

Assignment ④ 2301010122

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Q.1 - Rank

$$A = \begin{bmatrix} 1 & 2 & 3 & 0 \\ 2 & 4 & 3 & 2 \\ 3 & 2 & 4 & 3 \\ 6 & 8 & 7 & 5 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 - R_1 \\ R_3 \rightarrow R_3 - R_1 \\ R_4 \rightarrow R_4 - R_1 \end{array} \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & 0 & -3 & 2 \\ 0 & -4 & 1 & 3 \\ 0 & -4 & -11 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & -4 & -11 & 5 \\ 0 & 0 & -3 & 2 \\ 0 & 0 & -3 & 2 \end{bmatrix} \begin{array}{l} R_2 \rightarrow R_2 \\ R_3 \rightarrow R_3 - R_4 \end{array} \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & -4 & -11 & 5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -3 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & -4 & -11 & 5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{array}{l} R_4 \rightarrow R_4 + R_2 \\ R_3 \rightarrow R_3 + R_4 \end{array} \begin{bmatrix} 1 & 2 & 3 & 0 \\ 0 & -4 & -11 & 5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Rank = 3

2. For  $\dim$  of  $W$

$\therefore$  Symmetric matrix has 2 independent values

$\therefore \dim(W) = 3$

Rank of  $T = 3$

$T$  has all polynomials in  $P$  that can come by using

mapping to all polynomial of degree 2

$\therefore$  Rank of  $T = 3$

Using Rank Nullity theorem

$$\text{Nullity} = \dim(W) - \text{Rank}(T) = 3 - 3 = 0$$

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$$A = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$

Characteristic equation

$$\begin{vmatrix} 2-\lambda & -1 \\ -1 & 2-\lambda \end{vmatrix} = 0$$

$$(2-\lambda)(2-\lambda) - 1 = 0$$

$$\lambda^2 - 4\lambda + 3 = 0$$

$$\Rightarrow (\lambda-3)(\lambda-1) = 0$$

$$(\lambda-3)(\lambda-1) = 0 \Rightarrow \lambda = 3, 1$$

Eigen values are 1, 3

For  $\lambda = 1$

$$\begin{bmatrix} 1-1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$x - y = 0$$

$$-x + y = 0$$

$$\therefore \text{if } x = 3 \quad \begin{bmatrix} 1-1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$$

$$x - y = 0$$

$$-x + y = 0$$

$$\Rightarrow \begin{bmatrix} x \\ -x \end{bmatrix}$$

o.  $A$  is invertible, Eigen vector  $(A^{-1}) =$

o. Eigen vector of Eigen vector  $(A)$

$$(A + 4I) = \text{Eigen vector}(A)$$

o. Eigen values of  $A = 1, 3$

$$A^{-1} = \frac{1}{5} \begin{bmatrix} 1 & 1 \\ 1 & 3 \end{bmatrix}$$

$$A + 4I = 5, 7$$

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$$\begin{aligned}
 8x - 0.2z - 0.2z &= 7.8 \\
 0.3x + 7.0 &= -19.3 \\
 0.3x - 0.2y + 10z &= 75.4
 \end{aligned}$$

With initial values  $x(0) = 0, y(0) = 0, z(0) = 0$

$$\begin{aligned}
 & \frac{0.1}{2} \cdot 75.4 - 0.2 \cdot 0 - 0.2 \cdot 0 \\
 & = 3.77
 \end{aligned}$$

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$$z = \frac{7.1.4 - 0.3(7.716) - 0.2(2.36)}{10} = 6.956$$

for finding

$$\text{base case } (x, y, z) = (7.7, -0.36, 6.956)$$

$$x = 7.85 + 0.1 \left( \frac{-2.36}{2} \right) + 0.2(6.956)$$

$$x = 3.002$$

$$y = -13.3 + 0.1(3.002) + 0.3(6.956)$$

$$y = -2.45$$

$$z = \frac{7.1.4 - 0.3(3.002) - 0.2(-2.45)}{10}$$

$$z = 7.093$$

$$R_2 = R_3 - 2R_1$$

$$S_3 = \begin{bmatrix} 8 & 5 & 2 & 0 \\ 3 & -4 & 3 & 0 \\ 3 & -5 & 4 & 0 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

$$R_3 =$$

$$R_3 \rightarrow R_3 - 3R_1$$

$$R_4 \rightarrow R_4 - R_1$$

$$\begin{bmatrix} 8 & 5 & 2 & 0 \\ 3 & -4 & 3 & 0 \\ 0 & -11 & -20 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

$$P(4) = \frac{8(98)}{71}$$

Intercept

20/10

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$$\Rightarrow T(ax+bx+cx^2) = (ax+bx+cx^2)^2 + (cx)^2$$

for additivity  $T(u+v) = T(u) + T(v)$   
Homogeneity  $T(cu) = cT(u)$

$$\begin{aligned} (1) T(u) &= (ax+bx+cx^2)^2 + (cx)^2 \\ \text{assume } T(v) &= (ax+bx+cx^2)^2 + (cx)^2 \\ T(u+v) &= (ax+bx+cx^2)^2 + (b+bx+cx^2)^2 + (cx)^2 \end{aligned}$$

$\therefore$  Satisfies additivity

$$\begin{aligned} (2) \text{ Let } T(u) &= f_0 + f_1x + f_2x^2 \\ T(cu) &= T(f_0 + f_1x + f_2x^2) \\ T(cu) &= f_0(ax+bx+cx^2)^2 + f_1(cx)^2 + f_2(cx)^2 \end{aligned}$$

$\therefore$  Satisfies homogeneity

$\therefore$  It is a linear transformation

eg - One application is image filtering filters are small matrices that are applied to an image to

modify the pixel values. This can be done to achieve various effects, such as blurring images, sharpening edges or removing noise.

23/01/23 . suggest four steps

ex:- If a  $3 \times 3$  image where each pixel's value is intensity (0 to black, 255 white).

$$\text{Blurring} \rightarrow \left[ \begin{matrix} \sqrt{3} & 1 & \sqrt{3} \\ 1 & 1 & 1 \\ \sqrt{3} & 1 & \sqrt{3} \end{matrix} \right]$$

→ we perform element-wise multiplication.  
- then blur the filter & image & then take the average of the resulting values

10) Linear Transformation

powerful method for rotating 2D images in Computer Vision. They work by applying a rotation matrix to the image coordinates. This matrix

based on the rotation angle, essentially scales & rotates each point in the image.