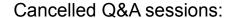


## Tutorial 3: Index Structures

Implementation of Databases (DBS2) Arik Ermshaus

# **Tutorial appointments**

Week	Topic
16.10 - 20.10	-
23.10 - 27.10	Organisation, Exercise Sheet 1
30.10 - 03.11	Q&A
06.11 - 10.11	Q&A
13.11 - 17.11	Exercise Sheet 2
20.11 - 24.11	Q&A
27.11 - 01.12	Q&A
04.12 - 08.12	Exercise Sheet 3
11.12 - 15.12	Q&A
18.12 - 22.12	Q&A
25.12 - 29.12	-
01.01 - 05.01	-
08.01 - 12.01	Exercise Sheet 4
15.01 - 19.01	Q&A
22.01 - 26.01	Q&A
29.01 - 02.02	Exercise Sheet 5
05.02 - 09.02	Q&A
12.02 - 16.02	Exam preparation



- 14.12.2023
- 19.12.2023

Disclaimer: Timetable is provisional, and will (probably) change!

### **Table of Contents**

Solutions of Exercise Sheet 2

• Exercise Sheet 3

• B+ Trees

# Task 1: Fixed and Variable-length Records

- DB stores collection of books
- Attributes: 5 required (64 bytes each), 15 optional (16 bytes each)
- Optional attributes are present with probability p

(a) Calculate size of "fixed-length" records in bytes. *Hint:* Empty optional fields are filled with NULL values.

• 
$$r_{fixed} = 5 \cdot 2^6 B + 15 \cdot 2^4 B = 560 B$$

# Task 1: Fixed and Variable-length Records

- DB stores collection of books
- Attributes: 5 required (64 bytes each), 15 optional (16 bytes each)
- Optional attributes are present with probability p

(b) Calculate expected size of "variable-length" records in bytes. End of attribute is terminated with tag of 2 bytes.

• 
$$r_{variable} = 5 \cdot 2^6 B + 15 \cdot p \cdot 2^4 B + 20 \cdot 2B$$

• 
$$r_{variable} = 360B + p \cdot 240B$$

# Task 1: Fixed and Variable-length Records

- DB stores collection of books
- Attributes: 5 required (64 bytes each), 15 optional (16 bytes each)
- Optional attributes are present with probability p

(c) For which range of probabilities *p* should one favour fixed-length records?

• 
$$r_{fest} < r_{variable} \leftrightarrow 560B < 360B + p \cdot 240B$$
  
•  $\frac{200B}{240B}$ 

- . For probabilities  $p > \frac{5}{6}$ , one should favour fixed-length records
- Expected to be smaller than variable-sized ones

## Task 2: Storing Relations in Blocks

- DB stores 2 relations; authors and books, associated by foreign key
- 5k authors (512 bytes each), 20k books (128 bytes each)
- Blocks: 4096 bytes, 64 bytes reserved for header information

(a) How many blocks are required, if authors and books are stored separately?

$$b_{authors} = \frac{5000}{\left[\frac{4096B - 64B}{512B}\right]} = \frac{5000}{7} \approx 715$$

$$b_{books} = \frac{20000}{\left|\frac{4096B - 64B}{128B}\right|} = \frac{20000}{31} \approx 646$$

• In total, one needs  $b_{authors} + b_{books} = 715 + 646 = 1361$  blocks

# Task 2: Storing Relations in Blocks

- DB stores 2 relations; authors and books, associated by foreign key
- 5k authors (512 bytes each), 20k books (128 bytes each)
- Blocks: 4096 bytes, 64 bytes reserved for header information

(b) How many blocks are required, if authors are stored with their books? *Hint:* Books are distributed equally over authors.

$$b_{all} = \frac{5000}{\left\lfloor \frac{4096B - 64B}{512B + 4 \cdot 128B} \right\rfloor} = \frac{5000}{3} \approx 1667$$

• In total, one needs  $b_{all}=1667\ \mathrm{blocks}$ 

## Task 2: Storing Relations in Blocks

- DB stores 2 relations; authors and books, associated by foreign key
- 5k authors (512 bytes each), 20k books (128 bytes each)
- Blocks: 4096 bytes, 64 bytes reserved for header information

