Table 1: Endogenous

Variable	₽TEX	Description
r	r	r
rk	rk	rk
W	w	W
b	b	b
у	y	У
varpi	varpi	varpi
S	s	$\mathbf{s}$
inv	inv	inv
С	c	C
CW	cw	cw
cwper	cwper	cwper
cr	cr	cr
crper	crper	crper
tauw	tauw	tauw
N	N	N
stoyw	stoyw	stoyw
PiF	PiF	PiF
Tw	Tw	$\operatorname{Tw}$
hw	hw	hw
Dr	Dr	$\operatorname{Dr}$
Dw	Dw	Dw
ер	ep	ep
varsig	varsig	varsig
zetar	zetar	zetar
zetay	zetay	zetay
gw	gw	gw
g	g	g
gE	gE	${ m gE}$
iy	iy	iy
gpc	gpc	$\operatorname{gpc}$
gy	gy	gy
ZZ	zz	ZZ
far	far	$\operatorname{far}$
faw	faw	faw
dr	dr	$\mathrm{d}\mathrm{r}$
dw	dw	$d\mathbf{w}$
mu	mu	mu
k	k	k
u	u	u
del	del	del
delprime	delprime	delprime
gM	gM	$\mathrm{gM}$
V	v	V
j	j	j

 $Table\ 1-Continued$ 

Variable	IATEX	Description
lam	lam	lam
gA	gA	gA
za	za	za
PiA	PiA	PiA
PiRD	PiRD	PiRD
fa	fa	fa
n	n	n
gn	gn	$\operatorname{gn}$
gamma	gamma	gamma
er	er	er
ey	ey	ey
en	en	en
psi	psi	psi
shockr	shockr	shockr
shocky	shocky	shocky
shockn	shockn	shockn
fert	fert	$\operatorname{fert}$
omegay	omegay	omegay
shareW	shareW	shareW
shareR	shareR	shareR
AUX_ENDO_LAG_37_1	AUX_ENDO_LAG_37_1	AUX_ENDO_LAG_37_1
AUX_ENDO_LAG_46_1	AUX_ENDO_LAG_46_1	AUX_ENDO_LAG_46_1
AUX_ENDO_LAG_59_1	AUX_ENDO_LAG_59_1	AUX_ENDO_LAG_59_1
AUX_ENDO_LAG_59_2	AUX_ENDO_LAG_59_2	AUX_ENDO_LAG_59_2
AUX_ENDO_LAG_59_3	AUX_ENDO_LAG_59_3	AUX_ENDO_LAG_59_3
AUX_ENDO_LAG_59_4	AUX_ENDO_LAG_59_4	AUX_ENDO_LAG_59_4
AUX_ENDO_LAG_59_5	AUX_ENDO_LAG_59_5	AUX_ENDO_LAG_59_5
AUX_ENDO_LAG_59_6	AUX_ENDO_LAG_59_6	AUX_ENDO_LAG_59_6
AUX_ENDO_LAG_59_7	AUX_ENDO_LAG_59_7	AUX_ENDO_LAG_59_7
AUX_ENDO_LAG_59_8	AUX_ENDO_LAG_59_8	AUX_ENDO_LAG_59_8
AUX_ENDO_LAG_59_9	AUX_ENDO_LAG_59_9	AUX_ENDO_LAG_59_9
AUX_ENDO_LAG_59_10	AUX_ENDO_LAG_59_10	AUX_ENDO_LAG_59_10
AUX_ENDO_LAG_59_11	AUX_ENDO_LAG_59_11	AUX_ENDO_LAG_59_11
AUX_ENDO_LAG_59_12	AUX_ENDO_LAG_59_12	AUX_ENDO_LAG_59_12
AUX_ENDO_LAG_59_13	AUX_ENDO_LAG_59_13	AUX_ENDO_LAG_59_13
AUX_ENDO_LAG_59_14	AUX_ENDO_LAG_59_14	AUX_ENDO_LAG_59_14
AUX_ENDO_LAG_59_15	AUX_ENDO_LAG_59_15	AUX_ENDO_LAG_59_15 AUX_ENDO_LAG_59_16
AUX_ENDO_LAG_59_16	AUX_ENDO_LAG_59_16	AUX_ENDO_LAG_59_17
AUX_ENDO_LAG_59_17	AUX_ENDO_LAG_59_17	AUX_ENDO_LAG_59_17 AUX_ENDO_LAG_59_18
AUX_ENDO_LAG_59_18	AUX_ENDO_LAG_59_18	
AUX_ENDO_LAG_59_19 AUX_ENDO_LAG_59_20	AUX_ENDO_LAG_59_19 AUX_ENDO_LAG_59_20	AUX_ENDO_LAG_59_19 AUX_ENDO_LAG_59_20
AUX_ENDO_LAG_59_20 AUX_ENDO_LAG_59_21	AUX_ENDO_LAG_59_20 AUX_ENDO_LAG_59_21	AUX_ENDO_LAG_59_21
AUX_ENDU_LAG_59_21 AUX_ENDO_LAG_59_22	AUX_ENDO_LAG_59_21 AUX_ENDO_LAG_59_22	AUX_ENDO_LAG_59_21 AUX_ENDO_LAG_59_22
AUX_ENDO_LAG_59_23	$AUX\_ENDO\_LAG\_59\_23$	AUX_ENDO_LAG_59_23

