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const int knockSensor = 0;
const int programSwitch = 2;
const int lockMotor = 3;
const int redLED = 4;
const int greenLED = 5;

const int threshold = 3;
const int rejectValue = 25;
const int averageRejectValue = 15;
const int knockFadeTime = 150;
const int lockTurnTime = 2000;

const int maximumKnocks = 20;
const int knockComplete = 1200;

int secretCode[maximumKnocks] = {50, 25, 25, 50, 100, 50, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0};
int knockReadings[maximumKnocks];
int knockSensorValue = 0;
int programButtonPressed = false;

void setup() {
  pinMode(lockMotor, OUTPUT);
  pinMode(redLED, OUTPUT);
  pinMode(greenLED, OUTPUT);
  pinMode(programSwitch, INPUT);

  Serial.begin(9600);
  Serial.println("Program start.");

  digitalWrite(greenLED, HIGH);
}

void loop() {
  knockSensorValue = analogRead(knockSensor);

  if (digitalRead(programSwitch)==HIGH){
    programButtonPressed = true;
    digitalWrite(redLED, HIGH);
  } else {
    programButtonPressed = false;
    digitalWrite(redLED, LOW);
  }

  if (knockSensorValue >=threshold){
    listenToSecretKnock();
  }
}

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    }
}
void listenToSecretKnock(){
    Serial.println("knock starting");

    int i = 0;
    for (i=0;i<maximumKnocks;i++){
        knockReadings[i]=0;
    }
    int currentKnockNumber=0;
    int startTime=millis();
    int now=millis();

    digitalWrite(greenLED, LOW);
    if (programButtonPressed==true){
        digitalWrite(redLED, LOW);
    }
    delay(knockFadeTime);
    digitalWrite(greenLED, HIGH);
    if (programButtonPressed==true){
        digitalWrite(redLED, HIGH);
    }
    do {
        knockSensorValue = analogRead(knockSensor);
        if (knockSensorValue >=threshold){
            Serial.println("knock.");
            now=millis();
            knockReadings[currentKnockNumber] = now-startTime;
            currentKnockNumber ++;
            startTime=now;
            digitalWrite(greenLED, LOW);
            if (programButtonPressed==true){
                digitalWrite(redLED, LOW);
            }
            delay(knockFadeTime);
            digitalWrite(greenLED, HIGH);
            if (programButtonPressed==true){
                digitalWrite(redLED, HIGH);
            }
        }
    }
    now=millis();
} while ((now-startTime < knockComplete) && (currentKnockNumber < maximumKnocks));
if (programButtonPressed==false){
    if (validateKnock() == true){

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    triggerDoorUnlock();
} else {
    Serial.println("Secret knock failed.");
    digitalWrite(greenLED, LOW);
    for (i=0;i<4;i++){
        digitalWrite(redLED, HIGH);
        delay(100);
        digitalWrite(redLED, LOW);
        delay(100);
    }
    digitalWrite(greenLED, HIGH);
}
} else {
    validateKnock();
    Serial.println("New lock stored.");
    digitalWrite(redLED, LOW);
    digitalWrite(greenLED, HIGH);
    for (i=0;i<3;i++){
        delay(100);
        digitalWrite(redLED, HIGH);
        digitalWrite(greenLED, LOW);
        delay(100);
        digitalWrite(redLED, LOW);
        digitalWrite(greenLED, HIGH);
    }
}
}
}

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void triggerDoorUnlock(){
    Serial.println("Door unlocked!");
    int i=0;

    digitalWrite(lockMotor, HIGH);
    digitalWrite(greenLED, HIGH);

    delay (lockTurnTime);

    digitalWrite(lockMotor, LOW);

    for (i=0; i < 5; i++){
        digitalWrite(greenLED, LOW);
        delay(100);
        digitalWrite(greenLED, HIGH);
    }
}

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    delay(100);
}
}
boolean validateKnock(){
    int i=0;

    int currentKnockCount = 0;
    int secretKnockCount = 0;
    int maxKnockInterval = 0;

    for (i=0;i<maximumKnocks;i++){
        if (knockReadings[i] > 0){
            currentKnockCount++;
        }
        if (secretCode[i] > 0){
            secretKnockCount++;
        }

        if (knockReadings[i] > maxKnockInterval){
            maxKnockInterval = knockReadings[i];
        }
    }

    if (programButtonPressed==true){
        for (i=0;i<maximumKnocks;i++){
            secretCode[i]= map(knockReadings[i],0, maxKnockInterval, 0, 100);
        }
        digitalWrite(greenLED, LOW);
        digitalWrite(redLED, LOW);
        delay(1000);
        digitalWrite(greenLED, HIGH);
        digitalWrite(redLED, HIGH);
        delay(50);
        for (i = 0; i < maximumKnocks ; i++){
            digitalWrite(greenLED, LOW);
            digitalWrite(redLED, LOW);
            if (secretCode[i] > 0){
                delay( map(secretCode[i],0, 100, 0, maxKnockInterval));
                digitalWrite(greenLED, HIGH);
                digitalWrite(redLED, HIGH);
            }
        }
        delay(50);
    }
    return false;
}

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}

if (currentKnockCount != secretKnockCount){
    return false;
}
int totalTimeDifferences=0;
int timeDiff=0;
for (i=0;i<maximumKnocks;i++){
    knockReadings[i]= map(knockReadings[i],0, maxKnockInterval, 0, 100);
    timeDiff = abs(knockReadings[i]-secretCode[i]);
    if (timeDiff > rejectValue){
        return false;
    }
    totalTimeDifferences += timeDiff;
}
if (totalTimeDifferences/secretKnockCount>averageRejectValue){
    return false;
}

return true;
}

```