



Eight Direction Sobel Edge's Brain Tumor Detection

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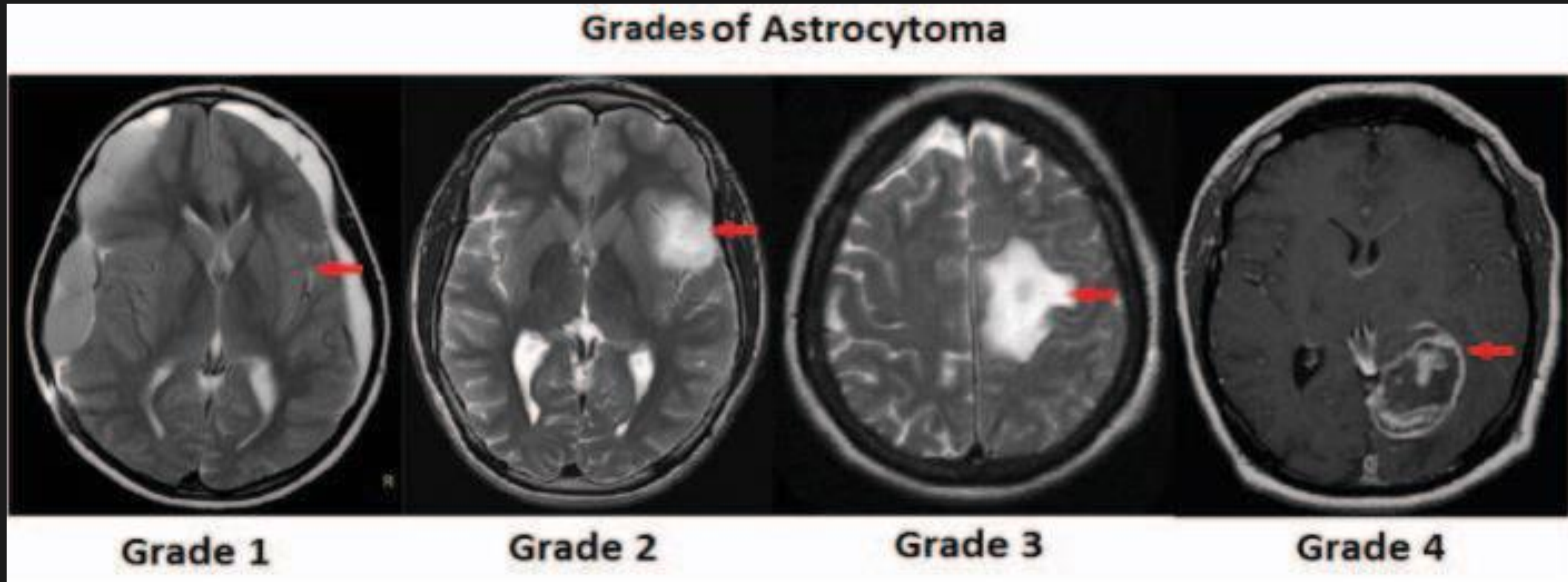
Addressed issue:

Developing a precise edge detector



- Article done by Remya Ajai A Sa, Sundararaman Gopalana
- Tumor detection requires high precision to distinguish accurately different grades of tumors
- The article proposes a novel method that provides this accuracy
- How? Using a Sobel edge detector applied in eight different directions instead of the traditional two directions method

Addressed issue



State of the art:

What has been done until today?

State of the art

- Histogram Thresholding and Artificial Neural Network technique by Chithambaram et al (The region of interests(ROIs) within the tumor area are extracted using histogram thresholding)[1]
- Reddy et al discussed the levelset algorithm along with image thresholding to extract tumor cells The effective pre-processing of images helps to gain better accuracy for classification problems using machine learning approaches[2]
- Indumathi et al used Co-occurrence filtering for image filtering before segmentation to analyse breast cancer[3]
- Deep learning approaches Fuzzy based edge detection and U-Net classification algorithms are used by Masqood et al for brain tumor detection[4]
- An interval based edge detection algorithm using laplacian technique was suggested by Zhang et al in for skin cancer detection [5]

Comments on the different edge detectors

$$\begin{array}{c} \text{Gx} \\ \begin{array}{|c|c|} \hline -1 & 0 \\ \hline 0 & +1 \\ \hline \end{array} \end{array} \quad \begin{array}{c} \text{Gy} \\ \begin{array}{|c|c|} \hline 0 & -1 \\ \hline +1 & 0 \\ \hline \end{array} \end{array}$$

