Sushant Vijay Chavan

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WORK EXPERIENCE

Student Research Assistant

KELO Robotics GmbH

- ₩ Jul 2020 Aug 2022
- Sankt Augustin, Germany
- Propose and use a novel indoor semantic map representation
- Design and implement single/multi robot simulation software using Gazebo and Unity3D (with ROS-Sharp) respectively

Student Research Assistant

ROPOD Project, Hochschule Bonn-Rhein-Sieg

- Sankt Augustin, Germany
- Develop a flexible Gazebo-based simulator for testing high-level execution of tasks by an arbitrary sized fleet of mobile robots
- Setup and maintain continuous integration of software packages

Senior Software Engineer

Robert Bosch Engineering and Business Solutions Private Limited

- ₩ Sep 2013 Dec 2017
- Pangalore, India / Hildesheim, Germany
- OpenSceneGraph & Navigation Data Standard (NDS) based 3D map visualization application for in-vehicle infotainment systems
- Implement highly optimized algorithms for rendering 3D building models on embedded devices with limited computing power

RELEVANT PROJECTS

Composable Ontology-based Indoor Semantic Map Master Thesis, Hochschule Bonn-Rhein-Sieg

- A novel framework to flexibly compose new maps from a prior collection of heterogeneous metric-semantic indoor maps
- Employ an ontological knowledge-base together with the composed maps to plan context-dependent indoor navigation plans

Simulator for modular KELO ROBILE mobile robots **KELO Robotics GmbH**

 A ROS package to simulate arbitrary configurations of modular mobile robots in Gazebo with an option to activate true physicsbased wheel motion, resulting in the motion of the platform

Comparative evaluation of experience-based path planners for multi robot systems

Hochschule Bonn-Rhein-Sieg

 Port and quantitatively evaluate the suitability of using single robot experience-based path planners for a fleet of logistic robots, using a custom-developed benchmarking framework

EDUCATION

M.Sc. in Autonomous Systems Hochschule Bonn-Rhein-Sieg, Germany

German GPA 1.1

B.E. in Electronics and Communications Visvesvaraya Technological University, India

₩ Aug 2009 - Jun 2013

Distinction with an aggregate score of 82%

ACHIEVEMENTS

- Co-authored a patent filed by Robert Bosch Car Multimedia GmbH
- Awarded the *Deutschlandstipendium* (German Scholarship) 2019/20
- Awarded the Fresher Of The Year 2013 at Robert Bosch, India
- Awarded the CSSS 2009 Scholarship by the Ministry of Human Resource Development (MHRD), India

TECHNICAL SKILLS

Programming Languages

Modern C++ Python Shell Scripting

Libraries/Frameworks/Tools

ROS PCL | CGAL OpenCV hdl_graph_slam mcl 3dl OctoMap URDF Xacro ROS# Gazebo Unity OWL 2 **SWRL** Protégé Owlready2 PlantUML GitLab CI Docker Doxygen **CMake** Jupyter VS Code Linux

Competencies

Indoor robot navigation Robot simulations

Classical AI (Search, Logics, & Planning)

Semantic mapping Multi-agent systems