Московский Авиационный Институт (Национальный исследовательский Университет)

Факультет: «Информационные технологии и прикладная математика» Кафедра: 806 «Вычислительная математика и программирование»

Лабораторная работа по курсу «ООП»

Тема: Основы работы с коллекциями: итераторы.

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```
1.Код на С++:
point.h:
#ifndef D POINT H
#define D_POINT_H_
#include <iostream>
template<class T>
struct point {
   double x,y;
    point<T> point 1(double x, double y);
};
template<class T>
point<T> point<T>::point 1(double x, double y) {
   point<T> p;
   p.x=x;
   p.y=y;
    return p;
}
template<class T>
std::istream& operator>> (std::istream& is, point<T>& p) {
   is >> p.x >>p.y;
    return is;
}
template<class T>
std::ostream& operator<< (std::ostream& os, const point<T>& p) {
   os << p.x << " " << p.y << " ";
    return os;
}
template<class T>
point<T> operator+(point<T> x1,point<T> x2) {
    point<T> x3;
   x3.x=x1.x+x2.x;
   x3.y=x1.y+x2.y;
    return x3;
}
template<class T>
point<T>& operator/= (point<T>& x1, int number) {
    x1.x=x1.x/number;
   x1.y=x1.y/number;
    return x1;
}
/*
template<class T>
std::istream& operator>>(std::istream& is, point<T>& p);
template<class T>
std::ostream& operator<<(std::ostream& os,const point<T>& p);
template < class T>
point<T> operator+(point<T> x1,point<T> x2);
template<class T>
point<T>& operator/= (point<T>& x1, int number);
* /
#endif
```

```
five_angles.h:
#ifndef D FIVE ANGLES H
#define D FIVE ANGLES H
#include <iostream>
#include "point.h"
template<class T>
struct five angles {
            five angles(std::istream &is);
           point<T> center() const ;
           void print() const ;
            double square() const ;
point<T> one, two, three, four, five;
};
template<class T>
five_angles<T>::five_angles(std::istream &is){
            is >> one >> two >> three >> four >> five;
}
template<class T>
point<T> five angles<T>::center() const {
           point<T> p;
           p=one+two+three+four+five;
           p/=5;
           return p;
}
template<class T>
void five angles<T>::print() const {
           std::cout << one << " " << two << " " << three << " " << four << " " <<
five <<"\n";
}
template<class T>
double five angles<T>::square() const {
            double s=0;
            s = (\texttt{one.x*two.y+two.x*three.y+three.x*four.y+four.x*five.y+five.x*one.y-three.x*four.y+four.x*five.y+five.x*four.y+five.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+five.x*four.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.y+four.x*five.x+four.x*five.y+four.x*five.y+four.x*five.x+four.x*five.x+four.x*five.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+four.x+f
two.x*one.y-
                      three.x*two.y-four.x*three.y-five.x*four.y-one.x*five.y)/2;
            if(s<0){
                       return -s;
            }else {
                       return s;
#endif
list.h:
#ifndef D LIST H
#define D_LIST_H_
#include <iostream>
#include "five angles.h"
```

```
#include <memory>
#include <functional>
#include <cassert>
#include <iterator>
namespace containersl {
    template<class T, class Allocator = std::allocator<T>>
   struct list {
   private:
       struct node;
   public:
        list() = default;
        struct forward iterator {
            using value type = T;
            using reference = T &;
            using pointer = T *;
            using difference type = ptrdiff t;
            using iterator category = std::forward iterator tag;
            forward iterator(node *ptr);
            T &operator*();
            forward_iterator &operator++();
            forward iterator operator+(int r);
            bool operator==(const forward iterator &o) const;
            bool operator!=(const forward iterator &o) const;
        private:
            node *ptr ;
            friend list;
        };
        forward iterator begin();
        forward iterator end();
        void insert(const forward iterator &it, const T &value);
        void erase(const forward_iterator &it);
        int is empty(){
           return root==nullptr;
        };
        size t size=0;
   private:
        using allocator type = typename Allocator::template
rebind<node>::other;
        struct deleter {
            deleter(allocator type* allocator): allocator (allocator) {}
```