- (c) Which scenario (subtask a or b) is preferable, if query outputs entire author relation? Justify.
- Scenario (a) is preferable, because DB needs to read 715 instead of 1667 blocks

## Task 3: Buffer Manager

Complete the provided buffer manager data structure with LRUn

replacement strategy.

```
• • •
std::shared ptr<Block> BufferManager::fix block(std::string const& block id)
   auto it = cache.find(block_id);
   if (it != cache.end()) {
       it->second.reference count++;
       return it->second.block;
   if (cache.size() >= n_blocks && unfixed_blocks.empty()) {
       throw std::runtime_error("Cannot fix block. Cache is already full.");
   if (cache.size() >= n_blocks) {
       std::string block_id_to_evict = unfixed_blocks.front();
       unfixed_blocks.pop_front();
       std::shared_ptr<Block> block_to_evict = cache[block_id_to_evict].block;
       if (block_to_evict->is_dirty()) {
       cache.erase(block_id_to_evict);
   std::shared_ptr<Block> block = std::make_shared<Block>(block_id);
   cache[block_id] = {block, 1};
    return block;
```

```
bool Block::write_data()
{
    // open file handle
    std::ofstream file(BLOCK_DIR + get_block_id(), std::ios::binary | std::ios::out);
    if (!file.is_open())
        return false;

    // write data
    char* buffer = static_cast<char*>(data.get());
    file.write(buffer, BLOCK_SIZE);

    // close file handle and reset dirty flag
    file.close();
    dirty = false;

    return true;
}
```

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Solutions of Exercise Sheet 2

Exercise Sheet 3

• B+ Trees

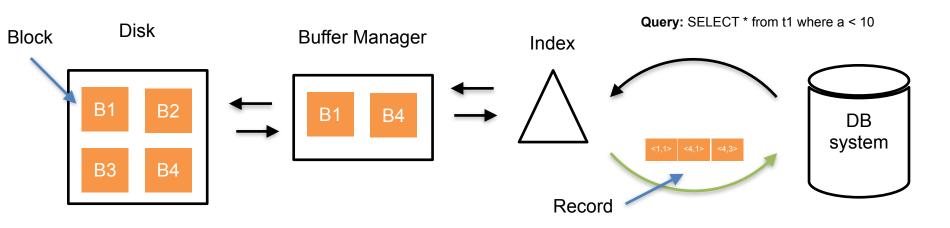
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Solutions of Exercise Sheet 2

• Exercise Sheet 3

B+ Trees

## Recap: From Attributes to Record IDs

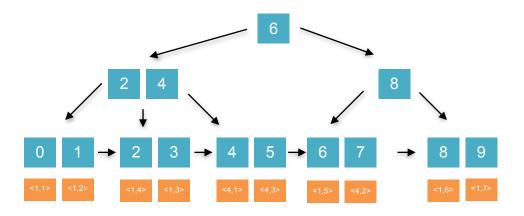


**Question**: How do you retrieve the relevant tuples?

- Problem: Queries ask for tuples based on data model; not record IDs
- Task: Retrieve all relevant tuples based on attributes
- Typical solutions: Scanning, hash files, index structures
- Challenges: selectivity of searches, IO access overhead, keeping data structures updated, degeneration

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## Recap: B+ Tree

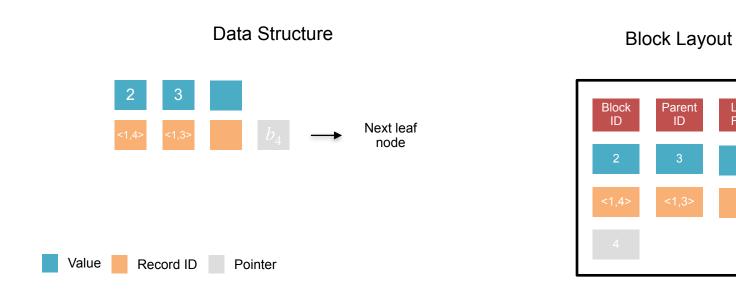


- *m*-ary tree structure with (typically) large number of children (per node)
- Structure: Root, internal nodes and leaves
  - Internal nodes: Signposts to leaf nodes
  - Leaves: (attribute, tuple id) pairs
- Block-oriented nodes with high fanout
- All CRUD operations in  $\mathcal{O}(\log_k b)$  IO accesses
  - with k values per node and b blocks in total