Table 1 – Continued

Variable	Ŀ₽ŢĘX	Description
AUX_ENDO_LAG_59_24	$AUX\_ENDO\_LAG\_59\_24$	AUX_ENDO_LAG_59_24
AUX_ENDO_LAG_59_25	$AUX\_ENDO\_LAG\_59\_25$	AUX_ENDO_LAG_59_25
AUX_ENDO_LAG_59_26	$AUX\_ENDO\_LAG\_59\_26$	AUX_ENDO_LAG_59_26
AUX_ENDO_LAG_59_27	$AUX\_ENDO\_LAG\_59\_27$	AUX_ENDO_LAG_59_27
AUX_ENDO_LAG_59_28	$AUX\_ENDO\_LAG\_59\_28$	AUX_ENDO_LAG_59_28

Table 2: Exogenous

Variable	ĿTEX	Description
delall	delall	delall

Table 3: Parameters

Variable	ĿTEX	Description
SHINNOVW	SHINNOVW	SHINNOVW
YINNOVSH	YINNOVSH	YINNOVSH
OMEGAR	OMEGAR	OMEGAR
ZETAYSS	ZETAYSS	ZETAYSS
ZETARSS	ZETARSS	ZETARSS
REPLACSS	REPLACSS	REPLACSS
RHOYW	RHOYW	RHOYW
LAMY	LAMY	LAMY
PSISS	PSISS	PSISS
GSS	GSS	GSS
PERS	PERS	PERS
RATIODEL	RATIODEL	RATIODEL
OMEGAYSS	OMEGAYSS	OMEGAYSS
RHOU	RHOU	RHOU
BBETA	BBETA	BBETA
ALPHA	ALPHA	ALPHA
GAMMAI	GAMMAI	GAMMAI
VARNU	VARNU	VARNU
BMEGA	BMEGA	BMEGA
CHI	CHI	CHI
RHO	RHO	RHO
PHI	PHI	PHI
ELASMU	ELASMU	ELASMU
ELASLAM	ELASLAM	ELASLAM
DELPRIMESS	DELPRIMESS	DELPRIMESS
DELSS	DELSS	DELSS

 $Table\ 3-Continued$ 

Variable	Ŀ₽ŢĘX	Description
MUSS	MUSS	MUSS
LAMSS	LAMSS	LAMSS
USS	USS	USS
VARPISS	VARPISS	VARPISS
ZASS	ZASS	ZASS
KSS	KSS	KSS
NSS	NSS	NSS
GAMMASS	GAMMASS	GAMMASS
RHOE	RHOE	RHOE
CHIE	CHIE	CHIE
$gn_{-}1$	$gn\_1$	$\mathrm{gn}1$
$gn_2$	$gn\_2$	$\mathrm{gn}2$
gn_3	$gn\_3$	$gn_{-}3$
$gn_4$	$gn\_4$	$\mathrm{gn}_{-4}$
gn_5	$gn\_5$	$\mathrm{gn}_{-}5$
$gn_{-}6$	$gn$ _6	$\mathrm{gn}_{-}6$
gn_7	$gn\_7$	$\mathrm{gn}_{-}7$
gn8	$gn$ _8	gn8
gn_9	$gn\_9$	$gn_{-}9$
gn_10	gn10	$gn_{-}10$
$gn_{-}11$	gn11	$gn_11$
$gn_{-}12$	$gn\_12$	$gn_{-}12$
gn_13	$gn\_13$	$gn_13$
$gn_{-}14$	$gn\_14$	$gn_{-}14$
gn_15	$gn\_15$	$gn_{-}15$
$gn_{-}16$	$gn\_16$	$gn_{-}16$
$gn_{-}17$	$gn\_17$	$\mathrm{gn}\_17$
$gn_{-}18$	gn18	$gn_{-}18$
$gn_{-}19$	$gn\_19$	$gn_19$
$gn_20$	$gn\_20$	$gn_{-}20$
gn_21	$gn\_21$	$gn_21$
$gn_22$	$gn\_22$	$gn_22$
gn_23	$gn\_23$	$gn_23$
$gn_24$	$gn\_24$	$gn_24$
gn_25	$gn\_25$	$gn_25$
gn_26	$gn\_26$	$gn_26$
$gn_27$	$gn\_27$	$gn_27$
gn_28	$gn\_28$	$gn_28$
gn_29	gn29	$gn_29$
gn_30	$gn_{-}30$	$gn_30$
$\mathtt{dws}_{-}1$	$dws\_1$	$\mathrm{dws}_{-1}$
$dws_2$	$dws\_2$	$dws_2$
$dws_3$	$dws\_3$	$dws_3$
${\tt dws\_4}$	$dws\_4$	$dws_4$
$dws_{-}5$	$dws\_5$	$\mathrm{dws}_{-5}$