```
void operator() (node* ptr) {
                if(ptr != nullptr){
std::allocator traits<allocator type>::destroy(*allocator , ptr);
                    allocator ->deallocate(ptr, 1);
                }
        private:
            allocator type* allocator;
        };
        using unique ptr = std::unique ptr<node, deleter>;
        node *end node = nullptr;
        node *end help(node *ptr);
        struct node {
            T value;
            unique ptr next{nullptr, deleter{nullptr}};
            node *parent = nullptr;
            forward_iterator nextf();
        };
        allocator type allocator {};
        unique ptr root{nullptr, deleter{nullptr}};
    };
//
    template<class T, class Allocator>
    typename list<T,Allocator>::node
*list<T,Allocator>::end help(containersl::list<T,Allocator>::node *ptr) {
        if ((ptr == nullptr) || (ptr->next == nullptr)) {
            return ptr;
        return list<T,Allocator>::end help(ptr->next.get());
    }
    template < class T, class Allocator >
    typename list<T,Allocator>::forward_iterator list<T,Allocator>::begin() {
        if (root == nullptr) {
            return nullptr;
        forward iterator it(root.get());
        return it;
    }
    template<class T, class Allocator>
    typename list<T,Allocator>::forward iterator list<T,Allocator>::end() {
       return nullptr;
    template<class T,class Allocator>
    void list<T,Allocator>::insert(const list<T,Allocator>::forward iterator
&it, const T &value) {
        std::unique ptr<node,list<T, Allocator>::deleter> new node{new
node{value},deleter{&allocator }};
```

```
if (it != nullptr) {
            node *ptr = it.ptr_->parent;
            new node->parent = it.ptr_->parent;
            it.ptr ->parent = new node.get();
            if (ptr) {
                new node->next = std::move(ptr->next);
                ptr->next = std::move(new node);
            } else {
                new node->next = std::move(root);
                root = std::move(new node);
            }
        } else {
            new node->next = nullptr;
            if(end node==nullptr) {
                new node->parent= nullptr;
                new node->next= nullptr;
                list<T,Allocator>::root = std::move(new node);
                new node->parent=end node;
                new node->next= nullptr;
                end node->next=std::move(new node);
        end node = end help(root.get());
        ++size;
    }
    template < class T, class Allocator >
    void list<T, Allocator>::erase(const list<T, Allocator>::forward iterator
&it) {
        if (it.ptr == nullptr) {
            throw std::logic error("erasing invalid iterator");
        unique ptr &pointer from parent = [&]() -> unique ptr & {
            if (it.ptr == root.get()) {
                return root;
            return it.ptr ->parent->next;
        }();
        pointer from parent = std::move(it.ptr ->next);
        end node = end help(root.get());
        --size;
//
    template<class T, class Allocator>
    typename list<T,Allocator>::forward iterator
list<T,Allocator>::node::nextf() {
        forward iterator result(this->next.get());
        return result;
    template < class T, class Allocator >
    list<T,Allocator>::forward iterator::forward iterator(node *ptr):
ptr {ptr} {}
    template<class T,class Allocator>
    T &list<T,Allocator>::forward iterator::operator*() {
        return ptr ->value;
    }
    template < class T, class Allocator >
```

```
typename list<T,Allocator>::forward iterator
&list<T,Allocator>::forward iterator::operator++() {
        if (*this != nullptr) {
            *this = ptr ->nextf();
            return *this;
        } else {
            throw std::logic error("invalid iterator");
        }
    }
    template<class T,class Allocator>
    typename list<T,Allocator>::forward iterator
list<T,Allocator>::forward iterator::operator+(int r) {
        for (int i = 0; i < r; ++i) {
            ++*this;
        }
        return *this;
    }
    template<class T, class Allocator>
    bool list<T,Allocator>::forward iterator::operator==(const
forward iterator &o) const {
       return ptr == o.ptr;
    template<class T, class Allocator>
   bool list<T,Allocator>::forward iterator::operator!=(const
forward iterator &o) const {
        return ptr != o.ptr ;
#endif
allocater.h:
#ifndef D ALLOCATOR H
#define D_ALLOCATOR_H_
#include <iostream>
#include "queue.h"
#include "list.h"
template<class T, size t ALLOC SIZE>
struct q allocator {
    using value_type = T;
    using size_type = std::size_t;
    using difference_type = std::ptrdiff_t;
    using is_always_equal = std::false_type;
    template<class U>
    struct rebind {
        using other = q allocator<U, ALLOC SIZE>;
    q allocator() :
            memory pool begin (new char[ALLOC SIZE]),
            memory_pool_end_(memory_pool_begin_ + ALLOC_SIZE),
            memory pool tail (memory pool begin ) {}
    q allocator(const q allocator &) = delete;
```

