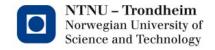


#### **MPI Programming**

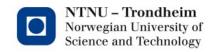
Henrik R. Nagel Scientific Computing IT Division

#### Outline

- Introduction
- Basic MPI programming
- Examples
  - Finite Difference Method
  - Finite Element Method
  - LU Factorization
  - Monte Carlo Method
  - Molecular Dynamics
  - MPMD Models

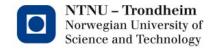


#### Introduction



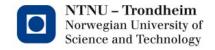
## Acknowledgments

- Thanks to Professor Lasse Natvig and Associate Professor Jørn Amundsen from IDI, NTNU for allowing me to copy from their "Parallel Programming" lecture slides
- Thanks to IBM for allowing me to copy from their MPI redbook:
  - www.redbooks.ibm.com/redbooks/pdfs/sg245380.pdf



## The Examples

- No exercises, but 7 working examples are explained
  - The last 6 are larger examples
- Kongull:
  - ssh -Y kongull.hpc.ntnu.no
  - cp -r /home/hrn/Kurs/mpi .
  - module load intelcomp
- Vilje:
  - ssh -Y vilje.hpc.ntnu.no
  - cp -r /home/ntnu/hrn/Kurs/mpi .
  - module load intelcomp mpt

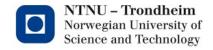


#### **Basic MPI Programming**



# MPI Programs in C

- A C program
  - Has a main() function
  - Includes stdio.h, string.h, etc.
- Need to include mpi.h header file
- Indentifiers defined by MPI start with "MPI\_"
- First letter following underscore is uppercase
  - For function names and MPI-defined types
  - Helps to avoid confusion



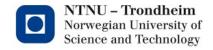
# MPI Programs in Fortran

- include 'mpif.h'
  - No argument checking! Don't use it.
- use mpi
  - Provide explicit interfaces for all MPI routines → compile time argument checking
- use mpi\_f08
  - Fully Fortran 2008 compatible definition of all MPI routines
  - New syntax TYPE(\*), DIMENSION(...) to define choice buffers in a standardized way

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## Identifying MPI Processes

- Common practice is to identify processes by nonnegative integer ranks
- p processes are numbered 0, 1, 2, ..., p-1
- This can be:
  - p processes distributed over p processors ("physical parallelism")
  - p processes running time-multiplexed on a single processor ("logical parallelism")

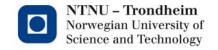


## Example 1: Hello, World!

- Change to the directory:
  - \$ cd mpi/ex1
- Compile the code:

```
$ make
cc -02 mpi_hello.c -o mpi_hello
```

- Edit the job script:\$ vim run.job (change ACCOUNT)
- Run the job\$ qsub run.job



#### MPI Start and End

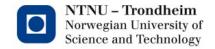
- MPI\_Init()
  - Tells MPI to do all the necessary setup

```
int MPI_Init(
    int* argc_p
    char*** argv_p);
```

Pointers to the arguments to main: argc & arv

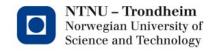
- MPI\_Finalize()
  - Tells MPI we're done, so clean up anything allocated

```
int MPI_Finalize(void);
```



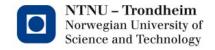
#### **Basic Outline**

```
#include <mpi.h>
...
int main(int argc, char* argv[]) {
    ...
    /* No MPI calls before this */
    MPI_Init(&argc, &argv);
    ...
    MPI_Finalize();
    /* No MPI calls after this */
    ...
    return 0;
}
```



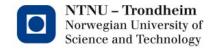
#### Communicators

- A collection of processes that can send messages to each other
- MPI\_Init() defines a communicator that consists of all the processes created when the program is started
  - MPI\_COMM\_WORLD



#### Communicators

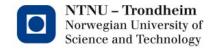
```
int MPI Comm size(
      MPI Comm
                comm /* in */,
      int*
                   size /* out */);
          number of processes in the communicator
int MPI Comm rank(
      MPI Comm
                   comm /* in */
      int*
                   rank /* out */);
                   my rank
                   (the process making this call)
```



### Communication

number of elements in the send buffer

```
int MPI Send(
      void*
                    buf
                                       /* in */,
      int
                                       /* in */,
                    count
                                       /* in */,
      MPI Datatype datatype
      int
                    dest
                                       /* in */,
                                       /* in */,
      int
                    tag
      MPI Comm
                    communicator
                                       /* in */);
```



