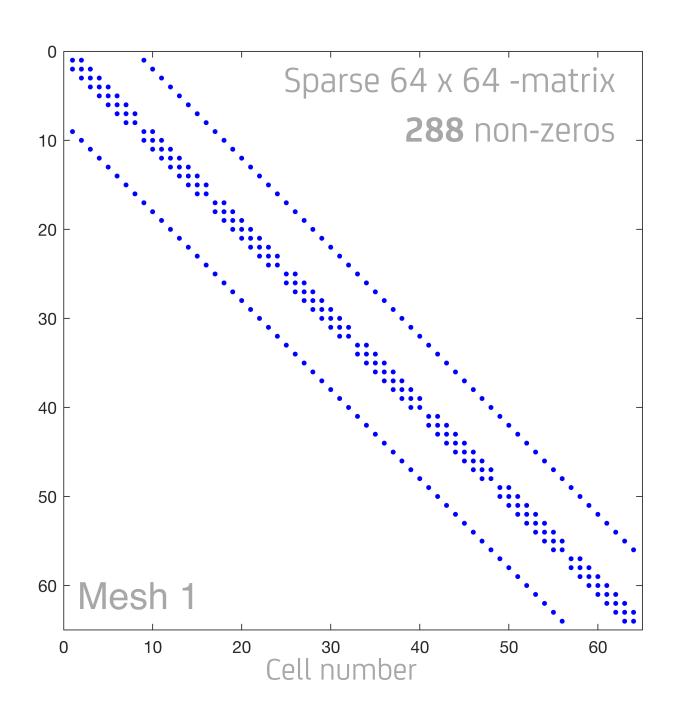
patterns

1

Pressure equation

Structured

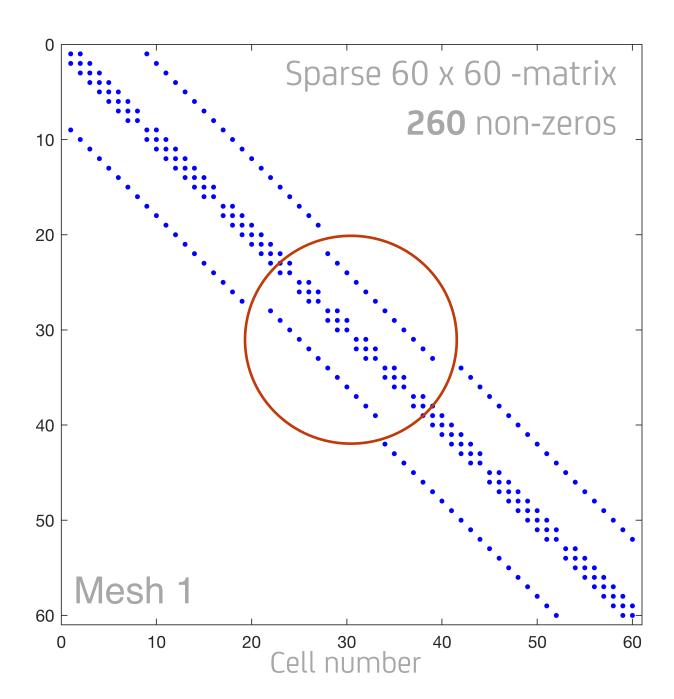
Highly regular Poisson matrix A



Highly optimized solvers usable (fast!)

Unstructured

Irregular Poisson matrix A



Need of more robust solvers (slower!)

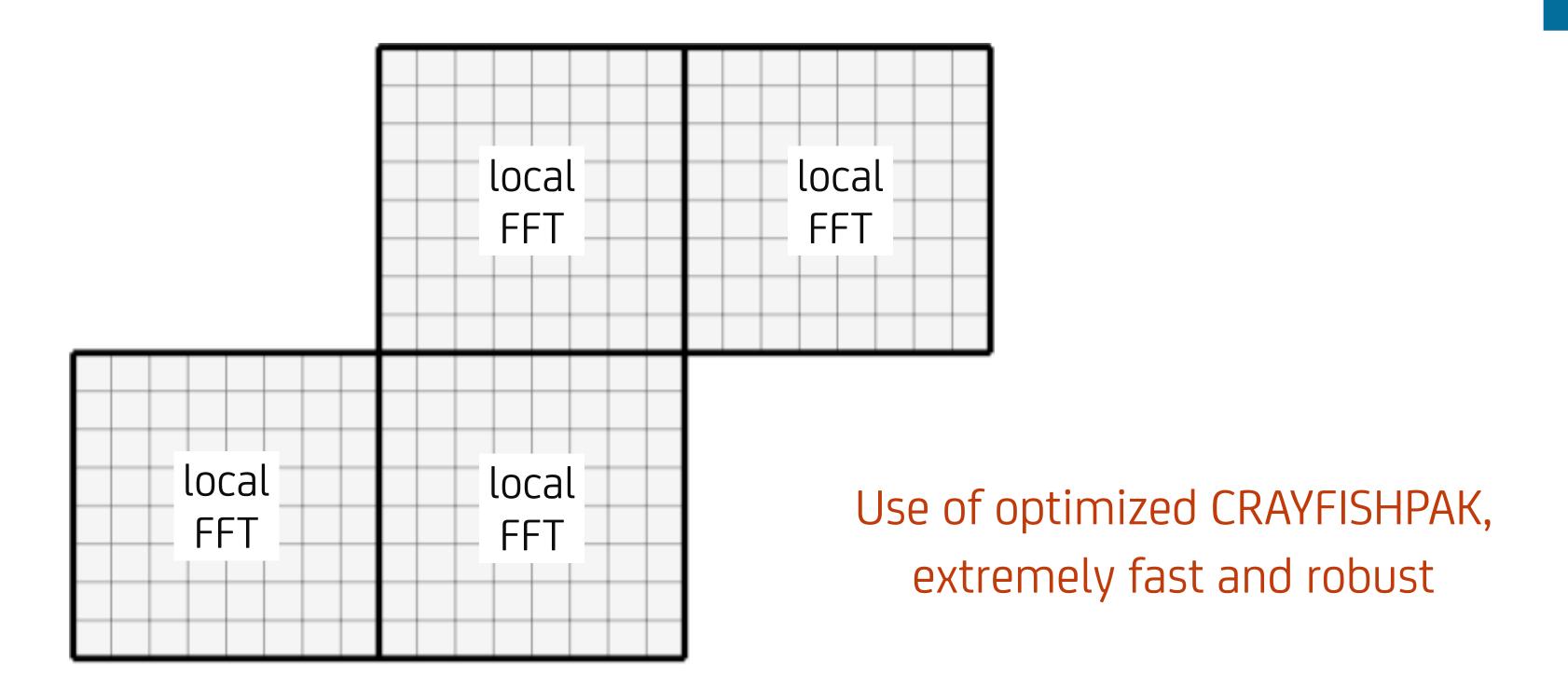


Current FDS pressure solver Mesh-wise FFT with pressure iteration



FFT solver

Local structured discretizations to solve the local Poisson problems by FFT's

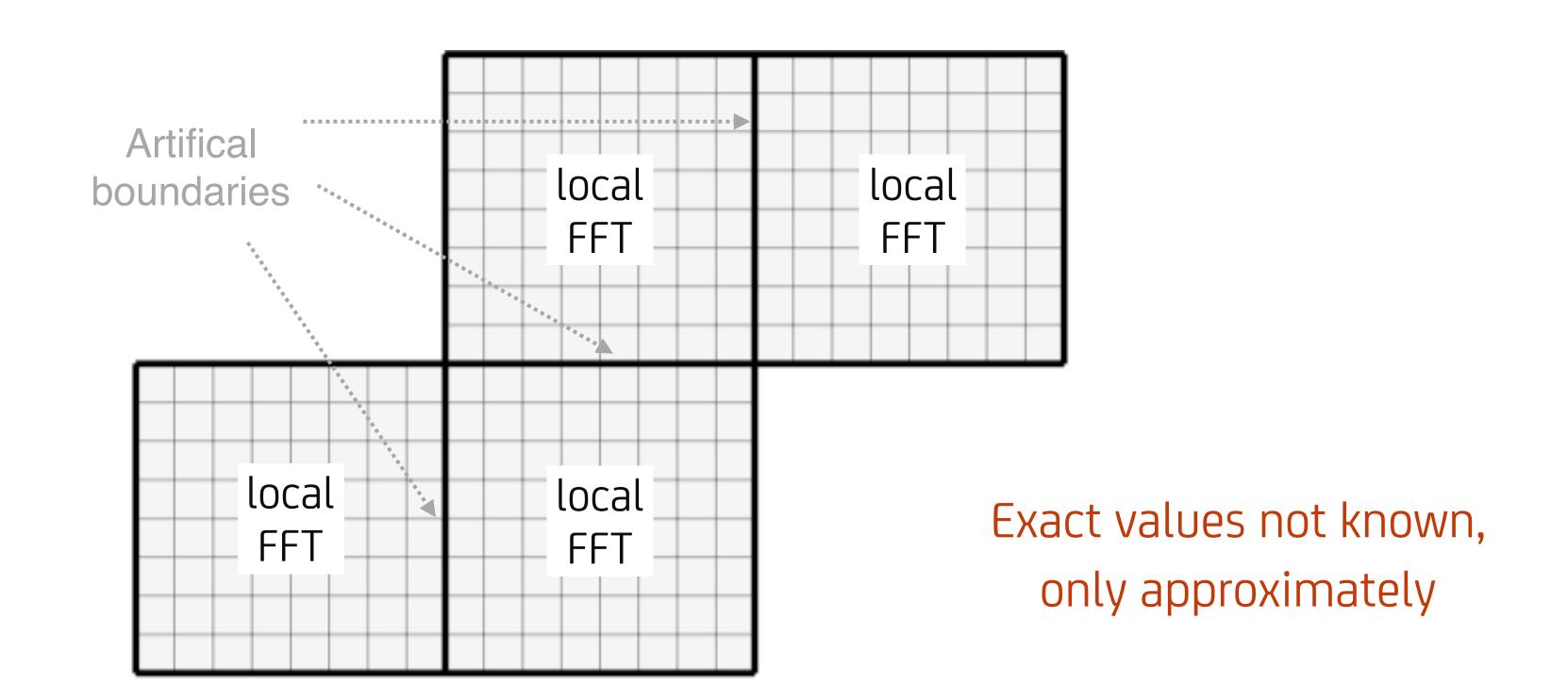




FFT solver

Mesh-wise FFT-solver

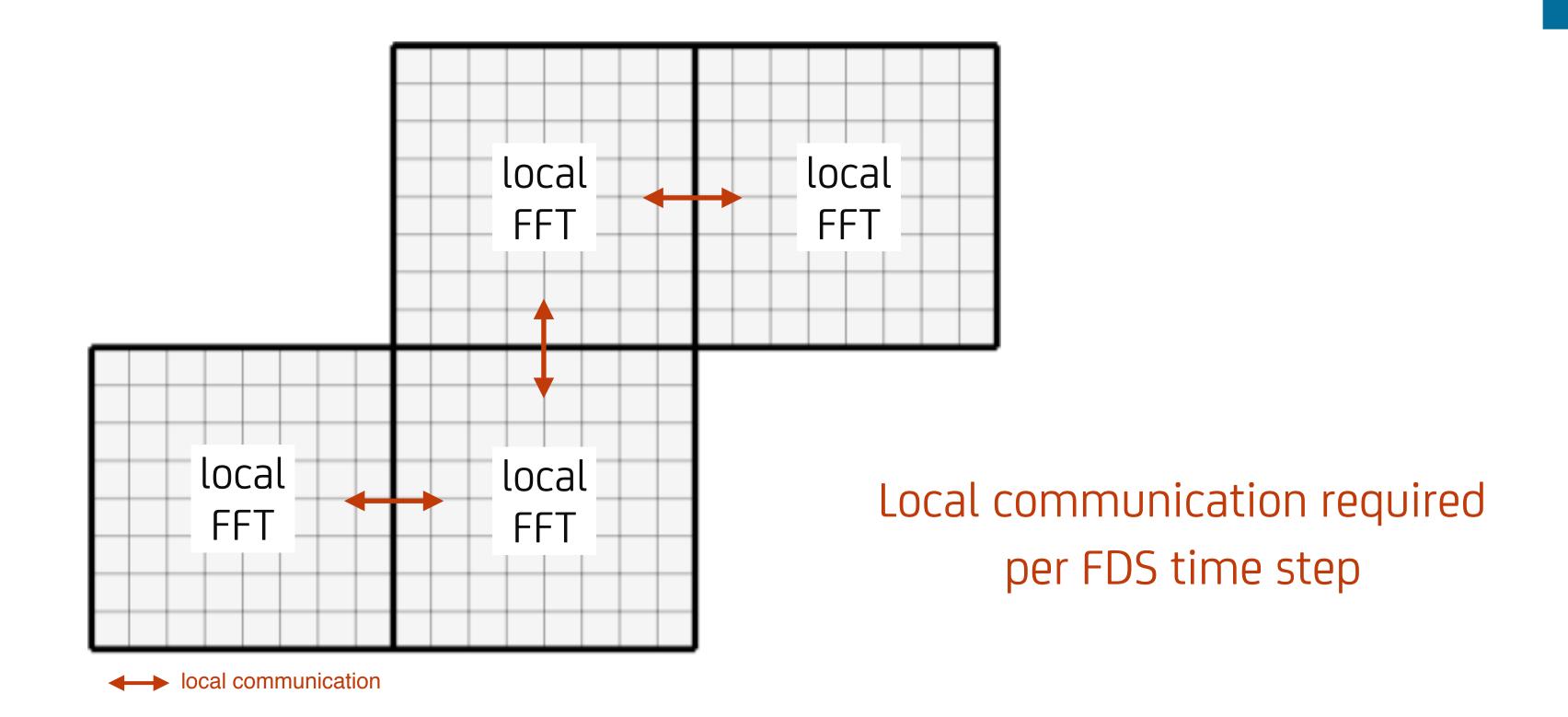
Mathematical solvability requires internal boundary conditions for local FFTs ...