Roberts Edge Operator

$$\begin{array}{c} \text{Gx} \\ \begin{array}{|c|c|c|} \hline -1 & -1 & -1 \\ \hline 0 & 0 & 0 \\ \hline +1 & +1 & +1 \\ \hline \end{array} \end{array} \quad \begin{array}{c} \text{Gy} \\ \begin{array}{|c|c|c|} \hline -1 & 0 & +1 \\ \hline -1 & 0 & +1 \\ \hline -1 & 0 & +1 \\ \hline \end{array} \end{array}$$

Prewitt Edge Operator

$$\begin{array}{c} \text{Gx} \\ \begin{array}{|c|c|c|} \hline 0 & -1 & 0 \\ \hline -1 & 4 & -1 \\ \hline 0 & -1 & 0 \\ \hline \end{array} \end{array} \quad \begin{array}{c} \text{Gy} \\ \begin{array}{|c|c|c|} \hline -1 & -1 & -1 \\ \hline -1 & 8 & -1 \\ \hline -1 & -1 & -1 \\ \hline \end{array} \end{array}$$

Laplacian of Guassian(LoG)
Edge Detection

$$\begin{array}{c} \text{Gx} \\ \begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline -2 & 0 & 2 \\ \hline -1 & 0 & -1 \\ \hline \end{array} \end{array} \quad \begin{array}{c} \text{Gy} \\ \begin{array}{|c|c|c|} \hline -1 & -2 & -1 \\ \hline 0 & 0 & 0 \\ \hline 1 & 2 & 1 \\ \hline \end{array} \end{array}$$

Sobel Edge Detection

$$\begin{array}{|c|c|c|} \hline 1 & 2 & 1 \\ \hline 0 & 0 & 0 \\ \hline -1 & -2 & -1 \\ \hline \end{array} \quad \begin{array}{|c|c|c|} \hline 0 & 1 & 2 \\ \hline -1 & 0 & 1 \\ \hline -2 & -1 & 0 \\ \hline \end{array} \quad \begin{array}{|c|c|c|} \hline -1 & 0 & 1 \\ \hline -2 & 0 & 2 \\ \hline -1 & 0 & 1 \\ \hline \end{array} \quad \begin{array}{|c|c|c|} \hline -2 & -1 & 0 \\ \hline -1 & 0 & 1 \\ \hline 0 & 1 & 2 \\ \hline \end{array}$$

D₁

D₂

D₃

D₄

$$\begin{array}{|c|c|c|} \hline -1 & -2 & -1 \\ \hline 0 & 0 & 0 \\ \hline 1 & 2 & 1 \\ \hline \end{array} \quad \begin{array}{|c|c|c|} \hline 2 & 1 & 0 \\ \hline 1 & 0 & -1 \\ \hline 0 & -1 & -2 \\ \hline \end{array} \quad \begin{array}{|c|c|c|} \hline 1 & 0 & -1 \\ \hline 2 & 0 & -2 \\ \hline 1 & 0 & -1 \\ \hline \end{array} \quad \begin{array}{|c|c|c|} \hline 0 & -1 & -2 \\ \hline 1 & 0 & -1 \\ \hline 2 & 1 & 0 \\ \hline \end{array}$$

D₅

D₆

D₇

D₈

8-Sobel Edge Detection

Critical analysis:

Developing a precise edge detector

Critical Analysis

- Larger datasets for analysing medical images using transfer learning technology is really challenging (Data Quality and Annotation...)
- Canny algorithm can produce sharp edges, but it is computationally complex (Gaussian Smoothing + Gradient Calculation + Non-maximum Suppression + Double thresholding and edge tracking by hysteresis)
- Fractional order Sobel (Fractional derivatives capture more information about the behavior of a function, it helps see smaller details)

