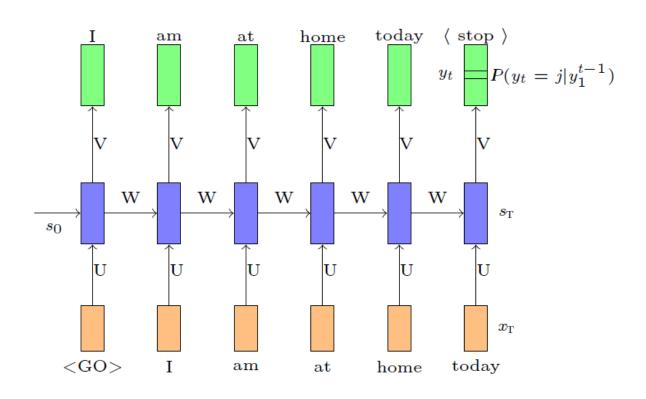
Encoder Decoder Models

DSE 5251 DEEP LEARNING

Rohini R Rao & Abhilash K Pai

Department of Data Science and Computer Applications
MIT Manipal

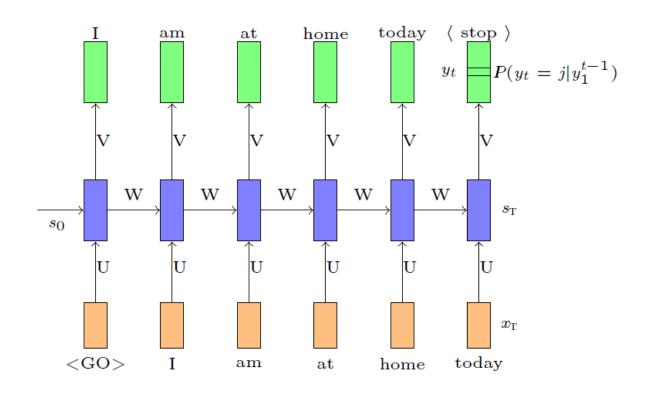
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Given the t-i words predict the tth word



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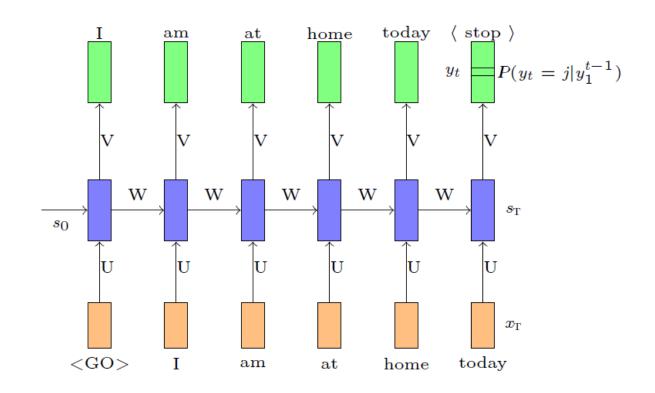


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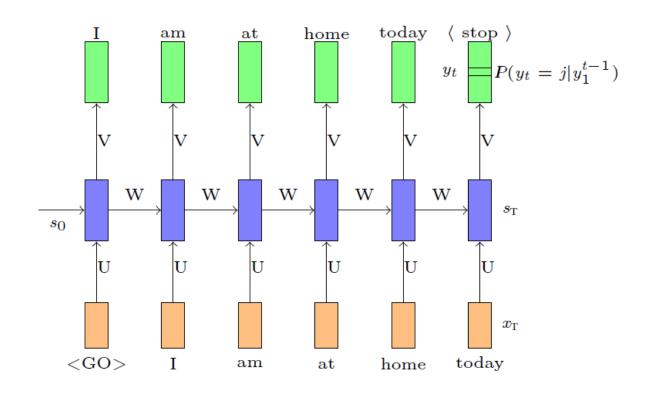
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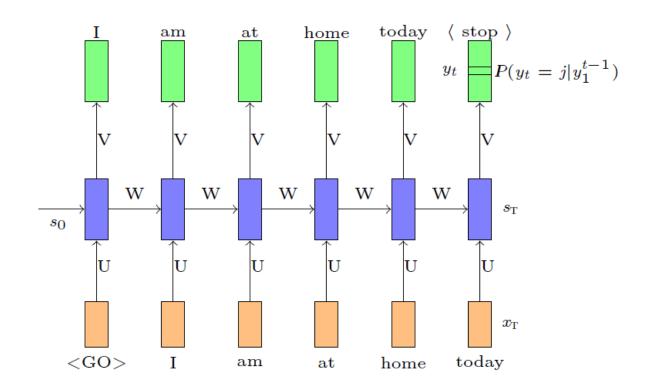
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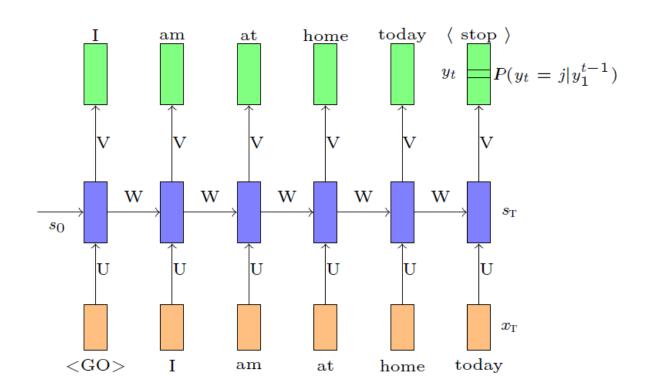
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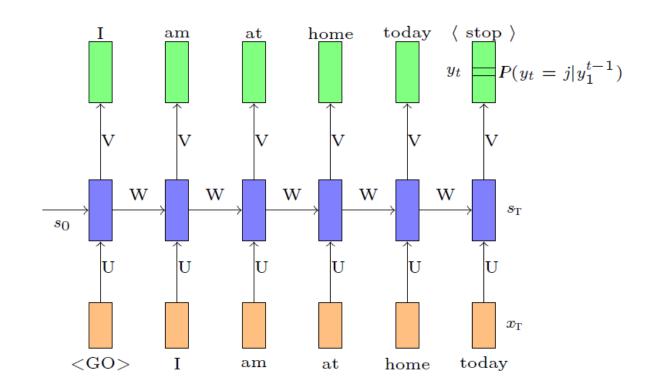
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Using an RNN we will compute this as:



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 Given the t-i words predict the tth word

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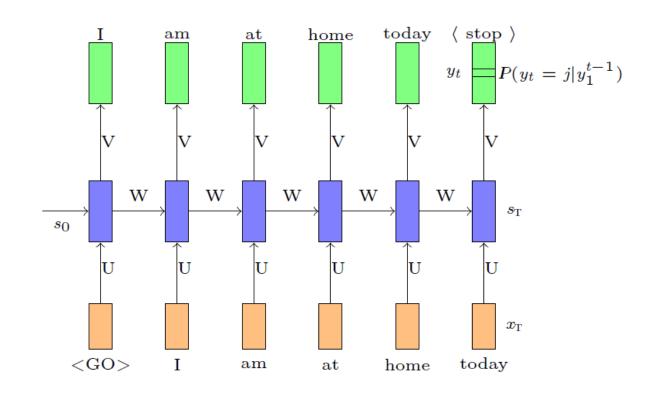
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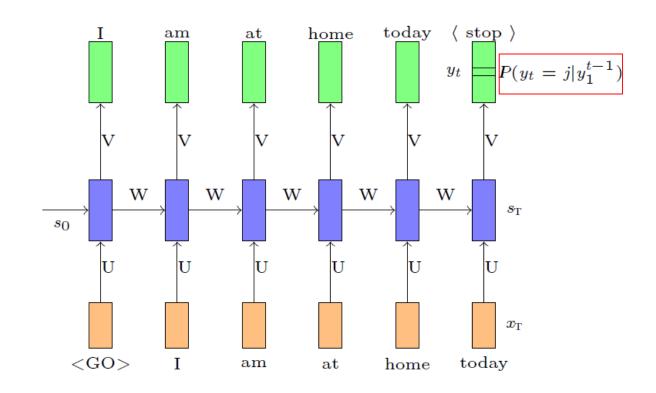
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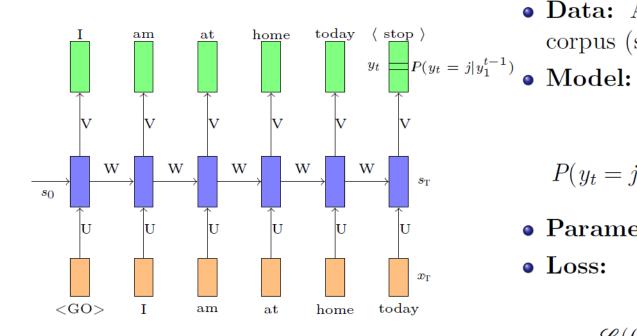
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Data:

India, officially the Republic of India, is a country in South Asia. It is the seventh-largest country by area,

• Data: All sentences from any large corpus (say wikipedia)

$$s_t = \sigma(Ws_{t-1} + Ux_t + b)$$
$$P(y_t = j|y_1^{t-1}) = softmax(Vs_t + c)_j$$

- Parameters: U, V, W, b, c
- Loss:

$$\mathcal{L}(\theta) = \sum_{t=1}^{T} \mathcal{L}_t(\theta)$$
$$\mathcal{L}_t(\theta) = -\log P(y_t = \ell_t | y_1^{t-1})$$