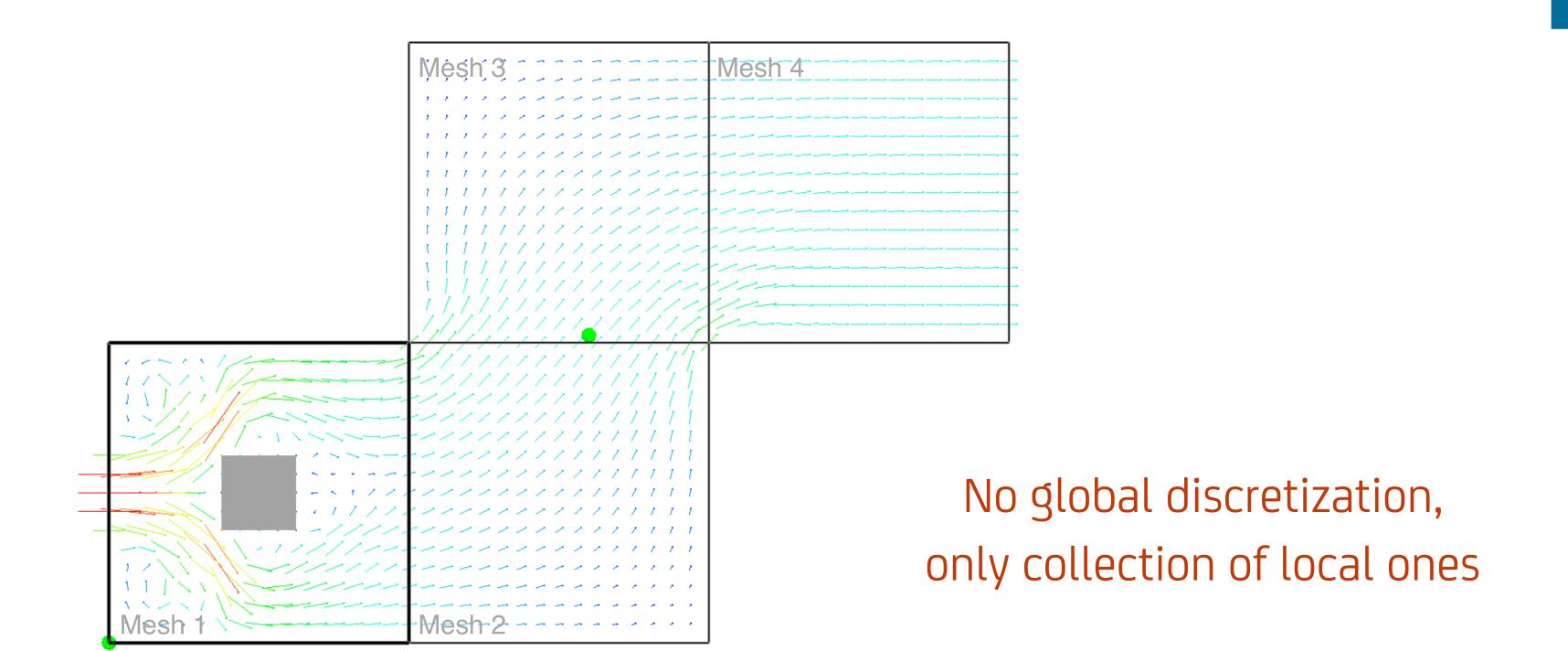
FFT solver

... average of neighboring cells from previous time step is used





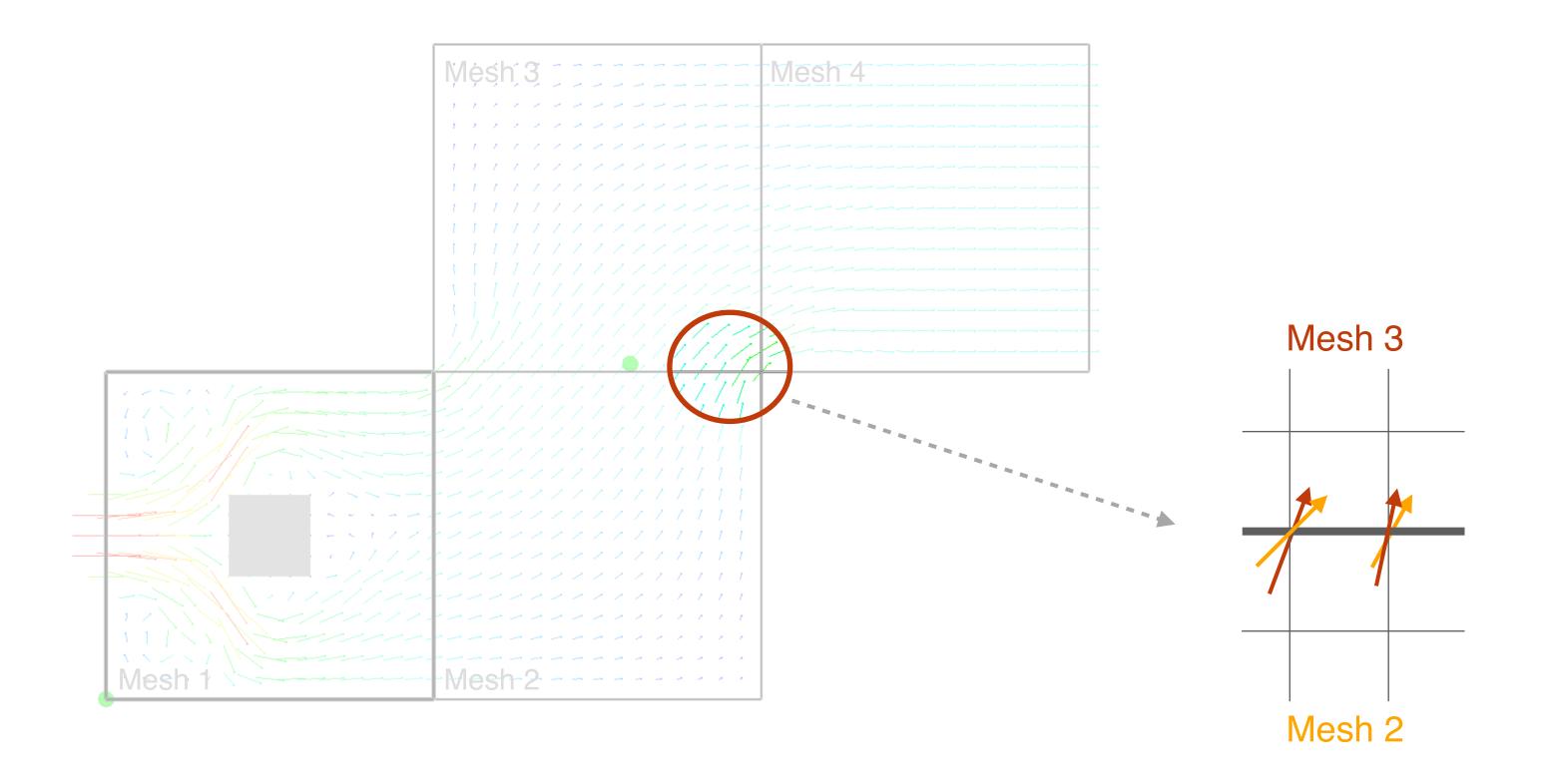
Question: How accurate is the velocity field at mesh interfaces?





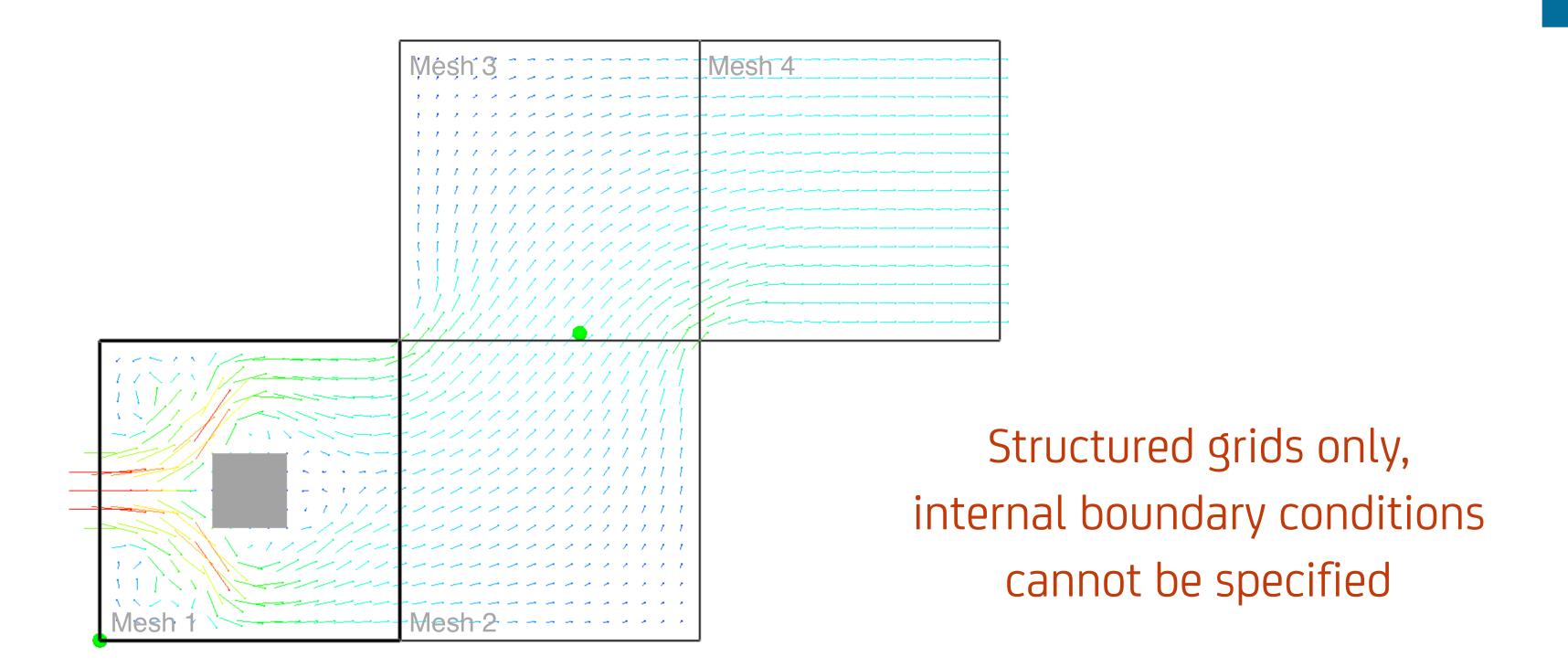
FFT solver

Local velocity components may be different along mesh interfaces



FFT solver

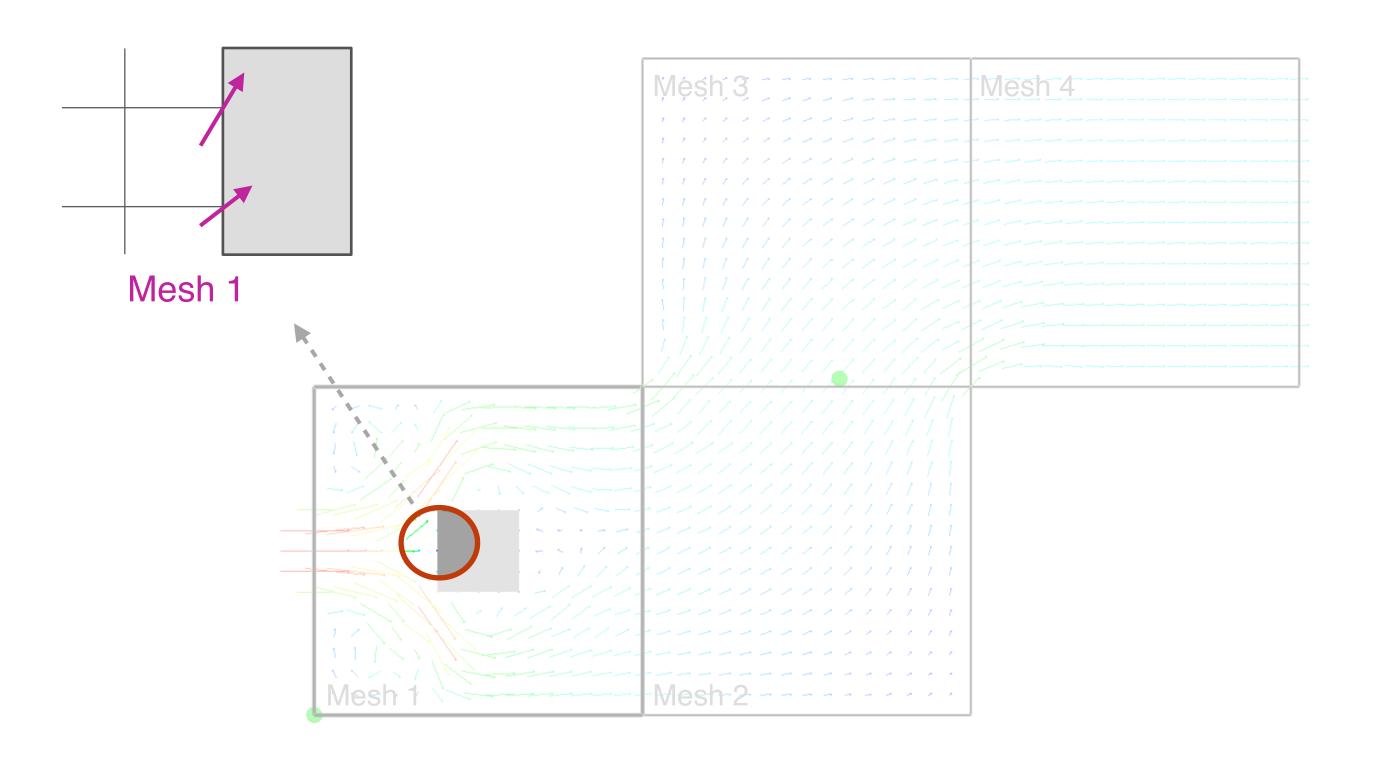
Question: How accurate is the velocity field along inner obstructions?





Accuracy along internal obstructions?

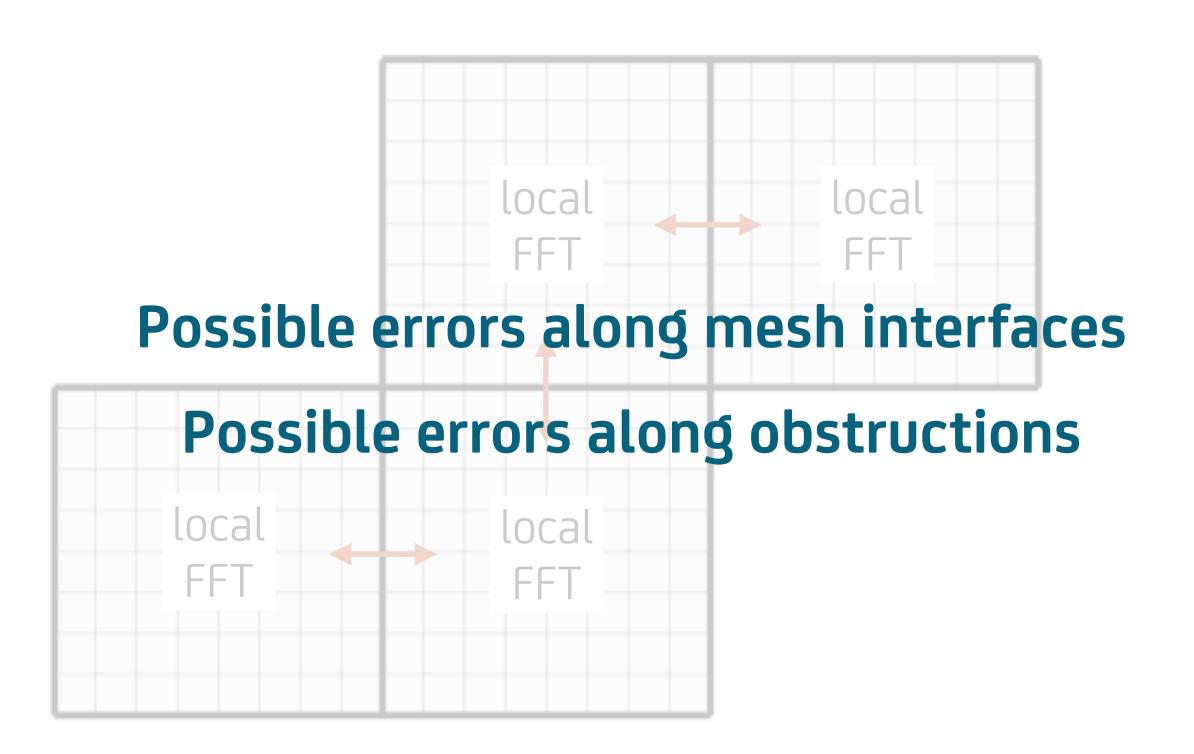
Velocity components may penetrate into the inner obstructions



