



**Ahmedabad
University**

Report 5

CSE541 Computer Vision Section-1

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Comparison of RetinaNet with Faster-RCNN:

>>> RetinaNet has low accuracy in terms of detecting smaller objects, occluded objects, and truncated objects. So we tried to implement Faster-RCNN which has more accuracy than RetinaNet ([Author links open overlay panel Onur Can Koyun a et al., "Focus-and-detect: A small object detection framework for aerial images," Signal Processing: Image Communication](#)).

Results:

RetinaNet:



Image 1



Image 2

Faster-RCNN:

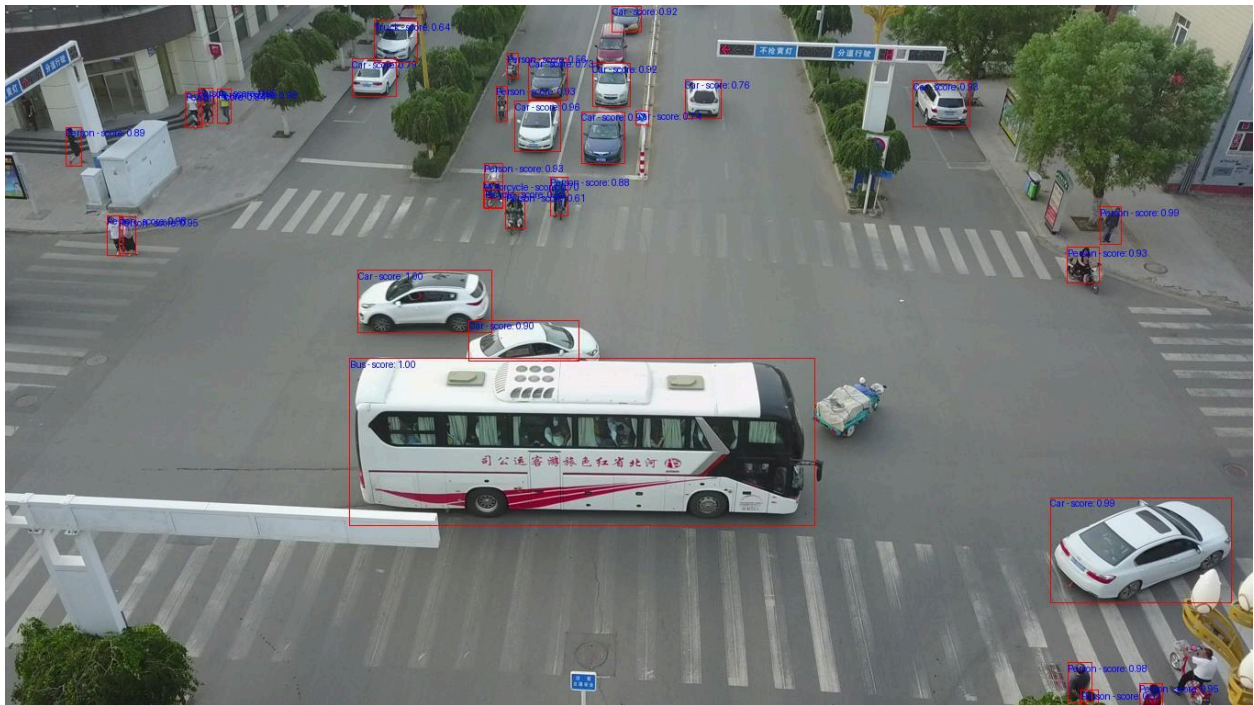


Image 3



Image 4

Accuracy:

```

=====RetinaNet=====
||                               ||
|| Average Accuracy  = : 43.0165 ||
||                               ||

=====Faster RCNN=====
||                               ||
|| Average Accuracy  = : 74.6716 ||

```

Conclusion and Summary:

>>> From the results that we got, we can conclude that Faster-RCNN is more effective than RetineNet in terms of detecting small objects. Faster-RCNN is even more efficient

in detecting occluded objects, too. By comparing image 1 and image 3 we can see the difference that Faster-RCNN effectively detects the person riding a bike and can also differentiate the person and bike. Moreover, Faster-RCNN is 74.67% accurate on the Visdrone-2019 dataset, while RetinaNet is 43.01% accurate. With this, we can conclude that faster-RCNN is better than RetinaNet for detecting small objects.

References:

Wikimedia Foundation. (2024, January 2). Small object detection. Wikipedia.
https://en.wikipedia.org/wiki/Small_object_detection

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Tsung-Yi Lin, Priya Goyal, Ross Girshick, Kaiming He, and Piotr Dollár. Focal loss for dense object detection. In Proceedings of the IEEE international conference on computer vision, pages 2980–2988, 2017.

Ren, S., He, K., Girshick, R., & Sun, J. (2016). Faster R-CNN: Towards real-time object detection with region proposal networks. Retrieved from <https://arxiv.org/abs/1506.01497>