Table 1: Endogenous

Variable	₽TEX	Description
r	r	r
rk	rk	rk
W	w	W
b	b	b
у	y	У
varpi	varpi	varpi
S	s	\mathbf{s}
inv	inv	inv
С	c	C
CW	cw	cw
cwper	cwper	cwper
cr	cr	cr
crper	crper	crper
tauw	tauw	tauw
N	N	N
stoyw	stoyw	stoyw
PiF	PiF	PiF
Tw	Tw	Tw
hw	hw	hw
Dr	Dr	Dr
Dw	Dw	Dw
ер	ep	ep
varsig	varsig	varsig
zetar	zetar	zetar
zetay	zetay	zetay
gw	gw	gw
g	g	g
gE	gE	${ m gE}$
iy	iy	iy
gpc	gpc	gpc
gy	gy	gy
ZZ	zz	ZZ
far	far	far
faw	faw	faw
dr	dr	$\mathrm{d}\mathrm{r}$
dw	dw	$d\mathbf{w}$
mu	mu	mu
k	k	k
u	u	u
del	del	del
delprime	delprime	delprime
gM	gM	gM
V	v	V
j	j	j

 $Table\ 1-Continued$

Variable	IATEX	Description
lam	lam	lam
gA	gA	gA
za	za	za
PiA	PiA	PiA
PiRD	PiRD	PiRD
fa	fa	fa
n	n	n
gn	gn	gn
gamma	gamma	gamma
er	er	er
ey	ey	ey
en	en	en
psi	psi	psi
shockr	shockr	shockr
shocky	shocky	shocky
shockn	shockn	shockn
fert	fert	fert
omegay	omegay	omegay
shareW	shareW	shareW
shareR	shareR	shareR
AUX_ENDO_LAG_37_1	AUX_ENDO_LAG_37_1	AUX_ENDO_LAG_37_1
AUX_ENDO_LAG_46_1	AUX_ENDO_LAG_46_1	AUX_ENDO_LAG_46_1
AUX_ENDO_LAG_59_1	AUX_ENDO_LAG_59_1	AUX_ENDO_LAG_59_1
AUX_ENDO_LAG_59_2	AUX_ENDO_LAG_59_2	AUX_ENDO_LAG_59_2
AUX_ENDO_LAG_59_3	AUX_ENDO_LAG_59_3	AUX_ENDO_LAG_59_3
AUX_ENDO_LAG_59_4	AUX_ENDO_LAG_59_4	AUX_ENDO_LAG_59_4
AUX_ENDO_LAG_59_5	AUX_ENDO_LAG_59_5	AUX_ENDO_LAG_59_5
AUX_ENDO_LAG_59_6	AUX_ENDO_LAG_59_6	AUX_ENDO_LAG_59_6
AUX_ENDO_LAG_59_7	AUX_ENDO_LAG_59_7	AUX_ENDO_LAG_59_7
AUX_ENDO_LAG_59_8	AUX_ENDO_LAG_59_8	AUX_ENDO_LAG_59_8
AUX_ENDO_LAG_59_9	AUX_ENDO_LAG_59_9	AUX_ENDO_LAG_59_9
AUX_ENDO_LAG_59_10	AUX_ENDO_LAG_59_10	AUX_ENDO_LAG_59_10
AUX_ENDO_LAG_59_11	AUX_ENDO_LAG_59_11	AUX_ENDO_LAG_59_11
AUX_ENDO_LAG_59_12	AUX_ENDO_LAG_59_12	AUX_ENDO_LAG_59_12
AUX_ENDO_LAG_59_13	AUX_ENDO_LAG_59_13	AUX_ENDO_LAG_59_13
AUX_ENDO_LAG_59_14	AUX_ENDO_LAG_59_14	AUX_ENDO_LAG_59_14
AUX_ENDO_LAG_59_15	AUX_ENDO_LAG_59_15	AUX_ENDO_LAG_59_15 AUX_ENDO_LAG_59_16
AUX_ENDO_LAG_59_16	AUX_ENDO_LAG_59_16	AUX_ENDO_LAG_59_17
AUX_ENDO_LAG_59_17	AUX_ENDO_LAG_59_17	AUX_ENDO_LAG_59_17 AUX_ENDO_LAG_59_18
AUX_ENDO_LAG_59_18	AUX_ENDO_LAG_59_18	
AUX_ENDO_LAG_59_19 AUX_ENDO_LAG_59_20	AUX_ENDO_LAG_59_19 AUX_ENDO_LAG_59_20	AUX_ENDO_LAG_59_19 AUX_ENDO_LAG_59_20
AUX_ENDO_LAG_59_20 AUX_ENDO_LAG_59_21	AUX_ENDO_LAG_59_20 AUX_ENDO_LAG_59_21	AUX_ENDO_LAG_59_21
AUX_ENDU_LAG_59_21 AUX_ENDO_LAG_59_22	AUX_ENDO_LAG_59_21 AUX_ENDO_LAG_59_22	AUX_ENDO_LAG_59_21 AUX_ENDO_LAG_59_22
AUX_ENDO_LAG_59_23	$AUX_ENDO_LAG_59_23$	AUX_ENDO_LAG_59_23