FFT solver

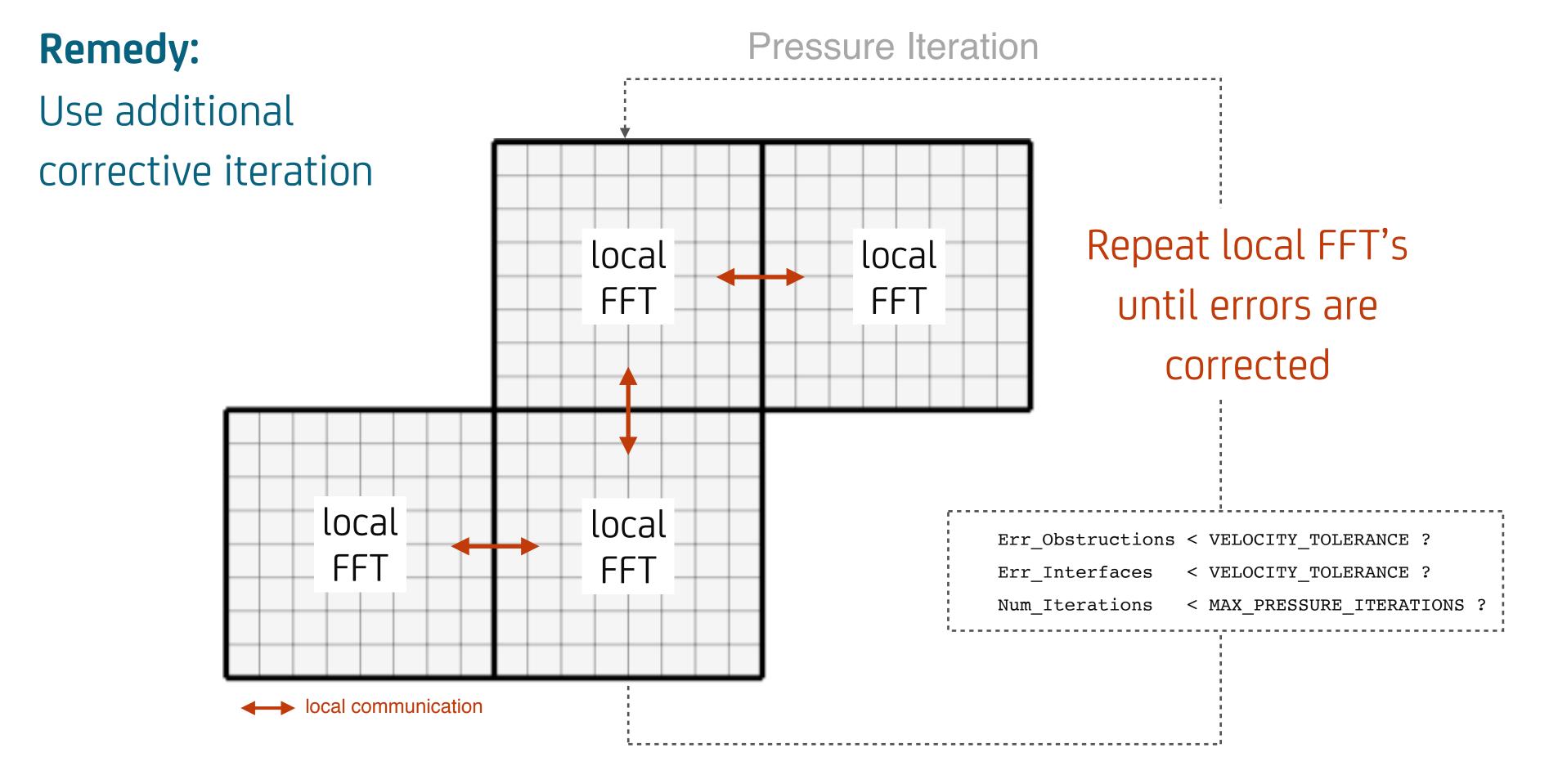


Mesh-wise FFT-solver



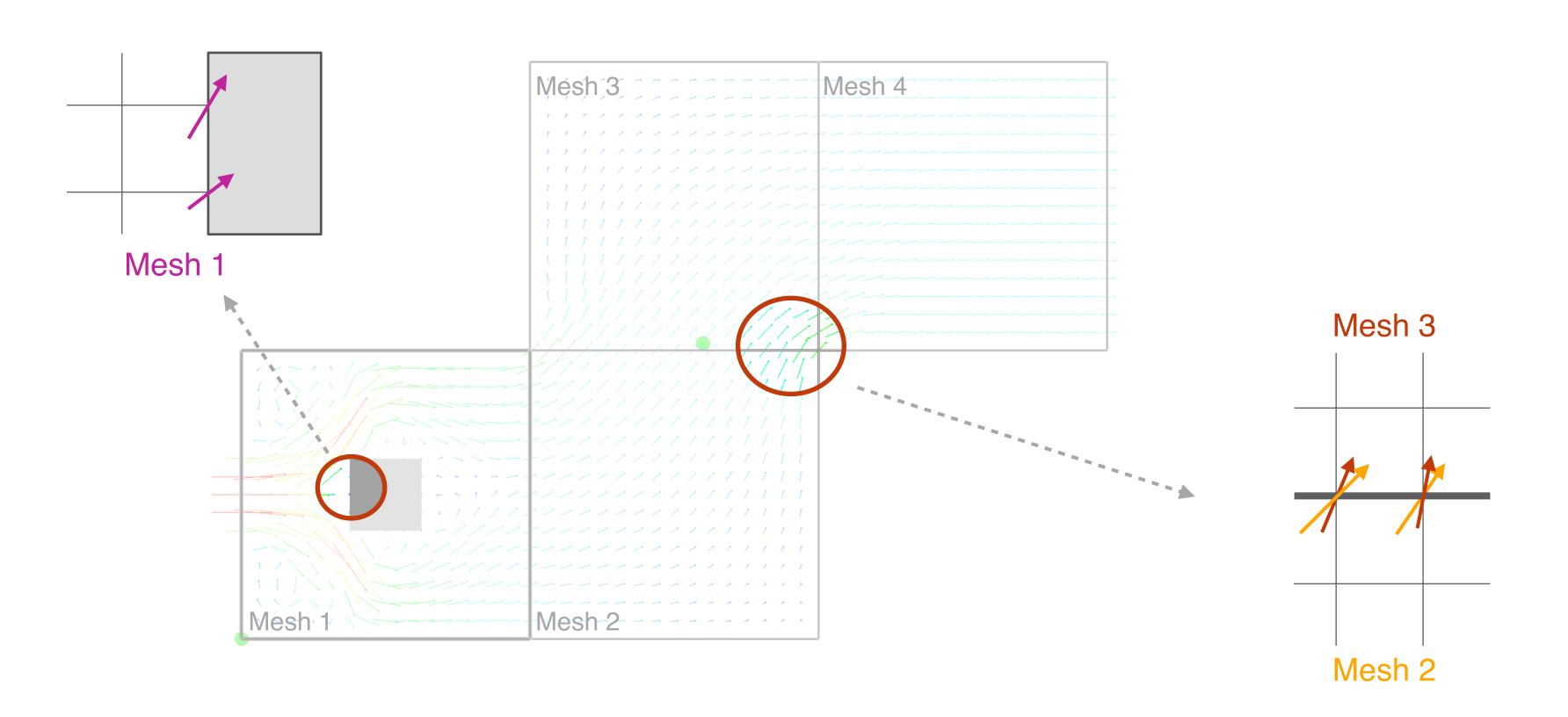
FFT solver





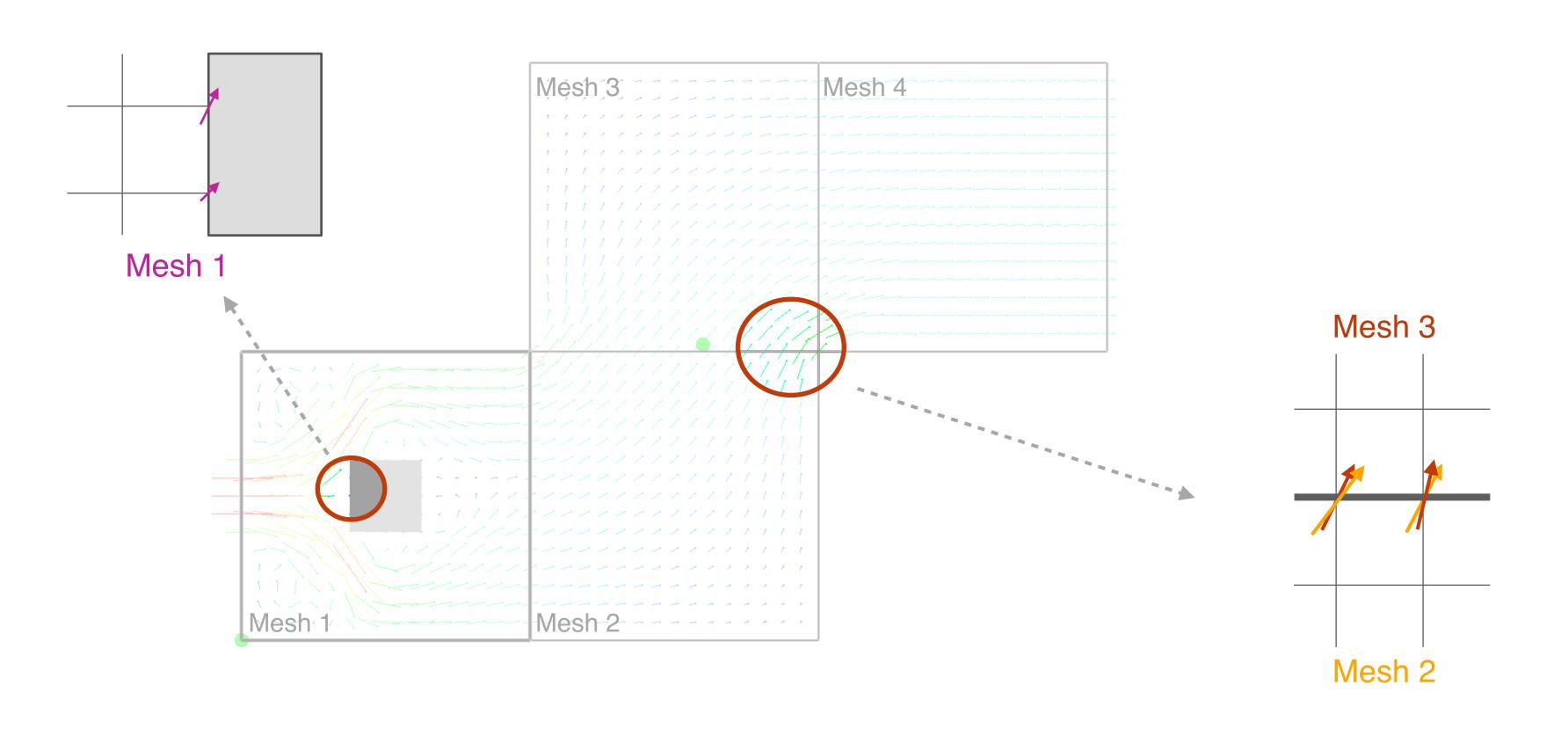


Start iteration: Initial velocity errors



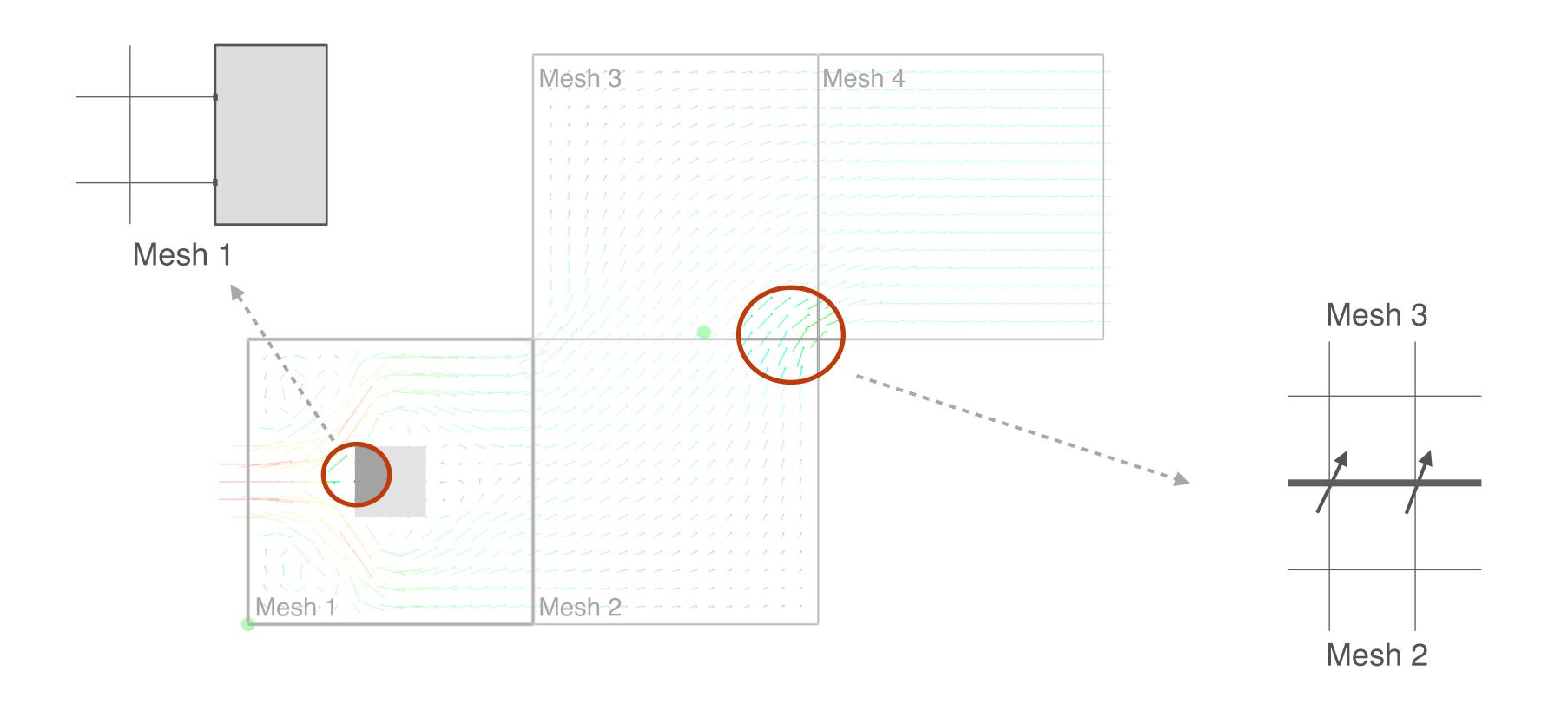


Intermediate iteration: Velocity errors are reduced more and more





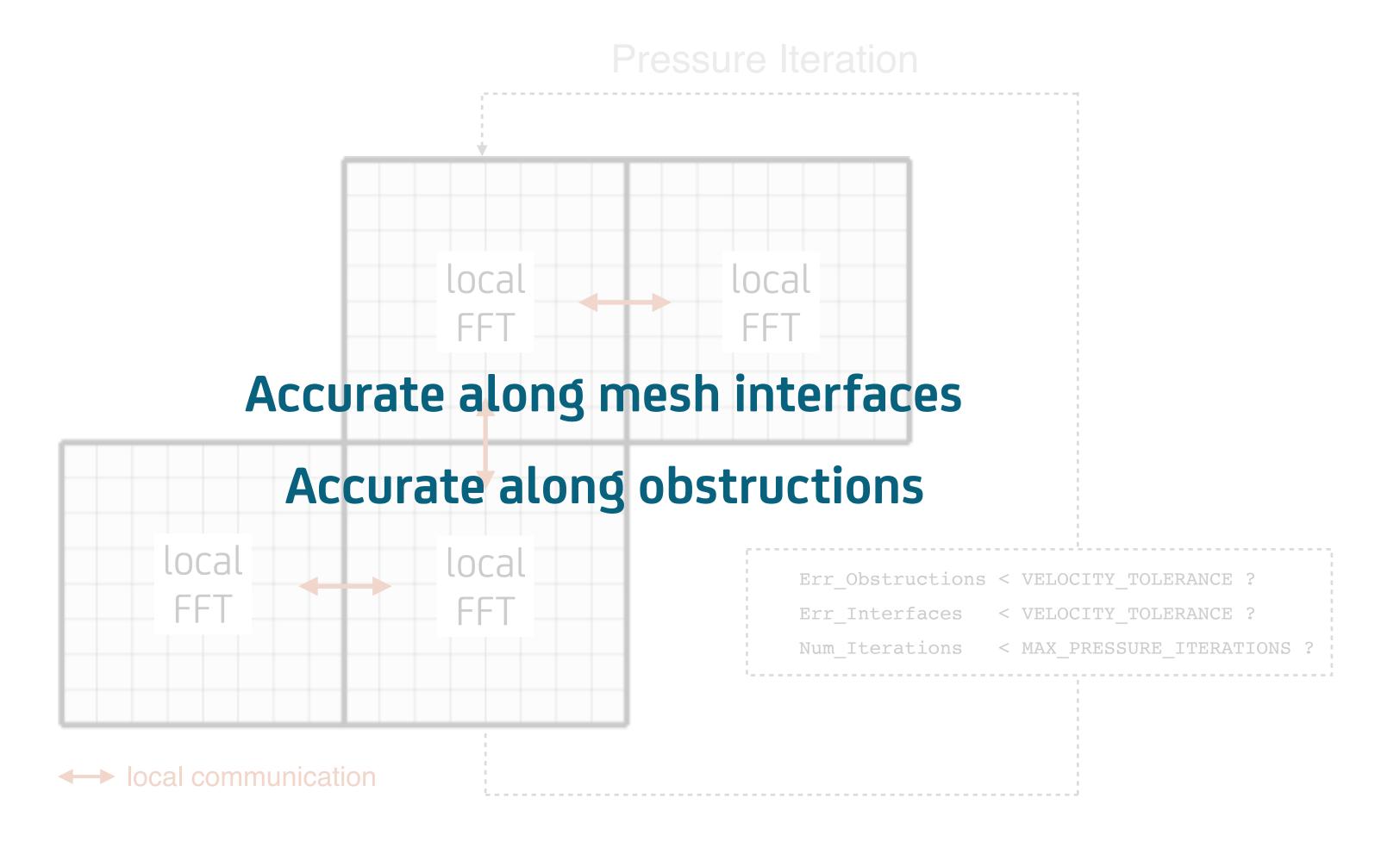
End of iteration: Velocity errors are below specified tolerance