Table 3 – Continued

	Table 3 – Continu	
Variable	Ŀ₽ŢĘX	Description
dws_6	$dws\_6$	$dws_6$
$\mathtt{dws}_{-}7$	$dws\_7$	$\mathrm{dws}_{-}7$
${\tt dws\_8}$	$dws\_8$	$\mathrm{dws}_{-8}$
dws_9	$dws\_9$	$dws_{-}9$
$dws_{-}10$	$dws\_10$	$\mathrm{dws}\_10$
$dws_{-}11$	$dws\_11$	$\mathrm{dws}\_11$
$dws_{-}12$	$dws\_12$	$\mathrm{dws}\_12$
$dws_13$	$dws\_13$	$dws_13$
${\tt dws\_14}$	$dws\_14$	$\mathrm{dws}\_14$
$dws_15$	$dws\_15$	$\mathrm{dws}\_15$
$dws_{-}16$	$dws\_16$	$\mathrm{dws}\_16$
$dws_17$	$dws\_17$	$\mathrm{dws}\_17$
dws_18	$dws\_18$	$\mathrm{dws}\_18$
$dws_19$	$dws\_19$	$dws_19$
dws_20	$dws\_20$	$\mathrm{dws}\_20$
$dws_21$	$dws\_21$	$\mathrm{dws}\-21$
dws_22	$dws\_22$	$\mathrm{dws}\_22$
dws_23	$dws\_23$	$\mathrm{dws}\-23$
dws_24	$dws\_24$	$dws_24$
$dws_25$	$dws\_25$	$\mathrm{dws}\_25$
dws_26	$dws\_26$	$\mathrm{dws}\_26$
dws_27	$dws\_27$	$\mathrm{dws}$ _27
dws_28	$dws\_28$	$\mathrm{dws}$ 28
dws_29	$dws\_29$	$\mathrm{dws}$ _29
dws_30	$dws\_30$	$dws\_30$
$\mathtt{drs}_{-}1$	$drs\_1$	$\mathrm{drs}$ -1
$\mathtt{drs}\_2$	$drs\_2$	$\mathrm{drs}_{-2}$
drs_3	$drs\_3$	$\mathrm{drs}\_3$
$\mathtt{drs}\_4$	$drs\_4$	$\mathrm{drs}\_4$
drs_5	$drs\_5$	$\mathrm{drs}_{-5}$
drs_6	$drs\_6$	$\mathrm{drs}_{-6}$
$drs_{-}7$	$drs_{-7}$	$\mathrm{drs}_{-7}$
drs_8	$drs\_8$	drs8
drs_9	$drs\_9$	$drs_{-}9$
$\mathtt{drs}\_10$	$drs\_10$	$\mathrm{drs}\_10$
$\mathtt{drs}_{-}11$	$drs\_11$	$drs_{-}11$
$drs_12$	$drs\_12$	$\mathrm{drs}\_12$
drs_13	$drs\_13$	$drs_13$
drs_14	$drs_{-}14$	$drs_{-}14$
drs_15	$drs\_15$	$drs_{-}15$
drs_16	$drs_{-}16$	$drs_{-}16$
drs_17	$drs\_17$	$drs_17$
drs_18	$drs_{-}18$	$drs_{-}18$
drs_19	$drs_{-}19$	$drs_{-}19$
drs_20	$drs\_20$	$\mathrm{drs}\-20$

Table 3 – Continued

Variable	ĿTEX	Description
drs_21	$drs\_21$	$drs_21$
$drs_22$	$drs\_22$	$\mathrm{drs}\_22$
drs_23	$drs\_23$	$drs_23$
$\mathtt{drs}\_24$	$drs\_24$	$\mathrm{drs}\-24$
$drs_25$	$drs\_25$	$\mathrm{drs}\-25$
$drs_26$	$drs\_26$	$\mathrm{drs}\-26$
$drs_27$	$drs\_27$	$\mathrm{drs}\-27$
$drs_28$	$drs\_28$	$\mathrm{drs}\-28$
drs_29	$drs\_29$	$drs_29$
$\mathtt{drs}\_30$	$drs\_30$	$\mathrm{drs}\_30$