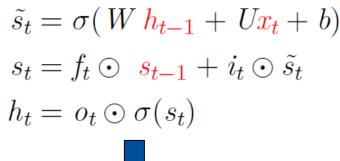
where ℓ_t is the true word at time step

Shorthand notations:

$$s_t = \sigma(U x_t + W s_{t-1} + b)$$

$$s_{t} = \sigma(U x_{t} + W s_{t-1} + b) \qquad \tilde{s}_{t} = \sigma(W(o_{t} \odot s_{t-1}) + U x_{t} + b) \qquad \tilde{s}_{t} = \sigma(W h_{t-1} + U x_{t} + b)$$

$$s_{t} = i_{t} \odot s_{t-1} + (1 - i_{t}) \odot \tilde{s}_{t} \qquad s_{t} = f_{t} \odot s_{t-1} + i_{t} \odot \tilde{s}_{t}$$







$$s_t = \text{RNN}(s_{t-1}, x_t)$$

$$s_t = \text{GRU}(s_{t-1}, x_t)$$

$$h_t, s_t = \text{LSTM}(\ h_{t-1}, s_{t-1}, x_t)$$

Task: generate a sentence given an image

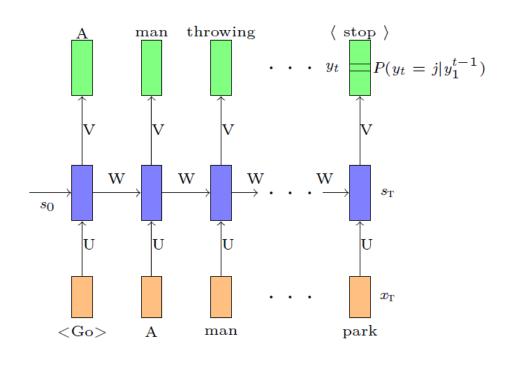


A man throwing a frisbee in a park

We are now interested in $P(y_t|y_1^{t-1}, I)$ instead of $P(y_t|y_1^{t-1})$ where I is an image

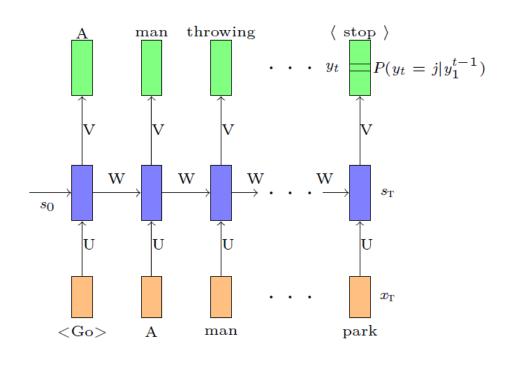
• Earlier we modeled $P(y_t|y_1^{t-1})$ as

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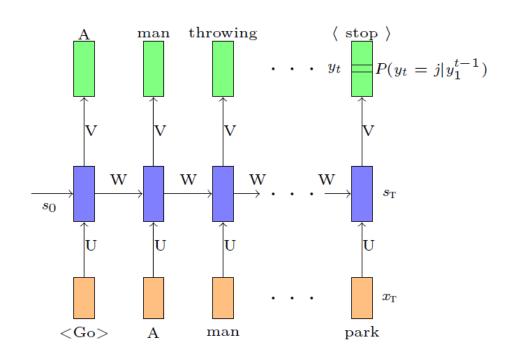
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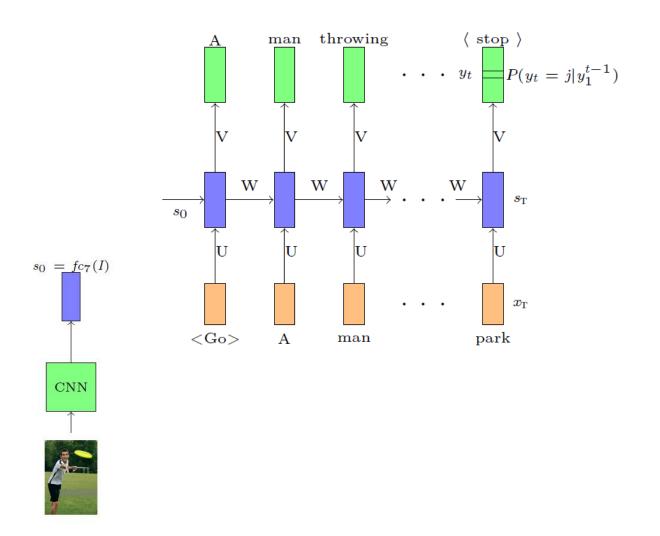
• Where s_t was a state capturing all the previous words



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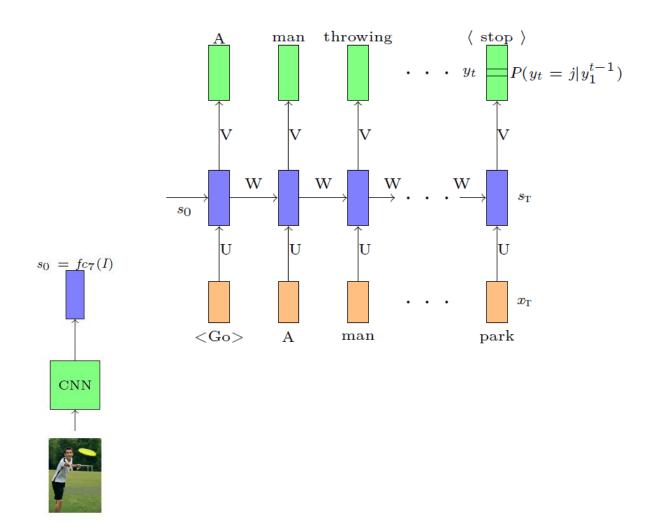
- Where s_t was a state capturing all the previous words
- We could now model $P(y_t = j | y_1^{t-1}, I)$ as $P(y_t = j | s_t, f_{c_7}(I))$



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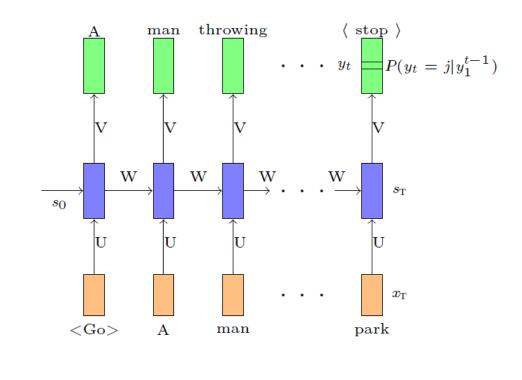
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- where $fc_7(I)$ is the representation obtained from the fc_7 layer of an image



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There are many ways of making $P(y_t = j)$ conditional on $f_{c7}(I)$

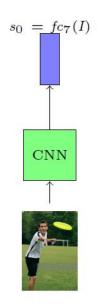
Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras

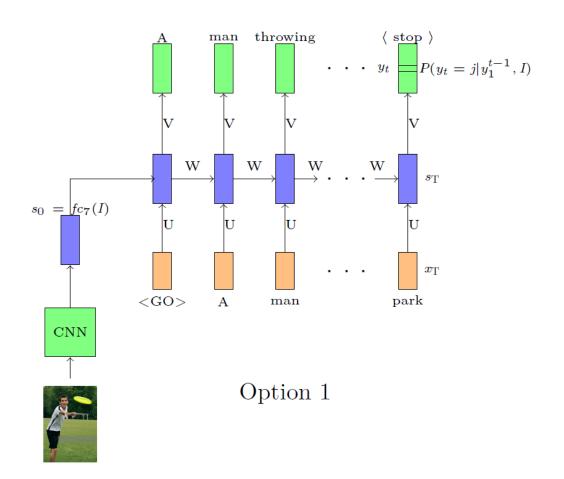
 $s_0 = \underline{f}c_7(I)$

CNN

Option 1: Set
$$s_0 = f_{c_7}(I)$$

Now s_0 and hence all subsequent s_t 's depend on $f_{c_7}(I)$



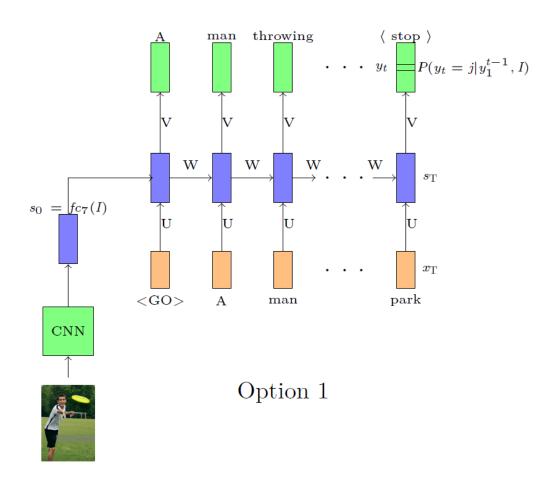


Option 1: Set $s_0 = f_{c_7}(I)$

Now s_0 and hence all subsequent s_t 's depend on $f_{c_7}(I)$

We can thus say that $P(y_t = j)$ depends on $f_{c_7}(I)$

In other words, we are computing $P(y_t = j | s_t, f_{c_7}(I))$

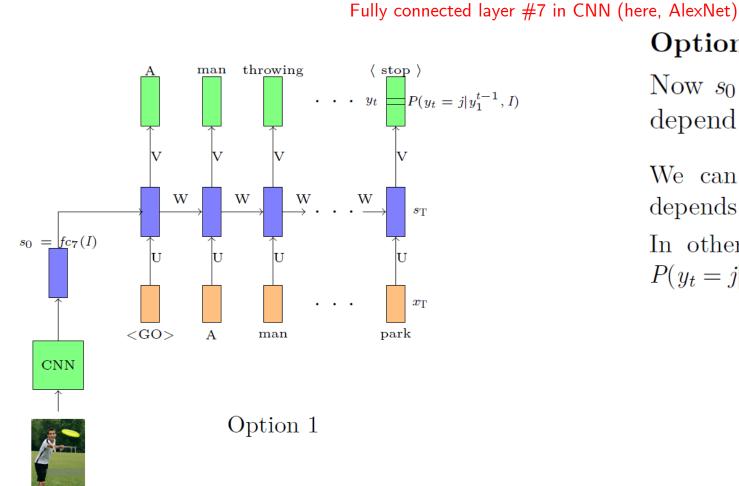


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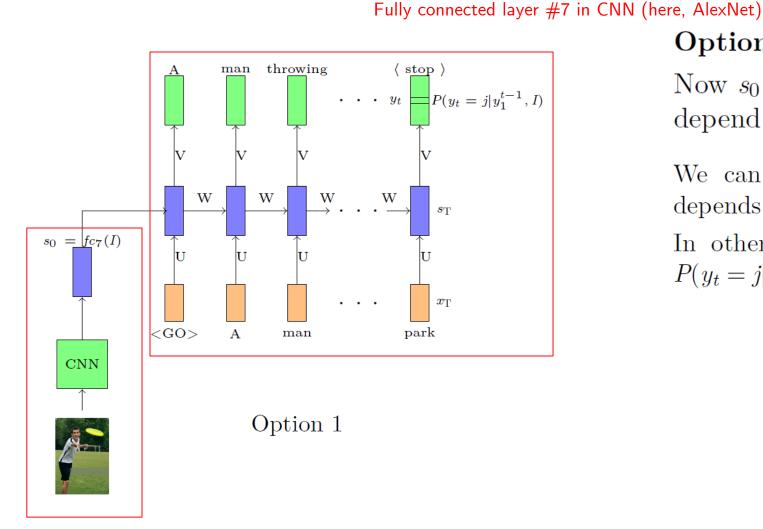