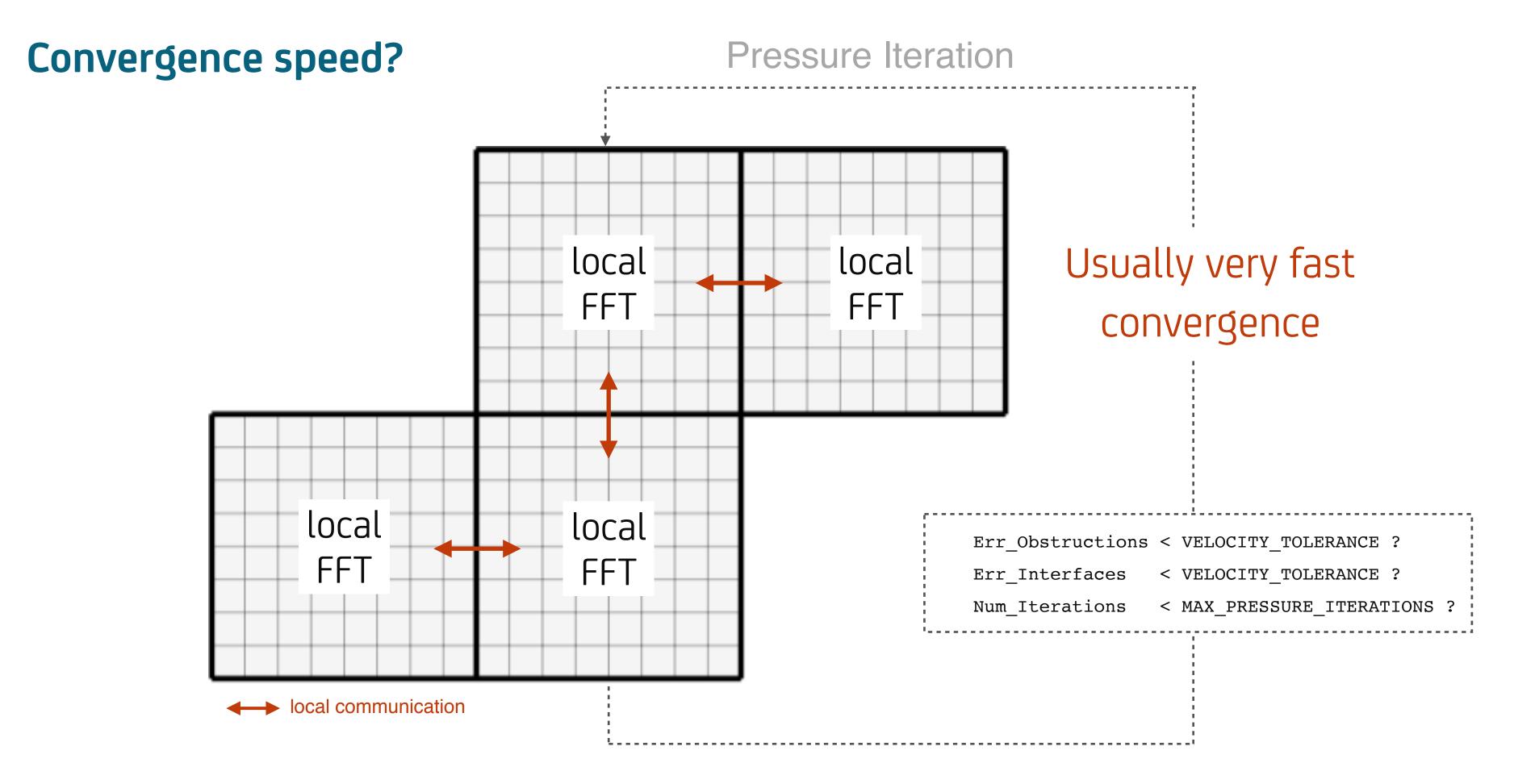




FFT solver





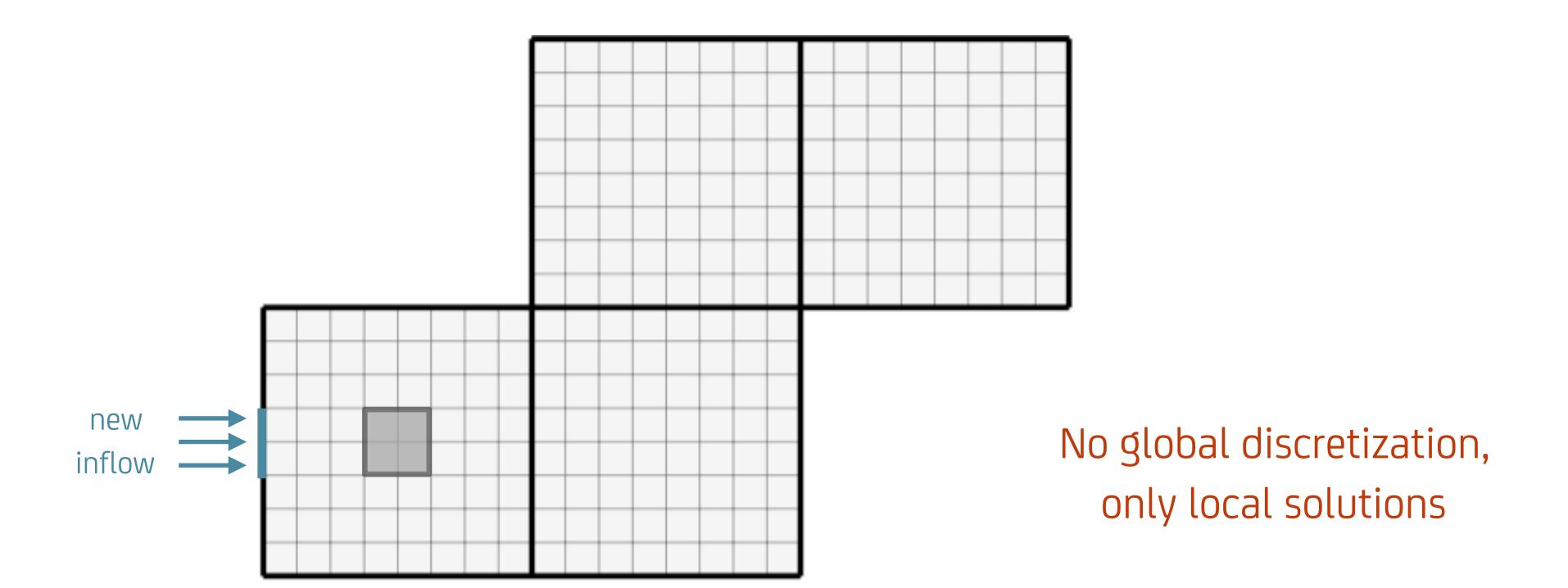




solver

Mapping of the global flow of information?

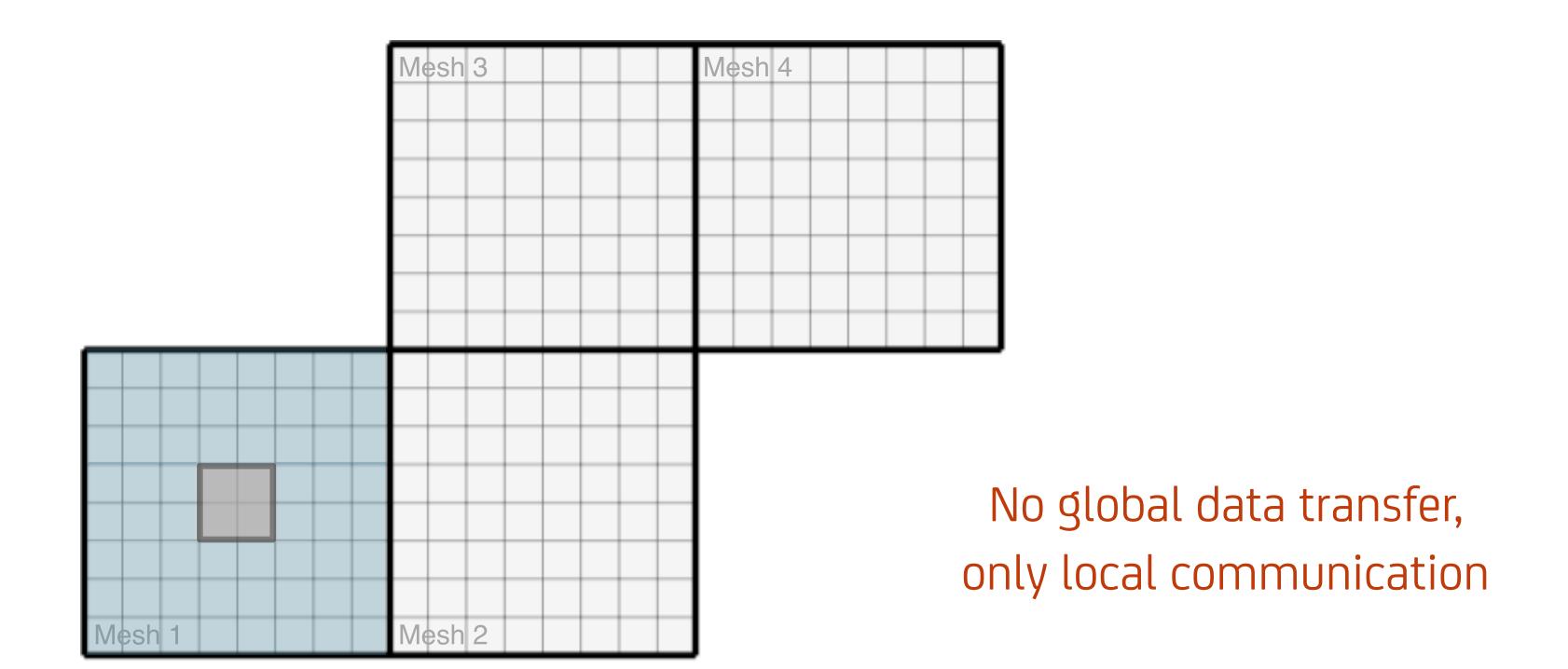
Question: How quickly does new local information spread?





FFT solver

1. Cycle: Information reaches Mesh 1



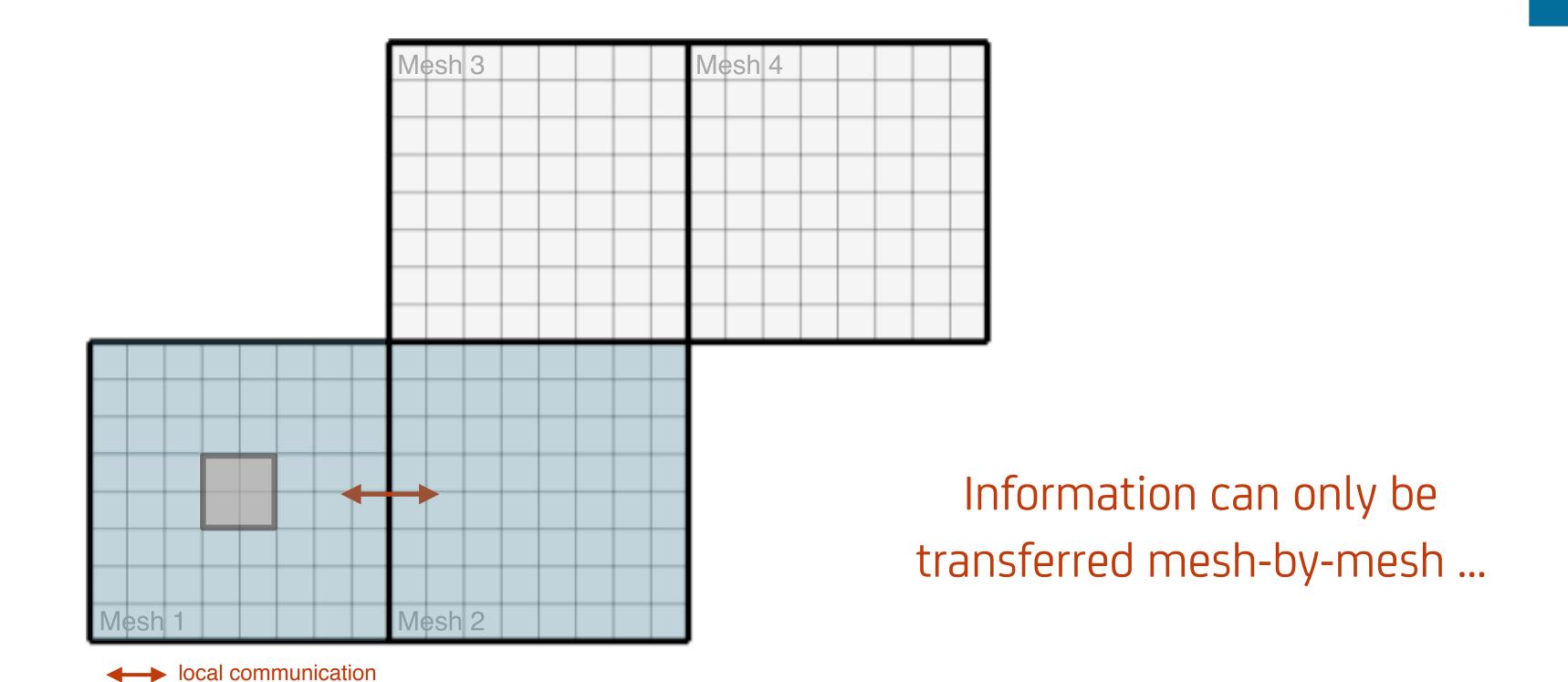


Mapping of the global flow of information?