Table 1 – Continued

Variable	Ŀ₽ŢĘX	Description
AUX_ENDO_LAG_59_24	$AUX_ENDO_LAG_59_24$	AUX_ENDO_LAG_59_24
AUX_ENDO_LAG_59_25	$AUX_ENDO_LAG_59_25$	AUX_ENDO_LAG_59_25
AUX_ENDO_LAG_59_26	$AUX_ENDO_LAG_59_26$	AUX_ENDO_LAG_59_26
AUX_ENDO_LAG_59_27	$AUX_ENDO_LAG_59_27$	AUX_ENDO_LAG_59_27
AUX_ENDO_LAG_59_28	$AUX_ENDO_LAG_59_28$	AUX_ENDO_LAG_59_28

Table 2: Exogenous

Variable	ĿTEX	Description
delall	delall	delall

Table 3: Parameters

Variable	ĿTEX	Description
SHINNOVW	SHINNOVW	SHINNOVW
YINNOVSH	YINNOVSH	YINNOVSH
OMEGAR	OMEGAR	OMEGAR
ZETAYSS	ZETAYSS	ZETAYSS
ZETARSS	ZETARSS	ZETARSS
REPLACSS	REPLACSS	REPLACSS
RHOYW	RHOYW	RHOYW
LAMY	LAMY	LAMY
PSISS	PSISS	PSISS
GSS	GSS	GSS
PERS	PERS	PERS
RATIODEL	RATIODEL	RATIODEL
OMEGAYSS	OMEGAYSS	OMEGAYSS
RHOU	RHOU	RHOU
BBETA	BBETA	BBETA
ALPHA	ALPHA	ALPHA
GAMMAI	GAMMAI	GAMMAI
VARNU	VARNU	VARNU
BMEGA	BMEGA	BMEGA
CHI	CHI	CHI
RHO	RHO	RHO
PHI	PHI	PHI
ELASMU	ELASMU	ELASMU
ELASLAM	ELASLAM	ELASLAM
DELPRIMESS	DELPRIMESS	DELPRIMESS
DELSS	DELSS	DELSS

 $Table\ 3-Continued$

Variable	Ŀ₽ŢĘX	Description
MUSS	MUSS	MUSS
LAMSS	LAMSS	LAMSS
USS	USS	USS
VARPISS	VARPISS	VARPISS
ZASS	ZASS	ZASS
KSS	KSS	KSS
NSS	NSS	NSS
GAMMASS	GAMMASS	GAMMASS
RHOE	RHOE	RHOE
CHIE	CHIE	CHIE
$gn_{-}1$	gn_1	$\mathrm{gn}1$
gn_2	gn_2	$\mathrm{gn}2$
gn_3	gn_3	$gn_{-}3$
gn_4	gn_4	gn_{-4}
gn_5	gn_5	$\mathrm{gn}_{-}5$
$gn_{-}6$	gn _6	$\mathrm{gn}_{-}6$
gn_7	gn_7	$\mathrm{gn}_{-}7$
gn8	gn _8	gn8
gn_9	gn_9	$gn_{-}9$
gn_10	gn10	$gn_{-}10$
$gn_{-}11$	gn11	gn_11
$gn_{-}12$	gn_12	$gn_{-}12$
gn_13	gn_13	gn_13
$gn_{-}14$	gn_14	$gn_{-}14$
gn_15	gn_15	$gn_{-}15$
$gn_{-}16$	gn_16	$gn_{-}16$
$gn_{-}17$	gn_17	gn_17
$gn_{-}18$	gn18	$gn_{-}18$
$gn_{-}19$	gn_19	gn_19
gn_20	gn_20	$gn_{-}20$
gn_21	gn_21	gn_21
gn_22	gn_22	gn_22
gn_23	gn_23	gn_23
gn_24	gn_24	gn_24
gn_25	gn_25	gn_25
gn_26	gn_26	gn_26
gn_27	gn_27	gn_27
gn_28	gn_28	gn_28
gn_29	gn29	gn_29
gn_30	$gn_{-}30$	gn_30
$\mathtt{dws}_{-}1$	dws_1	dws_{-1}
dws_2	dws_2	dws_2
dws_3	dws_3	dws_3
${\tt dws_4}$	dws_4	dws_4
$dws_{-}5$	dws_5	dws_{-5}