Table 4: Parameter Values

Parameter	Value
SHINNOVW	0.010
YINNOVSH	0.060
OMEGAR	0.975
ZETAYSS	0.700
ZETARSS	0.227
REPLACSS	0.756
RHOYW	0.512
LAMY	0.049
PSISS	0.708
GSS	1.046
PERS	0.900
RATIODEL	0.333
OMEGAYSS	0.950
RHOU	-3.000
BBETA	0.960
ALPHA	0.333
GAMMAI	0.500
VARNU	1.667
BMEGA	0.128
CHI	64.671
RHO	0.900
PHI	0.850
ELASMU	-1.000
ELASLAM	0.855
DELPRIMESS	0.301
DELSS	0.080
MUSS	1.100
LAMSS	0.100
USS	0.800
VARPISS	0.135
$ZASS \ KSS$	$3.126 \\ 0.658$
NSS	1.010
GAMMASS	0.900
RHOE	0.900
CHIE	1689.513
$gn_{-}1$	1.009
$gn_{-2}$	1.009
$gn_{-3}$	1.009
$gn\_4$	1.009
$gn_{-}5$	1.008
$gn\_6$	1.008
$gn\_7$	1.007
<i>J</i> · · - ·	•

Table 4 – Continued

Table 4 – Co	ontinued
Parameter	Value
$gn\_8$	1.007
$gn\_9$	1.007
$gn_{-}10$	1.007
$gn_{\text{-}}11$	1.007
gn12	1.007
$gn_{\text{-}}13$	1.007
$gn\_14$	1.007
$gn\_15$	1.007
$gn\_16$	1.007
$gn\_17$	1.007
$gn\_18$	1.007
$gn\_19$	1.007
gn20	1.007
$gn\_21$	1.007
$gn\_22$	1.007
gn23	1.006
$gn\_24$	1.006
$gn\_25$	1.006
$gn\_26$	1.006
$gn\_27$	1.006
$gn\_28$	1.006
gn29	1.005
$gn_{-}30$	1.005
$dws\_1$	-0.002
$dws\_2$	-0.002
$dws\_3$	-0.002
$dws\_4$	-0.002
$dws\_5$	-0.002
$dws\_6$	-0.002
$dws\_7 \ dws\_8$	-0.001 -0.001
$dws\_9$	-0.001
$dws\_9$ $dws\_10$	-0.001
$dws\_10$ $dws\_11$	-0.002
$dws\_12$	-0.003
$dws_{-}13$	-0.003
$dws\_14$	-0.003
$dws\_15$	-0.003
$dws\_16$	-0.004
$dws$ _17	-0.003
$dws_{-}18$	-0.003
$dws_{-}19$	-0.002
$dws\_20$	-0.002
$dws\_21$	-0.002

Table 4 – Continued

Table 4 – Continued	
Parameter	Value
$dws\_22$	-0.001
$dws\_23$	-0.001
$dws\_24$	-0.001
$dws\_25$	-0.001
$dws\_26$	-0.001
$dws\_27$	-0.001
$dws\_28$	-0.001
$dws\_29$	-0.001
$dws\_30$	-0.001
$drs\_1$	0.002
$drs\_2$	0.003
$drs\_3$	0.004
$drs\_4$	0.004
$drs\_5$	0.004
$drs\_6$	0.004
$drs\_7$	0.004
$drs\_8$	0.004
$drs\_9$	0.005
$drs\_10$	0.005
$drs\_11$	0.005
$drs\_12$	0.005
$drs\_13$	0.005
$drs\_14$	0.005
$drs\_15$	0.005
$drs\_16$	0.004
$drs\_17$	0.004
$drs\_18$	0.004
$drs\_19$	0.004
$drs\_20$	0.003
$drs\_21$	0.003
$drs\_22$	0.002
$drs\_23$	0.002
$drs\_24$	0.002
$drs\_25$	0.002
$drs\_26$	0.001
$drs\_27$	0.001
$drs_{-}28$	0.001
$drs\_29$	0.001
drs_30	0.001

$$hw_t = w_t + \frac{OMEGAR}{r_t z z_t} \frac{g_{t+1}}{g w_t} h w_{t+1} \tag{1}$$

$$Tw_t = tauw_t + \frac{OMEGAR}{r_t z z_t} \frac{g_{t+1}}{g w_t} Tw_{t+1}$$
(2)

$$Dr_t = dr_t + \frac{g_{t+1} Dr_{t+1} gamma_t zetar_{t-1}}{qw_t r_t zetar_t}$$
(3)

$$Dw_{t} = dw_{t} + \frac{OMEGAR}{r_{t}zz_{t}} \frac{g_{t+1}}{gw_{t}} Dw_{t+1} + Dr_{t+1} \frac{(1 - OMEGAR) ep_{t+1}^{\frac{RHOU-1}{RHOU}}}{r_{t}zz_{t}} \frac{g_{t+1}}{gw_{t}zetar_{t}}$$
(4)