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## Example: Leaf nodes

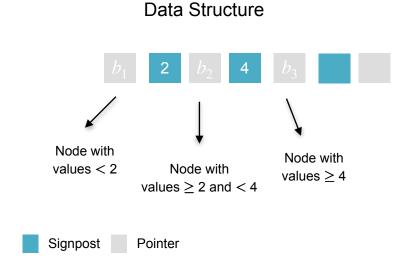


- . Number of values / record IDs:  $\lceil \frac{k}{2} \rceil$  to k (e.g. k=3)
- 1 pointer that links the subsequent leaf
- Values are ordered

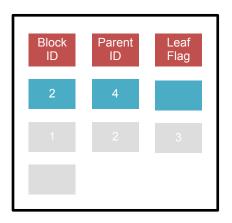
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Leaf Flag

## Example: Internal nodes



**Block Layout** 

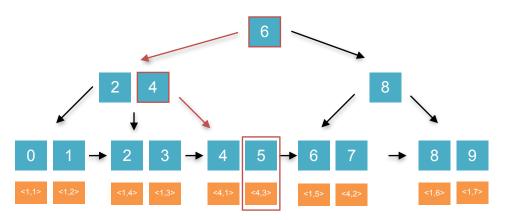


- . Number of values:  $\lfloor \frac{k}{2} \rfloor$  to k (e.g. k=3)
- . Number of pointers:  $\lfloor \frac{k}{2} \rfloor + 1$  to k + 1 (e.g. k=3)
- · Values are ordered, pointers link to respective subtrees

**Tutorial 3: Index Structures** 

## **Example: Search**

#### Search for tuple where attribute = 5

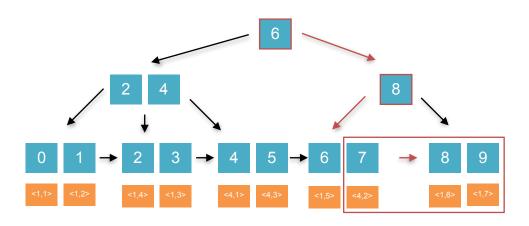


- 1. Find correct leaf node for search attribute v
  - Starting at the root node ...
  - Traverse to pointer where v < signpost</li>
  - ... or traverse to last pointer where  $v \ge \text{signpost}$
  - Repeat with new node until leaf is found
- 2. Search *v* in leaf node, return tuple ID
  - Duplicates: Traverse leaf node(s) to the right until new value
  - · Ranges: Search smallest value, traverse leaf node(s) right to largest value

Tutorial 3: Index Structures

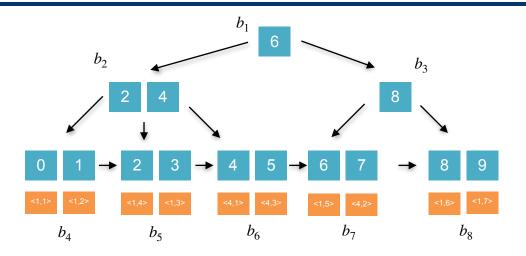
## Example: Range Search

#### Search for tuple where attribute > 6



- 1. Find correct leaf node for search attribute v
  - Starting at the root node ...
  - Traverse to pointer where v < signpost</li>
  - ... or traverse to last pointer where  $v \ge \text{signpost}$
  - Repeat with new node until leaf is found
- 2. Search *v* in leaf node, return tuple ID
  - Duplicates: Traverse leaf node(s) to the right until new value
  - · Ranges: Search smallest value, traverse leaf node(s) right to largest value

#### Task 1: B+ Tree Search



 Question: Assume a DB system can permanently fix 3 of the 8 index blocks. Which ones would be optimal to reduce IO access?

