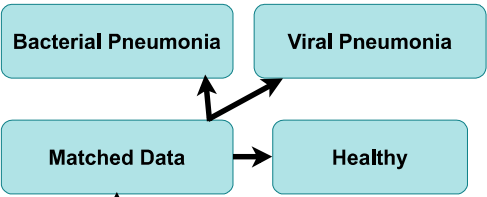
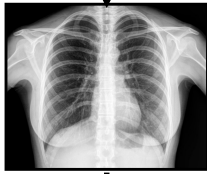
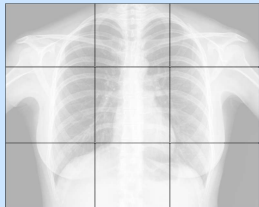


Input

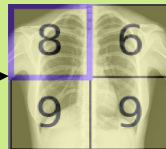


1. Grid Division (SxS Cells)
Divides the input image into a grid of cells.



5. Non-Maximum Suppression (NMS)
Removes overlapping boxes based on IoU threshold, retaining the most relevant detections.

| | | | |
|---|---|---|---|
| 7 | 3 | 5 | 2 |
| 8 | 7 | 1 | 6 |
| 4 | 9 | 3 | 9 |
| 0 | 8 | 4 | 5 |



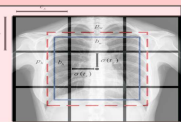
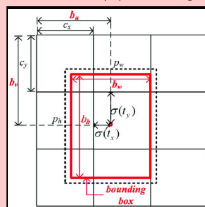
Input

Matched Data

2. Bounding Box Prediction

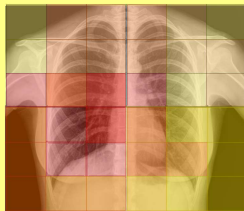
Each grid cell predicts multiple bounding boxes, each with:

- Center coordinates (x, y)
- Width (w) and height (h)
- Confidence score (C) indicating the likelihood of an object.



3. Class Probability Prediction

Given an object, algorithm predicts the probability of each class.



4. Final Detection Score

Represents the confidence of a detected class within the bounding box.
Score = Confidence * Class Probability

| | | | |
|---|---|---|---|
| 7 | 3 | 5 | 2 |
| 8 | 7 | 1 | 6 |
| 4 | 9 | 3 | 9 |
| 0 | 8 | 4 | 5 |

Ensemble Learning

Machine Learning