$$cw_t = varsig_t \left( Dw_t + hw_t + \frac{r_{t-1} faw_{t-1}}{g_t} - Tw_t \right)$$
 (5)

$$cr_t = varsig_t ep_t \left( Dr_t + \frac{r_{t-1} far_{t-1}}{g_t} \right)$$
 (6)

$$1 - varsig_t ep_t = \frac{gamma_t \ (r_t \ BBETA)^{\frac{1}{1 - RHOU}}}{r_t} \frac{varsig_t \ ep_t}{ep_{t+1} \ varsig_{t+1}}$$
 (7)

$$1 - varsig_t = \frac{(zz_t r_t BBETA)^{\frac{1}{1-RHOU}}}{r_t zz_t} \frac{varsig_t}{varsig_{t+1}}$$
(8)

$$zz_t = OMEGAR + (1 - OMEGAR) e_{t+1}^{\frac{RHOU - 1}{RHOU}}$$
(9)

$$cwper_t = cw_t \ (zetar_t + 1 + zetay_t) \tag{10}$$

$$crper_t = \frac{cr_t \left(zetar_t + 1 + zetay_t\right)}{zetar_t} \tag{11}$$

$$gw_t = OMEGAR + (1 - omegay_t) \ zetay_{t-1}$$
 (12)

$$n_t = gw_t \frac{zetay_t}{zetay_{t-1}} \tag{13}$$

$$gw_t zetar_t = 1 - OMEGAR + gamma_t zetar_{t-1}$$
(14)

$$gn_{t} = (gw_{t}zetar_{t} + gw_{t} + zetay_{t-1}n_{t}) (zetay_{t-1} + 1 + zetar_{t-1})^{(-1)}$$
(15)

$$gE_t = \frac{OMEGAR + (1 - omegay_t) \ zetay_{t-1} \ \left(RHOE + \frac{CHIE}{2} \ iy_t^2\right)}{gw_t} \tag{16}$$

$$tauw_t = w_t i y_t \tag{17}$$

$$varsig_{t}^{\frac{(-1)}{RHOU}} = \frac{g_{t+1} iy_{t} CHIE zetay_{t} BBETA varsig_{t+1}^{\frac{(-1)}{RHOU}} \left(1 - omegay_{t+1}\right) w_{t+1}}{n_{t} gE_{t} w_{t} gw_{t}}$$
(18)

$$fert_t = n_t - omegay_t \tag{19}$$

$$(1 - ALPHA) (1 - GAMMAI) = w_t m u_t$$
(20)

$$ALPHA (1 - GAMMAI) = mu_t (rk_t + del_t) \frac{k_{t-1}}{g_t}$$
(21)

$$ALPHA (1 - GAMMAI) = \frac{k_{t-1}}{g_t} mu_t delprime_t u_t$$
 (22)

$$g_t = \frac{mu_t}{mu_{t-1}} g M_t g A_{t-1}^{1-VARNU}$$
 (23)

$$g_{t} = gM_{t}^{GAMMAI} \left(gE_{t-1} gw_{t-1}\right)^{(1-ALPHA)} \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{k_{t-1} u_{t} g_{t-1}}{u_{t-1} AUX\_ENDO\_LAG\_37\_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{N_{t}^{mu_{t}-1}}{u_{t-1} AUX\_ENDO\_LAG\_37\_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{N_{t}^{mu_{t}-1}}{u_{t-1} AUX\_ENDO\_LAG\_37\_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{N_{t}^{mu_{t}-1}}{u_{t-1} AUX\_ENDO\_LAG\_37\_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \frac{N_{t}^{mu_{t}-1}}{u_{t-1}^{mu_{t}-1}} \frac{N_{t}^{mu_{t}-1}}{u_{t-1}^{mu$$

$$\frac{mu_t - 1}{mu_t} N_t^{(-mu_t)} = BMEGA v_t \tag{25}$$

$$mu_t = MUSS (1 + ELASMU (N_t - 1))$$
(26)

$$del_t = DELSS + delprime_t (u_t - USS)$$
(27)

$$delprime_{t} = DELPRIMESS + \frac{(u_{t} - USS) \ DELPRIMESS \ RATIODEL}{USS}$$
 (28)

$$\frac{gA_t za_t}{za_{t-1}} = stoyw_t^{RHOYW} CHI \left(\frac{s_t}{psi_t}\right)^{RHO} + PHI$$
 (29)

$$stoyw_{t} = \frac{zetay_{t-1} \left(1 - omegay_{t}\right) YINNOVSH}{zetar_{t-1} + 1 + zetay_{t-1}} + \frac{OMEGAR \left(1 - LAMY\right)}{gn_{t}} stoyw_{t-1} \quad (30)$$