Table 3 – Continued

	Table 3 – Continu	
Variable	Ŀ₽ŢĘX	Description
dws_6	dws_6	dws_6
$\mathtt{dws}_{-}7$	dws_7	$\mathrm{dws}_{-}7$
${\tt dws_8}$	dws_8	dws_{-8}
dws_9	dws_9	$dws_{-}9$
$dws_{-}10$	dws_10	$\mathrm{dws}\mbox{-}10$
$dws_{-}11$	dws_11	dws_11
$dws_{-}12$	dws_12	dws_12
dws_13	dws_13	dws_13
${\tt dws_14}$	dws_14	dws_14
dws_15	dws_15	dws_15
$dws_{-}16$	dws_16	dws_16
dws_17	dws_17	dws_17
dws_18	dws_18	dws_18
dws_19	dws_19	dws_19
dws_20	dws_20	dws_20
dws_21	dws_21	$\mathrm{dws}\-21$
dws_22	dws_22	dws_22
dws_23	dws_23	$\mathrm{dws}\-23$
dws_24	dws_24	dws_24
dws_25	dws_25	dws_25
dws_26	dws_26	dws_26
dws_27	dws_27	dws _27
dws_28	dws_28	dws 28
dws_29	dws_29	dws _29
dws_30	dws_30	dws_30
$\mathtt{drs}_{-}1$	drs_1	drs -1
\mathtt{drs}_2	drs_2	drs_{-2}
drs_3	drs_3	drs_3
\mathtt{drs}_4	drs_4	drs_4
drs_5	drs_5	drs_{-5}
drs_6	drs_6	drs_{-6}
$drs_{-}7$	drs_{-7}	drs_{-7}
drs_8	drs_8	drs8
drs_9	drs_9	$drs_{-}9$
\mathtt{drs}_10	drs_10	drs_10
$\mathtt{drs}_{-}11$	drs_11	$drs_{-}11$
drs_12	drs_12	drs_12
drs_13	$drs_{-}13$	drs_13
drs_14	$drs_{-}14$	$drs_{-}14$
drs_15	drs_15	$drs_{-}15$
drs_16	$drs_{-}16$	$drs_{-}16$
drs_17	drs_17	drs_17
drs_18	$drs_{-}18$	$drs_{-}18$
drs_19	$drs_{-}19$	$drs_{-}19$
drs_20	drs_20	$\mathrm{drs}\-20$

Table 3 – Continued

Variable	ĿTEX	Description
drs_21	drs_21	drs_21
drs_22	drs_22	drs_22
drs_23	drs_23	drs_23
\mathtt{drs}_24	drs_24	$\mathrm{drs}\-24$
drs_25	drs_25	$\mathrm{drs}\-25$
drs_26	drs_26	$\mathrm{drs}\-26$
drs_27	drs_27	$\mathrm{drs}\-27$
drs_28	drs_28	$\mathrm{drs}\-28$
drs_29	drs_29	drs_29
\mathtt{drs}_30	drs_30	drs_30

Table 4: Parameter Values

Parameter	Value
SHINNOVW	0.010
YINNOVSH	0.060
OMEGAR	0.975
ZETAYSS	0.700
ZETARSS	0.227
REPLACSS	0.756
RHOYW	0.512
LAMY	0.049
PSISS	0.708
GSS	1.046
PERS	0.900
RATIODEL	0.333
OMEGAYSS	0.950
RHOU	-3.000
BBETA	0.960
ALPHA	0.333
GAMMAI	0.500
VARNU	1.667
BMEGA	0.128
CHI	64.671
RHO	0.900
PHI	0.850
ELASMU	-1.000
ELASLAM	0.855
DELPRIMESS	0.301
DELSS	0.080
MUSS	1.100
LAMSS	0.100
USS	0.800
VARPISS	0.135
ZASS	3.126
KSS	0.658
NSS	1.010
GAMMASS	0.900
RHOE	0.900
CHIE	1689.513
gn_{-1}	1.009
gn_{-2}	1.009
gn_{-3}	1.009
gn_{-4}	1.009
$gn_{-}5$	1.009
$gn_{-}6$	1.008
gn_7	1.008