2

FFT solver

2. Cycle: Information reaches Mesh 2

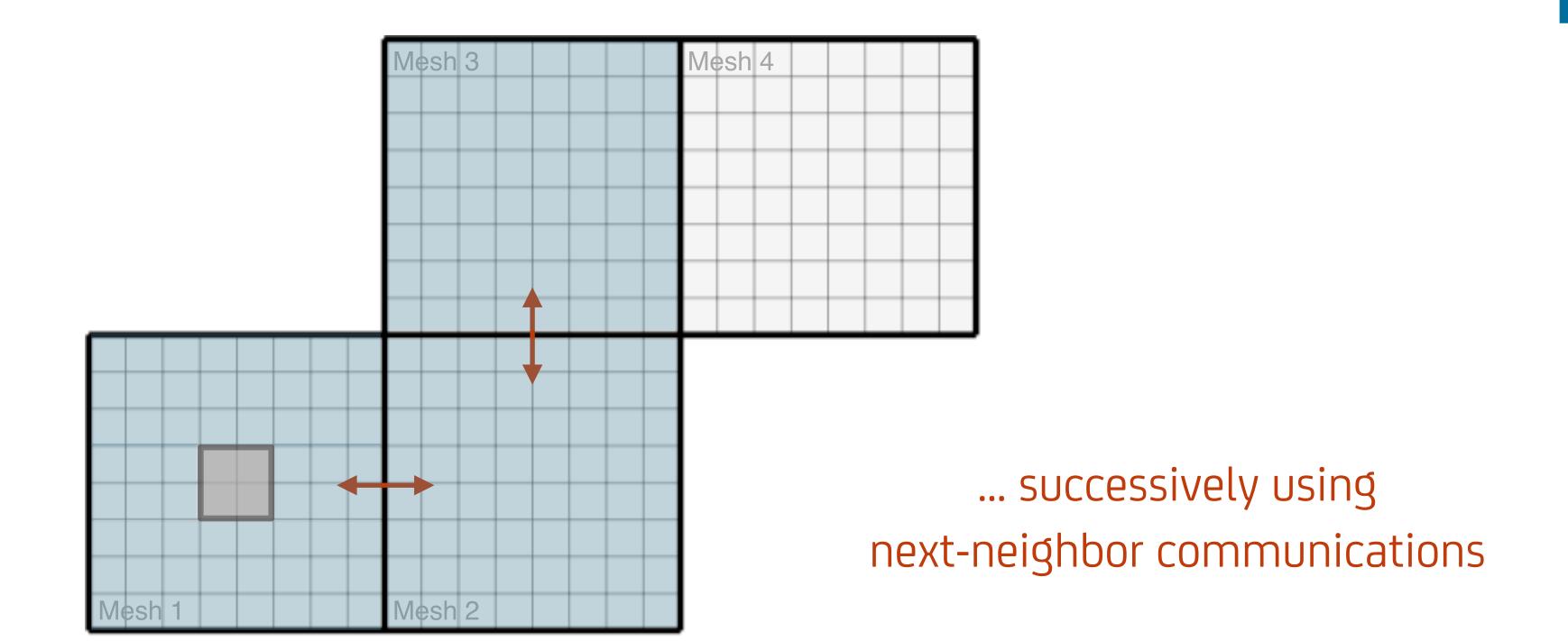




FFT solver

3. Cycle: Information reaches Mesh 3

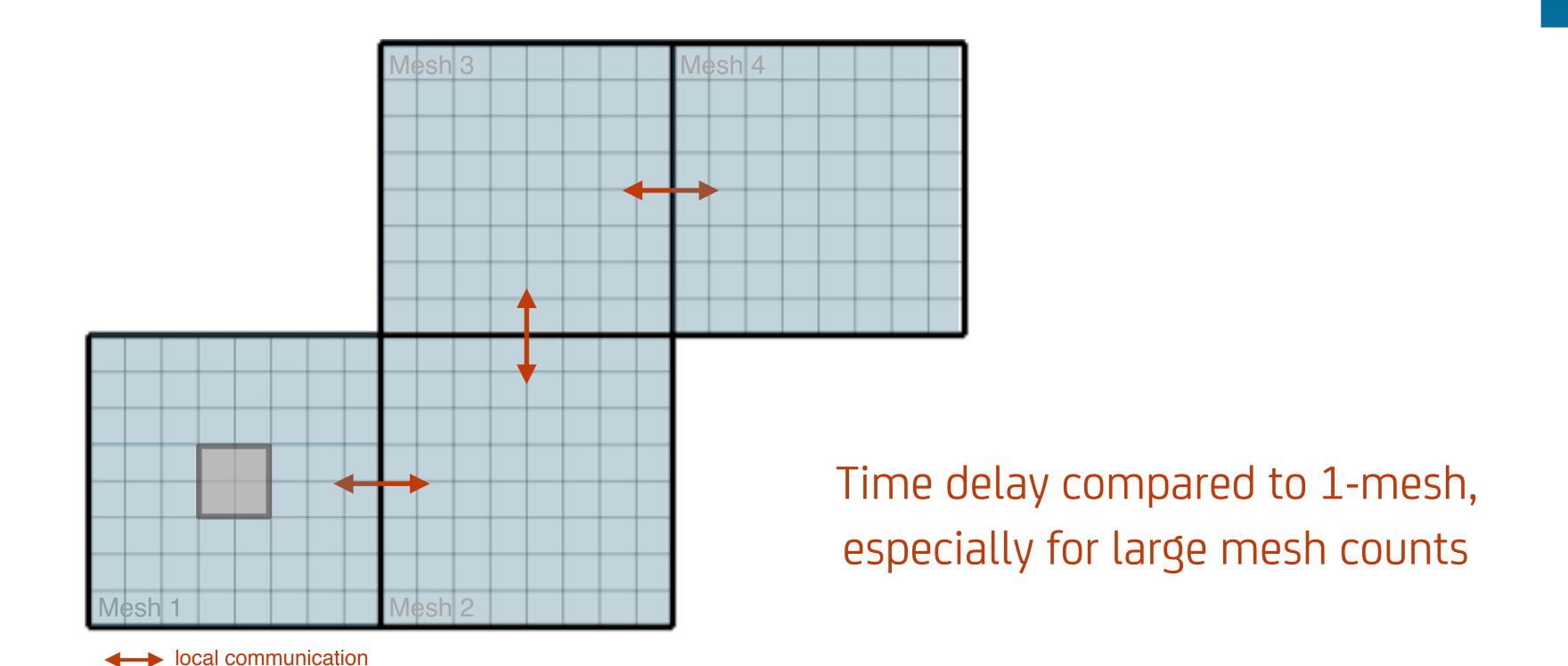
→ local communication



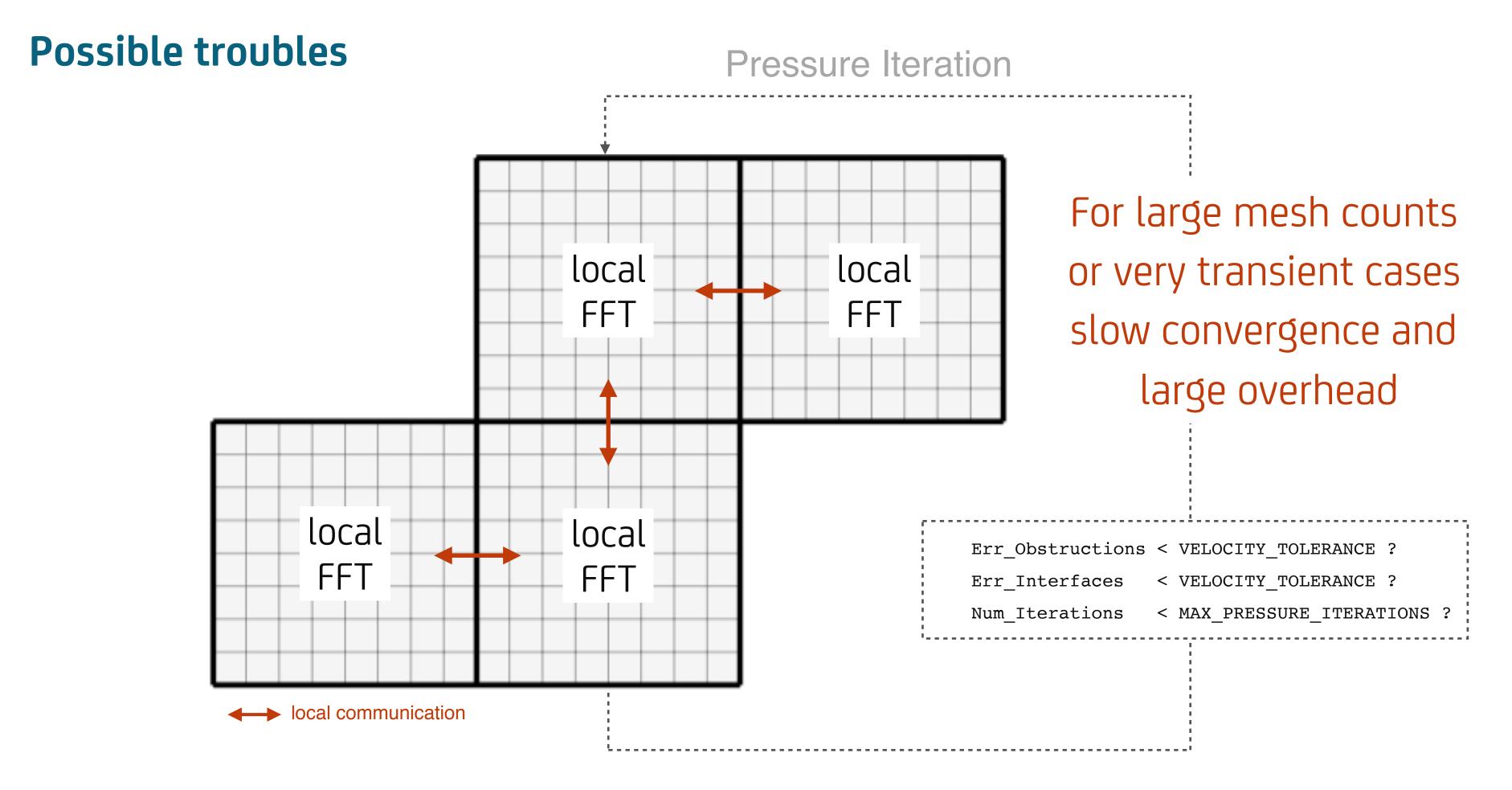
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FFT solver

4. Cycle: Information finally reaches Mesh 4









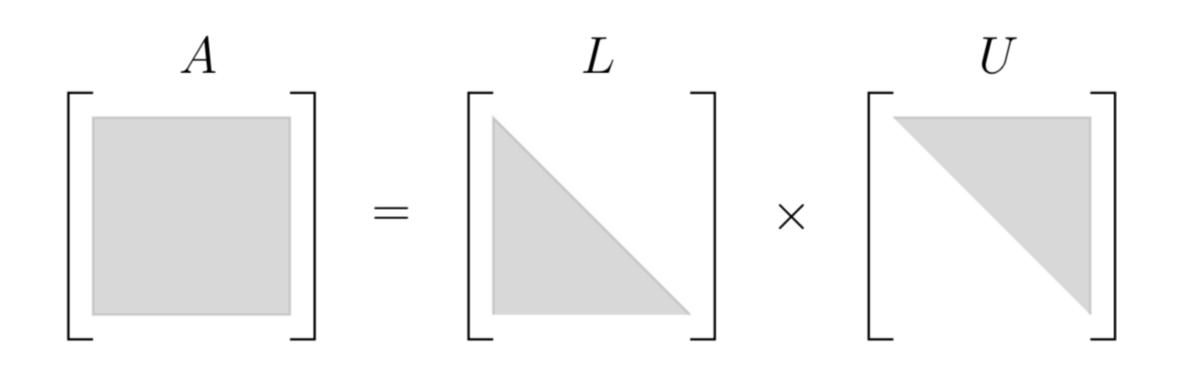
UGLMAT solver Optimized parallel LU-decomposition



solver

Alternative pressure solver UGLMAT

- Global unstructured discretization of whole domain
- ullet Decomposition of global Poisson matrix A in lower and upper triangular matrices L and U

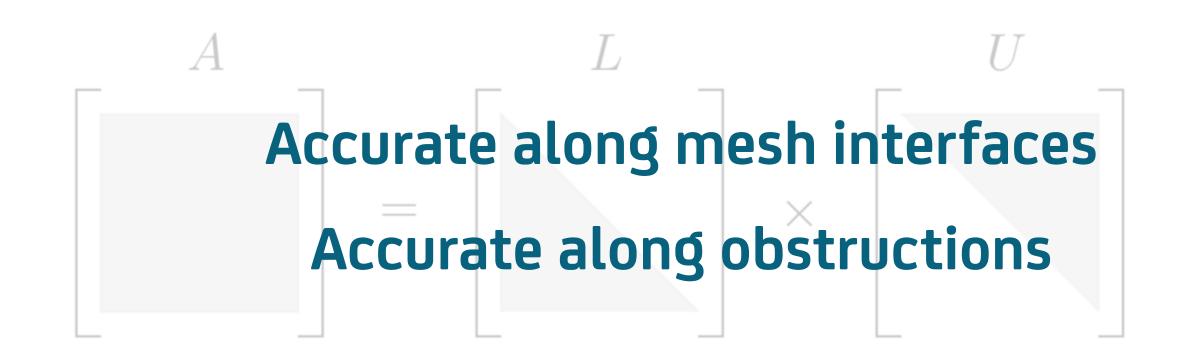


Parallel LU-decomposition

• Usage of optimized LU - solver from Intel Math Kernel Library (MKL)



- Global unstructured discretization of whole domain
- Decomposition of global Poisson matrix A in lower and upper triangular matrices L and U



Parallel LU-decomposition

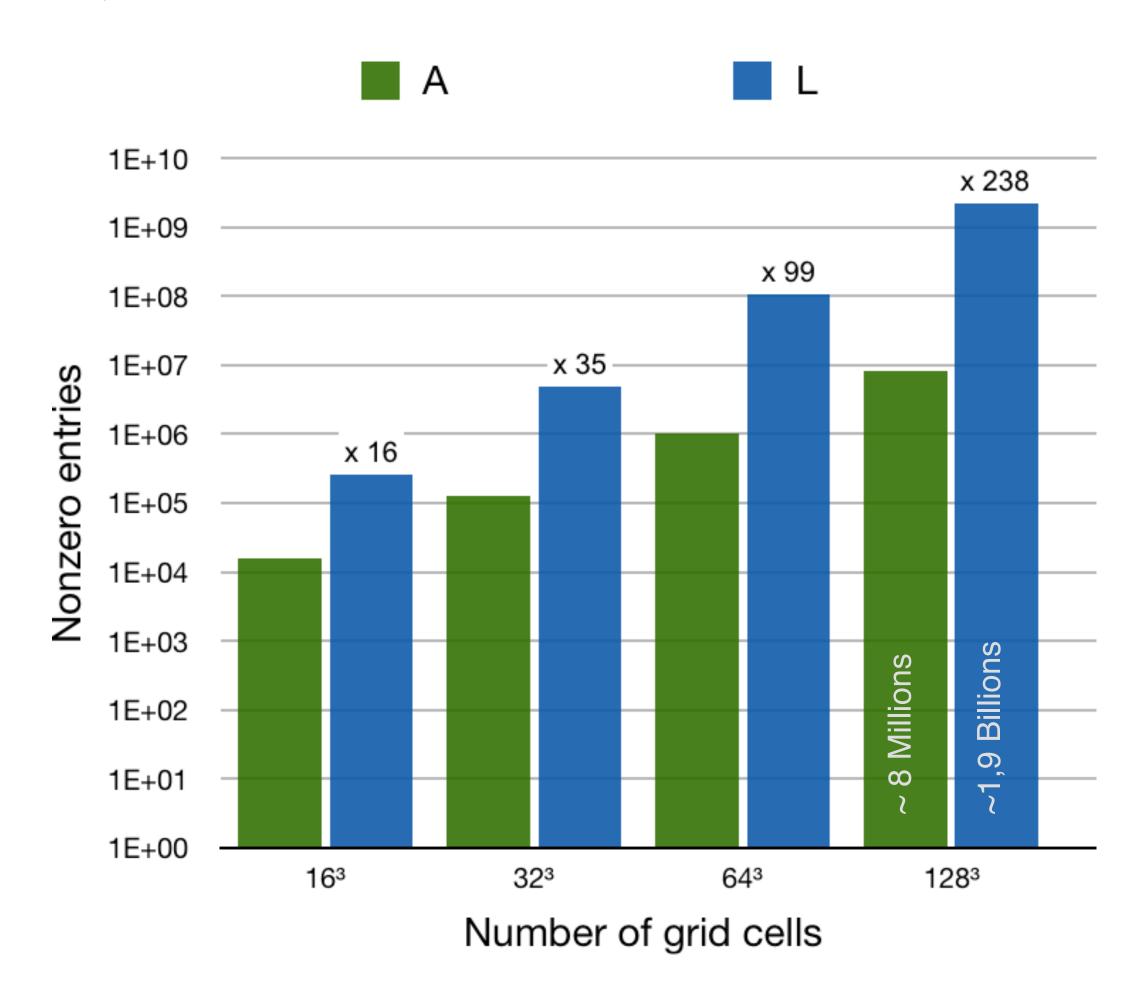
ullet Usage of optimized LU - solver from Intel Math Kernel Library (MKL)



UGLMAT - Memory needs for 3D-cube



UGLMAT solver



L has much more non-zero entries than A due to ,fill-in'

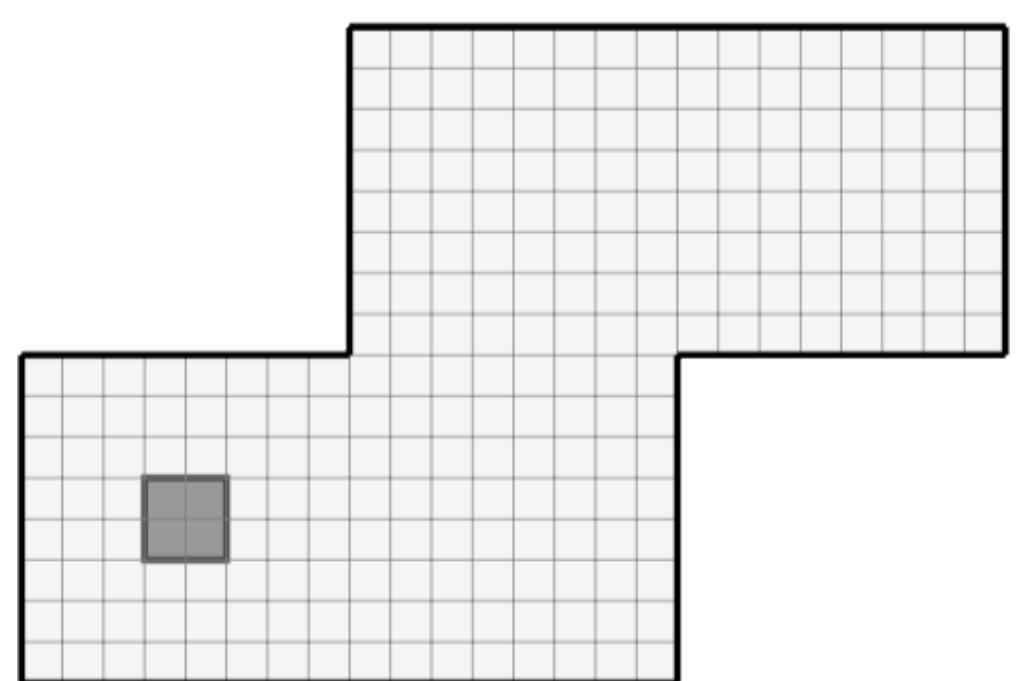
Huge memory requirements if grid is refined



