

#### Processes - Part III

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# **CPU Scheduling**

- ► CPU scheduling is the basis of multiprogrammed OSs.
- ▶ By switching the CPU among processes, the OS makes the computer more productive.

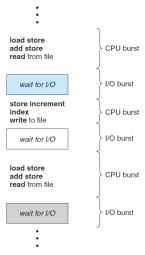


- ▶ In a single-processor system, only one process can run at a time.
- ▶ Others must wait until the CPU is free and can be rescheduled.
- ► The objective of multiprogramming is to have some process running at all times, to maximize CPU utilization.



#### **Basic Concepts**

- CPU-I/O burst cycle: process execution consists of a cycle of CPU execution and I/O wait.
- ► CPU burst followed by I/O burst.
- ► CPU burst distribution is of main concern.





#### CPU Scheduler

- ► CPU scheduler selects from among the processes in ready queue, and allocates the CPU to one of them.
- ► CPU scheduling decisions may take place when a process:
  - 1. Terminates.
  - 2. Switches from running to waiting (e.g., an I/O request).
  - 3. Switches from running to ready (e.g., interrupt).
  - 4. Switches from waiting to ready (e.g., I/O completion).
- ► For situations 1 and 2, there is no scheduling choice, as a new process must be selected for execution (non-preemptive).
- ▶ But, There is a choice, for situations 3 and 4 (preemptive).



#### Scheduling Criteria

- ▶ Different CPU-scheduling algorithms have different properties.
- ► CPU utilization: keep the CPU as busy as possible (Max).
- ► Throughput: # of completed processes per time unit (Max).
- ► Turnaround time: amount of time to execute a particular process (Min).
- ► Waiting time: amount of time a process has been waiting in the ready queue (Min).
- ▶ Response time: amount of time it takes from when a request was submitted until the first response is produced (Min).



# Scheduling Algorithms



#### Scheduling Algorithms

- ► First-Come, First-Served Scheduling
- ► Shortest-Job-First Scheduling
- ► Priority Scheduling
- ► Round-Robin Scheduling



# First-Come, First-Served (FCFS) Scheduling



## FCFS Scheduling (1/2)

▶ Suppose that the processes arrive in the order:  $P_1$ ,  $P_2$ ,  $P_3$ 

Process	Burst Time
$P_1$	24
$P_2$	3
$P_3$	3

	$P_{1}$	P <sub>2</sub>	P3	
(	2	.4 2	27 3	30

- ▶ Waiting time for  $P_1 = 0$ ;  $P_2 = 24$ ;  $P_3 = 27$
- Average waiting time:  $\frac{0+24+27}{3} = 17$
- ► FCFS scheduling is non-preemptive: process keeps the CPU until it releases the CPU (either by terminating or by requesting I/O).
- ► Convoy effect: all the other processes wait for the one big process to get off the CPU.



# FCFS Scheduling (2/2)

▶ Suppose that the processes arrive in the order:  $P_2$ ,  $P_3$ ,  $P_1$ 



- ▶ Waiting time for  $P_1 = 6$ ;  $P_2 = 0$ ;  $P_3 = 3$
- Average waiting time:  $\frac{6+0+3}{3} = 3$
- ► Much better than previous case.



# Shortest-Job-First (SJF) Scheduling



# SJF Scheduling (1/2)

- ► Associate with each process the length of its next CPU burst.
- ▶ Use these lengths to schedule the process with the shortest time.
- ► SJF is optimal: gives minimum average waiting time for a given set of processes.
- ▶ The difficulty is knowing the length of the next CPU request.



## SJF Scheduling (2/2)

Burst Time
6
8
7
3

► Select the processes according to their burst time (from shorter to longer).