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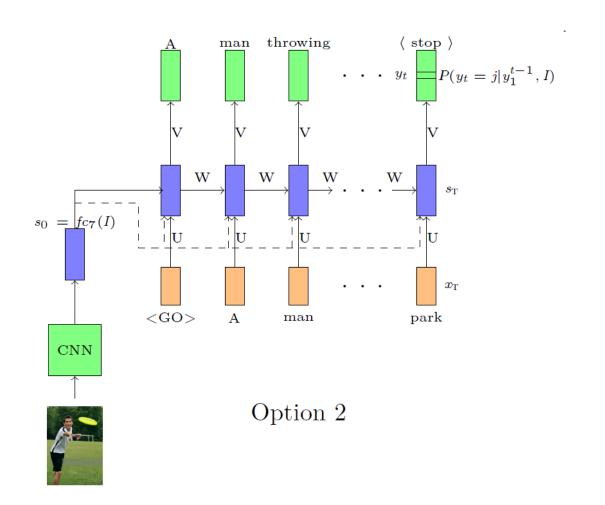


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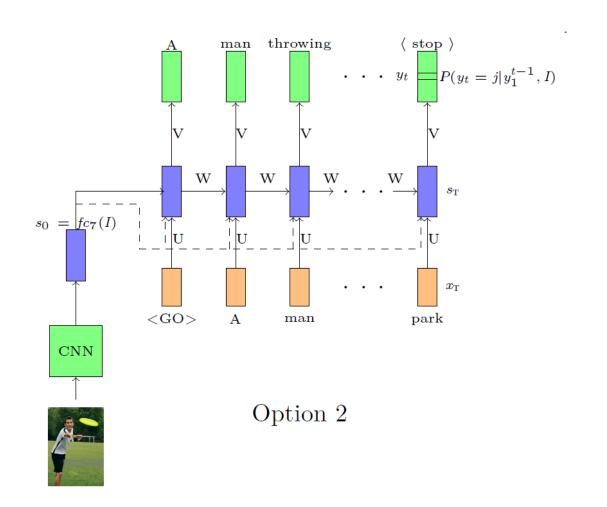
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Option 2: Another more explicit way of doing this is to compute

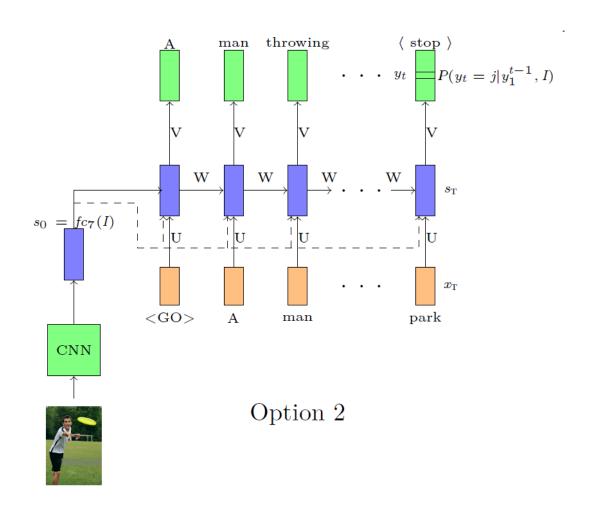
$$s_t = RNN(s_{t-1}, [x_t, f_{c_7}(I)])$$



Option 2: Another more explicit way of doing this is to compute

$$s_t = RNN(s_{t-1}, [x_t, f_{c_7}(I)])$$

In other words we are explicitly using $f_{c_7}(I)$ to compute s_t and hence $P(y_t = j)$

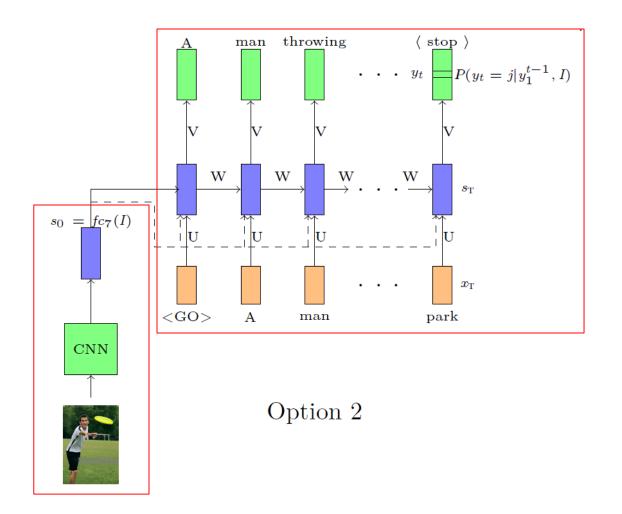


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The o/p of CNN is concatenated with the input embedding and then fed to the RNN as input at each time step.

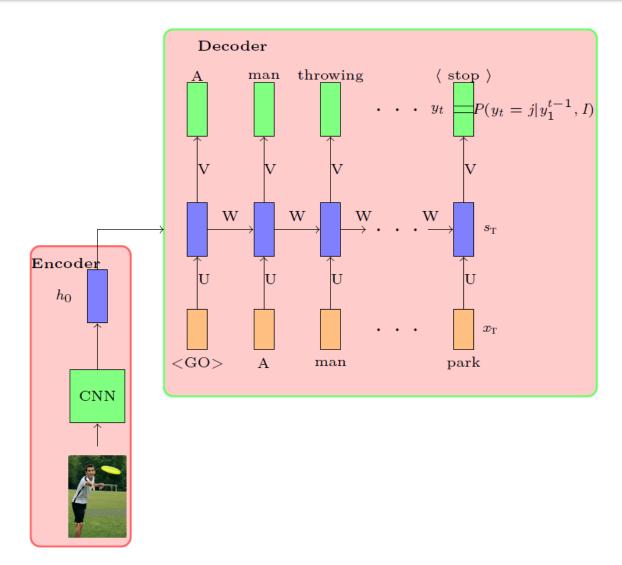


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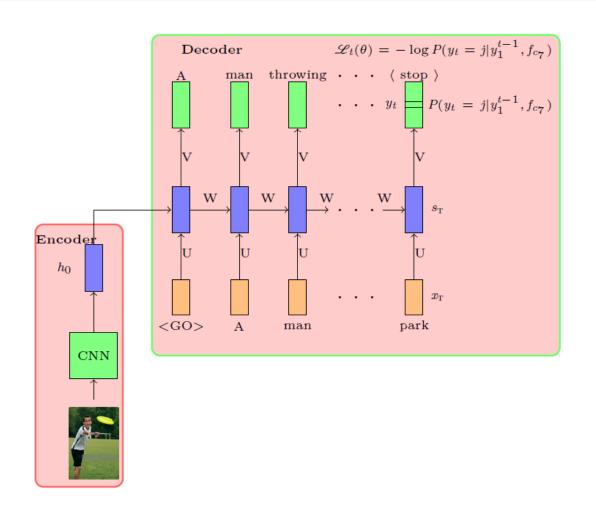
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This is typical encoder decoder architecture

Applications of Encoder Decoder Models: Image Captioning



- Task: Image captioning
- Data: $\{x_i = image_i, y_i = caption_i\}_{i=1}^N$
- Model:
 - Encoder:

$$s_0 = CNN(x_i)$$

Represents the input embedding of the $s_0 = CNN(x_i)$ embedding of the output obtained at time step t-1

• Decoder:

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

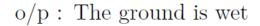
$$P(y_t|y_1^{t-1}, I) = softmax(Vs_t + b)$$

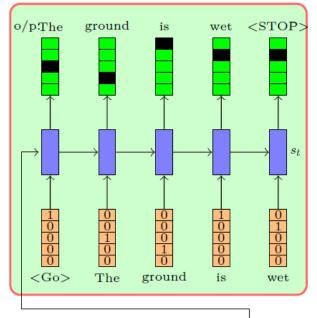
- Parameters: U_{dec} , V, W_{dec} , W_{conv} , b
- Loss:

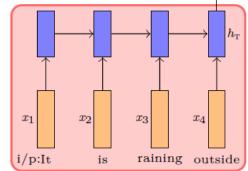
$$\mathscr{L}(\theta) = \sum_{i=1}^{T} \mathscr{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, I)$$

• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Textual Entailment







i/p : It is raining outside

Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras

- Task: Textual entailment
- Data: $\{x_i = premise_i, y_i = hypothesis_i\}_{i=1}^N$
- Model (Option 1):
 - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

$$s_0 = h_T \quad (T \text{ is length of input})$$

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

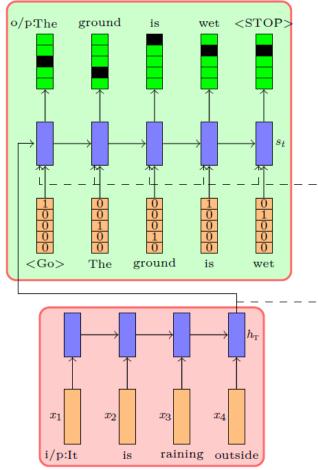
$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

- Parameters: U_{dec} , V, W_{dec} , U_{enc} , W_{enc} , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