# Data Types

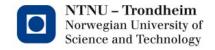
MPI datatype	C datatype
MPI_CHAR	signed <b>char</b>
MPI_SHORT	signed <b>short int</b>
MPI_INT	signed <b>int</b>
MPI_LONG	signed <b>long int</b>
MPI_LONG_LONG	signed long long int
MPI_UNSIGNED_CHAR	unsigned <b>cha</b> r
MPI_UNSIGNED_SHORT	unsigned <b>short int</b>
MPI_UNSIGNED	unsigned <b>int</b>
MPI_UNSIGNED_LONG	unsigned long int
MPI_FLOAT	float
MPI_DOUBLE	double
MPI_LONG_DOUBLE	long double
MPI_BYTE	
MPI PACKED	



### Communication

max. number of elements to receive

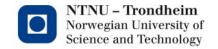
```
int MPI Recv(
      void*
                   buf
                                     /* out */,
      int
                                     /* in */,
                   count
                                     /* in */,
      MPI Datatype datatype
      int
                                     /* in */,
                   source
                                     /* in
      int
                   tag
      MPI Comm
                   communicator
                                     /* in */,
      MPI Status* status
                                     /* out */);
```



## Message Matching

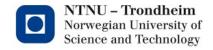
Process q calls MPI\_Send()

Process r calls MPI\_Recv()



## Receiving Messages

- A receiver can get a message without knowing:
  - the amount of data in the message,
  - the sender of the message
    - MPI ANY SOURCE
  - or the tag of the message
    - MPI ANY TAG

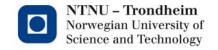


## The Status Argument

 If MPI\_ANY\_SOURCE or MPI\_ANY\_TAG have been used, you can get help from MPI\_Status

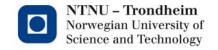
```
MPI_Recv(buf, count, datatype, src
     tag, comm, &status);
```

```
MPI_Status status;
status.MPI_SOURCE
status.MPI_TAG
```



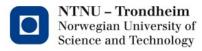
## How much data am I receiving?

```
int MPI Probe(
                          /* in */,
     int
                source
                          /* in */,
     int
                tag
     MPI Comm
                          /* in */
                comm
     MPI Status* status
                          /* out */);
int MPI Get_count(
     MPI Status* status /* in */,
     MPI_Datatype datatype /* in */,
     int*
                 count /* out */);
```



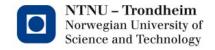
#### Issues with Send and Receive

- Exact behavior is determined by the MPI implementation
- MPI\_Send() is blocking as defined in the standard, but is non-blocking up to a certain message size in most implementations
  - MPI\_Ssend() might be used to force blocking untill a receive is posted
  - MPI\_Bsend() can be used with a user defined send buffer then always non-blocking
- MPI\_Recv() always blocks until a matching message is received



### Issues with Send and Receive

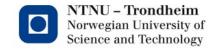
- AND, ...
  - MPI programs will easily hang!
    - A receive without corresponding send
    - A send without corresponding receive
    - Or deadlock
      - Circular waiting



## Non-Blocking Communication

```
int MPI Isend(void* buffer, int count, MPI Datatype
      datatype, int destination, int tag, MPI Comm comm,
      MPI Request* request);
int MPI Irecv(void* buffer, int count, MPI Datatype
      datatype, int source, int tag, MPI_Comm comm,
      MPI Request* request);
int MPI Wait(MPI Request* request, MPI Status* status);
int MPI_Waitall(int array_size,
      MPI_Request requests[], MPI_Status statuses[]);
```

I = Immediate



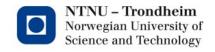
## Non-Blocking Communication

- Immediate-mode MPI\_Isend() and MPI\_Irecv() only start the data copy operation
- MPI\_Wait() and MPI\_Waitall() are used to complete the operations
- Useful in complicated send-receive situations (e.g. 2D grid of processes)
- Calculations can take place between those two calls
  - Difficult to make good use of
  - Communication and calculation at the same time is more efficient

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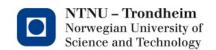
#### **Global Reduction**

- op determines which global reduction to perform
- Predefined reductions for the most used types, like MPI\_MAX, MPI\_MIN, MPI\_SUM, MPI\_PROD, etc.
- Also possible to specify user defined reduction operations with MPI\_Op\_create()
- MPI\_IN\_PLACE specified for sendbuf at rank root, makes the receive buffer a send-and-receive buffer



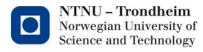
#### **Broadcast**

 Broadcasts a message from the process with rank root to all other processes of the communicator



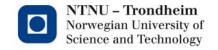
## Scatter and gather

- Routines to spread and collect data from or to root
- MPI\_Scatter: if root sends 100 numbers to 10 processes, then sendbuf on root must be 1000 long
- MPI\_Gather: if root receives 100 numbers from 10 processes, then recybuf on root must be 1000 long