Scalable Recursive Clustering





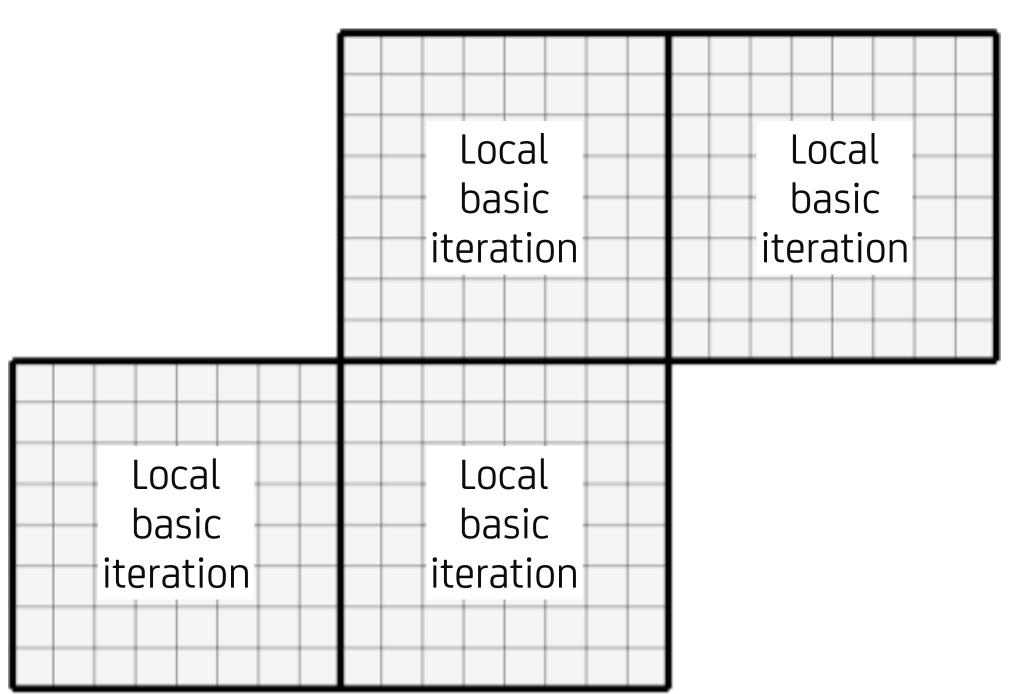


Global structured discretization

Data-parallel iterative method for global Poisson matrix



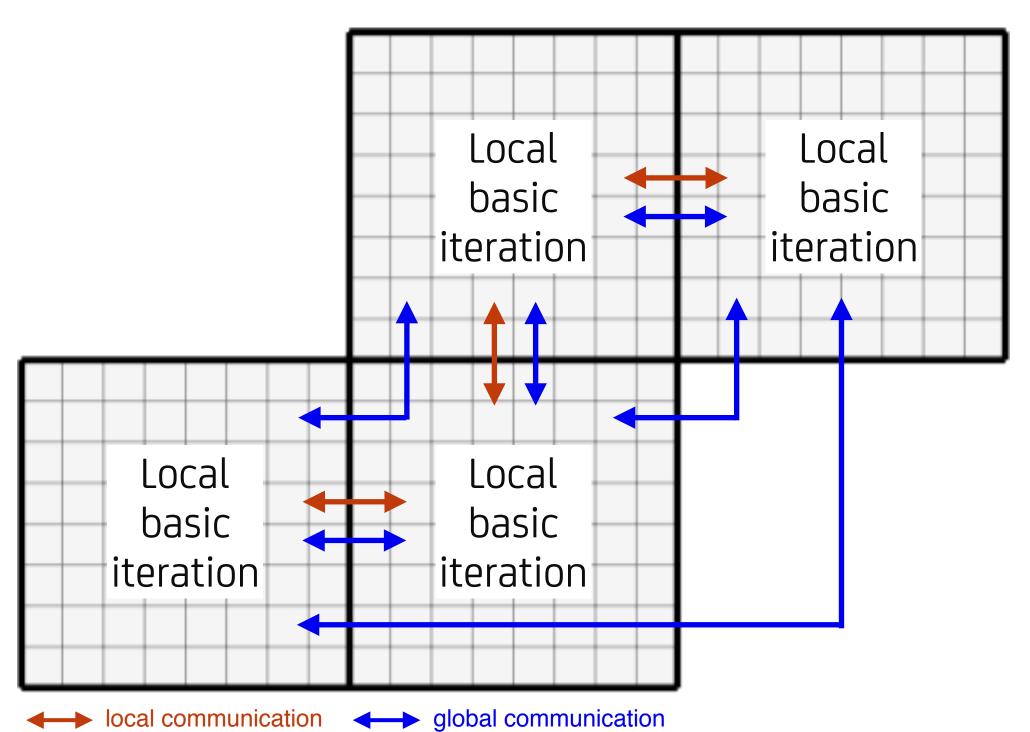
Global basic iteration



Not used as stand-alone solvers

only as corrections to global solution

Global basic iteration

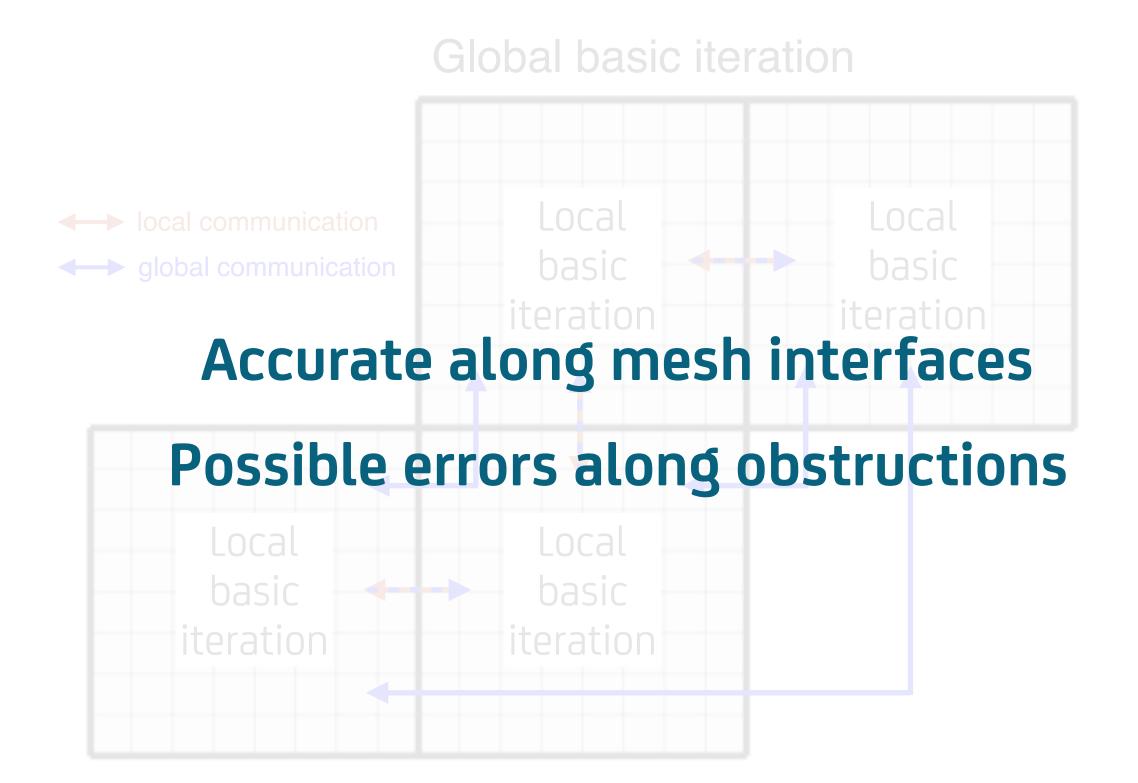


Local solvers offer fine grid accuracy

Basic information transfer is provided globally



ScaRC Core: Structured basic version



ScaRC solver



4

ScaRC solver

Use of different discretization techniques

- Pressure iteration for structured case --> Fix errors at obstructions
- Global unstructured discretization -- No errors at obstructions

Use of different global solvers

- Conjugated Gradient method (CG) Exploit basic robustness
- Geometric Multigrid method (MG) -- Improve global coupling

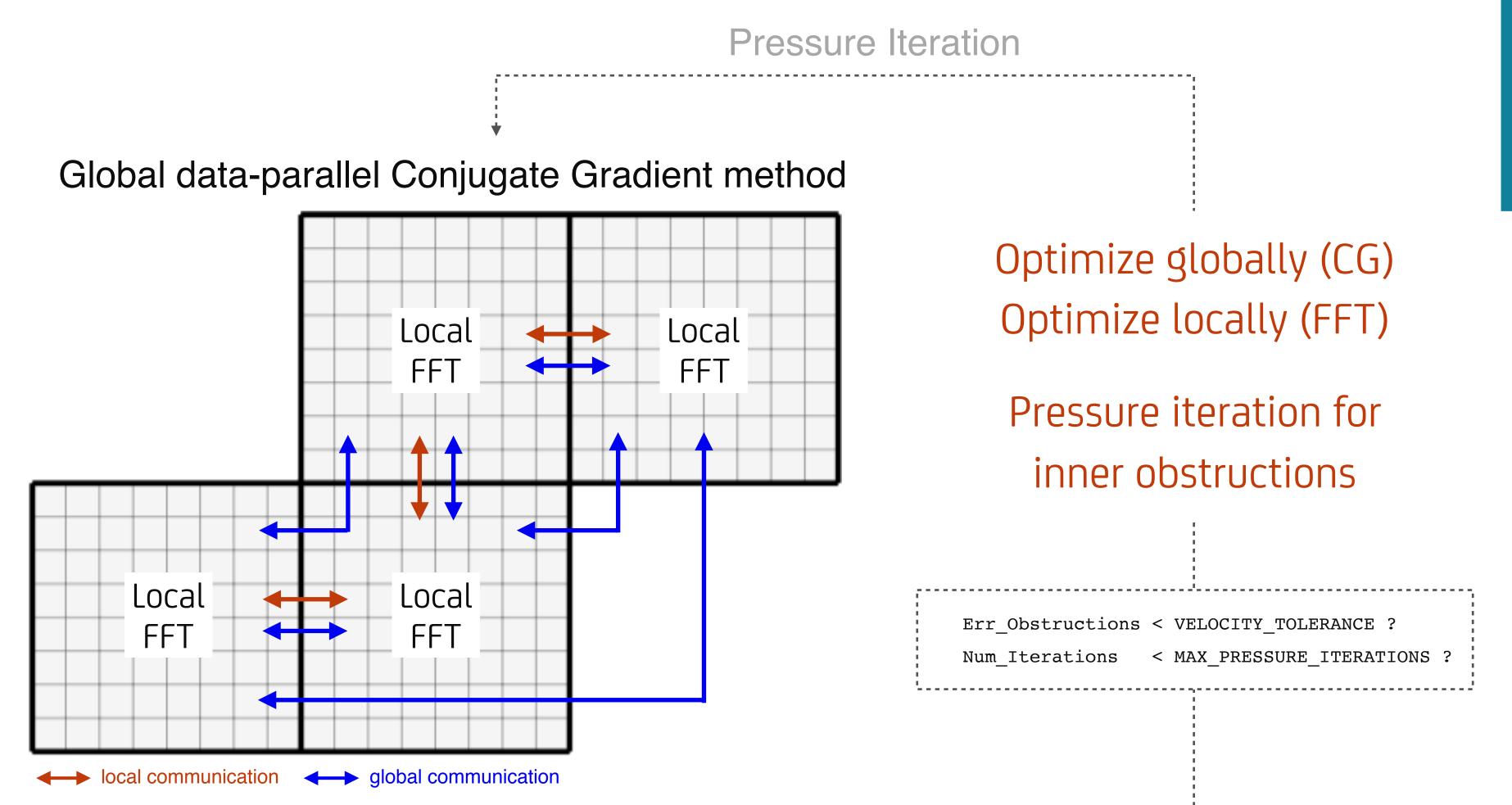
Use of different local solvers

- Optimized FFT (CRAYFISHPAK) --> Speed up local solutions in structured case
- Optimized LU (Intel MKL) -> Speed up local solutions in unstructured case

ScaRC-CG: Default for structured grids

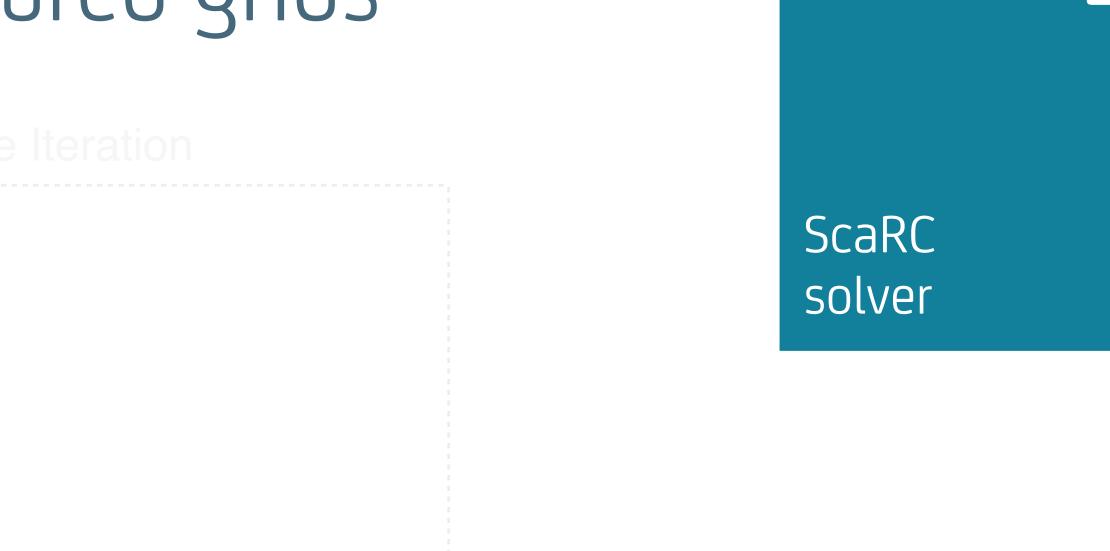


ScaRC solver





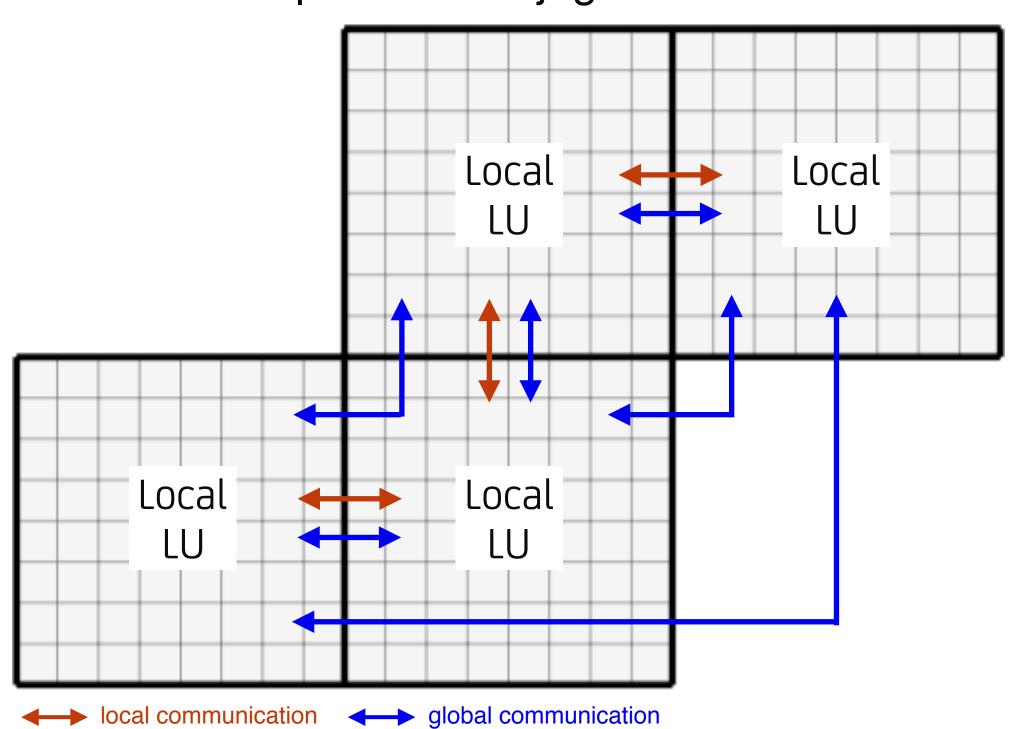
ScaRC-CG: Default for structured grids



Global data-parallel Conjugate Gradient method Accurate along mesh interfaces Accurate along obstructions



Global data-parallel Conjugate Gradient method



Optimize globally (CG)
Optimize locally (LU)