Applications of Encoder Decoder Models: Textual Entailment

o/p : The ground is wet



i/p: It is raining outside

- Task: Textual entailment
- Data: $\{x_i = premise_i, y_i = hypothesis_i\}_{i=1}^N$
- Model (Option 2):
 - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

$$s_0 = h_T \quad (T \text{ is length of input})$$

$$s_t = RNN(s_{t-1}, [h_T, e(\hat{y}_{t-1})])$$

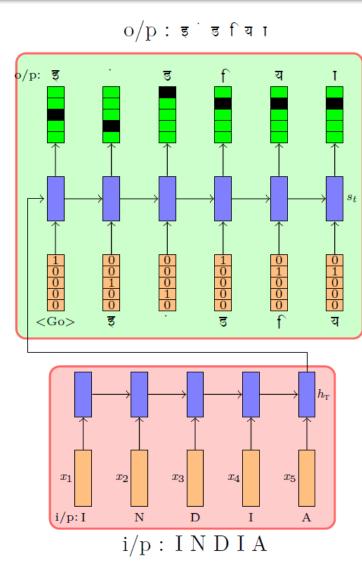
$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

- Parameters: U_{dec} , V, W_{dec} , U_{enc} , W_{enc} , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Transliteration



Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras

- Task: Transliteration
- Data: $\{x_i = srcword_i, y_i = tgtword_i\}_{i=1}^N$
- Model
 - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

$$s_0 = h_T \quad (T \text{ is length of input})$$

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

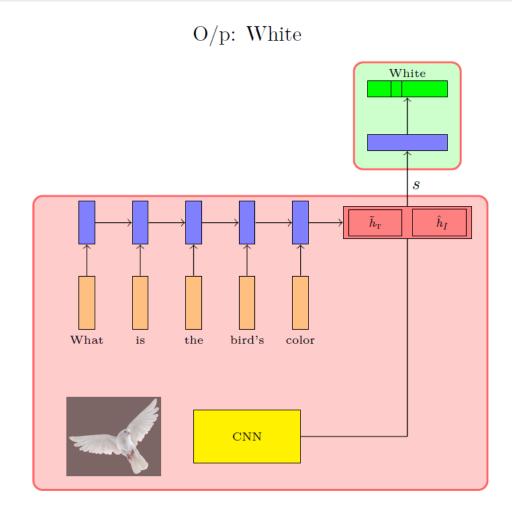
$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

- Parameters: U_{dec} , V, W_{dec} , U_{enc} , W_{enc} , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Image Question Answering



Question: What is the bird's color

- Task: Image Question Answeing
- Data: $\{x_i = \{I, q\}_i, y_i = Answer_i\}_{i=1}^N$
- Model:
 - Encoder:

$$\hat{h}_I = CNN(I), \ \tilde{h}_t = RNN(\tilde{h}_{t-1}, q_{it})$$

$$s = [\tilde{h}_T; \hat{h}_I]$$

• Decoder:

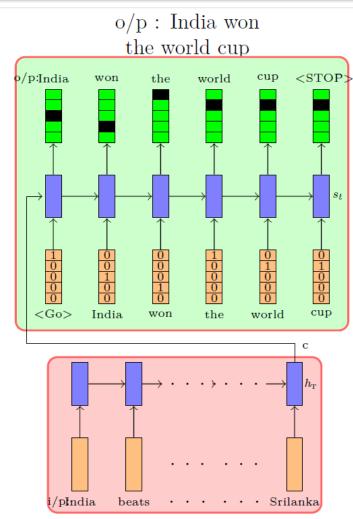
$$P(y|q, I) = softmax(Vs + b)$$

- Parameters: $V, b, U_q, W_q, W_{conv}, b$
- Loss:

$$\mathcal{L}(\theta) = -\log P(y = \ell | I, q)$$

• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Document Summarization



i/p : India beats Srilanka to win ICC WC 2011. Dhoni and Gambhir's half centuries help beat SL $\,$

• Task: Document Summarization

• Data: $\{x_i = Document_i, y_i = Summary_i\}_{i=1}^{N}$

- Model:
 - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

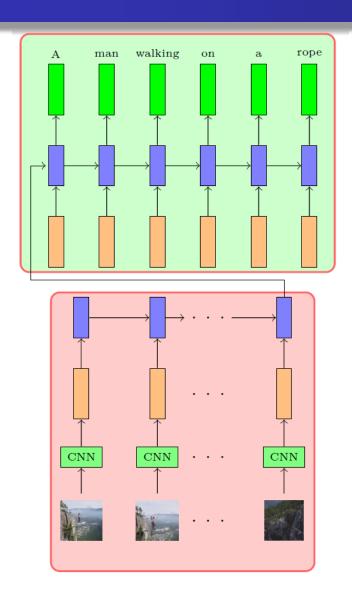
$$\begin{aligned} s_0 &= h_T \\ s_t &= RNN(s_{t-1}, e(\hat{y}_{t-1})) \\ P(y_t|y_1^{t-1}, x) &= softmax(Vs_t + b) \end{aligned}$$

- Parameters: U_{dec} , V, W_{dec} , U_{enc} , W_{enc} , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Video Captioning



- Task: Video Captioning
- Data: $\{x_i = video_i, y_i = desc_i\}_{i=1}^N$
- Model:
 - Encoder:

$$h_t = RNN(h_{t-1}, CNN(x_{it}))$$

• Decoder:

$$s_0 = h_T$$

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

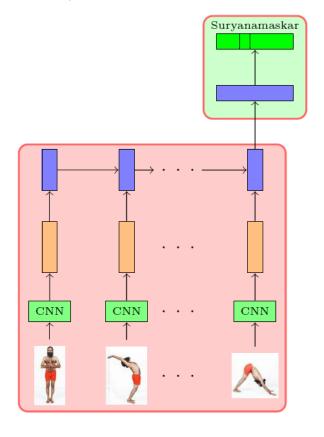
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• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Video Classification

o/p: Surya Namaskar



- Task: Video Classification
- Data: $\{x_i = Video_i, y_i = Activity_i\}_{i=1}^N$
- Model:
 - Encoder:

$$h_t = RNN(h_{t-1}, CNN(x_{it}))$$

• Decoder:

$$s = h_T$$

$$P(y|I) = softmax(Vs + b)$$

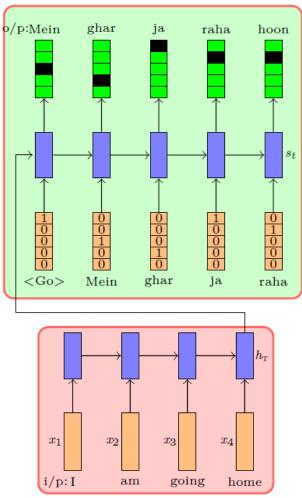
- Parameters: $V, b, W_{conv}, U_{enc}, W_{enc}, b$
- Loss:

$$\mathscr{L}(\theta) = -\log P(y = \ell | Video)$$

• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Machine Translation

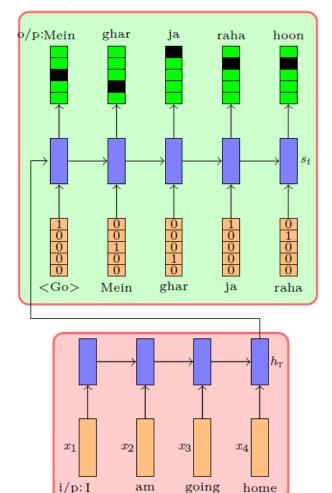
o/p : Mein ghar ja raha hoon



i/p : I am going home

Applications of Encoder Decoder Models: Machine Translation

o/p: Mein ghar ja raha hoon



i/p : I am going home

- Task: Machine translation
- Data: $\{x_i = source_i, y_i = target_i\}_{i=1}^N$
- Model (Option 1):
 - Encoder:

$$h_t = RNN(h_{t-1}, x_{it})$$

• Decoder:

$$s_0 = h_T \quad (T \text{ is length of input})$$

$$s_t = RNN(s_{t-1}, e(\hat{y}_{t-1}))$$

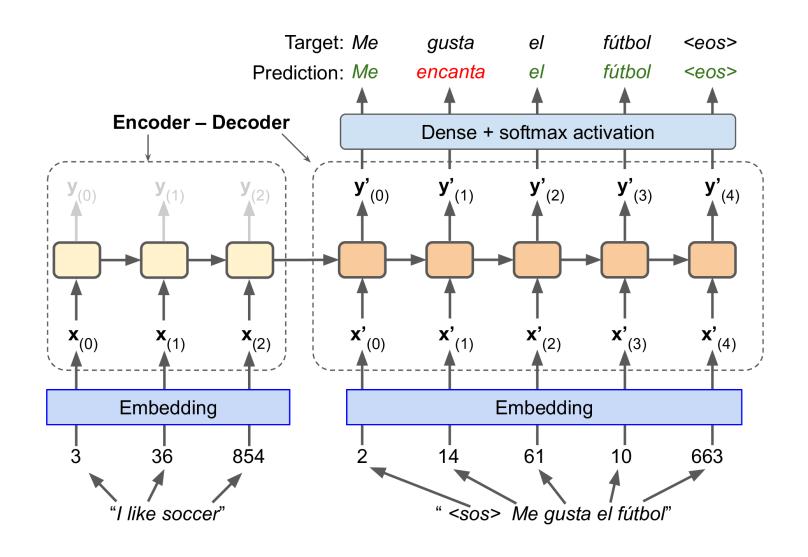
$$P(y_t|y_1^{t-1}, x) = softmax(Vs_t + b)$$

- Parameters: U_{dec} , V, W_{dec} , U_{enc} , W_{enc} , b
- Loss:

$$\mathcal{L}(\theta) = \sum_{i=1}^{T} \mathcal{L}_t(\theta) = -\sum_{t=1}^{T} \log P(y_t = \ell_t | y_1^{t-1}, x)$$

• Algorithm: Gradient descent with backpropagation

Applications of Encoder Decoder Models: Machine Translation



Machine Translation as Conditional Learning Problem

- Y = P(y1, y2, y3 ..., yn | x1,x2. ..., xm)
- Jane visitr l'Afrique en Septembre (x:French)
 - Jane is visiting Africa in September (y: English)
 - Jane is going to be visiting Africa in September September (y: English)
 - In September, Jane will visit Africa.

• $Y_{argmax(y1,..yn)} = P(y1, y2, y3 ..., yn | x1,x2...., xm)$

Beam Search

"Comment vas-tu?" - How are you? "Comment vas-tu jouer?" - How will you play?

Model could output "How will you?"

