

§ 10.51~52.

线性等式约束的凸优化问题

$$\begin{cases} \min f(x) \\ \text{s.t. } Ax=b \end{cases} \quad \text{KKT条件: } \begin{cases} Ax^*=b \\ \nabla f(x^*) + A^T v^* = 0 \end{cases}$$

$$\begin{cases} \min_d f(x^k+d) \\ \text{s.t. } A(x^k+d)=b \end{cases} \sim \begin{cases} f(x^k) + \nabla f(x^k)^T d + \frac{1}{2} d^T \nabla^2 f(x^k) d. \\ Ad=0 \end{cases}$$

$$d^k = \begin{bmatrix} \nabla f(x^k) & A^T \\ A & 0 \end{bmatrix} \begin{bmatrix} d^k \\ v^* \end{bmatrix} = \begin{bmatrix} -\nabla f(x^k) \\ 0 \end{bmatrix}$$

$$\alpha^k = \arg \min_{\alpha \geq 0} f(x^k + \alpha d^k)$$

$$x^{k+1} = x^k + \alpha^k d^k.$$

拉格朗日法.

$$x^{k+1} = x^k - \alpha^k (\nabla f(x^k) + A^T v^k)$$

$$v^{k+1} = v^k + \alpha^k (Ax^k - b)$$

增广拉格朗日法.

$$L_c(x, v) = f(x) + v^T (Ax - b) + \frac{c}{2} \|Ax - b\|_2^2$$

$$\begin{cases} \min f(x) + \frac{c}{2} \|Ax - b\|_2^2 \\ \text{s.t. } Ax=b \end{cases}$$

$$\text{KKT条件: } \nabla_x L(x^*, v^*) = 0. \quad ①$$

$$\Rightarrow \nabla_x \{f(x^*) + (v^*)^T (Ax^* - b)\} = 0.$$

$$\nabla_x L_c(x^*, v^*) = 0. \quad ②$$

$$\Rightarrow \nabla_x \{f(x^*) + (v^*)^T (Ax^* - b)\} + c A^T (Ax^* - b) = 0.$$

①②的最优解相同.

$$x^{k+1} = \underline{x}^k - \alpha^k \nabla L_c(\underline{x}^k, v^k)$$

$$v^{k+1} = v^k + \underline{\alpha}^k (A \underline{x}^k - b)$$

$$\Rightarrow x^{k+1} = \arg \min_x L_c(x, v^k).$$

$$\Rightarrow v^{k+1} = v^k + c (Ax^{k+1} - b).$$

并不需要十分精确的解.

Augmented Lagrangian Method.

性质 1): 若 $v = v^*$, 则 $\forall c > 0, x^* = \arg \min_x L_c(x, v^*)$.

2) 若 $c \rightarrow +\infty$, 则 $\forall v, x^* = \arg \min_x L_c(x, v)$.

$$\text{例: } \begin{cases} \min \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 \\ \text{s.t. } x_1=1 \end{cases} \quad x^* = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\Rightarrow L(x, v) = \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 + v(x_1-1).$$

$$\begin{cases} x_1=1 \\ x_1+v=0. \\ x_2=0. \end{cases} \quad \begin{cases} x_1^*=1 \\ v^*=-1 \\ x_2^*=0. \end{cases}$$

$$\Rightarrow L_C(x, v) = \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 + v(x_1-1) + \frac{C}{2}(x_1-1)^2$$

$$\operatorname{argmin}_x L_C(x, v^*) = \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 - (x_1-1) + \frac{C}{2}(x_1-1)^2$$

$$\begin{cases} \frac{\partial L_C(x, v^*)}{\partial x_1} = x_1 - 1 + C(x_1-1) = 0. \Leftrightarrow x_1=1 & \text{性质(1)} \\ \frac{\partial L_C(x, v^*)}{\partial x_2} = x_2 = 0. \end{cases}$$

$$\begin{cases} x_1 + v + C(x_1-1) = 0 \Leftrightarrow x_1 = \frac{C-v}{C+1} & \text{性质(2)} \\ x_2 = 0 \end{cases}$$

$$L_C(x, v) \Leftarrow \dots$$

$$1) x^{k+1} = \operatorname{argmin}_x L_C(x, v^k) \Leftrightarrow x^{k+1} = \begin{pmatrix} \frac{C-v^k}{C+1} \\ 0 \end{pmatrix}$$

$$\begin{aligned} 2) v^{k+1} &= v^k + C(x^{k+1} - 1) \\ &= v^k + C\left(\frac{C-v^k}{C+1} - 1\right) = v^k - \frac{C}{C+1}(v^k + 1) \end{aligned}$$

$$\begin{aligned} v^{k+1} - v^* &= v^{k+1} + 1 \\ &= (v^k + 1) - \frac{C}{C+1}(v^k + 1) \\ &= (v^k + 1) \frac{1}{C+1} \\ &= (v^k - v^*) \frac{1}{C+1} \quad (\text{线性收敛}). \end{aligned}$$

$$\text{例: } \min_x f(x) + g(x) \Leftrightarrow \min_{x, z} f(x) + g(z) \\ \text{s.t. } x=z.$$

$$\Rightarrow L_C(x, z, v) = f(x) + g(z) + v^T(x-z) + \frac{C}{2}\|x-z\|_2^2$$

$$1) \{x^{k+1}, z^{k+1}\} = \operatorname{argmin}_{x, z} f(x) + g(z) + (v^k)^T(x-z) + \frac{C}{2}\|x-z\|_2^2 \quad \text{坐标轮换法.}$$

$$2) v^{k+1} = v^k + C(x^{k+1} - z^{k+1}).$$

$$\begin{aligned}
 & \text{a). } x^{k+1|t} = \arg \min_x f(x) + \frac{c}{2} \|x - z^{k|t}\|_2^2 + \frac{v^k}{c} \|z\|_2^2 \\
 & \text{b). } z^{k+1|t+1} = \arg \min_z g(z) + \frac{c}{2} \|z - x^{k+1|t+1} - \frac{v^k}{c}\|_2^2 \\
 & \text{(2) } v^{k+1} = v^k + c(x^{k+1} - z^{k+1}).
 \end{aligned}$$

交替方向法.

$$\begin{aligned}
 \text{例} \quad \min \sum_{i=1}^n f_i(x) & \Leftrightarrow \min \sum_{i=1}^n f_i(x_i) \\
 \text{s.t. } x_i &= z, \quad i=1, 2, \dots, n
 \end{aligned}$$

$$L_c = \sum_{i=1}^n f_i(x_i) + \sum_{i=1}^n v_i^T (x_i - z) + \frac{c}{2} \sum_{i=1}^n \|x_i - z\|_2^2$$

$$(1) : x_i^{k+1} = \arg \min_{\{x_i\}} \sum_{i=1}^n f_i(x_i) + \frac{c}{2} \sum_{i=1}^n \|x_i - z^k + \frac{v_i^k}{c}\|_2^2$$

$$\Leftrightarrow x_i^{k+1} = \arg \min_{x_i} f_i(x_i) + \frac{c}{2} \|x_i - z^k + \frac{v_i^k}{c}\|_2^2$$

$$(2) \quad z^{k+1} = \arg \min_z \frac{c}{2} \sum_{i=1}^n \|z - x_i^{k+1} - \frac{v_i}{c}\|_2^2.$$

$$\Leftrightarrow z^{k+1} = \frac{1}{n} \sum_{i=1}^n (x_i^{k+1} + \frac{v_i}{c})$$

$$(3) \quad v_i^{k+1} = v_i^k + c(x_i^{k+1} - z^{k+1}), \quad \forall i$$

分布式计算