```
q allocator(q allocator &&) = delete;
    ~q allocator() {
        delete[] memory pool begin ;
    T *allocate(std::size t n);
   void deallocate(T *ptr, std::size t n);
private:
   char *memory pool begin ;
    char *memory pool end ;
    char *memory pool tail ;
    containersl::list<char *> free blocks ;
};
template<class T, size t ALLOC SIZE>
T* q allocator<T, ALLOC SIZE>::allocate(std::size t n) {
    if(size t(memory pool end - memory pool tail ) < sizeof(T)){</pre>
        if(!free_blocks_.is_empty()){
            char *ptr;
            for (size t i = 0; i < n; ++i) {
                auto it = free blocks .begin();
                ptr = *it;
                free blocks .erase(it);
            return reinterpret cast<T *>(ptr);
        throw std::bad alloc();
   T* result = reinterpret_cast<T*>(memory_pool_tail_);
   memory pool tail += sizeof(T);
   return result;
}
template<class T, size t ALLOC SIZE>
void q allocator<T, ALLOC_SIZE>::deallocate(T* ptr, std::size_t n) {
    if(ptr == nullptr){
        return;
    free_blocks_.insert(free_blocks_.end(),reinterpret_cast<char*>(ptr));
    memory pool tail -= sizeof(T);
#endif
queue.h:
#ifndef D QUEUE H
#define D QUEUE H
#include <iostream>
#include "five angles.h"
#include <memory>
#include <functional>
#include <cassert>
#include <iterator>
```

```
#include <type traits>
namespace containers {
    template<class T, class Allocator>
    struct queue {
   private:
       struct node;
   public:
       queue() = default;
        struct forward iterator {
            using value type = T;
            using reference = T &;
            using pointer = T *;
            using difference type = ptrdiff t;
            using iterator category = std::forward iterator tag;
            forward iterator(node *ptr);
            T &operator*();
            forward iterator &operator++();
            forward iterator operator+(int r);
            bool operator==(const forward iterator &o) const;
            bool operator!=(const forward iterator &o) const;
        private:
            node *ptr ;
            friend queue;
        };
        forward iterator begin();
        forward iterator end();
        void insert(const forward iterator &it, const T &value);
        void erase(const forward iterator &it);
        void pop();
        void push(const T &value);
        T front();
   private:
       using allocator type = typename Allocator::template
rebind<node>::other;
        struct deleter {
            deleter(allocator_type* allocator): allocator_(allocator) {}
            void operator() (node* ptr) {
                if(ptr != nullptr){
```

```
std::allocator traits<allocator type>::destroy(*allocator , ptr);
                    allocator ->deallocate(ptr, 1);
                }
        private:
            allocator type* allocator;
        };
        using unique ptr = std::unique ptr<node, deleter>;
        node *end node = nullptr;
        node *end help(node *ptr);
        struct node {
            T value;
            unique ptr next{nullptr, deleter{nullptr}};
            node *parent = nullptr;
            forward iterator nextf();
        };
        allocator type allocator {};
        unique ptr root{nullptr, deleter{nullptr}};
    };
//
    template<class T, class Allocater>
    typename queue<T,Allocater>::node
*queue<T,Allocater>::end help(containers::queue<T,Allocater>::node *ptr) {
        if ((ptr == nullptr) \mid | (ptr->next == nullptr)) {
            return ptr;
        return queue<T,Allocater>::end help(ptr->next.get());
    }
    template < class T, class Allocater >
    typename queue<T, Allocater>::forward iterator queue<T, Allocater>::begin()
        if (root == nullptr) {
            return nullptr;
        forward iterator it(root.get());
        return it;
    template<class T, class Allocater>
    typename queue<T,Allocater>::forward iterator queue<T,Allocater>::end() {
       return nullptr;
    }
    template<class T, class Allocator>
    void queue<T,Allocator>::insert(const
queue<T,Allocator>::forward iterator &it, const T &value) {
        node* ptr result =allocator .allocate(1);
        ptr result->value=value;
```