- Since model greedily outputs the most likely word at each step, it ended with suboptimal translation
- Can model go back and correct mistakes?
- Beam Search
 - Keeps track of a short list of the k most promising sentences
 - Parameter k is beam width
 - At each decoder step it tries to extend them by 1 word
- Step 1: First word could be "How" (Prob: 75%), "what" or "you"
- Step 2: 3 copies of model made to find the next word
- **Step 3:** First model will look for next word after "How" by computing conditional probabilities
 - Output could be "will (Prob:36%) "are", "do",
- Step 4: Compute the probabilities of each of the two word sentences the model considered and so on
- Advantage is that good translation for fairly short sentences can be obtained
- Disadvantage really bad at translating long sentences.
- Due to limited short term memory, let to ATTENTION MECHANISM

Attention Mechanism (Bahdanau et al , 2014)

- Technique that allowed the decoder to focus on the appropriate words at each time steps
- Ensures that the path to from an input word to its translation is much shorter
- For instance, at the time step where the decoder needs to output the word 'lait' it focusses on the word "milk"
- Path from input word to translation is smaller, so not affected by the short term limitations of RNNS
- Visual Attention
 - For example : Generating image captions using visual attentions
 - CNN processes image and outputs some feature maps
 - Then decoder RNN with attention generates the caption , one word at a time
- Leads to Explainability (Ribeiro et al. 2016)
 - What led the model to produce its output
 - Which leads to fairness in results
 - Google apologizes after its Vision AI produced racist results



Attention Mechanism (Bahdanau et al , 2014)

Attention is proposed as a method to both align and translate.

Alignment

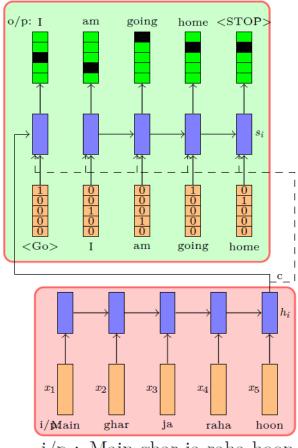
is the problem in machine translation that identifies which parts of the input sequence are relevant to each word in the output

translation

- is the process of using the relevant information to select the appropriate output
- "... we introduce an extension to the encoder—decoder model which learns to align and translate jointly. Each time the proposed model generates a word in a translation, it (soft-)searches for a set of positions in a source sentence where the most relevant information is concentrated. The model then predicts a target word based on the context vectors associated with these source positions and all the previous generated target words."
 - Neural Machine Translation by Jointly Learning to Align and Translate, 2015.

Task: Machine translation

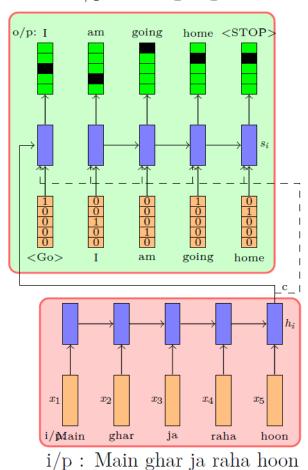
o/p: I am going home



i/p : Main ghar ja raha hoon

Task: Machine translation

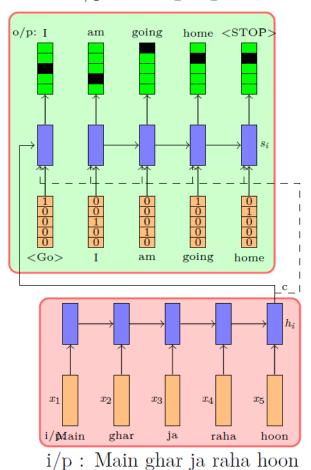
o/p: I am going home



In a typical encoder decoder network, each time step of the decoder uses the information obtained from the last time step of the encoder.

Task: Machine translation

o/p: I am going home



- In a typical encoder decoder network, each time step of the decoder uses the information obtained from the last time step of the encoder.
- However, the translation would be effective if the network could focus/or pay attention to specific input word that would contribute to the prediction.

Consider the task of machine translation:

While predicting each word in the o/p we would like our model to mimic humans and focus on specific words in the i/p

o/p : I am going home
$$t_1$$
 : [1 0 0 0 0]

i/p: Main ghar ja raha hoon

While predicting each word in the o/p we would like our model to mimic humans and focus on specific words in the i/p

o/p : I am going home
$$t_1$$
 : [1 0 0 0 0] t_2 : [0 0 0 0 1]

i/p : Main ghar ja raha hoon

While predicting each word in the o/p we would like our model to mimic humans and focus on specific words in the i/p

```
o/p: I am going home t_1: [ 1 0 0 0 0 ] t_2: [ 0 0 0 0 1 ] t_3: [ 0 0 0.5 0.5 0 ]
```

i/p : Main ghar ja raha hoon

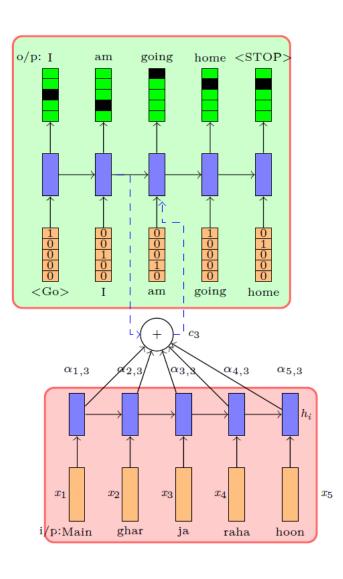
```
o/p: I am going home t_1: [ 1 0 0 0 0 ] t_2: [ 0 0 0 0 1 ] t_3: [ 0 0 0.5 0.5 0 ] t_4: [ 0 1 0 0 0 ]
```

i/p: Main ghar ja raha hoon

- Essentially, at each time step, a distribution on the input words must be introduced.
- This distribution tells the model how much attention to pay to each input words at each time step.

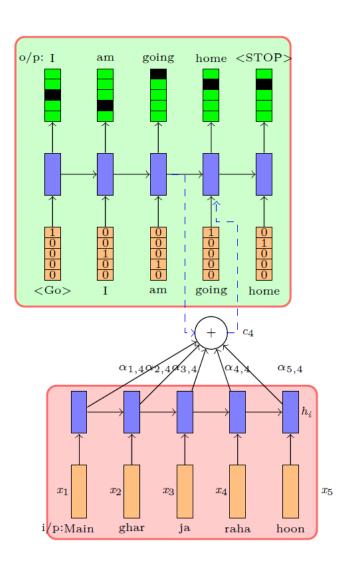
Task: Machine translation

 To do this, we could just take a weighted average of the corresponding word representations and feed it to the decoder



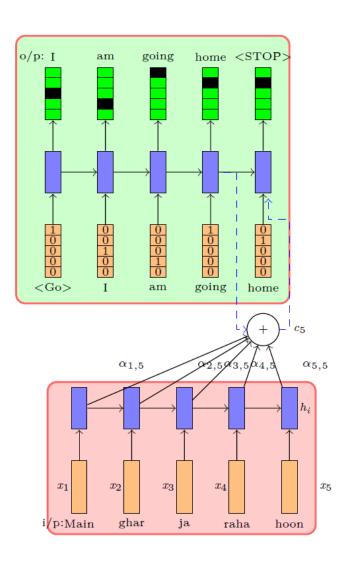
Task: Machine translation

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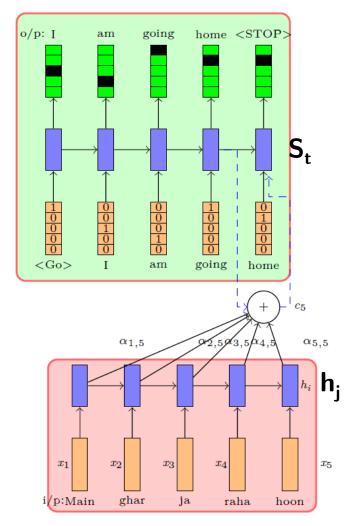


Task: Machine translation

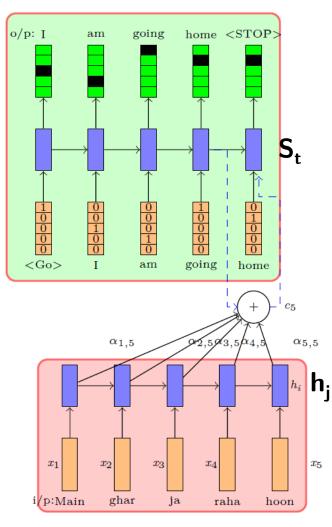
 To do this, we could just take a weighted average of the corresponding word representations and feed it to the decoder



Task: Machine translation

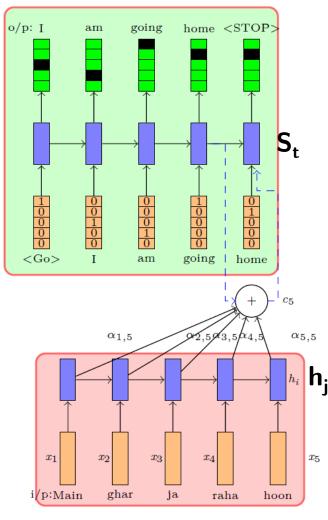


Task: Machine translation



To enable the network to focus on certain data we define the following function:

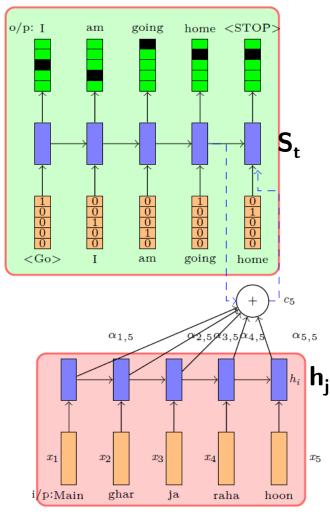
Task: Machine translation



 To enable the network to focus on certain data we define the following function:

$$e_{jt} = f_{ATT}(s_{t-1}, \mathbf{h_j})$$

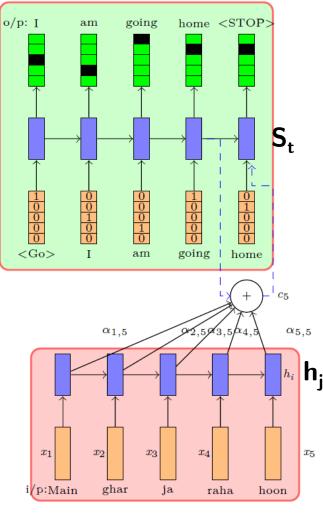
Task: Machine translation



 To enable the network to focus on certain data we define the following function:

$$e_{jt} = f_{ATT}(s_{t-1}, \mathbf{h_j}) \xrightarrow{\text{Can be considered as a separate feed forward network}}$$

Task: Machine translation

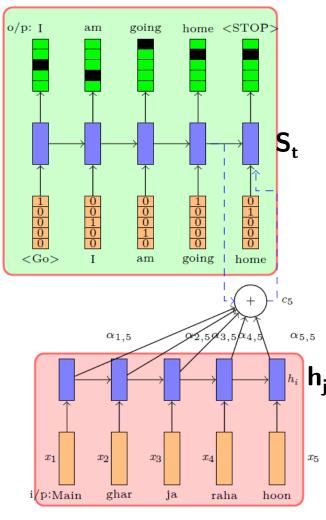


 To enable the network to focus on certain data we define the following function:

$$e_{jt} = f_{ATT}(s_{t-1}, \mathbf{h_j}) \longrightarrow \begin{array}{c} \text{Can be considered as a separate feed forward network} \end{array}$$

 This quantity captures the importance of the jth input word for decoding the tth output word.