Table 4 – Continued

Table 4 – Co	ontinued
Parameter	Value
gn_8	1.007
gn_9	1.007
$gn_{-}10$	1.007
gn11	1.006
gn12	1.006
gn_13	1.006
gn_14	1.006
gn_15	1.006
gn_16	1.007
gn_17	1.007
gn_18	1.007
gn_19	1.007
gn_20	1.007
gn_21	1.007
gn22	1.007
gn23	1.007
gn24	1.007
gn_25	1.007
gn26	1.007
gn_27	1.007
gn_28	1.007
gn29	1.007
$gn_{-}30$	1.007
dws_{-1}	-0.002
dws_2	-0.002
dws_3	-0.002
dws_4	-0.002
dws_5	-0.002
dws_6	-0.002
$dws_7 \ dws_8$	-0.001 -0.001
dws_9	-0.001
dws_9 dws_10	-0.001
dws_10 dws_11	-0.002
dws_11	-0.002
$dws_{-}13$	-0.003
dws_14	-0.003
dws_15	-0.002
dws_16	-0.004
dws _17	-0.003
$dws_{-}18$	-0.003
$dws_{-}19$	-0.003
dws_20	-0.002
dws_21	-0.002

Table 4 – Continued

Parameter	Value
dws_22	-0.002
dws_23	-0.002
dws_24	-0.002
dws_25	-0.002
dws_26	-0.002
dws_27	-0.002
dws_28	-0.002
dws_29	-0.002
dws_30	-0.002
drs_1	0.002
drs_2	0.003
drs_3	0.004
drs_4	0.004
drs_5	0.004
drs_6	0.004
drs_7	0.004
drs_8	0.004
drs_9	0.004
drs_10	0.005
drs_11	0.005
drs_12	0.005
drs_13	0.005
drs_14	0.005
drs_15	0.005
drs_16	0.005
drs_17	0.005
drs_18	0.004
drs_19	0.004
drs_20	0.003
drs_21	0.003
drs_22	0.003
drs_23	0.002
drs_24	0.002
drs_25	0.002
drs_26	0.002
drs_27	0.002
drs_28	0.001
drs_29	0.001
drs_30	0.001

$$hw_t = w_t + \frac{OMEGAR}{r_t z z_t} \frac{g_{t+1}}{g w_t} h w_{t+1} \tag{1}$$

$$Tw_t = tauw_t + \frac{OMEGAR}{r_t z z_t} \frac{g_{t+1}}{g w_t} Tw_{t+1}$$
(2)

$$Dr_t = dr_t + \frac{g_{t+1} Dr_{t+1} gamma_t zetar_{t-1}}{qw_t r_t zetar_t}$$
(3)

$$Dw_{t} = dw_{t} + \frac{OMEGAR}{r_{t}zz_{t}} \frac{g_{t+1}}{gw_{t}} Dw_{t+1} + Dr_{t+1} \frac{(1 - OMEGAR) ep_{t+1}^{\frac{RHOU-1}{RHOU}}}{r_{t}zz_{t}} \frac{g_{t+1}}{gw_{t}zetar_{t}}$$
(4)

$$cw_t = varsig_t \left(Dw_t + hw_t + \frac{r_{t-1} faw_{t-1}}{g_t} - Tw_t \right)$$
 (5)

$$cr_t = varsig_t ep_t \left(Dr_t + \frac{r_{t-1} far_{t-1}}{g_t} \right)$$
 (6)

$$1 - varsig_t ep_t = \frac{gamma_t \ (r_t \ BBETA)^{\frac{1}{1 - RHOU}}}{r_t} \frac{varsig_t \ ep_t}{ep_{t+1} \ varsig_{t+1}}$$
 (7)

$$1 - varsig_t = \frac{(zz_t r_t BBETA)^{\frac{1}{1-RHOU}}}{r_t zz_t} \frac{varsig_t}{varsig_{t+1}}$$
(8)

$$zz_t = OMEGAR + (1 - OMEGAR) e_{t+1}^{\frac{RHOU - 1}{RHOU}}$$
(9)

$$cwper_t = cw_t \ (zetar_t + 1 + zetay_t) \tag{10}$$

$$crper_t = \frac{cr_t \left(zetar_t + 1 + zetay_t\right)}{zetar_t} \tag{11}$$

$$gw_t = OMEGAR + (1 - omegay_t) \ zetay_{t-1}$$
 (12)