$$gA_t = PHI + PHI \, lam_t \, (za_{t-1} - 1) \tag{31}$$

$$s_{t} = PHI \frac{g_{t+1}}{r_{t}} j_{t+1} \left( 1 - \frac{za_{t-1}PHI}{gA_{t}za_{t}} \right)$$
 (32)

$$v_t = \frac{GAMMAI\left(1 - \frac{1}{VARNU}\right)}{mu_t} + \frac{g_{t+1}}{gA_t} \frac{PHI}{r_t} v_{t+1}$$
(33)

$$varpi_{t} = \frac{PHI}{r_{t}} \frac{g_{t+1}}{gA_{t}} za_{t-1} lam_{t} ELASLAM \left(v_{t+1} - \frac{j_{t+1}}{za_{t}}\right)$$

$$(34)$$

$$j_{t} = \frac{PHI}{r_{t}} z a_{t-1} \frac{g_{t+1}}{gA_{t}} \left( lam_{t} v_{t+1} + \frac{j_{t+1} (1 - lam_{t})}{z a_{t}} \right) - varpi_{t}$$
 (35)

$$lam_{t} = LAMSS \left(1 + ELASLAM \left(\frac{varpi_{t} - VARPISS}{VARPISS} - \frac{za_{t-1} - ZASS}{ZASS} - \frac{psi_{t} - PSISS}{PSISS}\right)\right)$$
(36)

$$PiA_{t} = \frac{GAMMAI \left(1 - \frac{1}{VARNU}\right)}{mu_{t}} - PHI j_{t} \left(1 - \frac{PHIAUX\_ENDO\_LAG\_46\_1_{t-1}}{gA_{t-1} z a_{t-1}}\right) - \frac{r_{t-1} varpi_{t-1} \left(1 - \frac{1}{AUX\_ENDO\_LAG\_46\_1_{t-1}}\right)}{g_{t}}$$

$$(37)$$

$$PiRD_{t} = PHI j_{t} \left( 1 - \frac{PHI AUX\_ENDO\_LAG\_46\_1_{t-1}}{gA_{t-1} za_{t-1}} \right) - \frac{r_{t-1} s_{t-1}}{g_{t}}$$
(38)

$$psi_t = v_t (39)$$

$$r_t = 1 + rk_{t+1} (40)$$

$$dr_t = \frac{far_{t-1}PiF_t}{fa_{t-1}} \tag{41}$$

$$dw_t = \frac{faw_{t-1}PiF_t}{fa_{t-1}} + SHINNOVW (PiA_t + PiRD_t)$$
(42)

$$b_t = s_t + varpi_t \left(1 - \frac{1}{za_{t-1}}\right) \tag{43}$$

$$PiF_{t} = \frac{k_{t-1}}{g_{t}} \left( 1 + rk_{t} \right) + \frac{r_{t-1}b_{t-1}}{g_{t}} - \frac{r_{t-1}fa_{t-1}}{g_{t}} - k_{t} - b_{t}$$

$$+ fa_{t} + (PiA_{t} + PiRD_{t}) \left( 1 - SHINNOVW \right)$$

$$(44)$$

$$k_t = \frac{k_{t-1}}{g_t} (1 - del_t) + inv_t \tag{45}$$

$$y_t = 1 - \frac{GAMMAI}{mu_t VARNU} - psi_t N_t BMEGA$$
 (46)

$$y_t = tauw_t + varpi_t \left(1 - \frac{1}{za_{t-1}}\right) + s_t + inv_t + c_t \tag{47}$$

$$c_t = cw_t + cr_t \tag{48}$$

$$fa_t = b_t + k_t \tag{49}$$

$$far_{t} = dr_{t} + \frac{r_{t-1} far_{t-1}}{g_{t}} - cr_{t} + (1 - OMEGAR) \left( dw_{t} + w_{t} + \frac{r_{t-1} faw_{t-1}}{g_{t}} - cw_{t} - tauw_{t} \right)$$
(50)

$$fa_t = far_t + faw_t (51)$$

$$gpc_t = \frac{g_{t-1} \frac{y_t}{y_{t-1}}}{gn_{t-1}} \tag{52}$$

$$gy_t = g_t \frac{y_t}{y_{t-1}} \tag{53}$$

$$gn_t = NSS + en_t (54)$$

$$shareW_t = \frac{1}{zetar_t + 1 + zetay_t} \tag{55}$$

$$shareR_t = \frac{zetar_t}{zetar_t + 1 + zetay_t} \tag{56}$$

$$\frac{1}{zetar_t + 1 + zetay_t} = \frac{1}{1 + ZETAYSS + ZETARSS} + ey_t \tag{57}$$