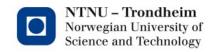


## Allreduce, allgather and more

- MPI\_Allreduce() and MPI\_Allgather() are identical to their siblings, except that the end result is made available to all ranks
- As if the operation was followed by a broadcast
- There are also more elaborate combined all-to-all scatter-gather functions, like MPI\_Alltoall(), MPI\_Alltoallv() and MPI\_Alltoallw()
- Use the man pages to get more information, e.g.:
   \$ man MPI Allreduce



#### **Examples**



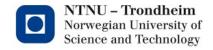
## Writing Larger MPI Programs

#### Question:

– Now that we can write "Hello World!" MPI programs, then what do we need in order to write larger MPI programs for scientific projects?

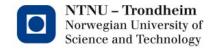
#### Answer:

- Parallel algorithms
- Data must be distributed to all proceses so that they all are kept busy during the entire execution of MPI programs



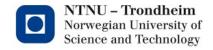
#### **Data Distribution**

- The majority of time is usually spent in DO/FOR loops
- Multiple data distribution methods:
  - Block distribution
    - Column wise
    - Row wise
    - In both dimensions
  - Cyclic distribution
  - Master-worker
- 6 examples



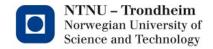
### 2. Finite Difference Method

- Wikipedia:
  - "Numerical methods for solving differential equations by approximating them with difference equations"
- Only a skeleton 2D FDM program is shown here
- Coefficients and the enclosing loop are omitted
- Data dependencies exist in both dimensions

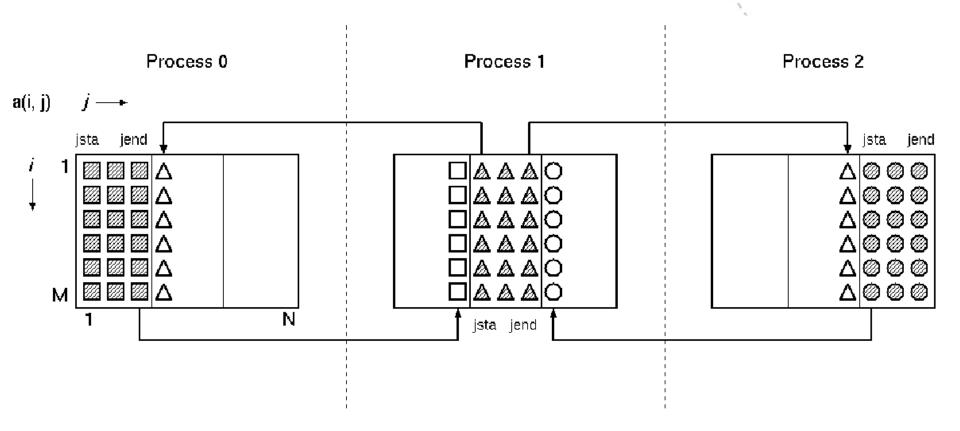


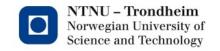
# The Sequential Algorithm

```
PROGRAM main
IMPLICIT REAL*8 (a-h,o-z)
PARAMETER (m=6, n=9)
DIMENSION a(m,n), b(m,n)
D0 j=1, n
  DO i=1, m
    a(i,j) = i + 10.0 * j
  ENDD0
ENDDO
D0 j=2, n-1
  D0 i=2, m-1
    b(i,j) = a(i-1,j) + a(i,j-1) + a(i,j+1) + a(i+1,j)
  ENDDO
FNDDO
END
```