```
//std::allocator traits<allocator type>::construct(allocator ,ptr result,
value);
        std::unique ptr<node,queue<T, Allocator>::deleter>
new node(ptr result,deleter{&allocator });
        if (\overline{it} != nullptr) {
            node *ptr = it.ptr_->parent;
            new node->parent = it.ptr ->parent;
            it.ptr ->parent = new node.get();
            if (ptr) {
                new node->next = std::move(ptr->next);
                ptr->next = std::move(new node);
            } else {
                new node->next = std::move(root);
                root = std::move(new node);
            }
        } else {
            new node->next = nullptr;
            if(end node==nullptr) {
                new node->parent= nullptr;
                new node->next= nullptr;
                queue<T,Allocator>::root = std::move(new node);
            }else{
                new node->parent=end node;
                new node->next= nullptr;
                end node->next=std::move(new_node);
        }
        end node = end help(root.get());
    template<class T,class Allocater>
    void queue<T,Allocater>::erase(const queue<T,Allocater>::forward iterator
&it) {
        if (it.ptr == nullptr) {
            throw std::logic error("erasing invalid iterator");
        unique ptr &pointer from parent = [&]() -> unique ptr & {
            if (it.ptr == root.get()) {
                return root;
            return it.ptr ->parent->next;
        }();
        if(it.ptr_->next) {
            it.ptr ->next->parent = it.ptr ->parent;
        pointer from parent = std::move(it.ptr ->next);
        end node = end help(root.get());
    }
    template<class T, class Allocater>
    typename queue<T,Allocater>::forward iterator
queue<T,Allocater>::node::nextf() {
        forward iterator result(this->next.get());
        return result;
    }
    template<class T,class Allocater>
    queue<T,Allocater>::forward iterator::forward iterator(node *ptr):
ptr {ptr} {}
    template < class T, class Allocater >
    T &queue<T,Allocater>::forward iterator::operator*() {
```

```
return ptr ->value;
    }
    template<class T, class Allocater>
    typename queue<T,Allocater>::forward iterator
&queue<T, Allocater>::forward iterator::operator++() {
        if (*this != nullptr) {
            *this = ptr ->nextf();
            return *this;
        } else {
            throw std::logic error("invalid iterator");
    }
    template<class T, class Allocater>
    typename queue<T,Allocater>::forward iterator
queue<T,Allocater>::forward iterator::operator+(int r) {
        for (int i = 0; i < r; ++i) {
            ++*this;
       return *this;
    }
    template<class T, class Allocater>
   bool queue<T,Allocater>::forward iterator::operator==(const
forward iterator &o) const {
       return ptr == o.ptr;
    template < class T, class Allocater >
   bool queue<T,Allocater>::forward iterator::operator!=(const
forward iterator &o) const {
       return ptr != o.ptr ;
    template<class T, class Allocater>
    T queue<T,Allocater>::front() {
        if (queue<T,Allocater>::root == nullptr) {
            throw std::logic error("no elements");
        return queue<T,Allocater>::root->value;
    template < class T, class Allocater >
    void queue<T,Allocater>::pop() {
        if (queue<T,Allocater>::root == nullptr) {
            throw std::logic error("no elements");
        erase(queue<T,Allocater>::begin());
    template<class T,class Allocater>
    void queue<T,Allocater>::push(const T &value) {
        forward iterator it(end node);
        node* ptr result =allocator .allocate(1);
        ptr result->value=value;
//std::allocator traits<allocator type>::construct(allocator ,ptr result,
value);
        std::unique ptr<node,queue<T, Allocater>::deleter>
new node(ptr result,deleter{&allocator });
        if (it.ptr ) {
            new node->parent = it.ptr ;
            it.ptr ->next = std::move(new node);
```