Task: Machine translation

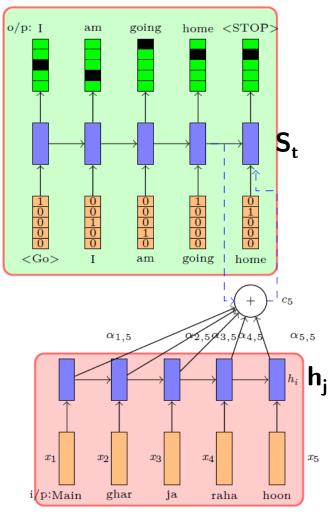


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- This quantity captures the importance of the jth input word for decoding the tth output word.
- We could compute α_{jt} by normalizing these weights using the softmax function.

Task: Machine translation



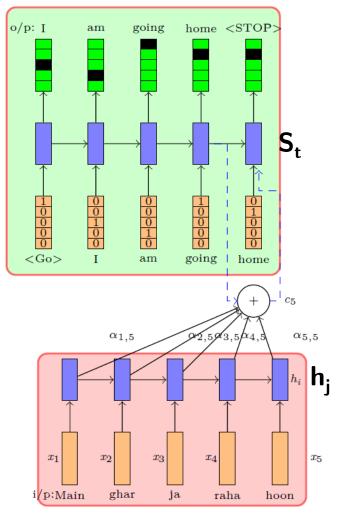
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$$\alpha_{jt} = \frac{exp(e_{jt})}{\sum_{j=1}^{M} exp(e_{jt})}$$

Task: Machine translation



 To enable the network to focus on certain data we define the following function:

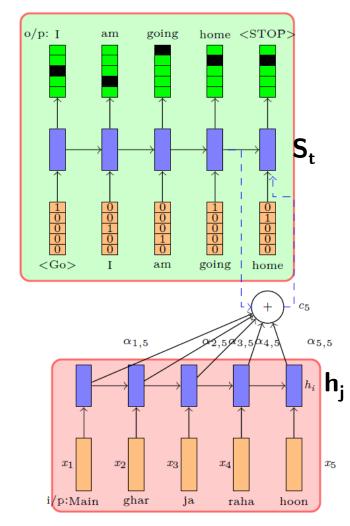
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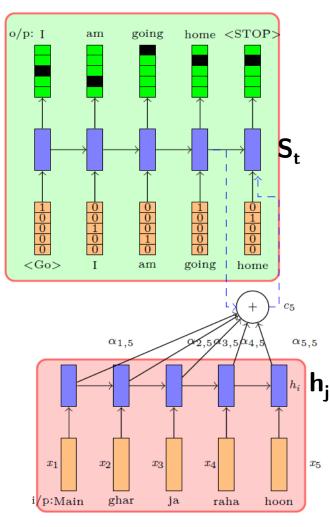
$$\alpha_{jt} = \frac{exp(e_{jt})}{\sum_{j=1}^{M} exp(e_{jt})}$$

• Where, α_{jt} denotes the probability of focusing on the jth word to produce the tth output word

Task: Machine translation

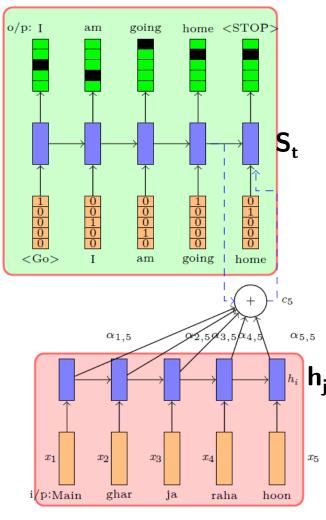


Task: Machine translation



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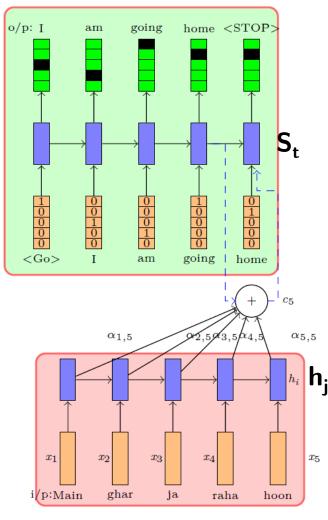
Task: Machine translation



To enable the network to focus on certain data we define the following function:

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Task: Machine translation

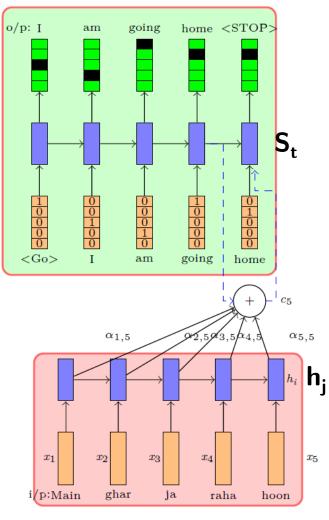


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Task: Machine translation

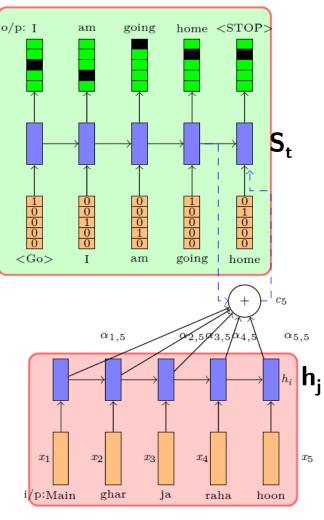


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Task: Machine translation



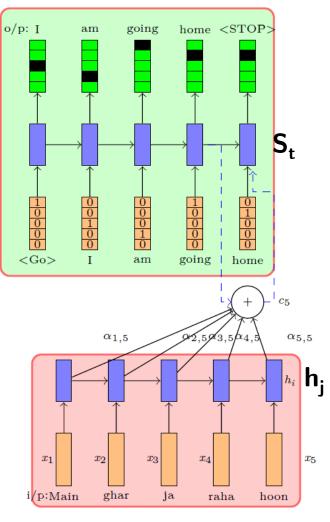
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Task: Machine translation



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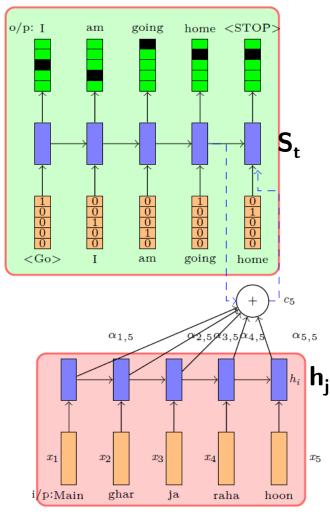
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• Where, α_{jt} denotes the probability of focusing on the jth word to produce the tth output word

Task: Machine translation



• Introducing the parametric form of lpha :

$$e_{jt} = V_{attn}^{T} tanh(U_{attn}h_{j} + W_{attn}s_{t})$$

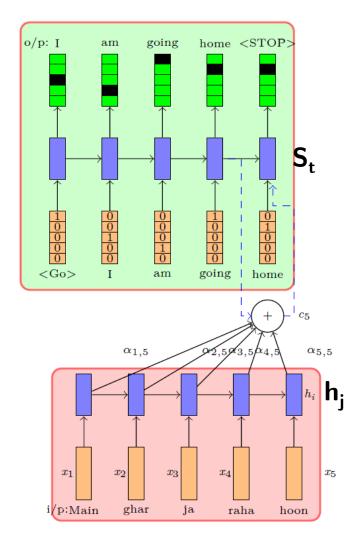
$$\alpha_{jt} = \frac{exp(e_{jt})}{\sum_{j=1}^{M} exp(e_{jt})}$$

$$c_t = \sum_{j=1}^{T} \alpha_{jt} h_j$$

Where, c_t (context) gives a weighted sum over the inputs.