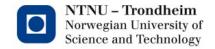
### Column-Wise Block Distribution



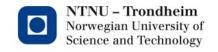


### Column-Wise Block Distribution

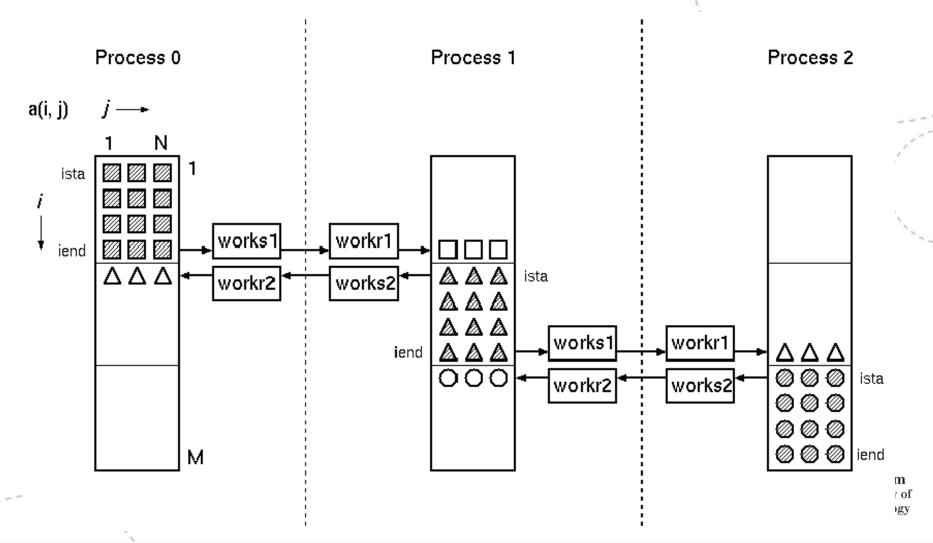
- We must distribute a 2D matrix onto the processes
- Fortran stores arrays in column-major order
- Boundary elements between processes are contiguous in memory
- There are no problems with using MPI\_SEND and MPI\_RECV



ex2/fdm1.f90

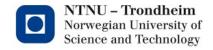


#### **Row-Wise Block Distribution**

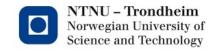


#### Row-Wise Block Distribution

- Fortran stores arrays in column-major order
- Boundary elements between processes are not contiguous in memory
- Boundary elements can be copied by:
  - Using derived data types
  - Writing code for packing data, sending/receiving it, and then unpacking it

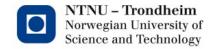


ex2/fdm2.f90

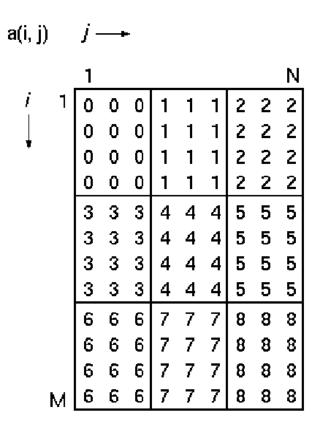


### Block Distribution in Both Dim. (1)

- The amount of data transferred might be minimized
  - Depends upon the matrix size and the number of processes
- A process grid itable is prepared for looking up processes quickly



### Block Distribution in Both Dim. (1)

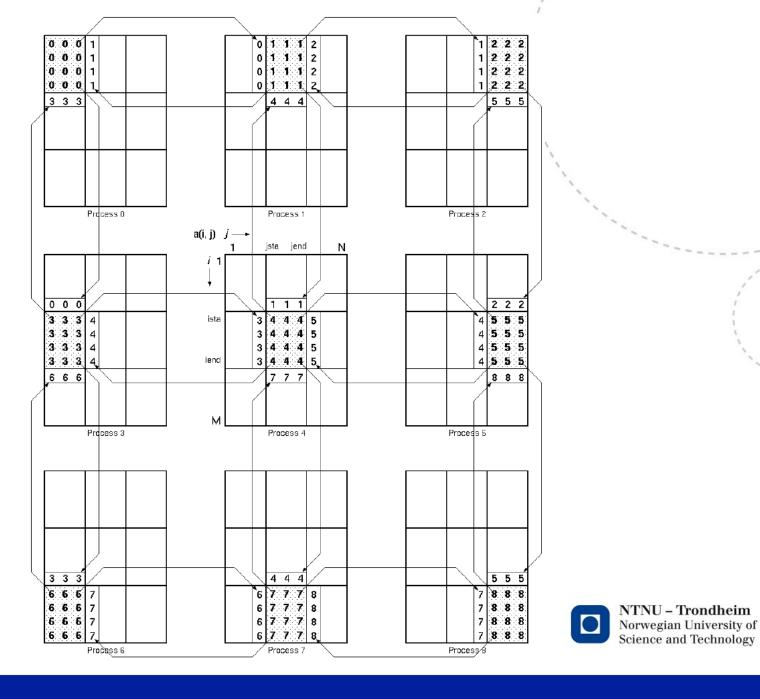


itable(i, j)		<i>j</i> →				
		<u>-1</u>	0	1		_3_
	-1	null	null	null	null	null
i	0	null	0	1	2	null
1	1	null	3	4	5	null
•	2	null	6	7	8	null
	3	null	null	null	null	null

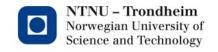
(a) The distribution of a()

(b) The process grid

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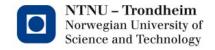


ex2/fdm3.f90



## Block Distribution in Both Dim. (2)

- The corner elements are now included
- The data dependencies are therefore more complex