$$\frac{zetar_t}{zetar_t + 1 + zetay_t} = \frac{ZETARSS}{1 + ZETAYSS + ZETARSS} + er_t \tag{58}$$

```
en_t = shockn_t (gn_1 - NSS) + shockn_{t-1} (gn_2 - NSS)
           + (gn_3 - NSS) AUX_ENDO_LAG_59_1_{t-1} + (gn_4 - NSS) AUX_ENDO_LAG_59_2_{t-1}
           + (gn_5 - NSS) AUX_ENDO_LAG_59_3_{t-1} + (gn_6 - NSS) AUX_ENDO_LAG_59_4_{t-1}
           +(qn_{-}7-NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}5_{t-1}+(qn_{-}8-NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}6_{t-1}
           +(gn\_9-NSS) AUX\_ENDO\_LAG\_59\_7_{t-1}+(gn\_10-NSS) AUX\_ENDO\_LAG\_59\_8_{t-1}
           + (gn_11 - NSS) AUX_ENDO_LAG_59_9_{t-1}
           + (gn_12 - NSS) AUX_ENDO_LAG_59_10_{t-1}
           + (qn_13 - NSS) AUX_ENDO_LAG_59_11_{t-1}
           + (qn_14 - NSS) AUX_ENDO_LAG_59_12_{t-1}
           + (gn_{-}15 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}13_{t-1}
           + (qn_16 - NSS) AUX_ENDO_LAG_59_14_{t-1}
           + (gn_{-}17 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}15_{t-1}
           + (qn_18 - NSS) AUX_ENDO_LAG_59_16_{t-1}
           + (qn_{-}19 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}17_{t-1}
           + (qn_20 - NSS) AUX_ENDO_LAG_59_18_{t-1}
           + (gn_21 - NSS) AUX_ENDO_LAG_59_19_{t-1}
           + (gn_{-}22 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}20_{t-1}
           + (gn_2 - NSS) AUX_ENDO_LAG_59_21_{t-1}
           + (qn_24 - NSS) AUX_ENDO_LAG_59_22_{t-1}
           + (gn_{-}25 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}23_{t-1}
           + (qn_{-}26 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}24_{t-1}
           + (gn_{27} - NSS) AUX_{ENDO}_{LAG_{59}_{25}_{t-1}}
           + (qn_28 - NSS) AUX_ENDO_LAG_59_26_{t-1}
           + (qn_{-}29 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}27_{t-1}
           + (gn_{-}30 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}28_{t-1}
                                                                                                                                                                               (59)
                                                                              er_t = shockr_t
                                                                                                                                                                               (60)
                                                                              ey_t = shocky_t
                                                                                                                                                                               (61)
     shocky_t = shocky_{t-1} + delall_t dws_1 + delall_{t-1} dws_2 + delall_{t-2} dws_3
                         + delall_{t-3} dws_4 + delall_{t-4} dws_5 + delall_{t-5} dws_6 + delall_{t-6} dws_7
                         + delall_{t-7} dws_8 + delall_{t-8} dws_9 + delall_{t-9} dws_10 + delall_{t-10} dws_111
                         + delall_{t-11} dws_12 + delall_{t-12} dws_13 + delall_{t-13} dws_14 + delall_{t-14} dws_15
                                                                                                                                                                               (62)
                         + delall_{t-15} dws_{-16} + delall_{t-16} dws_{-17} + delall_{t-17} dws_{-18} + delall_{t-18} dws_{-19}
                         + delall_{t-19} dws_20 + delall_{t-20} dws_21 + delall_{t-21} dws_22 + delall_{t-22} dws_23
                         + delall_{t-23} dws_2 + delall_{t-24} dws_2 + delall_{t-25} dws_2 + delall_{t-26} dws_
                         + delall_{t-27} dws_2 + delall_{t-28} dws_2 + delall_{t-29} dws_3 = 30
          shockr_t = delall_t dws_1 + shockr_{t-1} + delall_{t-1} drs_2 + delall_{t-2} drs_3
                              + delall_{t-3} drs_{-4} + delall_{t-4} drs_{-5} + delall_{t-5} drs_{-6} + delall_{t-6} drs_{-7}
                              + delall_{t-7} drs_{-8} + delall_{t-8} drs_{-9} + delall_{t-9} drs_{-10} + delall_{t-10} drs_{-11}
                              + delall_{t-11} drs_{-1}2 + delall_{t-12} drs_{-1}3 + delall_{t-13} drs_{-1}4 + delall_{t-14} drs_{-1}5
                                                                                                                                                                               (63)
                              + delall_{t-15} drs_{-16} + delall_{t-16} drs_{-17} + delall_{t-17} drs_{-18} + delall_{t-18} drs_{-19}