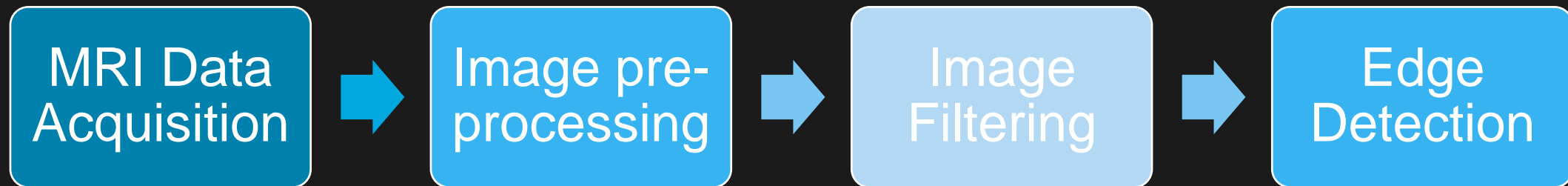


Article's pipeline

Towards a precise edge detector

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Article's pipeline

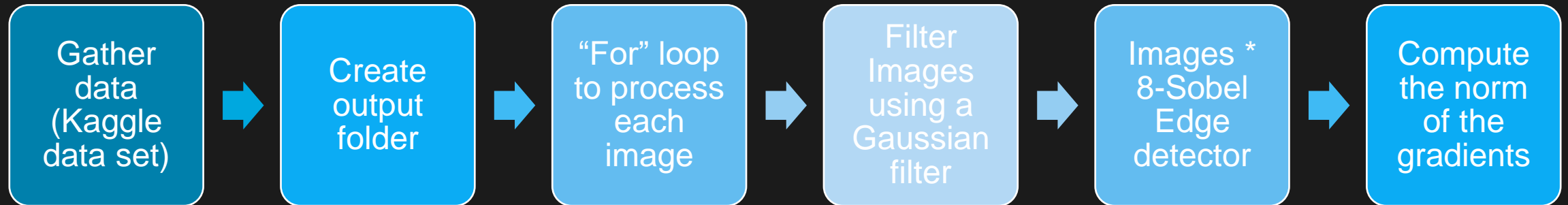


Noise Removal:
Avoids redundant pixel
information and helps in
further analysis of images

Suggested prototype

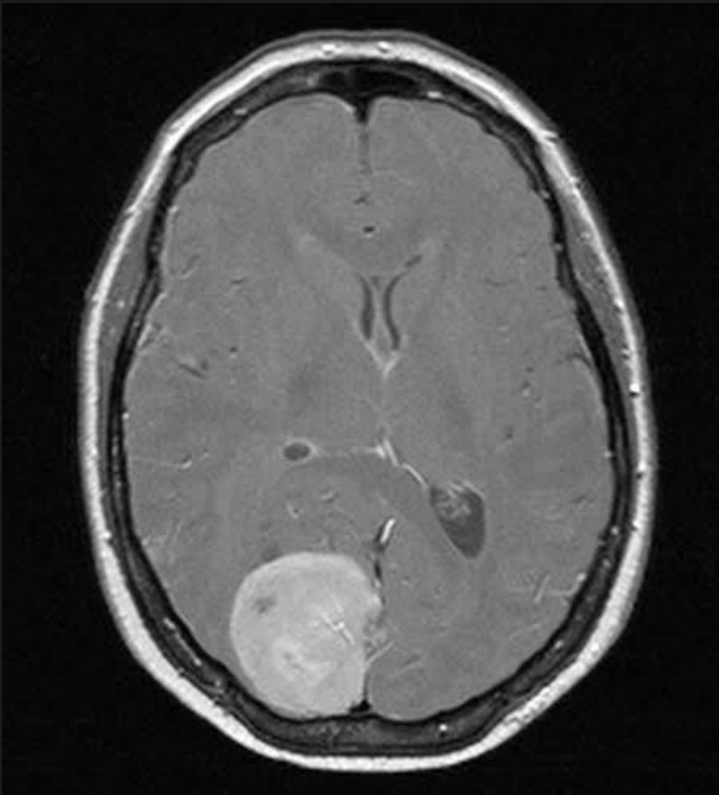
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Suggested prototype