$$n_t = gw_t \frac{zetay_t}{zetay_{t-1}} \tag{13}$$

$$gw_t zetar_t = 1 - OMEGAR + gamma_t zetar_{t-1}$$
(14)

$$gn_{t} = (gw_{t}zetar_{t} + gw_{t} + zetay_{t-1}n_{t}) (zetay_{t-1} + 1 + zetar_{t-1})^{(-1)}$$
(15)

$$gE_t = \frac{OMEGAR + (1 - omegay_t) \ zetay_{t-1} \ \left(RHOE + \frac{CHIE}{2} \ iy_t^2\right)}{gw_t} \tag{16}$$

$$tauw_t = w_t i y_t \tag{17}$$

$$varsig_{t}^{\frac{(-1)}{RHOU}} = \frac{g_{t+1} iy_{t} CHIE zetay_{t} BBETA varsig_{t+1}^{\frac{(-1)}{RHOU}} \left(1 - omegay_{t+1}\right) w_{t+1}}{n_{t} gE_{t} w_{t} gw_{t}}$$
(18)

$$fert_t = n_t - omegay_t \tag{19}$$

$$(1 - ALPHA) (1 - GAMMAI) = w_t m u_t$$
(20)

$$ALPHA (1 - GAMMAI) = mu_t (rk_t + del_t) \frac{k_{t-1}}{g_t}$$
(21)

$$ALPHA (1 - GAMMAI) = \frac{k_{t-1}}{g_t} mu_t delprime_t u_t$$
 (22)

$$g_t = \frac{mu_t}{mu_{t-1}} g M_t g A_{t-1}^{1-VARNU}$$
 (23)

$$g_{t} = gM_{t}^{GAMMAI} \left(gE_{t-1} gw_{t-1}\right)^{(1-ALPHA)} \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{k_{t-1} u_{t} g_{t-1}}{u_{t-1} AUX_ENDO_LAG_37_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{N_{t}^{mu_{t}-1}}{u_{t-1} AUX_ENDO_LAG_37_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{N_{t}^{mu_{t}-1}}{u_{t-1} AUX_ENDO_LAG_37_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \left(\frac{N_{t}^{mu_{t}-1}}{u_{t-1} AUX_ENDO_LAG_37_1_{t-1}}\right)^{ALPHA} (1-GAMMAI) \frac{N_{t}^{mu_{t}-1}}{N_{t-1}^{mu_{t}-1}} \frac{N_{t}^{mu_{t}-1}}{u_{t-1}^{mu_{t}-1}} \frac{N_{t}^{mu_{t}-1}}{u_{t-1}^{mu$$

$$\frac{mu_t - 1}{mu_t} N_t^{(-mu_t)} = BMEGA v_t \tag{25}$$

$$mu_t = MUSS (1 + ELASMU (N_t - 1))$$
(26)

$$del_t = DELSS + delprime_t (u_t - USS)$$
(27)

$$delprime_{t} = DELPRIMESS + \frac{(u_{t} - USS) \ DELPRIMESS \ RATIODEL}{USS}$$
 (28)

$$\frac{gA_t za_t}{za_{t-1}} = stoyw_t^{RHOYW} CHI \left(\frac{s_t}{psi_t}\right)^{RHO} + PHI$$
 (29)

$$stoyw_{t} = \frac{zetay_{t-1} \left(1 - omegay_{t}\right) YINNOVSH}{zetar_{t-1} + 1 + zetay_{t-1}} + \frac{OMEGAR \left(1 - LAMY\right)}{gn_{t}} stoyw_{t-1} \quad (30)$$

$$gA_t = PHI + PHI \, lam_t \, (za_{t-1} - 1) \tag{31}$$

$$s_{t} = PHI \frac{g_{t+1}}{r_{t}} j_{t+1} \left(1 - \frac{za_{t-1}PHI}{gA_{t}za_{t}} \right)$$
 (32)

$$v_t = \frac{GAMMAI\left(1 - \frac{1}{VARNU}\right)}{mu_t} + \frac{g_{t+1}}{gA_t} \frac{PHI}{r_t} v_{t+1}$$
(33)

$$varpi_{t} = \frac{PHI}{r_{t}} \frac{g_{t+1}}{gA_{t}} za_{t-1} lam_{t} ELASLAM \left(v_{t+1} - \frac{j_{t+1}}{za_{t}}\right)$$