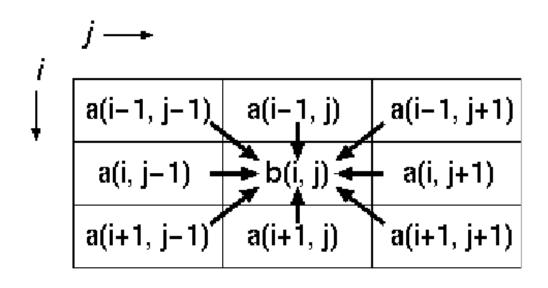


## The Sequential Algorithm

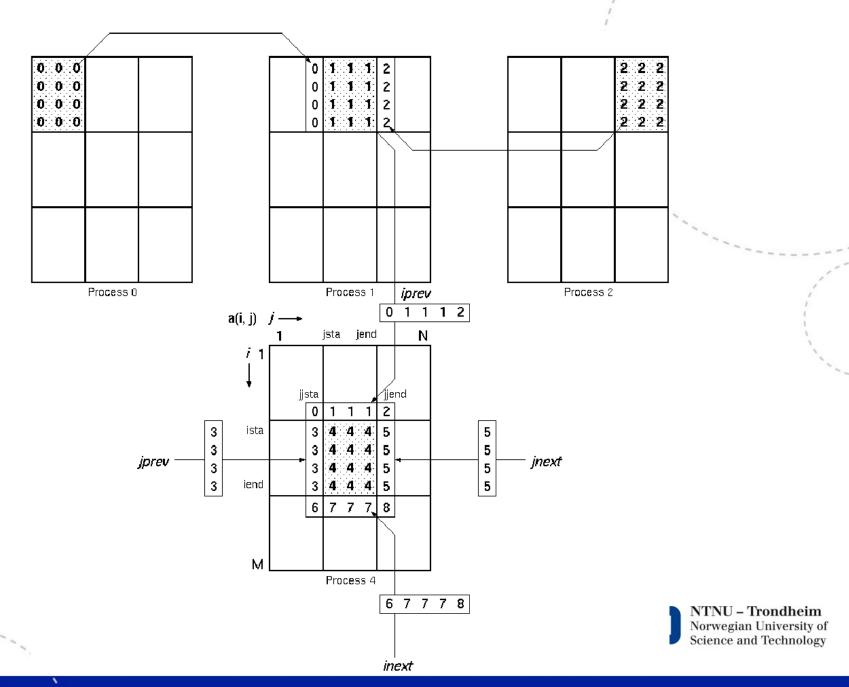
```
PROGRAM main
IMPLICIT REAL*8 (a-h,o-z)
PARAMETER (m=12, n=9)
DIMENSION a(m,n), b(m,n)
D0 j=1, n
  DO i=1, m
    a(i,j) = i + 10.0 * j
  ENDDO
FNDDO
D0 j=2, n-1
  D0 i=2, m-1
    b(i,j) = a(i-1,j) + a(i,j-1) + a(i,j+1) + a(i+1,j) + &
             a(i-1,j-1) + a(i+1,j-1) + a(i-1,j+1) + a(i+1,j+1)
  FNDDO
ENDDO
END
                                                        NTNU - Trondheim
```

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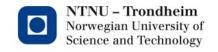
### The Data Dependency







ex2/fdm4.f90

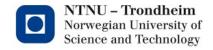


#### 3. Finite Element Method

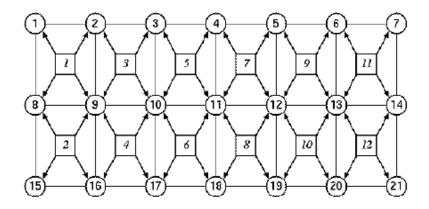
Wikipedia:

"Numerical technique for finding approximate solutions to boundary value problems for partial differential equations"