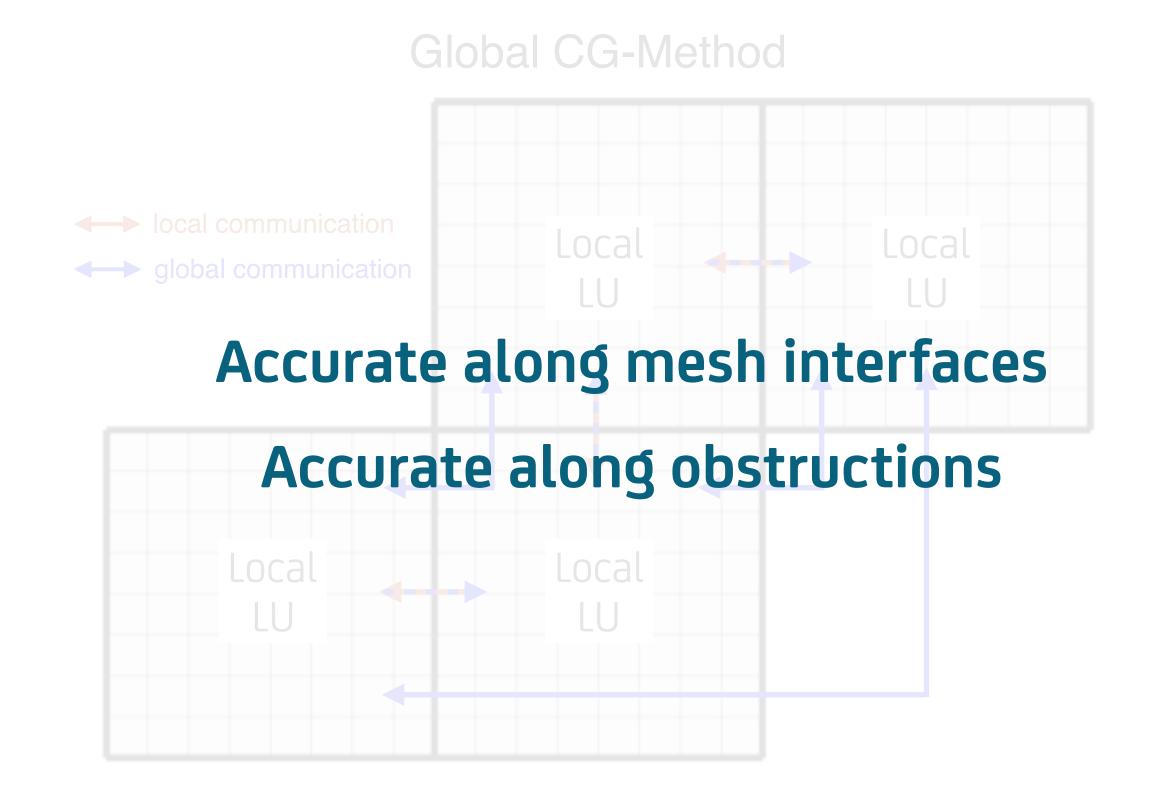
No need for pressure iteration



UScaRC-CG: Default for unstructured grids



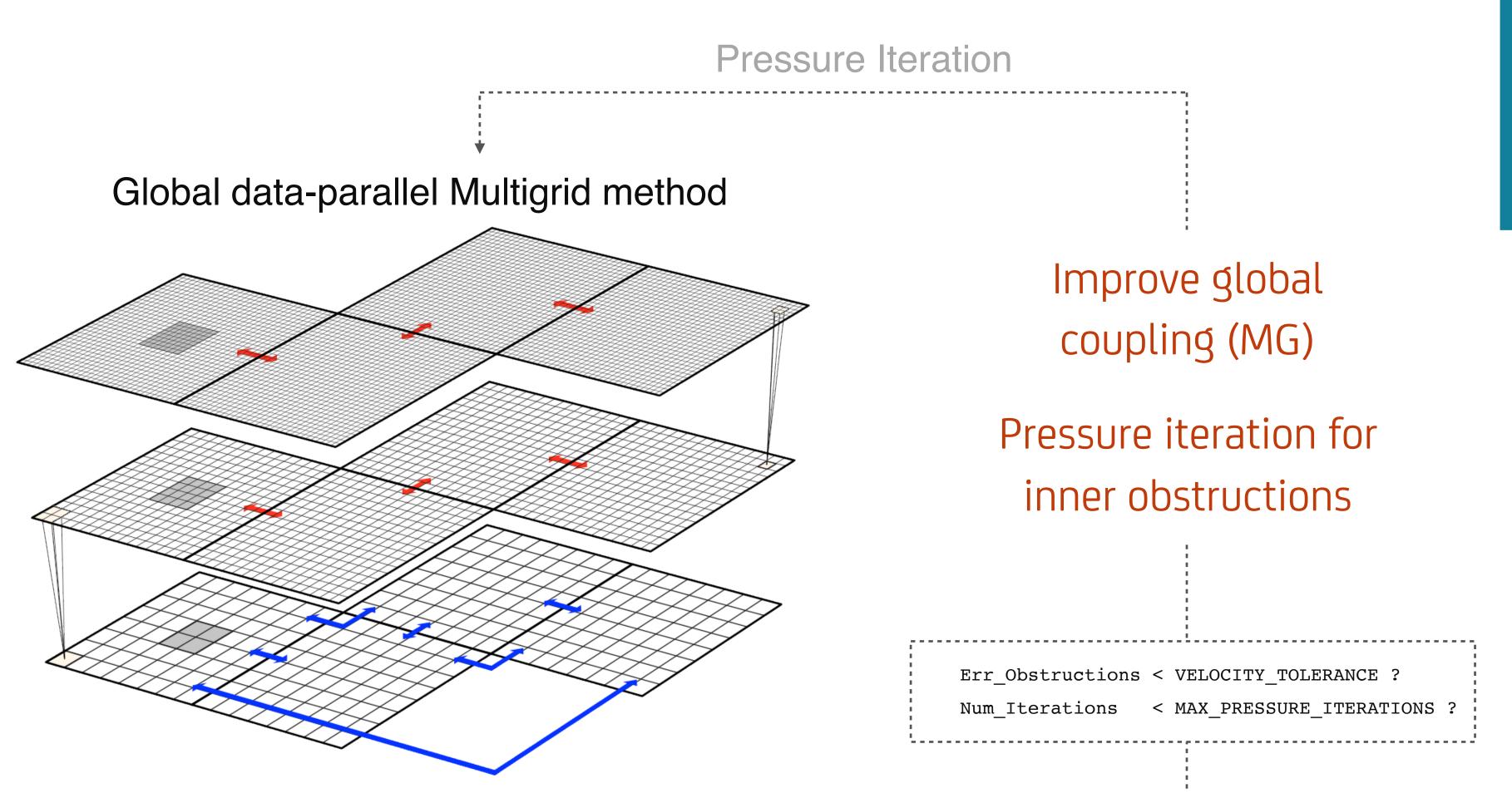
ScaRC solver



ScaRC-MG: Alternative for structured grids

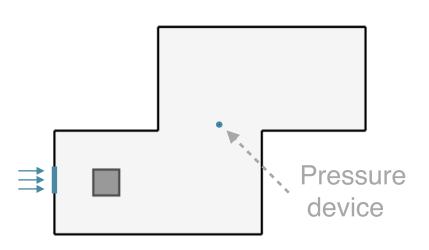


ScaRC solver





→ local communication ←→ global communication

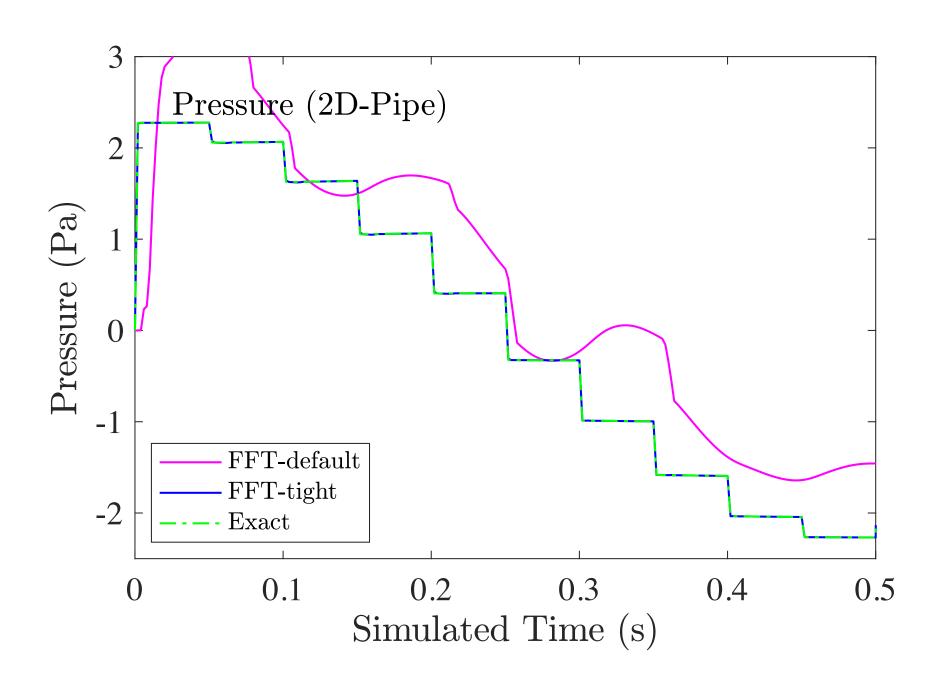


Pressure trace for 2D-pipe

4

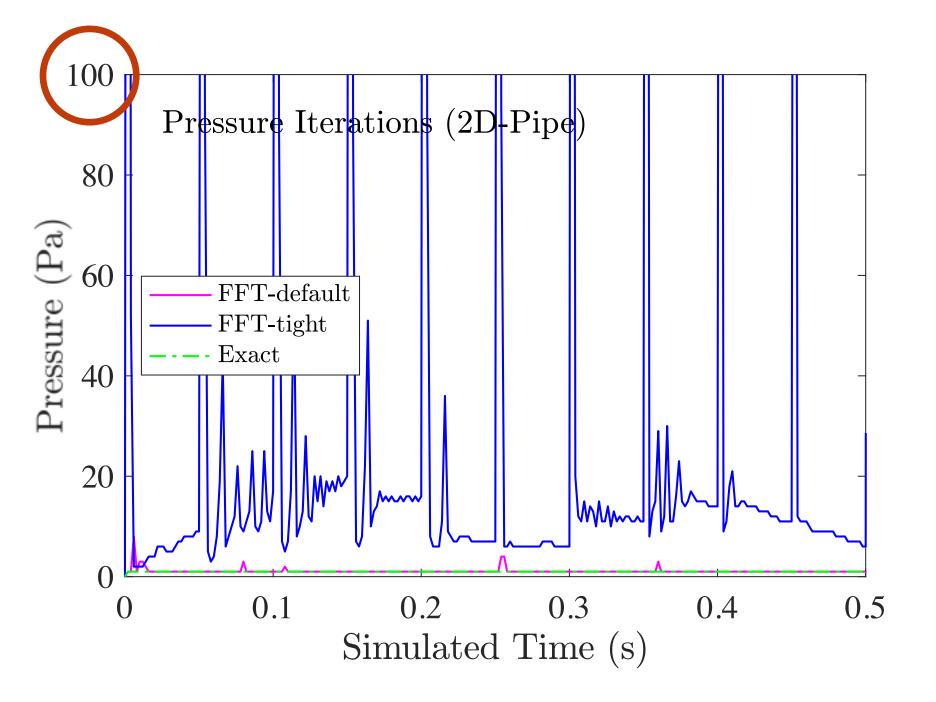
ScaRC solver

FFT default and tight (tol=10⁻⁵ m/s)



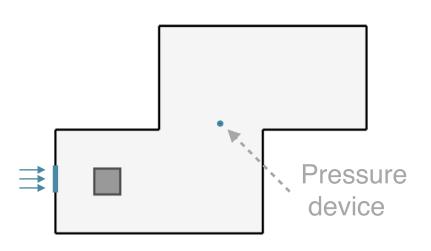
Only accurate for tight pressure iteration

Number of required pressure iterations



Increased number of pressure iterations (Ø 28)



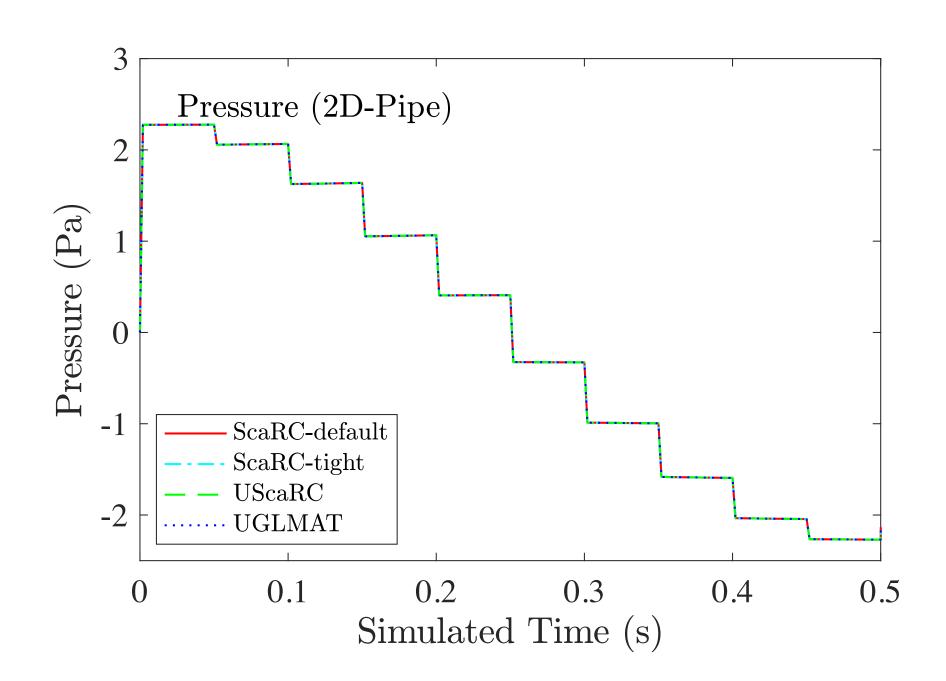


Pressure trace for 2D-pipe

4

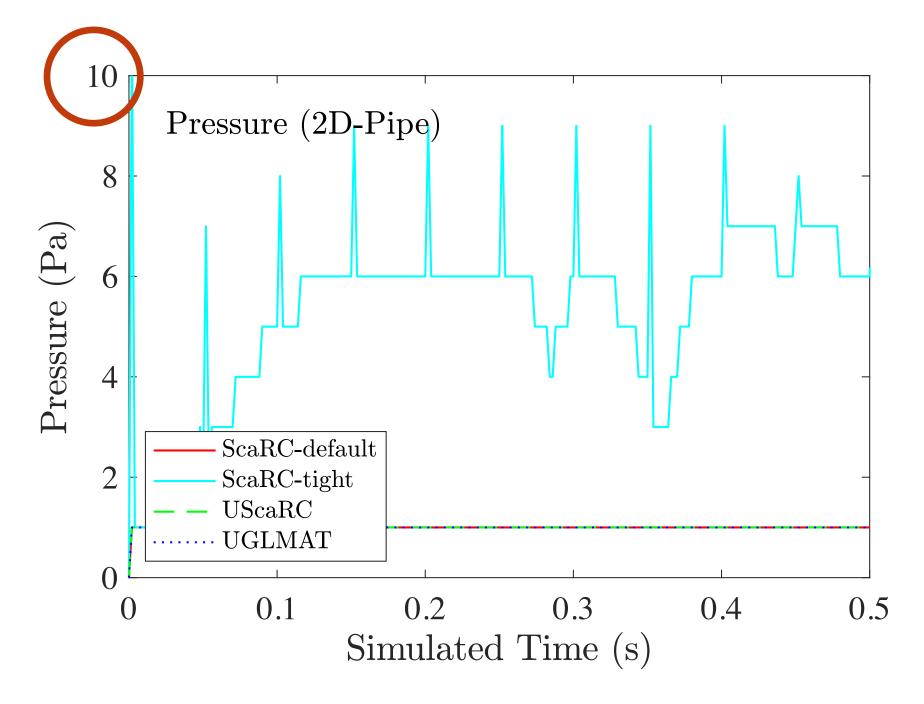
ScaRC solver

Different variants of ScaRC and UGLMAT



Accurate for all variants

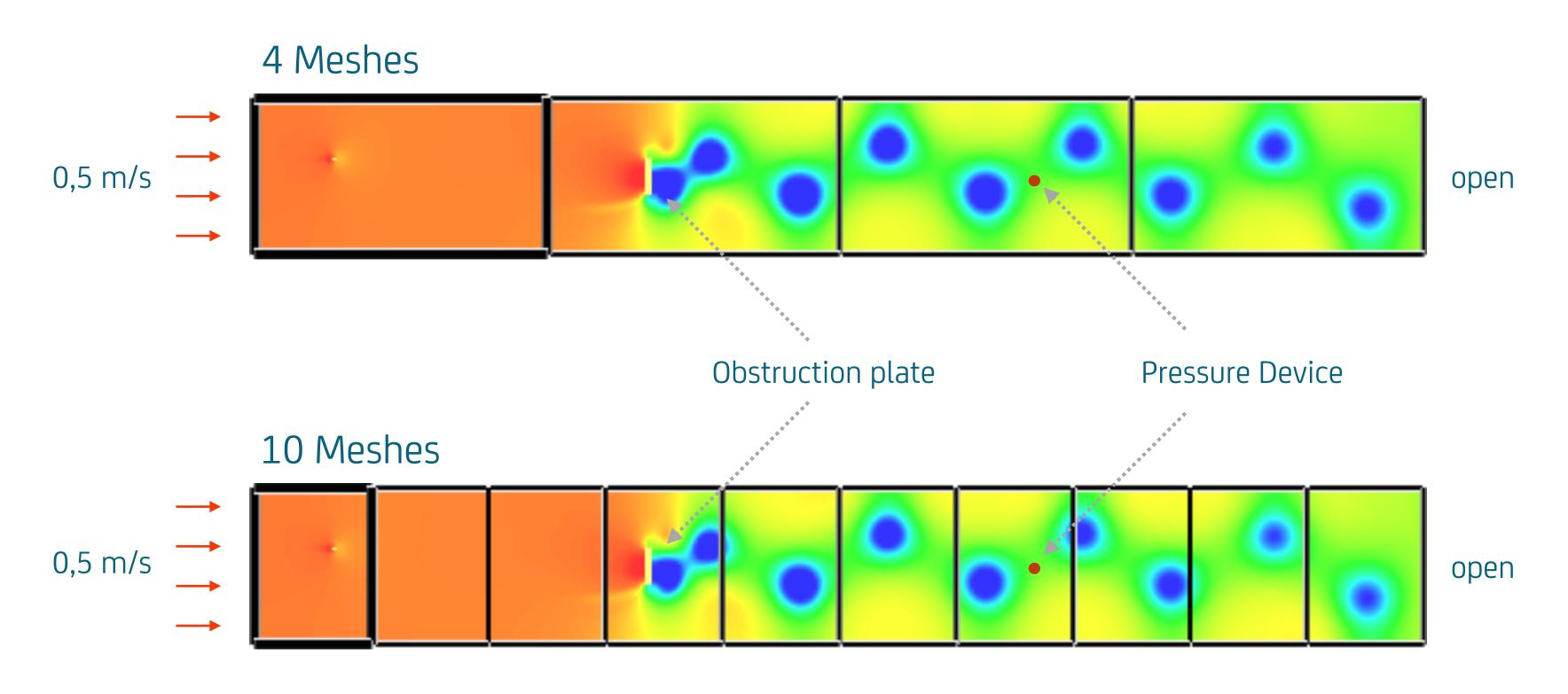




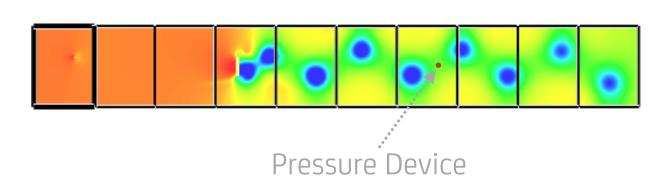
Less pressure iterations: 1 (default), max 9 (tight)