Encoder Decoder with Attention Mechanism

Task: Machine translation



- Data: $\{x_i = source_i, y_i = target_i\}_{i=1}^N$
- Encoder:

$$h_t = RNN(h_{t-1}, x_t)$$
$$s_0 = h_T$$

• Decoder:

$$e_{jt} = V_{attn}^{T} tanh(U_{attn}h_{j} + W_{attn}s_{t})$$

$$\alpha_{jt} = softmax(e_{jt})$$

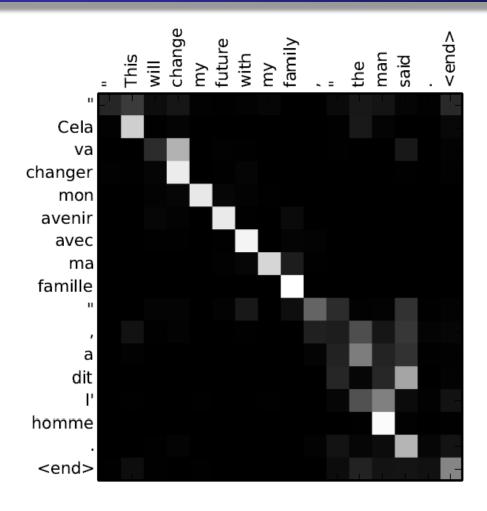
$$c_{t} = \sum_{j=1}^{T} \alpha_{jt}h_{j}$$

$$s_{t} = RNN(s_{t-1}, [e(\hat{y}_{t-1}), c_{t}])$$

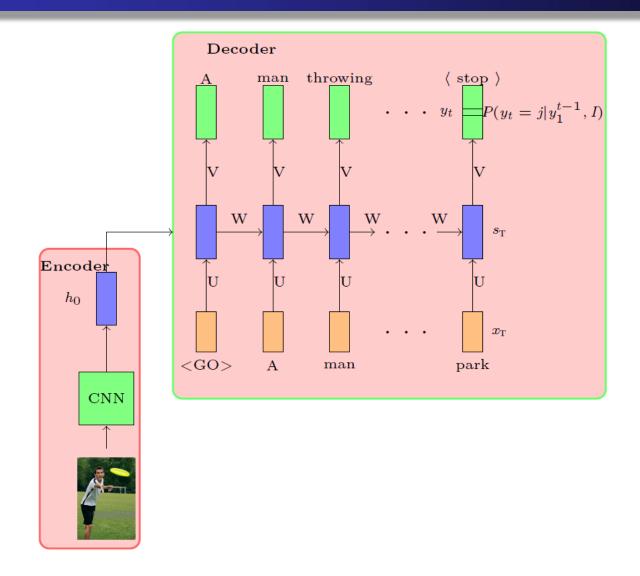
$$\ell_{t} = softmax(Vs_{t} + b)$$

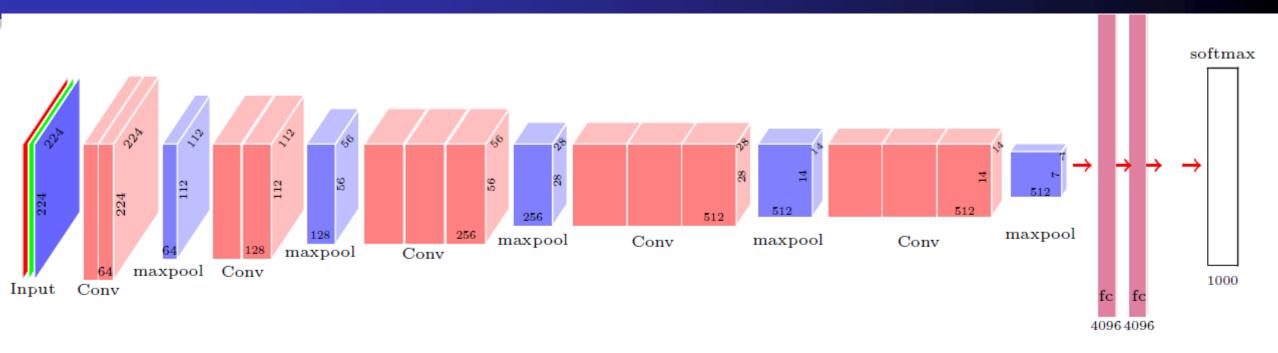
- Parameters: U_{dec} , V, W_{dec} , U_{enc} , W_{enc} , b, U_{attn} , V_{attn}
- Loss and Algorithm remains same

Encoder Decoder with Attention Mechanism: Visualization



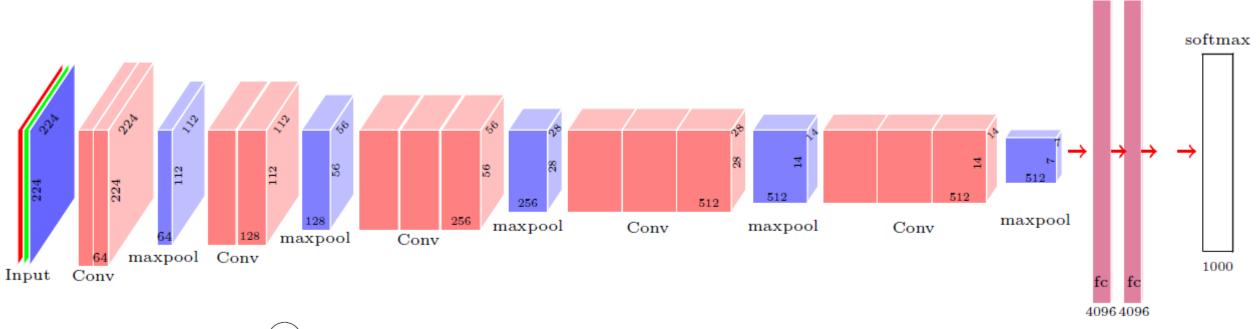
Example output of attention-based neural machine translation model Bahdanau et al. 2015

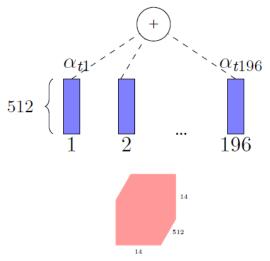




- For a CNN (eg: VGG-16) we would consider the convolution layer to be an input to the decoder, instead of the fully connected layers.
- This is because, the information about the image is contained in the feature maps in the convolution layer.
- Therefore, we could add attention weights to each pixel of the feature map volume to make the model focus on a particular pixel or region in the image.

Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras





- For a CNN (eg: VGG-16) we would consider the convolution layer to be an input to the decoder, instead of the fully connected layers.
- This is because, the information about the image is contained in the feature maps in the convolution layer.
- Therefore, we could add attention weights to each pixel of the feature map volume to make the model focus on a particular pixel or region in the image.



A woman is throwing a frisbee in a park.



A <u>dog</u> is standing on a hardwood floor.





A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.



A group of <u>people</u> sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

Figure: Examples of the attention-based model attending to the correct object (white indicates the attended regions, underlines indicates the corresponding word) [Kyunghyun Cho et al. 2015.]

- Bilingual Evaluation Understudy (BLUE) is a score for comparing a candidate translation of text to one or more reference translations.
- Correlates to human judgment of quality
- Scores are calculated for individual translated segments by comparing them with a set of good quality reference translations.
- Scores are then averaged over the whole corpus to reach an estimate of the translation's overall quality.
- Intelligibility or grammatical correctness are not taken into account
- Number between 0 and 1

German: Ich bin zur Zeit nicht im Büro

Reference English: I am currently out of the office

MT English: am am am am am am

Precision (uni-gram):

$$p_1 = \frac{(1+1+1+1+1+1)}{6} = 1$$

German: Ich bin zur Zeit nicht im Büro

Reference English: I am currently out of the office

MT English: am am am am am am

Modified Precision (uni-gram):

$$p_1 = \frac{(1+0+0+0+0+0)}{6} = 0.16$$

German: Ich bin zur Zeit nicht im Büro

Reference English: I am currently out of the office

MT English: I am currently not in the office

Modified Precision (unigram):

$$p_1 = \frac{1+1+1+0+0+1+1}{7} = \frac{5}{7} = 0.71$$

Modified Precision (bi-gram):

English: (I am), (am currently), (currently out), (out, of), (of the), (the office)

MT English: (I am), (am currently), (currently not), (not in), (in the), (the office)

$$p_2 = \frac{1+1+1+0+0+1}{6} = \frac{4}{6} = 0.66$$

German: Ich bin zur Zeit nicht im Büro

Reference English: I am currently out of the office

MT English: I am

Modified Precision (unigram): $p_1 = 1$

Modified Precision (bigram): $p_2 = 1$

Modifier Precision (n-gram): $p_n = 1$

German: Ich bin zur Zeit nicht im Büro

Reference English: I am currently out of the office

MT English: I am

$$BP = \begin{cases} 1 & \text{if } c > r \\ e^{(1-r/c)} & \text{if } c \le r \end{cases}$$

Brievity Penalty

Bleu Score =
$$BP \cdot e^{\left(\frac{1}{N}\sum_{n=1}^{N}P_{n}\right)}$$

German: Ich bin zur Zeit nicht im Büro

Reference English: I am currently out of the office

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$$BP = \begin{cases} 1 & \text{if } c > r \\ e^{(1-r/c)} & \text{if } c \le r \end{cases}$$

Brievity Penalty

Bleu Score =
$$BP \cdot e^{\left(\frac{1}{N}\sum_{n=1}^{N}P_{n}\right)}$$

Evaluation of machine translation

NIST

- n-gram precision
 - counts how many (i=1,...,4) grams match their n-gram counterpart in the reference translations.
- BLEU simply calculates n-gram precision adding equal weight to each segment
- NIST also calculates how informative a particular n-gram is.
- when a correct n-gram is found, the rarer that n-gram is, the more weight it will be given

Evaluation of machine translation

WORD ERROR RATE

- metric based on the Levenshtein distance at the word level.
- based on the calculation of the number of words that differ between a piece of machine-translated text and a reference translation.
- METEOR (Metric for Evaluation of Translation with Explicit ORdering)
 - Recall the proportion of the matched n-grams out of the total number of n-grams in the reference translation
 - based on the harmonic mean of unigram precision and recall, with recall weighted higher than precision
 - Features include stemming and synonymy matching along with exact word matching
- LEPOR (Length Penalty, Precision, n-gram Position difference Penalty and Recall)
 - Language Independent overcomes language bias problem
 - factors of
 - enhanced length penalty Translator is punished if longer or shorter than the reference translation
 precision score reflects the accuracy of the hypothesis translation
 - recall score reflects the loyalty of the hypothesis translation to the reference translation or source language.
 - n-gram word order penalty- is designed for the different position orders between the hypothesis translation and reference translation.

Task: Chat Bot

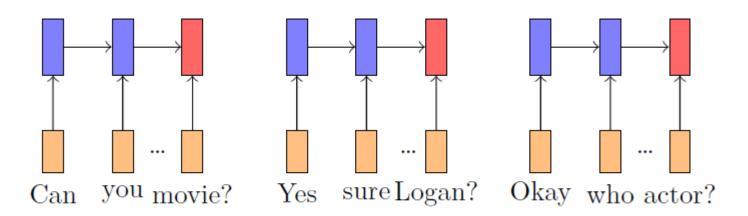
Context

U: Can you suggest a good movie?

