# SUSHANT VIJAY CHAVAN

### **Graduate student at Hochschule Bonn-Rhein-Sieg**

- Grantham-Allee 21, 53757 Sankt Augustin, Germany 0163-9809177
- @ sushant.chavan@smail.inf.h-brs.de in linkedin.com/in/sushantvchavan
- github.com/Sushant-Chavan



### CAREER OBJECTIVE

Pursuing a master's degree in autonomous systems with 4+ years of professional experience in the software development industry. Seeking an internship/master's thesis position in the field of robot navigation, multi-robot systems, and/or classical AI.

### **EXPERIENCE**

### Wissenschaftliche Hilfskraft (Research Assistant) ROPOD Project, Hochschule Bonn-Rhein-Sieg

₩ June 2019 - Ongoing

Sankt Augustin, Germany

• Development of software for the fleet management system, writing software tests for testing the coordination and resource usage by the robot fleet, conducting experiments & documenting them.

#### Senior Software Engineer

#### **Robert Bosch Engineering and Business Solutions Private Limited**

• Fulfilled various roles as a C++ & 3D computer graphics developer. I was responsible for the design and development of next-gen, enhanced 3D navigation map graphics features, that are optimized to run on low-end embedded in-vehicle infotainment systems.

### **PROJECTS**

# Comparative analysis of Experience Based Path Planning Frameworks for Multi-Robot Systems

#### Hochschule Bonn-Rhein-Sieg

December 2018 - August 2019

- We ported three experience-based planning frameworks (Lightning, Thunder, and EGraphs) to solve multi-robot path planning problems and quantitatively compared them using a custom-written benchmarking framework.
- Our goal was to evaluate the suitability of experience-based planners in the context of the ROPOD project, where a fleet of multiple robots is assigned a task to pick up and deliver several supply-carts to different locations in a hospital environment.

# Development of RViz plugins for RoboCup teams b-it-bots, Hochschule Bonn-Rhein-Sieg

October 2018 - January 2019

 We developed two RViz plugins called Map Annotation Tool and Action Client Panel. The map annotation tool facilitates annotating navigation maps efficiently and flexibly. The action client panel provides a GUI for selecting actions, setting their parameters, sending action goals and monitoring the progress of action execution.

### **EDUCATION**

M.Sc. in Autonomous Systems Hochschule Bonn-Rhein-Sieg, Germany

April 2018 - August 2020 (expected)

Current German GPA 1.21

# B.E. in Electronics and Communications

Visvesvaraya Technological University, India

m Sept 2009 - June 2013

Distinction with 82% score

### **ACHIEVEMENTS**



Co-authored a patent filed by Robert Bosch GMBH



Awarded the *Deutschlandstipendium* (Germany Scholarship) 2019/20

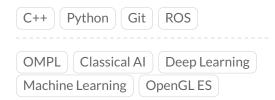


Awarded the Fresher Of The Year 2013 at Robert Bosch, India



Awarded the CSSS 2009 Scholarship by the Ministry of Human Resource Development (MHRD), India

## **SKILLS**



## **LANGUAGES**

English	••••
Hindi	••••
German	•••••