

Q 1) [10 points] The program heatExp.py solves the partial differential equation  $\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$  by the explicit method, subject to the boundary conditions  $u(0, t) = u(L, t) = 0$  and the initial condition

$$u(x, 0) = \begin{cases} 2h\frac{x}{L} & x < \frac{L}{2} \\ 2h(1 - \frac{x}{L}) & x \geq \frac{L}{2} \end{cases}$$

where we have used  $h = L = 1$ . The code is nearly complete, except for one crucial line.

i) Correct the code and run it. [4 points]

ii) Change the boundary condition to  $u(0, t) = 0$  and  $u(L, t) = A \sin^2(\omega t)$ . Use the values  $A = 1$ , and  $\omega = 25$ . Take a screenshot of the output at any instant of your choice. [3 points]

iii) Experiment with the value of  $\Delta t$  to try and pinpoint the minimum value where instability sets in (to see what instability looks like, just use the larger value of  $\Delta t$  that is commented out in the given program). [3 points]

Q 2) [10 points] The code heatImp.py uses the implicit algorithm to solve the same problem. Note that the set of simultaneous equations is solved here simply using numpy's inverse function to invert a matrix. Pay attention to how a non-zero boundary condition is handled here. Modify the code in heatImp.py to solve this problem using the Crank-Nicolson algorithm. Run it for the same initial value in Q 1, and for both sets of boundary conditions in 1i and 1ii.