- ▶ Waiting time for  $P_1 = 3$ ;  $P_2 = 16$ ;  $P_3 = 9$ ,  $P_4 = 0$
- Average waiting time:  $\frac{3+16+9+0}{4} = 7$



#### Determining Length of Next CPU Burst

- ► Estimate the length, and pick process with shortest predicted next CPU burst.
- ▶ The next CPU burst
  - 1.  $t_n = \text{actual length of } n^{th} \text{ CPU burst}$
  - 2.  $\tau_{n+1} = \text{predeicted}$  value for the next CPU burst
  - 3.  $\tau_{n+1} = \alpha t_n + (1 \alpha)\tau_n$ , where  $0 \le \alpha \le 1$
- ho  $\alpha$  = 0 then  $au_{n+1} = au$
- $ightharpoonup \alpha = 1$  then  $\tau_{n+1} = t_n$
- ▶ Commonly,  $\alpha$  set to  $\frac{1}{2}$

- ▶ The SJF algorithm can be either preemptive or non-preemptive.
- ► Preemptive version called shortest-remaining-time-first



#### Example of Shortest-Remaining-Time-First

Process	Arrival Time	Burst Time
$P_1$	0	8
$P_2$	1	4
$P_3$	2	9
$P_4$	3	5

► Now we add the concepts of varying arrival times and preemption to the analysis.



• Average waiting time:  $\frac{(10-1)+(1-1)+(17-2)+(5-3)}{4} = \frac{26}{4} = 6.5$ 



# **Priority Scheduling**



## Priority Scheduling (1/2)

- ► A priority number (integer) is associated with each process.
- ▶ The CPU is allocated to the process with the highest priority.
  - Smallest integer = Highest priority
  - Preemptive and non-preemptive
- ► SJF is priority scheduling where priority is the inverse of predicted next CPU burst time.
- ▶ Problem: starvation low priority processes may never execute
- ► Solution: aging as time progresses increase the priority of the process



## Priority Scheduling (2/2)

Process	Burst Time	Priority
$P_1$	10	3
$P_2$	1	1
$P_3$	2	4
$P_4$	1	5
$P_5$	5	2

$P_2$	$P_{5}$	P <sub>1</sub>	$P_3$	$P_{4}$
0	1 (	3 1	6	18 1

• Average waiting time:  $\frac{0+1+6+16+18}{5} = 8.2$ 



# Round-Robin (RR) Scheduling



## RR Scheduling (1/2)

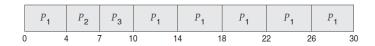
- ▶ Each process gets a small unit of CPU time (time quantum q), usually 10-100 milliseconds.
- ► After this time has elapsed, the process is preempted and added to the end of the ready queue.
- ▶ If there are *n* processes in the ready queue and the time quantum is *q*, then each process gets 1/*n* of the CPU time in chunks of at most *q* time units at once.
- ▶ No process waits more than (n-1)q time units.



# RR Scheduling (2/2)

Process	Burst Time
$P_1$	24
$P_2$	3
$P_3$	3

ightharpoonup Time quantum q=4



• Average waiting time:  $\frac{(10-4)+4+7}{3} = 5.66$ 



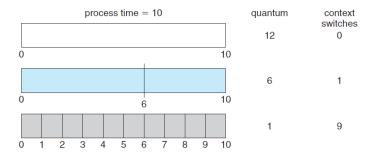
### Time Quantum and Context Switch Time (1/2)

- ▶ Timer interrupts every quantum to schedule next process.
- Performance
  - $q \text{ large} \Rightarrow \text{FIFO}$
  - $q \text{ small} \Rightarrow q \text{ must}$  be large with respect to context switch, otherwise overhead is too high.



## Time Quantum and Context Switch Time (2/2)

▶ *q* should be large compared to context switch time.









# Linux Scheduling (1/2)

- Completely Fair Scheduler (CFS)
- ▶ n users want to share a resource, e.g., CPU.
  - Solution: allocate each  $\frac{1}{n}$  of the shared resource.



- Generalized by max-min fairness.
  - Handles if a user wants less than its fair share.
  - E.g., user 1 wants no more than 20%.



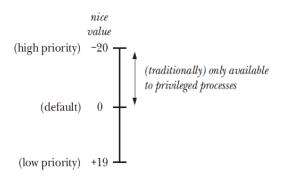
- ► Generalized by weighted max-min fairness.
  - Give weights to users according to importance.
  - E.g., user 1 gets weight 1, user 2 weight 2.





## Linux Scheduling (2/2)

▶ Quantum calculated based on nice value from -20 to +19.