$$(34)$$

$$j_{t} = \frac{PHI}{r_{t}} z a_{t-1} \frac{g_{t+1}}{gA_{t}} \left(lam_{t} v_{t+1} + \frac{j_{t+1} (1 - lam_{t})}{z a_{t}} \right) - varpi_{t}$$
 (35)

$$lam_{t} = LAMSS \left(1 + ELASLAM \left(\frac{varpi_{t} - VARPISS}{VARPISS} - \frac{za_{t-1} - ZASS}{ZASS} - \frac{psi_{t} - PSISS}{PSISS}\right)\right)$$
(36)

$$PiA_{t} = \frac{GAMMAI \left(1 - \frac{1}{VARNU}\right)}{mu_{t}} - PHI j_{t} \left(1 - \frac{PHIAUX_ENDO_LAG_46_1_{t-1}}{gA_{t-1} z a_{t-1}}\right) - \frac{r_{t-1} varpi_{t-1} \left(1 - \frac{1}{AUX_ENDO_LAG_46_1_{t-1}}\right)}{g_{t}}$$

$$(37)$$

$$PiRD_{t} = PHI j_{t} \left(1 - \frac{PHI AUX_ENDO_LAG_46_1_{t-1}}{gA_{t-1} za_{t-1}} \right) - \frac{r_{t-1} s_{t-1}}{g_{t}}$$
(38)

$$psi_t = v_t (39)$$

$$r_t = 1 + rk_{t+1} (40)$$

$$dr_t = \frac{far_{t-1}PiF_t}{fa_{t-1}} \tag{41}$$

$$dw_t = \frac{faw_{t-1}PiF_t}{fa_{t-1}} + SHINNOVW (PiA_t + PiRD_t)$$
(42)

$$b_t = s_t + varpi_t \left(1 - \frac{1}{za_{t-1}}\right) \tag{43}$$

$$PiF_{t} = \frac{k_{t-1}}{g_{t}} \left(1 + rk_{t} \right) + \frac{r_{t-1}b_{t-1}}{g_{t}} - \frac{r_{t-1}fa_{t-1}}{g_{t}} - k_{t} - b_{t}$$

$$+ fa_{t} + (PiA_{t} + PiRD_{t}) \left(1 - SHINNOVW \right)$$

$$(44)$$

$$k_t = \frac{k_{t-1}}{g_t} (1 - del_t) + inv_t \tag{45}$$

$$y_t = 1 - \frac{GAMMAI}{mu_t VARNU} - psi_t N_t BMEGA$$
 (46)

$$y_t = tauw_t + varpi_t \left(1 - \frac{1}{za_{t-1}}\right) + s_t + inv_t + c_t \tag{47}$$

$$c_t = cw_t + cr_t \tag{48}$$

$$fa_t = b_t + k_t \tag{49}$$

$$far_{t} = dr_{t} + \frac{r_{t-1} far_{t-1}}{g_{t}} - cr_{t} + (1 - OMEGAR) \left(dw_{t} + w_{t} + \frac{r_{t-1} faw_{t-1}}{g_{t}} - cw_{t} - tauw_{t} \right)$$
(50)

$$fa_t = far_t + faw_t (51)$$

$$gpc_t = \frac{g_{t-1} \frac{y_t}{y_{t-1}}}{gn_{t-1}} \tag{52}$$

$$gy_t = g_t \frac{y_t}{y_{t-1}} \tag{53}$$

$$gn_t = NSS + en_t (54)$$

$$shareW_t = \frac{1}{zetar_t + 1 + zetay_t} \tag{55}$$

$$shareR_t = \frac{zetar_t}{zetar_t + 1 + zetay_t} \tag{56}$$

$$\frac{1}{zetar_t + 1 + zetay_t} = \frac{1}{1 + ZETAYSS + ZETARSS} + ey_t \tag{57}$$