A more complete example that produces a result

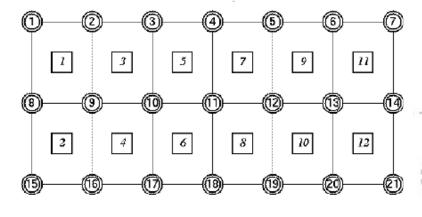


#### Finite Element Method

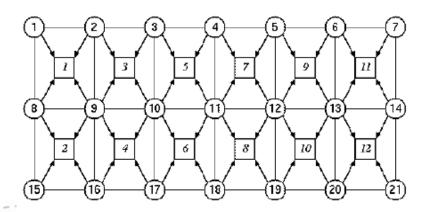


(a) Elements -> Nodes

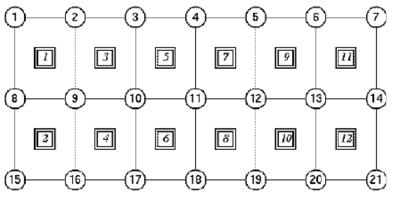
(c) Nodes -> Elements



(b) Update Nodes



(d) Update Elements

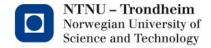


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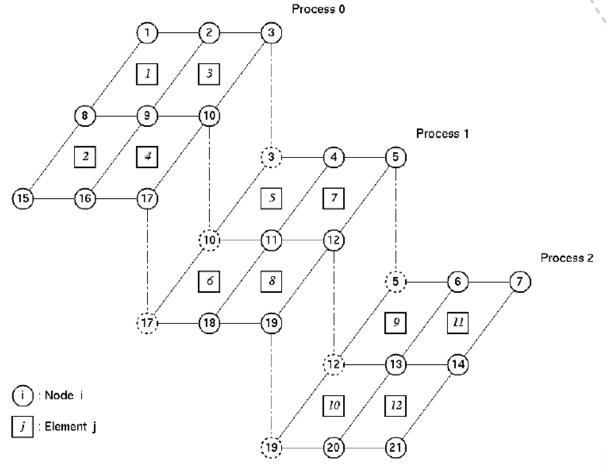
### The Sequential Algorithm

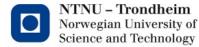
```
PARAMETER(iemax=12, inmax=21)
REAL*8 ve(iemax), vn(inmax)
INTEGER index(4,iemax)
DO ie=1, iemax
 ve(ie) = ie * 10.0
ENDDO
DO in=1. inmax
  vn(in) = in * 100.0
ENDDO
DO itime=1, 10
  DO ie=1, iemax
    D0 j=1, 4
      vn(index(j,ie)) =
vn(index(j,ie)) + ve(ie)
    ENDDO
  ENDDO
```

```
D0 in = 1, inmax
    vn(in) = vn(in) * 0.25
  ENDDO
  D0 ie = 1. iemax
    D0 j = 1, 4
      ve(ie) = ve(ie) + vn(index(j,ie))
    ENDDO
  ENDDO
  D0 ie = 1, iemax
    ve(ie) = ve(ie) * 0.25
  FNDDO
ENDDO
PRINT *,'Result', vn, ve
```



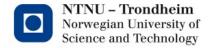
# Distributing the Data



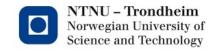


#### Differences from IBM version

- 2D enumeration (row, column) is used instead of 1D enumeration
- The amount of memory allocated by each process is minimized
- A node column is sent to the right
- An element column is sent to the left

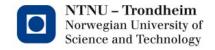


ex3/main.f90 and ex3/grid.f90



#### 4. LU Factorization

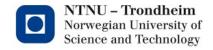
- Wikipedia:
  - "Factors a matrix as the product of a lower triangular matrix and an upper triangular matrix"
  - Used for solving square systems of linear equations:Ax = b
- ScaLAPACK and Intel's MKL library have optimized subroutines for this (outside the scope of this course)
- Pivoting and loop-unrolling is not considered



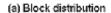
### The Sequential Algorithm

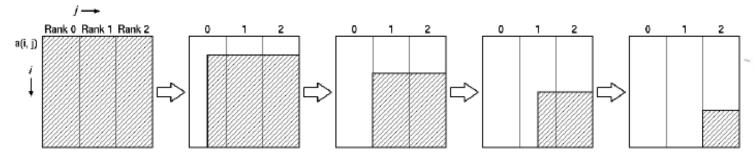
```
PROGRAM main
PARAMETER (n = ...)
REAL a(n,n), b(n)
! LU factorization
D0 k = 1, n-1
  D0 i = k+1, n
    a(i,k) = a(i,k) / a(k,k)
  FNDDO
  D0 j = k+1, n
    D0 i = k+1, n
      a(i,j) = a(i,j)-a(i,k)*a(k,j)
    ENDDO
  FNDDO
ENDDO
```

```
! Forward elimination
D0 i = 2, n
  D0 j = 1, i - 1
    b(i) = b(i) - a(i,j)*b(j)
  FNDDO
ENDDO
! Backward substitution
D0 i = n, 1, -1
  D0 j = i + 1, n
    b(i) = b(i) - a(i,j)*b(j)
  ENDDO
  b(i) = b(i) / a(i,i)
ENDDO
END
```