#### Modifying the Nice Value

- ▶ nice() increments a process's nice value by inc and returns the newly updated value.
- ▶ Only processes owned by root may provide a negative value for inc.

```
#include <unistd.h>
int nice(int inc);
```



#### Retrieving and Modifying Priorities

► The getpriority() and setpriority() system calls allow a process to retrieve and change its own nice value or that of another process.

```
#include <sys/resource.h>
int getpriority(int which, id_t who);
int setpriority(int which, id_t who, int prio);
```



# Thread Scheduling



### Thread Scheduling (1/2)

- ▶ Distinction between user-level and kernel-level threads.
- Process-Contention Scope (PCS)
  - In many-to-one and many-to-many models.
  - Scheduling competition is within the process.
- System-Contention Scope (SCS)
  - In one-to-one model.
  - Scheduling competition among all threads in system.







### Pthread Scheduling

- ► API allows specifying either PCS or SCS during thread creation.
  - PTHREAD\_SCOPE\_PROCESS schedules threads using PCS scheduling.
  - PTHREAD\_SCOPE\_SYSTEM schedules threads using SCS scheduling.
- ▶ pthread\_attr\_setscope and pthread\_attr\_getscope set/get contention scope attribute in thread attributes object.

```
#include <pthread.h>
int pthread_attr_setscope(pthread_attr_t *attr, int scope);
int pthread_attr_getscope(const pthread_attr_t *attr, int *scope);
```



#### Pthread Scheduling API

```
int main(int argc, char *argv[]) {
  pthread_t t1, t2;
  pthread_attr_t attr;
  pthread_attr_init(&attr);
  pthread_attr_setscope(&attr, PTHREAD_SCOPE_SYSTEM);
  pthread_create(&t1, &attr, thread_func, NULL);
  pthread_create(&t2, &attr, thread_func, NULL);
  pthread_join(t1, NULL);
  pthread_join(t2, NULL);
void *thread_func(void *param) {
  /* do some work ... */
  pthread_exit(0);
```

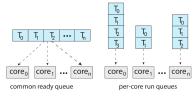


# Multi-Processor Scheduling



### Multiple-Processor Scheduling

- Asymmetric multiprocessing
  - Only one processor does all scheduling decisions, I/O processing, and other system activities.
  - The other processors execute only user code.
- Symmetric multiprocessing (SMP)
  - Each processor is self-scheduling
  - All processes in common ready queue, or each has its own private queue of ready processes.





- ▶ Processor affinity: keep a process running on the same processor.
- ► Soft affinity: the OS attempts to keep a process on a single processor, but it is possible for a process to migrate between processors.
- ► Hard affinity: allowing a process to specify a subset of processors on which it may run.





sched\_setaffinity() and sched\_getaffinity() sets/gets the CPU affinity of the process specified by pid.

```
#define _GNU_SOURCE
#include <sched.h>
int sched_setaffinity(pid_t pid, size_t len, cpu_set_t *set);
int sched_getaffinity(pid_t pid, size_t len, cpu_set_t *set);
```



### **CPU Affinity Macros**

- ► CPU\_ZERO() initializes set to be empty.
- ► CPU\_SET() adds the CPU cpu to set.
- ► CPU\_CLR() removes the CPU cpu from set.
- ► CPU\_ISSET() returns true if the CPU cpu is a member of set.

```
#define _GNU_SOURCE
#include <sched.h>

void CPU_ZERO(cpu_set_t *set);
void CPU_SET(int cpu, cpu_set_t *set);
void CPU_CLR(int cpu, cpu_set_t *set);
int CPU_ISSET(int cpu, cpu_set_t *set);
```



► The process identified by pid runs on any CPU other than the first CPU of a four-processor system.

```
cpu_set_t set;

CPU_ZERO(&set);
CPU_SET(1, &set);
CPU_SET(2, &set);
CPU_SET(3, &set);
sched_setaffinity(pid, sizeof(set), &set);
```



# Summary

# Summary

- ► CPU scheduling
- ► Scheduling criteria: cpu utilization, throughput, turnaround time, waiting time, response time
- Scheduling algorithms: FCFS, SJF, Priority, RR
- ► Thread scheduling: PCS and SCS
- ▶ Multi-processor scheduling: SMP, processor affinity



# Questions?

#### Acknowledgements

Some slides were derived from Avi Silberschatz slides.