$$\frac{zetar_t}{zetar_t + 1 + zetay_t} = \frac{ZETARSS}{1 + ZETAYSS + ZETARSS} + er_t \tag{58}$$

```
en_t = shockn_t (gn_1 - NSS) + shockn_{t-1} (gn_2 - NSS)
           + (gn_3 - NSS) AUX_ENDO_LAG_59_1_{t-1} + (gn_4 - NSS) AUX_ENDO_LAG_59_2_{t-1}
           + (gn_5 - NSS) AUX_ENDO_LAG_59_3_{t-1} + (gn_6 - NSS) AUX_ENDO_LAG_59_4_{t-1}
           +(qn_{-}7-NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}5_{t-1}+(qn_{-}8-NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}6_{t-1}
           +(gn\_9-NSS) AUX\_ENDO\_LAG\_59\_7_{t-1}+(gn\_10-NSS) AUX\_ENDO\_LAG\_59\_8_{t-1}
           + (gn_11 - NSS) AUX_ENDO_LAG_59_9_{t-1}
           + (gn_12 - NSS) AUX_ENDO_LAG_59_10_{t-1}
           + (qn_13 - NSS) AUX_ENDO_LAG_59_11_{t-1}
           + (qn_14 - NSS) AUX_ENDO_LAG_59_12_{t-1}
           + (gn_{-}15 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}13_{t-1}
           + (qn_16 - NSS) AUX_ENDO_LAG_59_14_{t-1}
           + (gn_{-}17 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}15_{t-1}
           + (qn_18 - NSS) AUX_ENDO_LAG_59_16_{t-1}
           + (qn_{-}19 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}17_{t-1}
           + (qn_20 - NSS) AUX_ENDO_LAG_59_18_{t-1}
           + (gn_21 - NSS) AUX_ENDO_LAG_59_19_{t-1}
           + (gn_{-}22 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}20_{t-1}
           + (gn_2 - NSS) AUX_ENDO_LAG_59_21_{t-1}
           + (qn_24 - NSS) AUX_ENDO_LAG_59_22_{t-1}
           + (gn_{-}25 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}23_{t-1}
           + (qn_{-}26 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}24_{t-1}
           + (gn_{27} - NSS) AUX_{ENDO}_{LAG_{59}_{25}_{t-1}}
           + (qn_28 - NSS) AUX_ENDO_LAG_59_26_{t-1}
           + (qn_{-}29 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}27_{t-1}
           + (gn_{-}30 - NSS) AUX_{-}ENDO_{-}LAG_{-}59_{-}28_{t-1}
                                                                                                                                                                               (59)
                                                                              er_t = shockr_t
                                                                                                                                                                               (60)
                                                                              ey_t = shocky_t
                                                                                                                                                                               (61)
     shocky_t = shocky_{t-1} + delall_t dws_1 + delall_{t-1} dws_2 + delall_{t-2} dws_3
                         + delall_{t-3} dws_4 + delall_{t-4} dws_5 + delall_{t-5} dws_6 + delall_{t-6} dws_7
                         + delall_{t-7} dws_8 + delall_{t-8} dws_9 + delall_{t-9} dws_10 + delall_{t-10} dws_111
                         + delall_{t-11} dws_12 + delall_{t-12} dws_13 + delall_{t-13} dws_14 + delall_{t-14} dws_15
                                                                                                                                                                               (62)
                         + delall_{t-15} dws_{-16} + delall_{t-16} dws_{-17} + delall_{t-17} dws_{-18} + delall_{t-18} dws_{-19}
                         + delall_{t-19} dws_20 + delall_{t-20} dws_21 + delall_{t-21} dws_22 + delall_{t-22} dws_23
                         + delall_{t-23} dws_2 + delall_{t-24} dws_2 + delall_{t-25} dws_2 + delall_{t-26} dws_
                         + delall_{t-27} dws_2 + delall_{t-28} dws_2 + delall_{t-29} dws_3 = 30
          shockr_t = delall_t dws_1 + shockr_{t-1} + delall_{t-1} drs_2 + delall_{t-2} drs_3
                              + delall_{t-3} drs_{-4} + delall_{t-4} drs_{-5} + delall_{t-5} drs_{-6} + delall_{t-6} drs_{-7}
                              + delall_{t-7} drs_{-8} + delall_{t-8} drs_{-9} + delall_{t-9} drs_{-10} + delall_{t-10} drs_{-11}
                              + delall_{t-11} drs_{-1}2 + delall_{t-12} drs_{-1}3 + delall_{t-13} drs_{-1}4 + delall_{t-14} drs_{-1}5
                                                                                                                                                                               (63)
                              + delall_{t-15} drs_{-16} + delall_{t-16} drs_{-17} + delall_{t-17} drs_{-18} + delall_{t-18} drs_{-19}