dancing_eddies

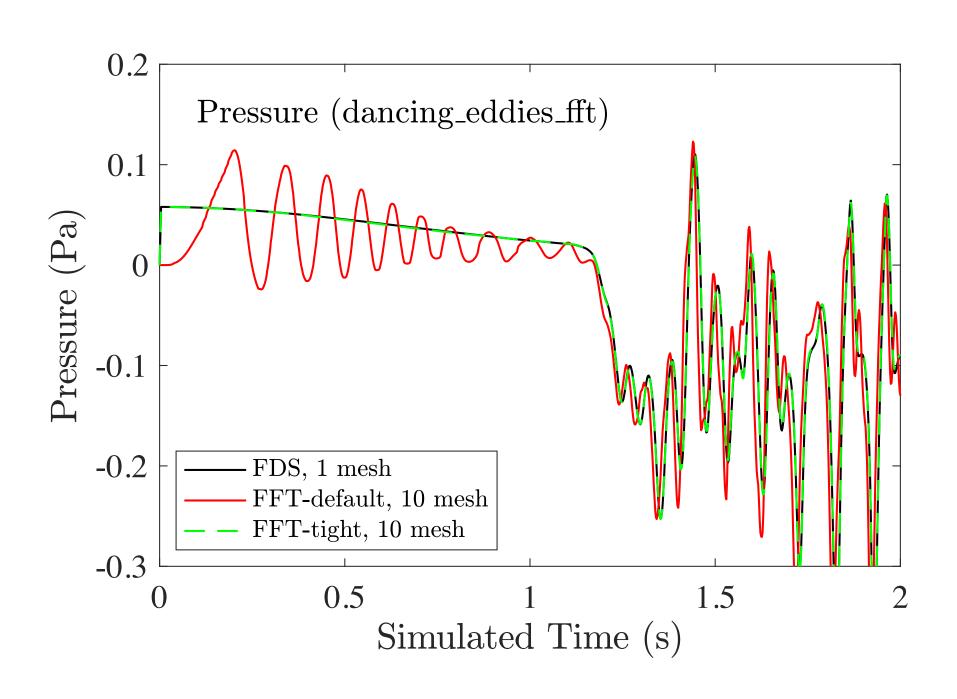




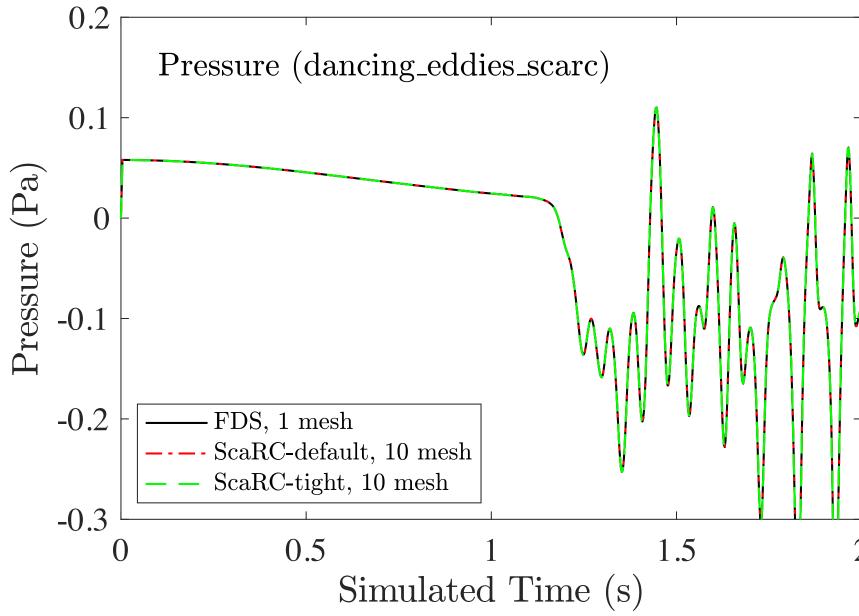


Pressure trace 10-mesh case

FFT default and tight (tol=10⁻⁵ m/s)



ScaRC default and tight (tol=10⁻⁵ m/s)

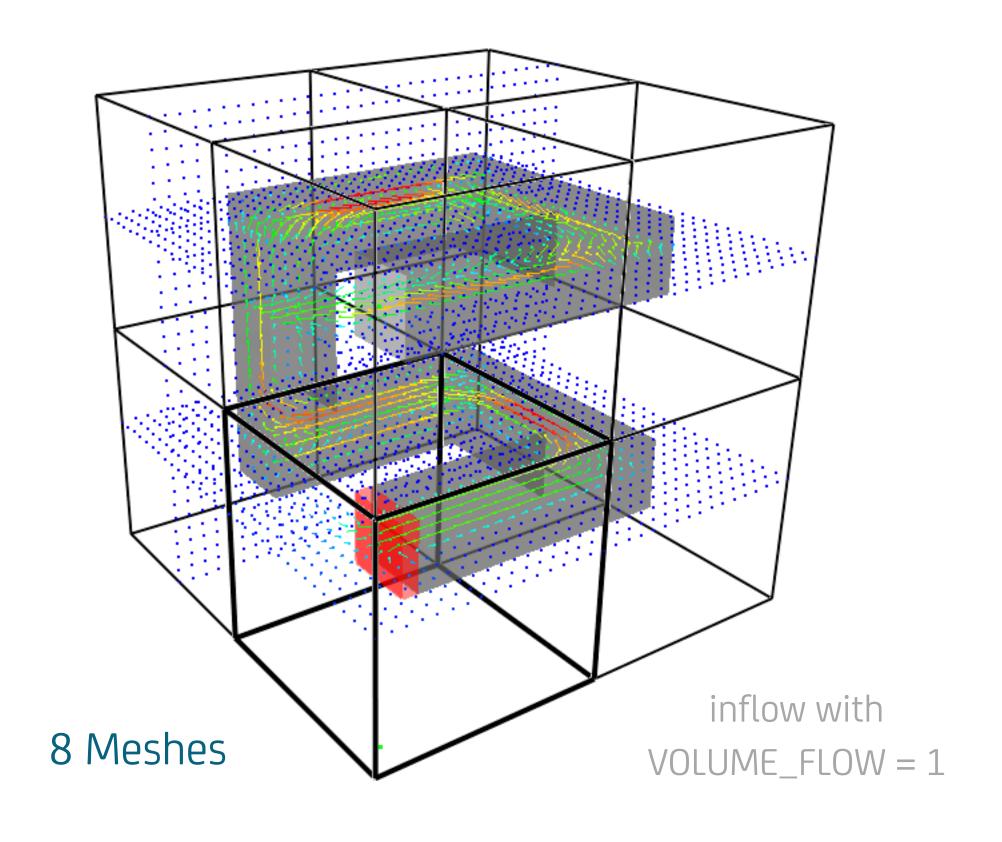


Accurate only for tight tolerance, but increased number of pressure iterations (Ø 28)

Accurate already for default tolerance, max 4 pressure iterations for tight tolerance

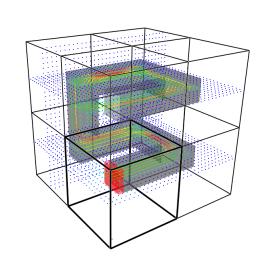


duct_flow



Many internal obstructions
which cause frequent
changes of flow direction



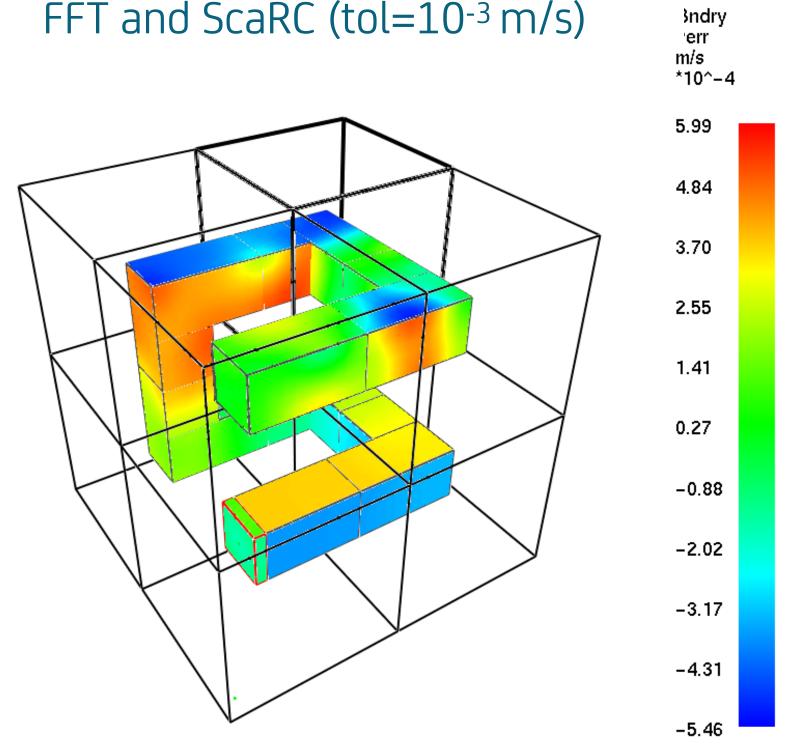


Velocity error along channel

ScaRC solver

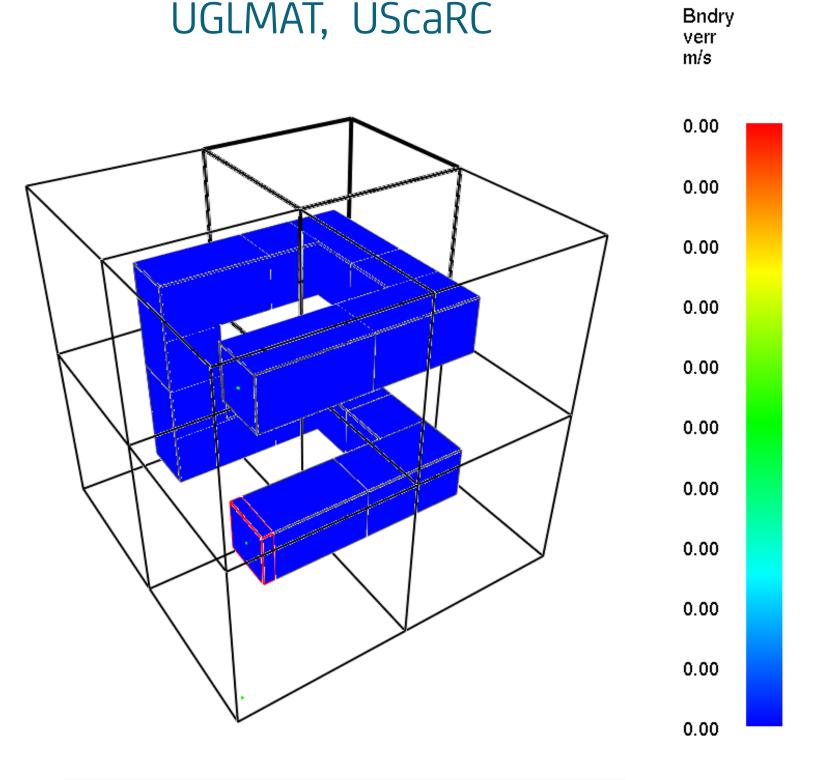
Structured

FFT and ScaRC (tol=10⁻³ m/s)



Unstructured

UGLMAT, UScaRC



Time: 43.8

hhpberlin 1

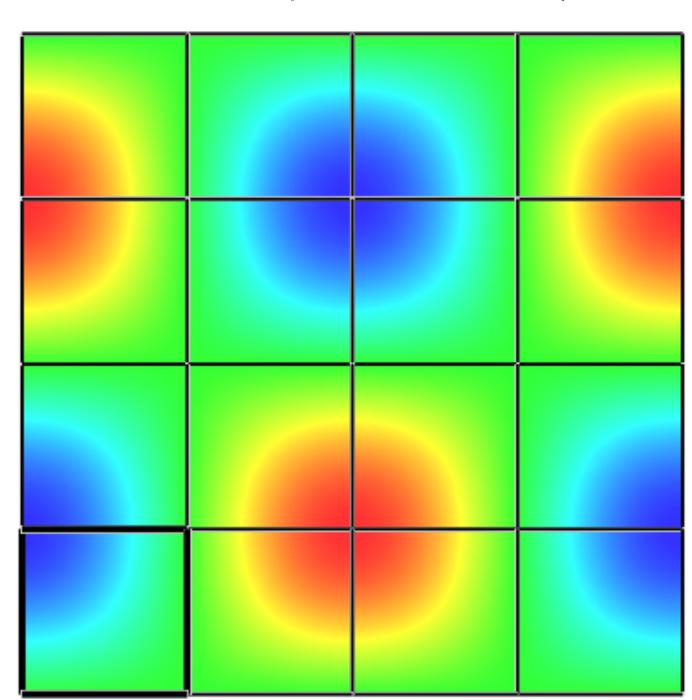
Verification cases: Periodic boundaries

4

ScaRC solver

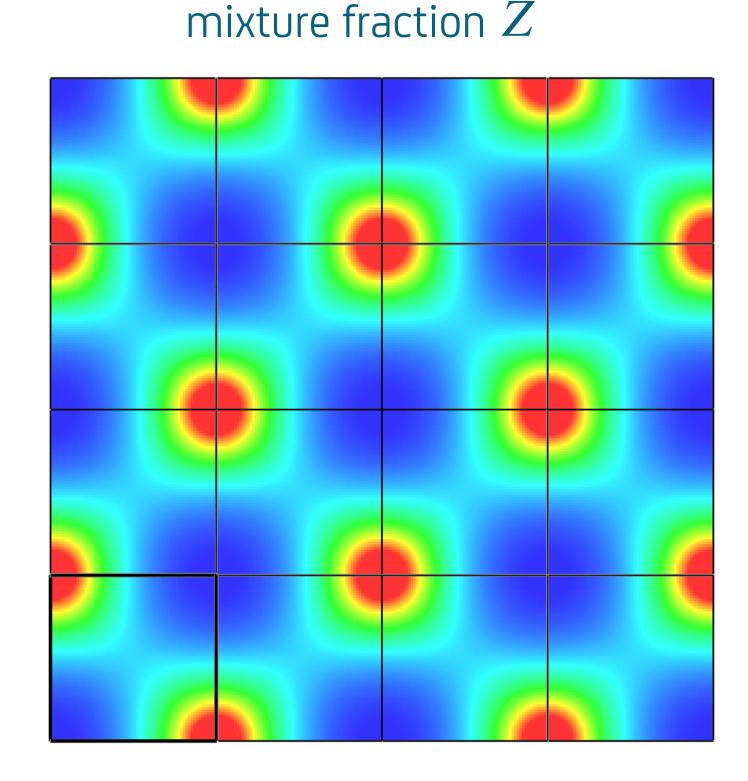
NS_Analytical_Solution

u - component velocity



ScaRC 16 meshes

Preserves periodic behavior



shunn3

Still to do/to improve

- use different refinement levels between meshes (currently same is needed)
- test further global methods (i.e. algebraic multigrid) and local methods (ILU)
- optimise runtime of single components and incorporate OpenMP-directives
- optimise parameter settings for global and local iterations

Verification & Validation

- run all pressure related verification tests
- run selected validation tests