```
} else {
             new node->next = nullptr;
             queue<T,Allocater>::root = std::move(new node);
        }
        queue<T,Allocater>::end node = end help(root.get());
    }
#endif
main.cpp:
#include <iostream>
#include "five angles.h"
#include "point.h"
#include "queue.h"
#include <string.h>
#include <algorithm>
#include "allocator.h"
#include <map>
int main() {
    char str[10];
    containers::queue<five angles<double>,q allocator<five angles<double
>,5*sizeof(five angles<double>)>> q;
    while(std::cin >> str){
        if (strcmp(str, "push") == 0) {
             five angles<double> five angle(std::cin);
             try {
                 q.push(five angle);
             }catch (std::exception& ex) {
                 std::cout <<ex.what() << "\n";</pre>
        }else if(strcmp(str,"pop")==0) {
             try {
                 q.pop();
                 std::cout << "\n";</pre>
             }catch (std::exception& ex) {
                 std::cout <<ex.what() << "\n";</pre>
             }
        }else if(strcmp(str,"front")==0) {
             try {
                 q.front().print();
                 std::cout << "\n";
             }catch (std::exception& ex) {
                 std::cout <<ex.what() << "\n";</pre>
        }else if(strcmp(str, "square") == 0) {
             int g;
             std::cin >> g;
             long res=std::count if(q.begin(),q.end(),[g](five angles<double>
f) { return f.square() < g;});</pre>
             std::cout << res << "\n";
        }else if(strcmp(str, "erase") == 0) {
             int r;
             std::cin >>r;
             try {
                 q.erase(q.begin() + r);
             }catch(std::exception& ex) {
                 std::cout <<ex.what() << "\n";</pre>
             }
```

```
} else if(strcmp(str,"insert") == 0) {
    int r;
    std::cin >> r;
    five_angles < double > five_angle(std::cin);
    try {
        q.insert(q.begin() + r, five_angle);
    } catch (std::exception& ex) {
        std::cout << ex.what() << "\n";
    }
    } else if(strcmp(str,"all") == 0) {
        std::for_each(q.begin(),q.end(),[](five_angles < double > f) {f.print(); });
        std::cout << "\n";
    }
    }
    return 0;
}</pre>
```

2. Ссылка на репозиторий в GitHub:

https://github.com/Suvorova-Sofya/oop_exercise_06

3. Habop testcases:

```
test1:
pop
no elements
push 1 1 2 2 3 3 4 4 5 5
pop
1122334455
pop
no elements
test2:
push 1 1 2 2 3 3 4 4 5 5
push 2 2 3 3 4 4 5 5 6 6
1122334455
2233445566
test3:
push 1 1 2 2 3 3 4 4 5 5
push 2 2 3 3 4 4 5 5 6 6
square 10
square 0
```

4. Результаты выполнения программы:

```
test1:
pop
no elements
push 1 1 2 2 3 3 4 4 5 5
pop
1 1 2 2 3 3 4 4 5 5
pop
no elements
```

test2:

```
push 1 1 2 2 3 3 4 4 5 5
push 2 2 3 3 4 4 5 5 6 6
all
1 1 2 2 3 3 4 4 5 5
2 2 3 3 4 4 5 5 6 6
test3:
push 1 1 2 2 3 3 4 4 5 5
push 2 2 3 3 4 4 5 5 6 6
square 10
2
square 0
```

5. Объяснение результатов работы программы:

Пользователь вводит команду, и если команда была push -координаты фигуры. Далее программа выполняет определенное действие с очередью взависимости от команды и либо возвращает определенное значение ,либо нет. Также пользователь должен знать какой объем памяти дал ему аллокатор, чтобы не выйти за её пределы.

6.Вывод:

В данной программе показывается ,каким образом можно создать собственный аллокатор, чтобы лучше понимать каким образом работает данная структура данных, и следовательно знать наиболее эффективный способ её использования.