Assignment-1

Internet of Things

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Objective:

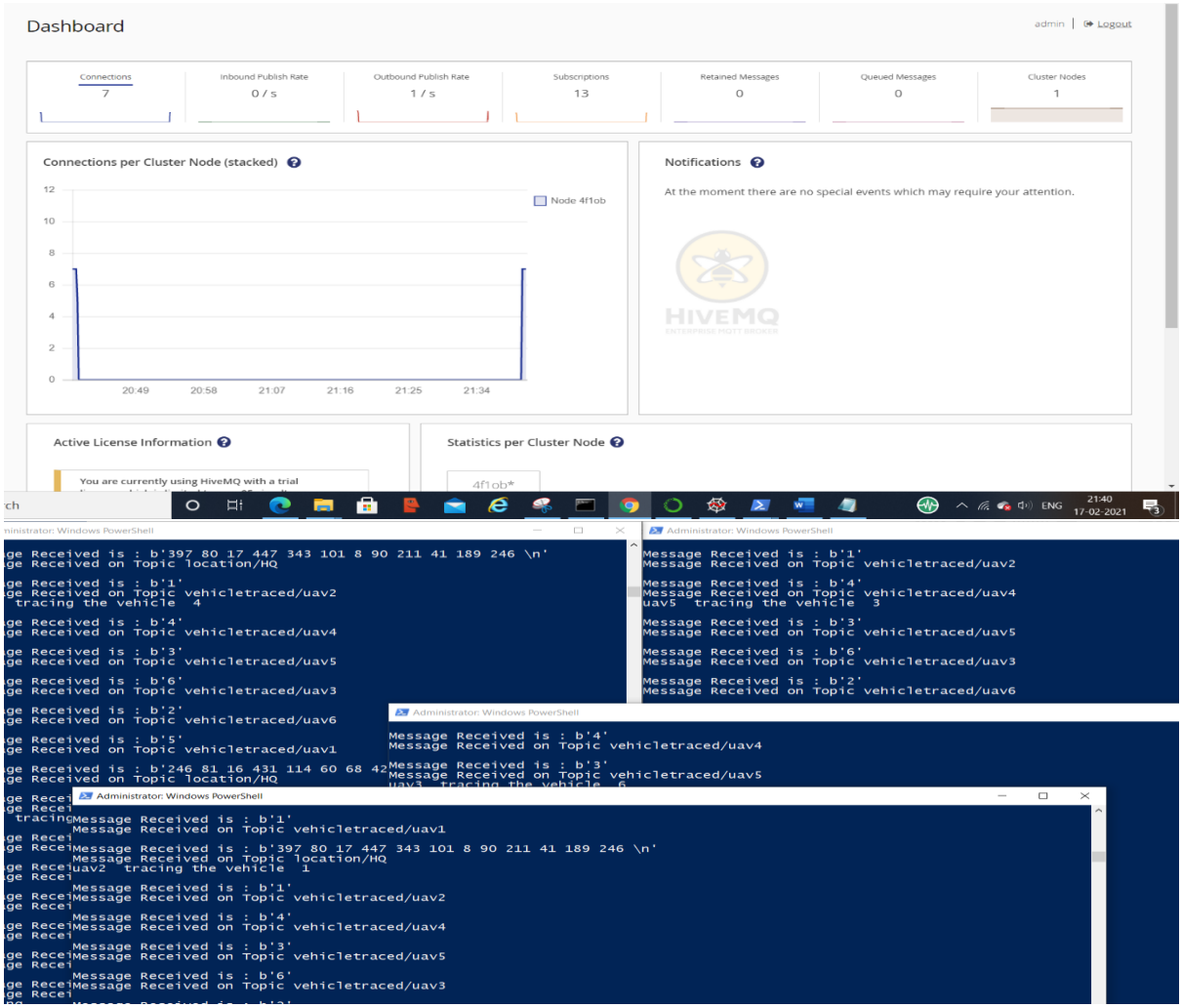
Our Objective is to keep track of the highly crucial vehicles locations continuously with the help of UAVs using an IoT broker, HiveMq. We have 6 vehicles and 6 UAVs. At any point of time, no two UAVs should track the same vehicle.

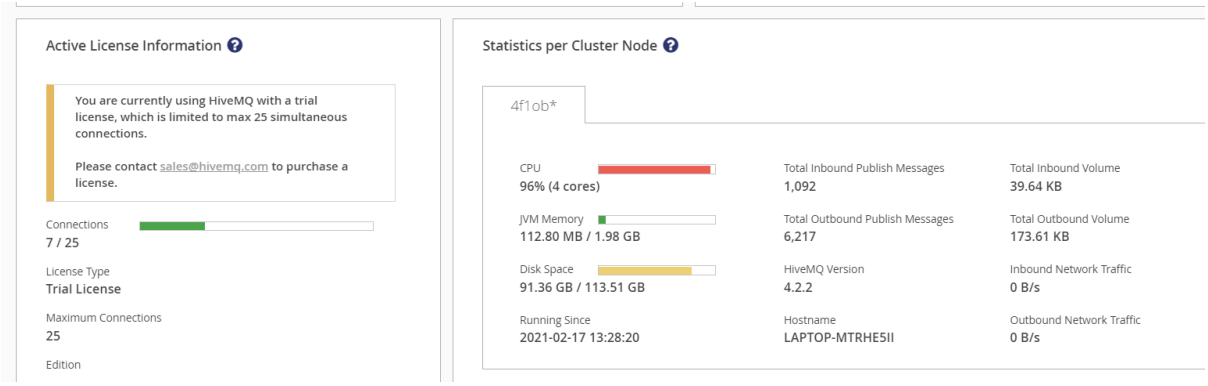
Procedure:

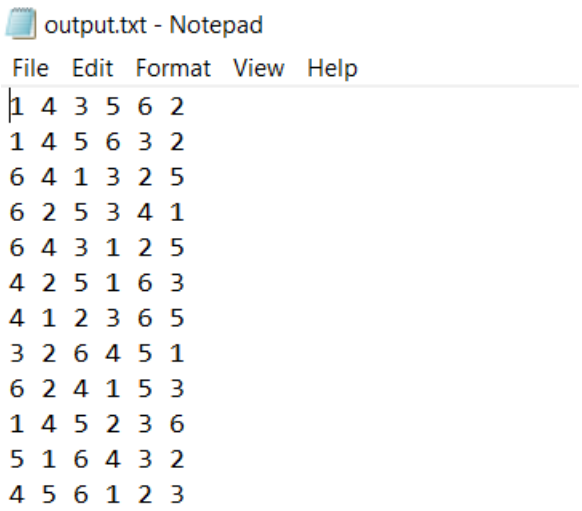
- We have 3 kinds of devices here.
- 1. HQ which has the information of the all-vehicle locations for each time stamps.
- 2. UAV which must find out its nearest vehicle and report back to HQ saying that it is tracking this vehicle.
- 3. IoT broker (here MQTT) which connects both.
- Process that has been followed is-
- At HQ.py
- Read the vehicle_location.txt and published the vehicle locations with respect to the time stamps.
- At UAV.py
- Received those messages and read its own location at that time stamp from uav(id).txt file.
- Calculated the distances between uav and all vehicles at that timestamp and stored.
- Calculated minimum distanced vehicle (Vmin) for that uav and Deployed conflict resolution algorithm.
- Checked whether any other uav is also tracing the same vehicle.
- If yes, then find out the next minimum distanced vehicle.
- Finally, It publishes the traced vehicle details.
- At HQ.py
- HQ already subscribed to all uav clients' messages, HQ receives them and write them to an output file called "output.txt".

- **Conflict Resolution Algorithm: -**
- Each UAV subscribes to the other UAVs messages also.
- For each timestamp-
- Whenever ‘present UAV’ receives any message from other UAVs about the vehicle number that they are tracing, ‘present UAV’ stores that vehicle number into a list. (here completed_veh_ids)
- ‘Present UAV’, just before publishing the minimum distanced vehicle (Vmin), it checks the above list whether Vmin is present in it or not.
- If yes, 'present UAV’ goes to search next minimum distanced vehicle.
- Now above 2 steps repeat again to check for this next minimum vehicle.
- Like this loop will run till ‘present UAV’ gets the possible minimum distanced vehicle which is not traced by other UAVs.
- After publishing the vehicle number that ‘present UAV’ is tracing, it will empty the completed_veh_ids so that it can store for the next timestamp.
- In simple words, it is like listen before talking, checking other UAVs status before ‘present UAV’ publishes its own status.

Output:


Dashboard
admin | Logout
Connections
7
Inbound Publish Rate
0 / s
Outbound Publish Rate
1 / s
Subscriptions
13
Retained Messages
0
Queued Messages
0
Cluster Nodes
1
Connections per Cluster Node (stacked)
Node 4f1ob
12
10
8
6
4
2
0
20:49
20:58
21:07
21:16
21:25
21:34
Notifications
At the moment there are no special events which may require your attention.
HIVEMQ
Active License Information
You are currently using HiveMQ with a trial
Statistics per Cluster Node
4f1ob*
ENG
21:40
17-02-2021
Administrator: Windows PowerShell
ge Received is : b'397 80 17 447 343 101 8 90 211 41 189 246 \n'
ge Received on Topic location/HQ
ge Received is : b'1'
ge Received on Topic vehicletraced/uav2
tracing the vehicle 4
ge Received is : b'4'
ge Received on Topic vehicletraced/uav4
ge Received is : b'3'
ge Received on Topic vehicletraced/uav5
ge Received is : b'6'
ge Received on Topic vehicletraced/uav3
ge Received is : b'2'
ge Received on Topic vehicletraced/uav6
ge Received is : b'5'
ge Received on Topic vehicletraced/uav1
ge Received is : b'246 81 16 431 114 60 68 42
ge Received on Topic location/HQ
Message Received is : b'1'
Message Received on Topic vehicletraced/uav2
Message Received is : b'4'
Message Received on Topic vehicletraced/uav4
uav5 tracing the vehicle 3
Message Received is : b'3'
Message Received on Topic vehicletraced/uav5
Message Received is : b'6'
Message Received on Topic vehicletraced/uav3
Message Received is : b'2'
Message Received on Topic vehicletraced/uav6
Message Received is : b'4'
Message Received on Topic vehicletraced/uav4
Message Received is : b'3'
Message Received on Topic vehicletraced/uav5
Message Received is : b'1'
Message Received on Topic vehicletraced/uav1
Message Received is : b'397 80 17 447 343 101 8 90 211 41 189 246 \n'
Message Received on Topic location/HQ
uav2 tracing the vehicle 1
Message Received is : b'1'
Message Received on Topic vehicletraced/uav2
Message Received is : b'4'
Message Received on Topic vehicletraced/uav4
Message Received is : b'3'
Message Received on Topic vehicletraced/uav5
Message Received is : b'6'
Message Received on Topic vehicletraced/uav3





Conclusion:

We have successfully assigned 6 UAVs to trace 6 vehicles at every timestamp.