                              + delall_{t-19} drs_{-}20 + delall_{t-20} drs_{-}21 + delall_{t-21} drs_{-}22 + delall_{t-22} drs_{-}23
                              + delall_{t-23} drs_{-}24 + delall_{t-24} drs_{-}25 + delall_{t-25} drs_{-}26 + delall_{t-26} drs_{-}27
                              + delall_{t-27} drs_{-28} + delall_{t-28} drs_{-29} + delall_{t-29} drs_{-30}
```

```
shockn_t = delall_t
                                                                       (64)
            AUX\_ENDO\_LAG\_37\_1_t = k_{t-1}
                                                                       (65)
            AUX\_ENDO\_LAG\_46\_1_t = za_{t-1}
                                                                       (66)
         AUX\_ENDO\_LAG\_59\_1_t = shockn_{t-1}
                                                                       (67)
 AUX\_ENDO\_LAG\_59\_2_t = AUX\_ENDO\_LAG\_59\_1_{t-1}
                                                                       (68)
 AUX\_ENDO\_LAG\_59\_3_t = AUX\_ENDO\_LAG\_59\_2_{t-1}
                                                                       (69)
 AUX\_ENDO\_LAG\_59\_4_t = AUX\_ENDO\_LAG\_59\_3_{t-1}
                                                                       (70)
 AUX\_ENDO\_LAG\_59\_5_t = AUX\_ENDO\_LAG\_59\_4_{t-1}
                                                                       (71)
 AUX\_ENDO\_LAG\_59\_6_t = AUX\_ENDO\_LAG\_59\_5_{t-1}
                                                                       (72)
 AUX\_ENDO\_LAG\_59\_7_t = AUX\_ENDO\_LAG\_59\_6_{t-1}
                                                                       (73)
 AUX\_ENDO\_LAG\_59\_8_t = AUX\_ENDO\_LAG\_59\_7_{t-1}
                                                                       (74)
 AUX\_ENDO\_LAG\_59\_9_t = AUX\_ENDO\_LAG\_59\_8_{t-1}
                                                                       (75)
AUX\_ENDO\_LAG\_59\_10_t = AUX\_ENDO\_LAG\_59\_9_{t-1}
                                                                       (76)
AUX\_ENDO\_LAG\_59\_11_t = AUX\_ENDO\_LAG\_59\_10_{t-1}
                                                                       (77)
AUX\_ENDO\_LAG\_59\_12_t = AUX\_ENDO\_LAG\_59\_11_{t-1}
                                                                       (78)
AUX\_ENDO\_LAG\_59\_13_t = AUX\_ENDO\_LAG\_59\_12_{t-1}
                                                                       (79)
AUX\_ENDO\_LAG\_59\_14_t = AUX\_ENDO\_LAG\_59\_13_{t-1}
                                                                       (80)
AUX\_ENDO\_LAG\_59\_15_t = AUX\_ENDO\_LAG\_59\_14_{t-1}
                                                                       (81)
AUX\_ENDO\_LAG\_59\_16_t = AUX\_ENDO\_LAG\_59\_15_{t-1}
                                                                       (82)
AUX\_ENDO\_LAG\_59\_17_t = AUX\_ENDO\_LAG\_59\_16_{t-1}
                                                                       (83)
AUX\_ENDO\_LAG\_59\_18_t = AUX\_ENDO\_LAG\_59\_17_{t-1}
                                                                       (84)
AUX\_ENDO\_LAG\_59\_19_t = AUX\_ENDO\_LAG\_59\_18_{t-1}
                                                                       (85)
AUX\_ENDO\_LAG\_59\_20_t = AUX\_ENDO\_LAG\_59\_19_{t-1}
                                                                       (86)
AUX\_ENDO\_LAG\_59\_21_t = AUX\_ENDO\_LAG\_59\_20_{t-1}
                                                                       (87)
AUX\_ENDO\_LAG\_59\_22_t = AUX\_ENDO\_LAG\_59\_21_{t-1}
                                                                       (88)
AUX\_ENDO\_LAG\_59\_23_t = AUX\_ENDO\_LAG\_59\_22_{t-1}
                                                                       (89)
AUX\_ENDO\_LAG\_59\_24_t = AUX\_ENDO\_LAG\_59\_23_{t-1}
                                                                       (90)
AUX\_ENDO\_LAG\_59\_25_t = AUX\_ENDO\_LAG\_59\_24_{t-1}
                                                                       (91)
AUX\_ENDO\_LAG\_59\_26_t = AUX\_ENDO\_LAG\_59\_25_{t-1}
                                                                       (92)
AUX\_ENDO\_LAG\_59\_27_t = AUX\_ENDO\_LAG\_59\_26_{t-1}
                                                                       (93)
AUX\_ENDO\_LAG\_59\_28_t = AUX\_ENDO\_LAG\_59\_27_{t-1}
                                                                       (94)
```