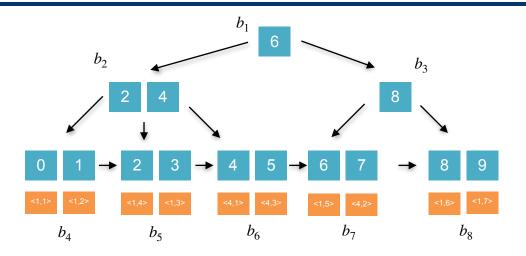
(A)  $b_1, b_2, b_4$ 

(B)  $b_4, b_5, b_6$ 

(C)  $b_1, b_2, b_3$ 

(D)  $b_1, b_3, b_8$ 

#### Task 1: B+ Tree Search

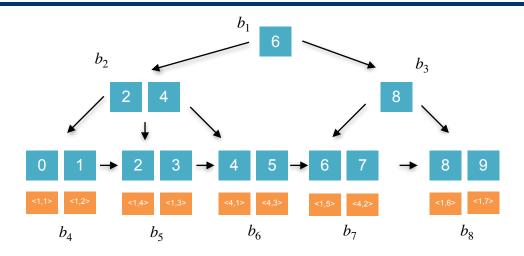


 Question: Assume a DB system can permanently fix 3 of the 8 index blocks. Which ones would be optimal to reduce IO access?



Internal nodes are accessed more frequently than leaves

### Task 2: B+ Tree Search

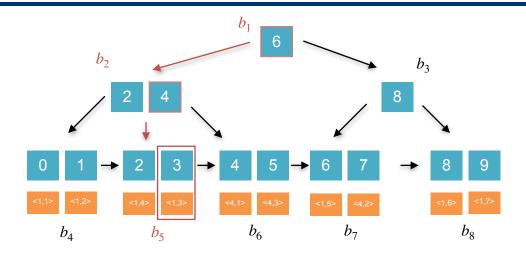


 Question: How many index blocks must be accessed to search for the attribute 3?

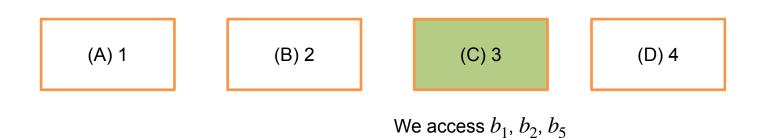
(A) 1 (B) 2 (C) 3 (D) 4

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### Task 2: B+ Tree Search

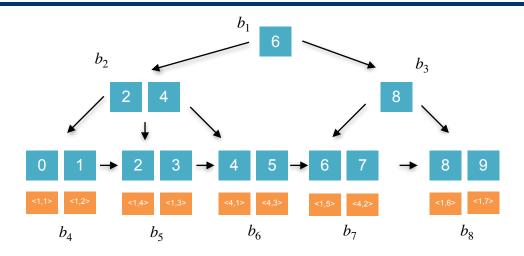


 Question: How many index blocks must be accessed to search for the attribute 3?



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### Task 3: B+ Tree Search



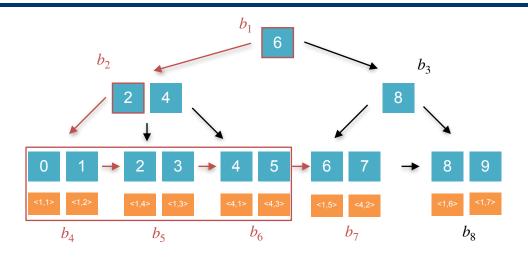
 Question: How many index blocks must be accessed to search for the attributes < 6?</li>

(A) 7 (B) 6 (C) 5 (D) 3

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### Task 3: B+ Tree Search



 Question: How many index blocks must be accessed to search for the attributes < 6?</li>



We access  $b_1$ ,  $b_2$ ,  $b_4$ ,  $b_5$ ,  $b_6$ ,  $b_7$ 



- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor \text{values}$
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5