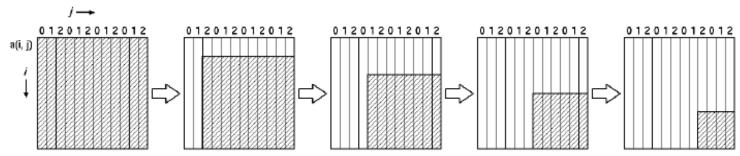


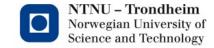
# Cyclic Data Distributing

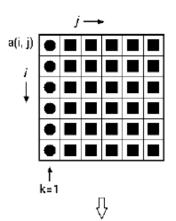


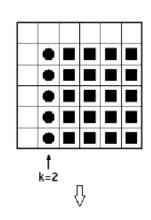


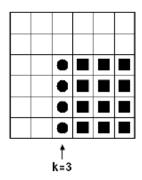
#### (b) Cyclic distribution

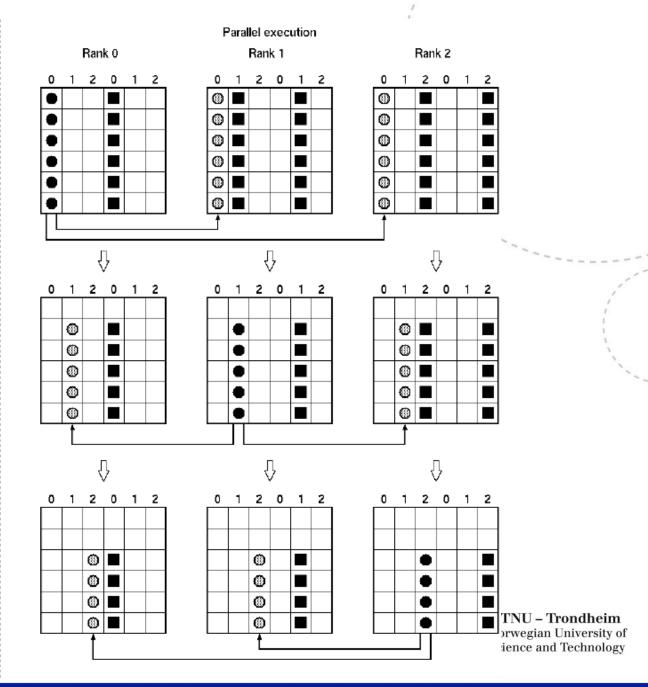




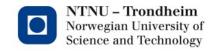








ex4/lu.f90

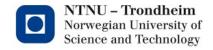


#### 5. The Monte Carlo Method

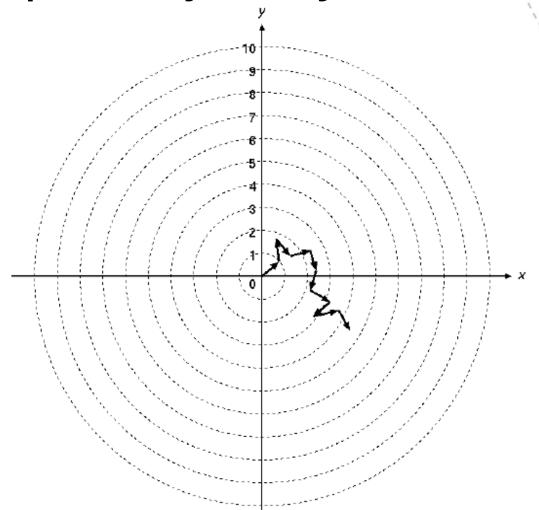
Wikipedia:

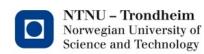
"A broad class of computational algorithms that rely on repeated random sampling to obtain numerical results"

- A random walk in 2D
- 100,000 particles
- 10 steps



# A Sample Trajectory

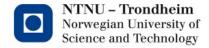




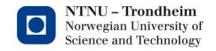
### The Sequential Algorithm

```
PROGRAM main
PARAMETER (n=100000)
INTEGER itotal(0:9)
REAL seed
pi = 3.1415926
D0 i = 0, 9
  itotal(i) = 0
ENDDO
seed = 0.5
CALL srand(seed)
```

```
D0 i = 1, n
    x = 0.0
    y = 0.0
    D0 istep = 1, 10
        angle = 2.0 * pi * rand()
        x = x + cos(angle)
        y = y + sin(angle)
    ENDDO
    itemp = sqrt(x**2 + y**2)
    itotal(itemp) = itotal(itemp) + 1
ENDDO
PRINT *,'total =',itotal
END
```



ex5/mc.f90



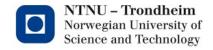
# 6. Molecular Dynamics

Wikipedia:

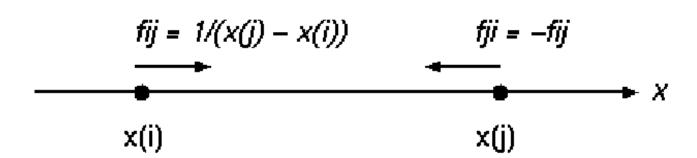
"a computer simulation of physical movements of atoms and molecules"

