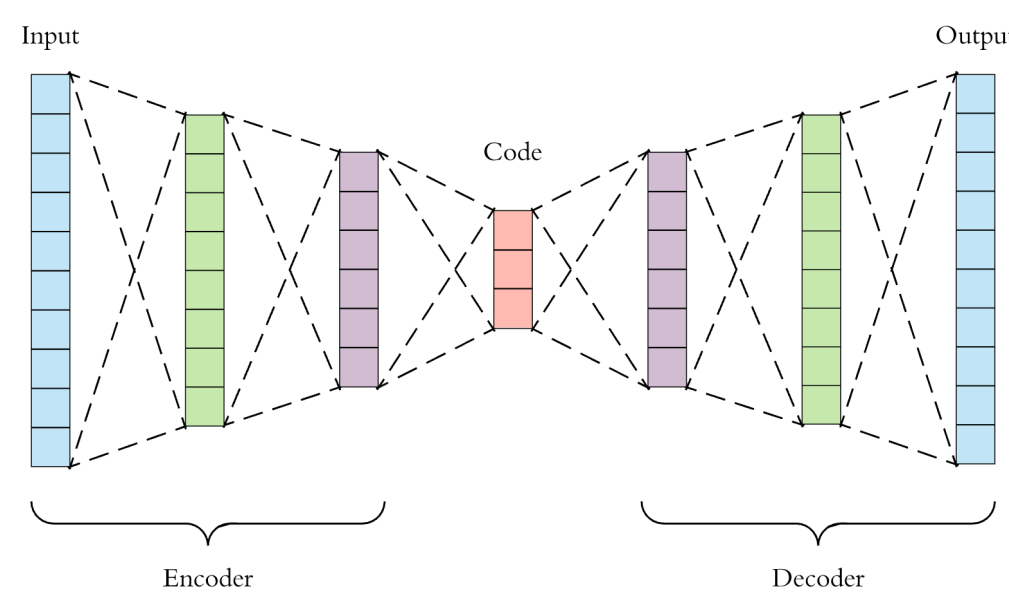


## Introduction

### Encoder-Decoder Neural Network

- Autoencoder
- Encoder-Decoder

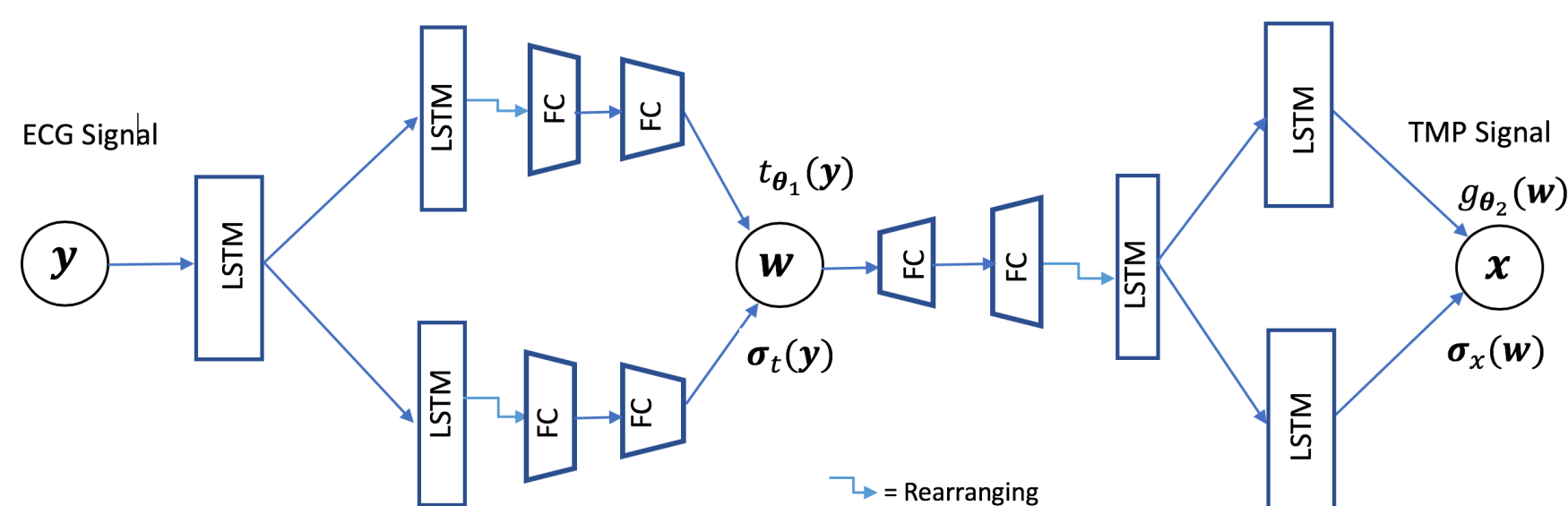


### Key Ideas

- How to improve generalization ability of an encoder decoder network?
- With constrained stochasticity of latent space
- Why does constrained stochasticity help?
- Because it renders decoder less sensitive to variation in latent space