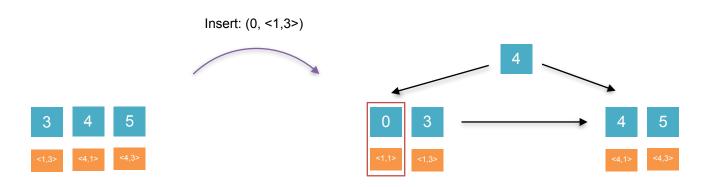


- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
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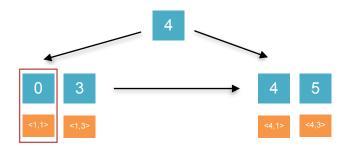


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- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5

## **Example: Leaf Splitting**

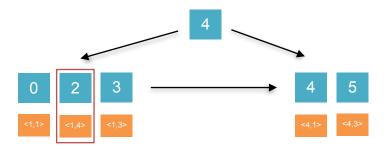


- 1. Insert  $(v, t_{id})$  at correct position and split node in two halves
  - . Original leaf node has  $\lceil \frac{k+1}{2} \rceil$  and new one has  $\lfloor \frac{k+1}{2} \rfloor$  values (e.g. k=3)
- 2. Copy left-most value of new node to parent, adjust pointers
- 3. Set new node's parent ID accordingly



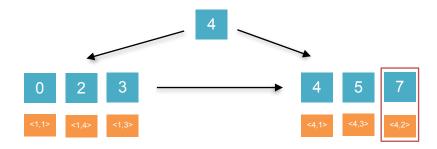
Insert: (0, <1,3>); Steps: 1,3,4

- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor \text{values}$
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5



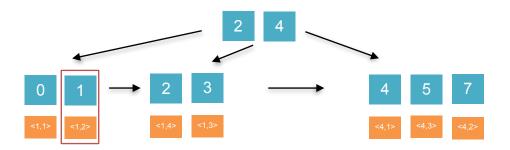
Insert: (2, <1,4>); Steps: 1,2

- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor$  values
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5



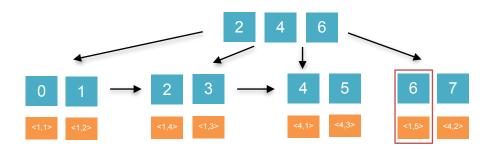
Insert: (7, <4,2>); Steps: 1,2

- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor$  values
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5



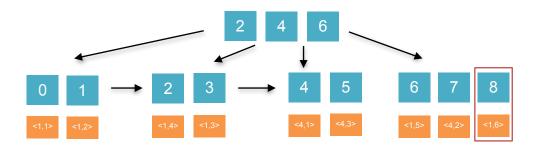
Insert: (1, <1,2>); Steps: 1,3,4

- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor$  values
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5



Insert: (6, <1,5>); Steps: 1,3,4

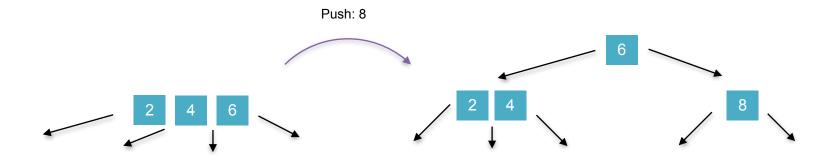
- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor$  values
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5



Insert: (8, <1,6>); Steps: 1,2

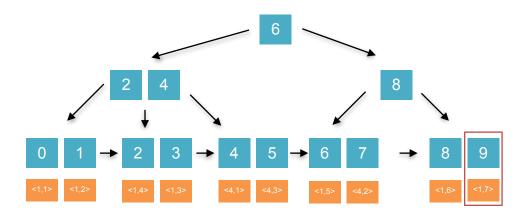
- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor$  values
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5

# **Example: Internal Node Splitting**



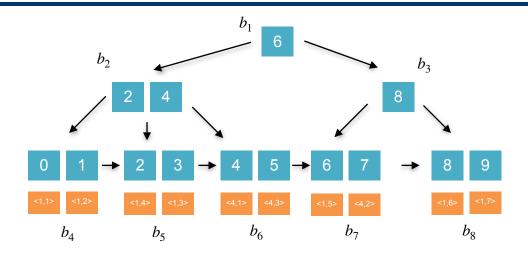
- 1. Insert *v* at correct position and split node in two halves
  - Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor$  values (e.g. k=3)
- 2. Push left-most value of new node to parent, adjust pointers
- 3. Update parent IDs accordingly