B: Yes, sure. How about Logan?

U: Okay, who is the lead actor?

Response



Task: Chat Bot

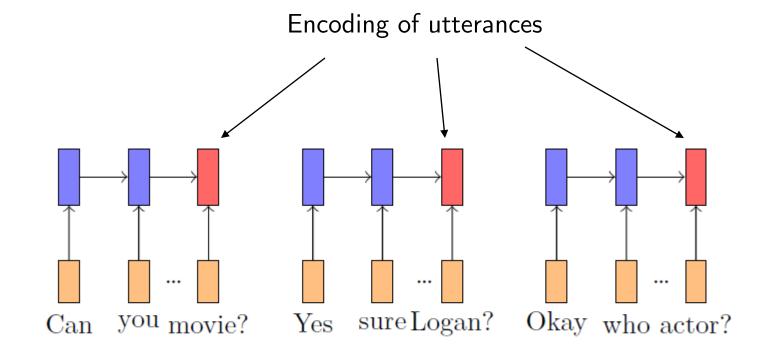
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Task: Chat Bot

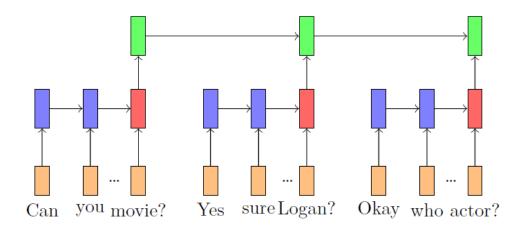
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Task: Chat Bot

Context

U: Can you suggest a good movie?

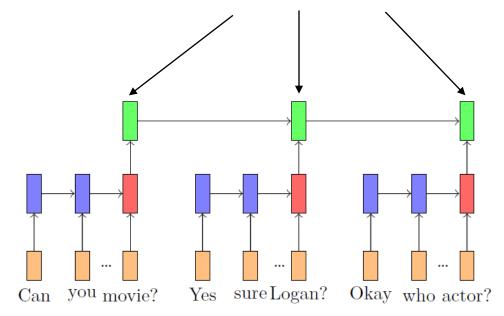
B: Yes, sure. How about Logan?

U: Okay, who is the lead actor?

Response

B: Hugh Jackman, of course

Encoding of sequence of utterances



Task: Chat Bot

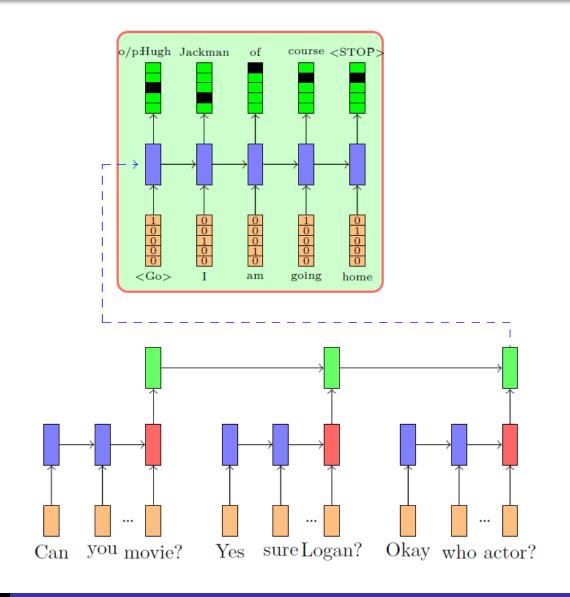
Context

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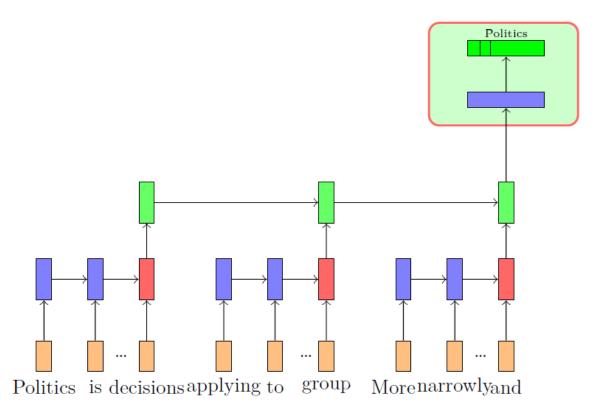
Response



Task: Document Summarization

Politics is the process of making decisions applying to all members of each group.

More narrowly, it refers to achieving and ...



- Data: $\{Document_i, class_i\}_{i=1}^N$
- Word level (1) encoder:

$$h_{ij}^1 = RNN(h_{ij-1}^1, w_{ij})$$

 $s_i = h_{iT_i}^1 \quad [T \text{ is length of sentence } i]$

• Sentence level (2) encoder:

$$h_i^2 = RNN(h_{i-1}^2, s_i)$$

 $s = h_K^2$ [K is number of sentences]

• Decoder:

$$P(y|document) = softmax(Vs + b)$$

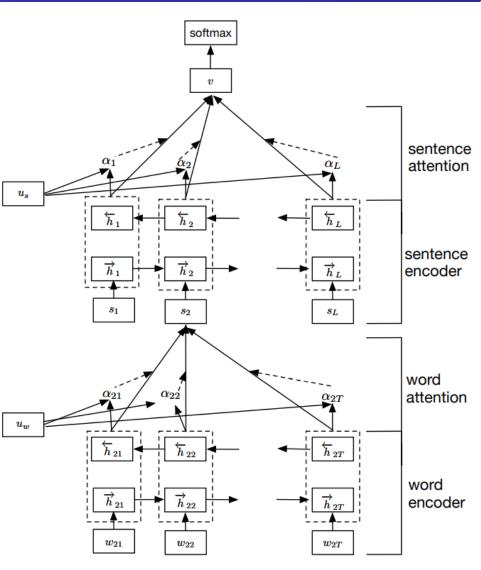
- Params: W_{enc}^1 , U_{enc}^1 , W_{enc}^2 , U_{enc}^2 , V, b
- Loss: Cross Entropy
- Algorithm: Gradient Descent with backpropagation

Source: CS7015 Deep Learning, Dept. of CSE, IIT Madras

Document Classification using Hierarchical Attention Networks

- To understand the main message of a document
 - Not every word in a sentence and every sentence in a document are equally important
- Meaning of word depends on context
 - For example "The bouquet of flowers is pretty" vs. "The food is pretty bad".
- HAN
 - considers the hierarchical structure of documents (document sentences words)
 - Includes an attention mechanism that is able to find the most important words and sentences in a document while taking the context into consideration

Hierarchical Attention Networks



- Data: $\{Document_i, class_i\}_{i=1}^N$
- Word level (1) encoder:

$$h_{ij} = RNN(h_{ij-1}, w_{ij})$$

$$u_{ij} = tanh(W_w h_{ij} + b_w)$$

$$\alpha_{ij} = \frac{exp(u_{ij}^T u_w)}{\sum_t exp(u_{it}^T u_w)}$$

$$s_i = \sum_i \alpha_{ij} h_{ij}$$

• Sentence level (2) encoder:

$$h_{i} = RNN(h_{i-1}, s_{i})$$

$$u_{i} = tanh(W_{s}h_{i} + b_{s})$$

$$\alpha_{i} = \frac{exp(u_{i}^{T}u_{s})}{\sum_{i} exp(u_{i}^{T}u_{s})}$$

$$s = \sum_{i} \alpha_{i}h_{i}$$

• Decoder:

$$P(y|document) = softmax(Vs + b)$$

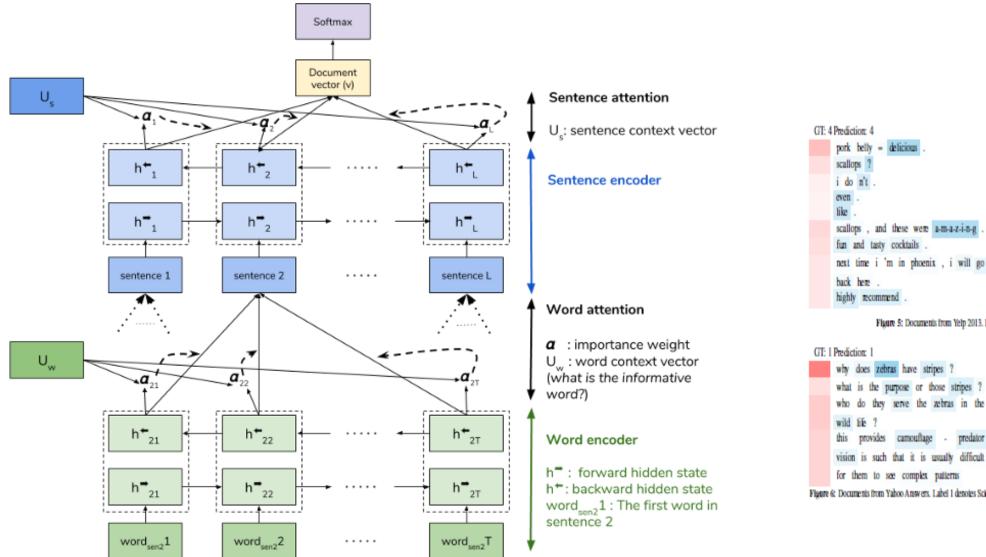
• Parameters:

 W_w , W_s , V, b_w , b_s , b, u_w , u_s

- Loss: cross entropy
- Algorithm: Gradient Descent and backpropagation

Yang et al. Hierarchical Attention Networks for Document Classification, Proceedings of NAACL-HLT 2016

Hierarchical Attention Networks (Yang et al. 2016)



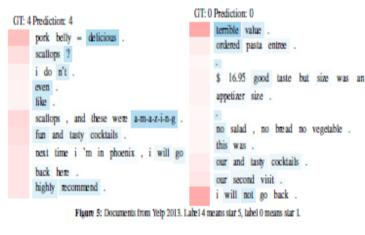


Figure 6: Documents from Yahoo Answers. Label 1 denotes Science and Mathematics and label 4 denotes Computers and Internet.

GT: 4 Prediction: 4

searches i have on my web browser ?

i want to clean up my web browser

clean up temporary internet files . "