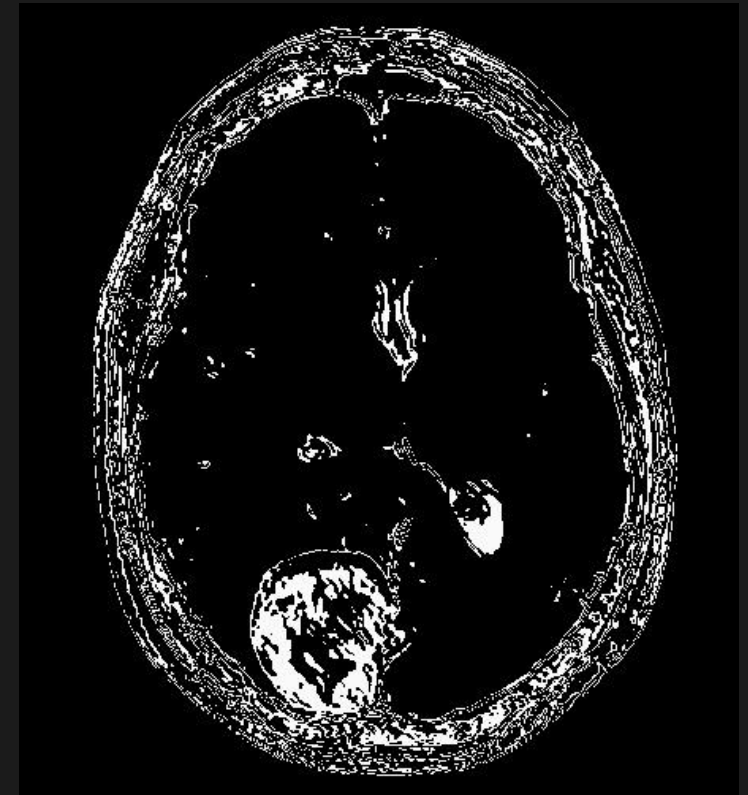


Prototype testing

Kaggle brain Tumor Dataset



Eight directions
Sobel edge Detector



Conclusions

Eight Direction Sobel Edge's Brain Tumor Detection

Conclusion

- Need for a highly precise edge detector to distinguish several grades of tumors
- The 8-Sobel edge detector
- Article's result : The RMSE (Root Mean Square Error) value is the lowest for 8 Sobel algorithm when tested with other edge detectors
- Precision at the cost of time



Perspectives

Eight Direction Sobel Edge's Brain Tumor Detection

Perspectives

- Applicable in Deep Learning-based pipelines for MRI images processing which architectures accounts for the flaws of the method
- A less time-costing solution should also be considered
- In the future, combine the solution with appropriate hardware (FPGA) as suggested by the article at the end



Thank you for your attention

Questions ?

References

- [1] T. Chithambaram and K. Perumal, “Edge detection algorithms using brain tumor detection and segmentation using artificial neural network techniques,” *International Research Journal of Advanced Engineering and Science*, vol. 1, no. 3, pp. 135–140, 2016.
- [2] D. Reddy, Dheeraj, Kiran, V. Bhavana, and H. Krishnappa, “Brain tumor detection using image segmentation techniques,” in *2018 International Conference on Communication and Signal Processing (ICCSP)*, 2018, pp. 0018–0022.
- [3] T. Indumathi, K. Sannihith, S. Krishna, and R. A. AS, “Effect of co-occurrence filtering for recognizing abnormality from breast thermograms,” in *2021 Second International Conference on Electronics and Sustainable Communication Systems (ICESC)*. IEEE, 2021, pp. 1170–1175.
- [4] S. Kadry, D. Taniar, R. Damasevicius, and V. Rajinikanth, “Automated detection of schizophrenia from brain mri slices using optimized deep-features,” in *2021 Seventh International conference on Bio Signals, Images, and Instrumentation (ICBSII)*. IEEE, 2021, pp. 1–5.
- [5] H. Zhang, Z. Wang, L. Liang, and F. R. Sheykhahmad, “A robust method for skin cancer diagnosis based on interval analysis,” *Automatika*, vol. 62, no. 1, pp. 43–53, 2021.

Used Figures

- Introduction Figure : Tests after a Brain Tumour Has Been Identified | Irish Cancer Society. 1. November 2020, <https://www.cancer.ie/cancer-information-and-support/cancer-types/brain-tumours/tests-after-a-brain-tumour-has-been-identified>.
- Figure 1 CT Scan vs MRI for Brain Tumor Diagnosis: What You Need to Know :: CTBTA. <https://www.ctbta.org/news/blog/ct-scan-vs-mri-brain-tumor-diagnosis-what-you-need-know>. Zugegriffen 16. April 2024.
- Figure 2 Devlin, Hannah, und Hannah Devlin Science correspondent. „Make Brain Scans Routine for New Psychosis Patients, Experts Say“. The Guardian, 12. Juli 2023. The Guardian, <https://www.theguardian.com/science/2023/jul/12/make-brain-scans-routine-for-new-psychosis-patients-experts-say>.
- Figure 3 Using Deep Learning to Classify Brain Tumors with a Single Scan, AUGUST 11, 2021 <https://www.mir.wustl.edu/using-deep-learning-to-classify-brain-tumors-with-a-single-scan/>
- Figure 4 Rodriguez, Arnaud. „L’IRM du futur en développement sur le campus bordelais“. Bordeaux Neurocampus, 29. September 2021, <https://www.bordeaux-neurocampus.fr/lirm-du-futur-en-developpement-sur-le-campus-bordelais/>.