Tutorial 3: Index Structures



Insert: (9, <1,7>); Steps: 1,3,4,3,4

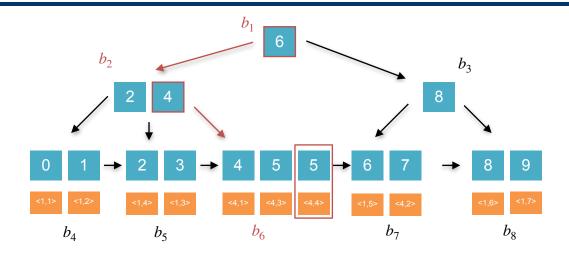
- 1. Search correct leaf node to insert attribute tuple ID pair  $(v, t_{id})$
- 2. If leaf is not full, insert  $(v, t_{id})$  and stop
- 3. Otherwise, insert  $(v, t_{id})$  and split node into two nodes
  - . Original internal node has  $\lceil \frac{k}{2} \rceil$  and new one has  $\lfloor \frac{k}{2} \rfloor$  values
- 4. Copy/Push left-most value of new node to parent, adjust pointers
- 5. Repeat until parent found that needs no split
  - If root splits, create new root as parent and execute step 4 and 5



• Question: In which block will the entry (5, <4,4>) be inserted?

(A)  $b_2$  (B)  $b_3$  (C)  $b_5$  (D)  $b_6$ 

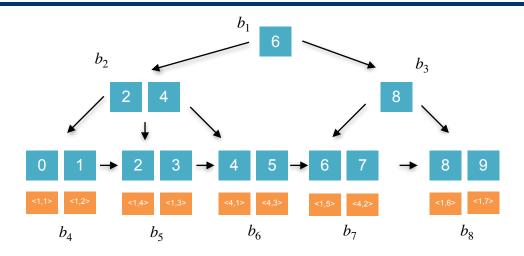
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Question: In which block will the entry (5, <4,4>) be inserted?

(A)  $b_2$  (B)  $b_3$  (C)  $b_5$  (D)  $b_6$ 

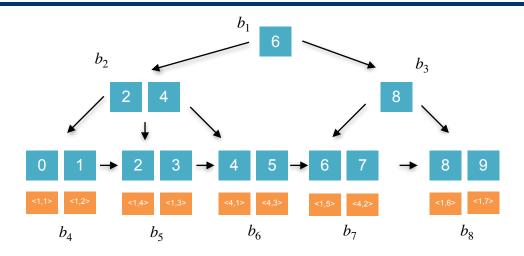
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 Question: Which of the following aggregates can be used to compute signposts in the node splitting process?

(A) Median (B) Max (C) Min (D) Mode

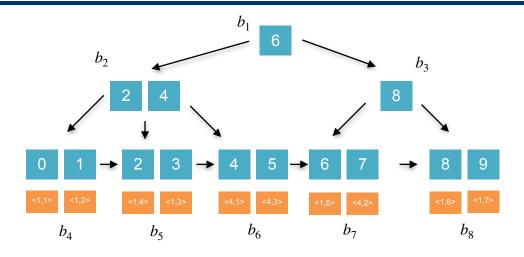
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 Question: Which of the following aggregates can be used to compute signposts in the node splitting process?

(A) Median (B) Max (C) Min (D) Mode

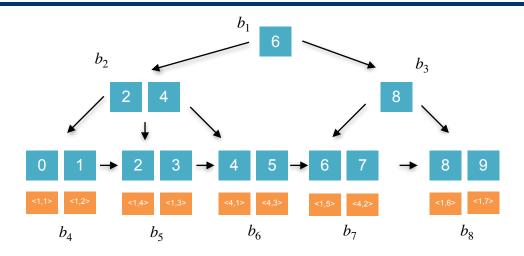
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Question: In which direction does a B+ tree grow?

(A) Downwards (B) Upwards

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Question: In which direction does a B+ tree grow?



Parent nodes are created while splitting

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