## Application to ECGi

- Inverse reconstruction of TMP from ECG signal
- Ill posed inverse problem
- Estimating sequence from sequence



- LSTM and FC layer in both encoder and decoder
- Conditional distributions as Gaussian

## Contribution

- Theoretically show that stochastic latent space helps in improving generalization
- Experimentally support the theory with application to ECGi

## Theory

### Generalization Gap

$\mathcal{T}$  = Encoder

$f$  = loss composite decoder

**Theorem 1** ((Kawaguchi and Bengio 2018)). For any  $\ell$ , let  $(\mathcal{T}, f)$  be a pair such that  $\mathcal{T} : (\mathcal{Z}, \mathcal{S}) \rightarrow ([0, 1]^d, \mathcal{B}([0, 1]^d))$  is a measurable function,  $f : ([0, 1]^d, \mathcal{B}([0, 1]^d)) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$  is of bounded variation as  $V[f] < \infty$ , and  $\ell(x, h(y)) = (f \circ \mathcal{T})(z) \forall z \in \mathcal{Z}$ , where  $\mathcal{B}(A)$  indicates the Borel  $\sigma$ -algebra on  $A$ . Then for any dataset pair  $(D_m, Z_m)$  and any  $\ell(x, h_{\mathcal{A}(D_m)}(y))$ ,

$$E_{\mu} \ell(x, h_{\mathcal{A}(D_m)}(y)) - E_{Z_m} \ell(x, h_{\mathcal{A}(D_m)}(y)) \leq V[f] \mathcal{D}^*[\mathcal{T}_* \mu, \mathcal{T}(Z_m)]$$

where  $\mathcal{T}_* \mu$  is pushforward measure of  $\mu$  under the map  $\mathcal{T}$ .

**Proposition 1** ((Kawaguchi and Bengio 2018)). Suppose that  $f_{j_1, \dots, j_k}$  is a function for which  $\partial_{1, \dots, k} f_{j_1, \dots, j_k}$  exists on  $[0, 1]^k$ . Then,

$$V^k[f_{j_1, \dots, j_k}] \leq \sup_{t_{j_1}, \dots, t_{j_k} \in [0, 1]^k} |\partial_{1, \dots, k} f_{j_1, \dots, j_k}(t_{j_1}, \dots, t_{j_k})|.$$

If  $\partial_{1, \dots, k} f_{j_1, \dots, j_k}$  is also continuous on  $[0, 1]^k$ ,

$$V^k[f_{j_1, \dots, j_k}] = \int_{[0, 1]^k} |\partial_{1, \dots, k} f_{j_1, \dots, j_k}(t_{j_1}, \dots, t_{j_k})| dt_{j_1} \dots dt_{j_k}.$$

### Learning with Stochastic Latent Space

$$p_{\theta_1}(w|y) = \mathcal{N}(w|t_{\theta_1}(y), \sigma_t^2(y)) \quad \text{minimize } -E_{P(x,y)} \log \int p_{\theta_2}(x|w) p_{\theta_1}(w|y) dw$$

$$p_{\theta_2}(x|w) = \mathcal{N}(x|g_{\theta_2}(w), \sigma_x^2(w)) \quad \text{such that } D_{KL}(p_{\theta_1}(w|y) || \mathcal{N}(w|0, I)) < \delta$$

Loss Function

$$\mathcal{L} \leq E_{P(x,y)} \left[ E_{\epsilon \sim \mathcal{N}(0, I)} \left( \sum_i \frac{1}{\sigma_{x_i}^2} (x_i - g_i(t + \sigma_t \odot \epsilon))^2 \right) + \log \sigma_{x_i}^2 \right] + \lambda \cdot D_{KL}(p_{\theta_1}(w|y) || \mathcal{N}(w|0, I)) + \text{constant}$$

Result 1  
(Using Taylor series)

$$T_1 = \sum_i \frac{1}{\sigma_{x_i}^2} \left[ \overbrace{\ell_i(x_i, t)}^{\text{Deterministic loss}} + \langle \sigma_t \odot E_{\epsilon}[\epsilon], \frac{\partial}{\partial t} \ell_i(x_i, t) \rangle + \frac{1}{2} \langle [\sigma_t \otimes \sigma_t] \odot E_{\epsilon}[\epsilon \otimes \epsilon], \left[ \frac{\partial^2}{\partial t_{j_1} \partial t_{j_2}} \ell_i(x_i, t) \right] \rangle + \dots + \frac{1}{k!} \langle [\sigma_t \otimes^k \sigma_t] \odot E_{\epsilon}[\epsilon \otimes^k \epsilon], \left[ \frac{\partial^k}{\partial t_{j_1} \dots \partial t_{j_k}} \ell_i(x_i, t) \right] \rangle + \dots \right]$$

Weight for partial derivative (blue arrow pointing to  $\frac{\partial^k}{\partial t_{j_1} \dots \partial t_{j_k}}$ )

Tensor modulating noise (green arrow pointing to  $[\sigma_t \otimes^k \sigma_t]$ )