                              + delall_{t-19} drs_{-}20 + delall_{t-20} drs_{-}21 + delall_{t-21} drs_{-}22 + delall_{t-22} drs_{-}23
                              + delall_{t-23} drs_{-}24 + delall_{t-24} drs_{-}25 + delall_{t-25} drs_{-}26 + delall_{t-26} drs_{-}27
                              + delall_{t-27} drs_{-28} + delall_{t-28} drs_{-29} + delall_{t-29} drs_{-30}
```

```
shockn_t = delall_t
                                                                       (64)
            AUX\_ENDO\_LAG\_37\_1_t = k_{t-1}
                                                                       (65)
            AUX\_ENDO\_LAG\_46\_1_t = za_{t-1}
                                                                       (66)
         AUX\_ENDO\_LAG\_59\_1_t = shockn_{t-1}
                                                                       (67)
 AUX\_ENDO\_LAG\_59\_2_t = AUX\_ENDO\_LAG\_59\_1_{t-1}
                                                                       (68)
 AUX\_ENDO\_LAG\_59\_3_t = AUX\_ENDO\_LAG\_59\_2_{t-1}
                                                                       (69)
 AUX\_ENDO\_LAG\_59\_4_t = AUX\_ENDO\_LAG\_59\_3_{t-1}
                                                                       (70)
 AUX\_ENDO\_LAG\_59\_5_t = AUX\_ENDO\_LAG\_59\_4_{t-1}
                                                                       (71)
 AUX\_ENDO\_LAG\_59\_6_t = AUX\_ENDO\_LAG\_59\_5_{t-1}
                                                                       (72)
 AUX\_ENDO\_LAG\_59\_7_t = AUX\_ENDO\_LAG\_59\_6_{t-1}
                                                                       (73)
 AUX\_ENDO\_LAG\_59\_8_t = AUX\_ENDO\_LAG\_59\_7_{t-1}
                                                                       (74)
 AUX\_ENDO\_LAG\_59\_9_t = AUX\_ENDO\_LAG\_59\_8_{t-1}
                                                                       (75)
AUX\_ENDO\_LAG\_59\_10_t = AUX\_ENDO\_LAG\_59\_9_{t-1}
                                                                       (76)
AUX\_ENDO\_LAG\_59\_11_t = AUX\_ENDO\_LAG\_59\_10_{t-1}
                                                                       (77)
AUX\_ENDO\_LAG\_59\_12_t = AUX\_ENDO\_LAG\_59\_11_{t-1}
                                                                       (78)
AUX\_ENDO\_LAG\_59\_13_t = AUX\_ENDO\_LAG\_59\_12_{t-1}
                                                                       (79)
AUX\_ENDO\_LAG\_59\_14_t = AUX\_ENDO\_LAG\_59\_13_{t-1}
                                                                       (80)
AUX\_ENDO\_LAG\_59\_15_t = AUX\_ENDO\_LAG\_59\_14_{t-1}
                                                                       (81)
AUX\_ENDO\_LAG\_59\_16_t = AUX\_ENDO\_LAG\_59\_15_{t-1}
                                                                       (82)
AUX\_ENDO\_LAG\_59\_17_t = AUX\_ENDO\_LAG\_59\_16_{t-1}
                                                                       (83)
AUX\_ENDO\_LAG\_59\_18_t = AUX\_ENDO\_LAG\_59\_17_{t-1}
                                                                       (84)
AUX\_ENDO\_LAG\_59\_19_t = AUX\_ENDO\_LAG\_59\_18_{t-1}
                                                                       (85)
AUX\_ENDO\_LAG\_59\_20_t = AUX\_ENDO\_LAG\_59\_19_{t-1}
                                                                       (86)
AUX\_ENDO\_LAG\_59\_21_t = AUX\_ENDO\_LAG\_59\_20_{t-1}
                                                                       (87)
AUX\_ENDO\_LAG\_59\_22_t = AUX\_ENDO\_LAG\_59\_21_{t-1}
                                                                       (88)
AUX\_ENDO\_LAG\_59\_23_t = AUX\_ENDO\_LAG\_59\_22_{t-1}
                                                                       (89)
AUX\_ENDO\_LAG\_59\_24_t = AUX\_ENDO\_LAG\_59\_23_{t-1}
                                                                       (90)
AUX\_ENDO\_LAG\_59\_25_t = AUX\_ENDO\_LAG\_59\_24_{t-1}
                                                                       (91)
AUX\_ENDO\_LAG\_59\_26_t = AUX\_ENDO\_LAG\_59\_25_{t-1}
                                                                       (92)
AUX\_ENDO\_LAG\_59\_27_t = AUX\_ENDO\_LAG\_59\_26_{t-1}
                                                                       (93)
AUX\_ENDO\_LAG\_59\_28_t = AUX\_ENDO\_LAG\_59\_27_{t-1}
                                                                       (94)
```