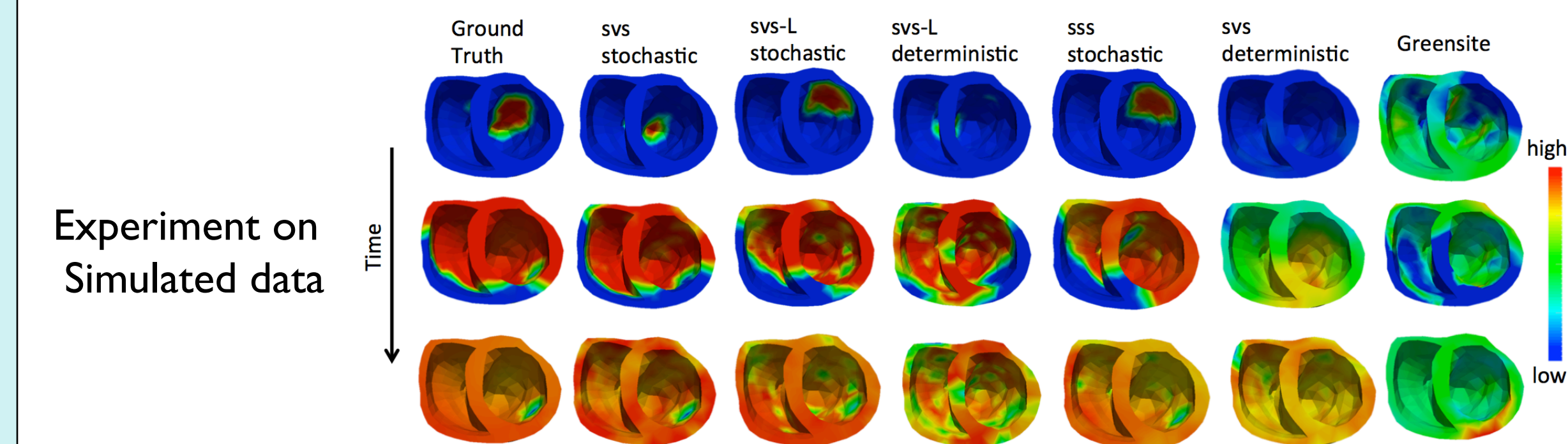
Noise tensor (red arrow pointing to  $E_{\epsilon}[\epsilon \otimes^k \epsilon]$ )

Partial derivative tensor (blue arrow pointing to  $\ell_i(x_i, t)$ )

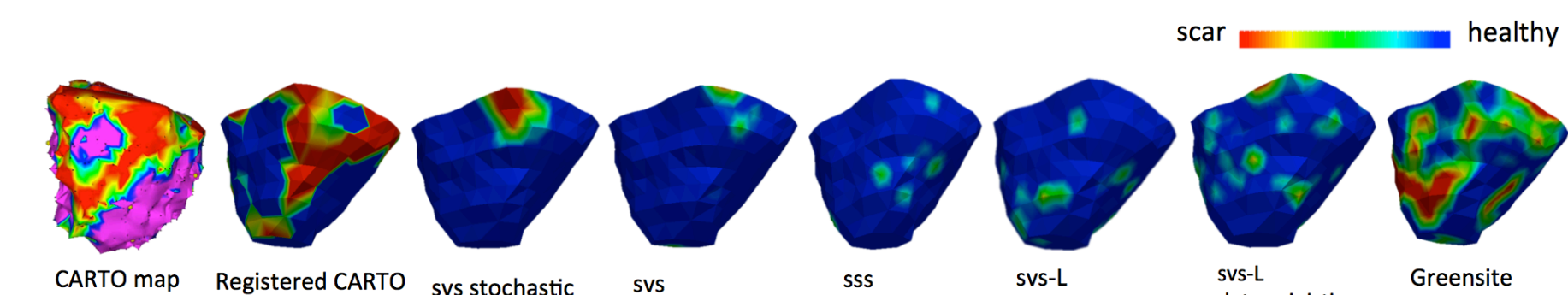
## Experiment

### Settings:

- TMP simulated using Aliev Panfilov model on 3 human-torso geometry models.
- Simulations varying origin of excitation and tissue property
- Test data simulated with new origin of excitation and tissue property



Experiment on Real data



Stochastic latent space generalizes well in both svS and svS-L architectures qualitatively and quantitatively

Metric	MSE	TMP Corr.	AT Corr.	Dice Coeff.
svS stochastic	0.037 ± 0.021	0.885 ± 0.061	0.885 ± 0.072	0.645 ± 0.181
svS deterministic	0.075 ± 0.013	0.77 ± 0.038	0.12 ± 0.13	0.01 ± 0.006
svS-L stochastic	0.068 ± 0.023	0.838 ± 0.053	0.601 ± 0.074	0.28 ± 0.154
svS-L deterministic	0.067 ± 0.02	0.84 ± 0.053	0.57 ± 0.052	0.165 ± 0.092
Greensite	—	—	0.514 ± 0.006	0.138 ± 0.005

## Conclusion

By drawing from analytical learning theory, we have shown that constrained stochasticity of latent variable improves generalization ability and then supported the theory with experiments on electrophysiological imaging.

### Acknowledgements

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