- N particles interact in 1 dimension
- The force on particle i from particle j is given by  $f_{ij} = 1/(x_i-x_j)$
- The law of action and reaction applies:

$$f_{ij} = -f_{ji}$$

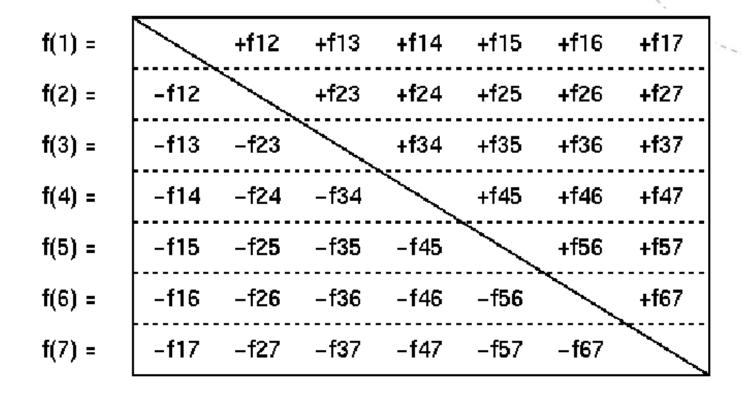


#### Forces in 1D





### Forces Acting on 7 Particles





### The Sequential Algorithm

```
PARAMETER (n = ...)
REAL f(n), x(n)
D0 itime = 1, 100
  D0 i = 1, n
    f(i) = 0.0
  ENDDO
  D0 i = 1, n-1
    D0 j = i+1, n
      fij = 1.0 / (x(j)-x(i))
      f(i) = f(i) + fij
      f(j) = f(j) - fij
    ENDDO
  ENDD0
  D0 i = 1, n
    x(i) = x(i) + f(i)
  ENDDO
ENDD0
```

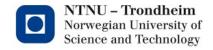


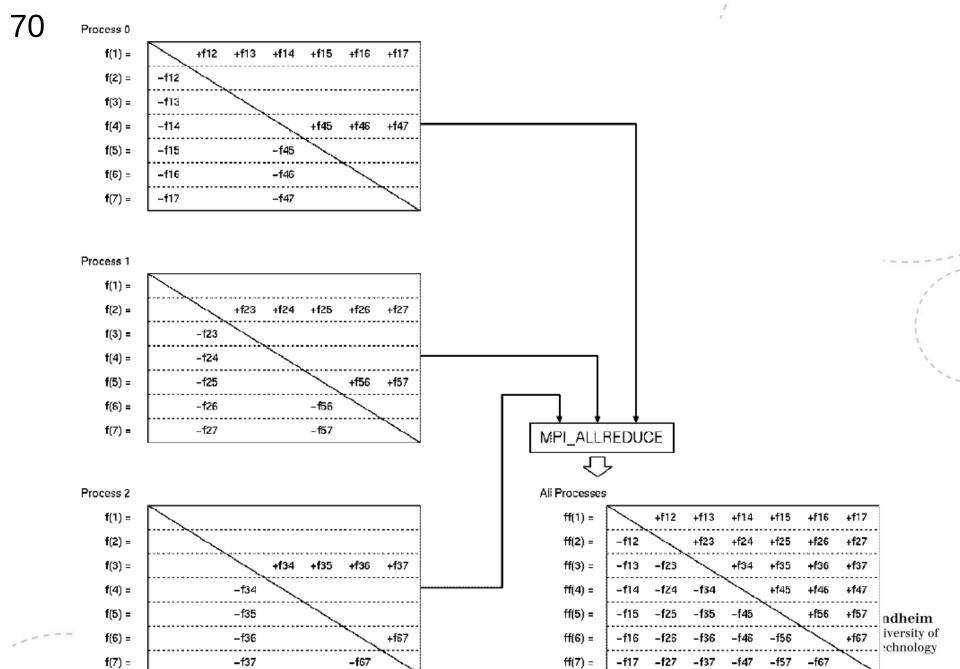
#### Two Parallelisation Methods

Most of the time is spent in the calculation loop:

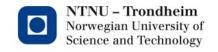
```
D0 i = 1, n-1
  D0 j = i+1, n
    fij = 1.0/(x(j) - x(i))
    f(i) = f(i) + fij
    f(j) = f(j) - fij
  ENDDO
ENDDO
```

- Two parallelization methods:
  - Cyclic distribution of the outer loop
  - Cyclic distribution of the inner loop

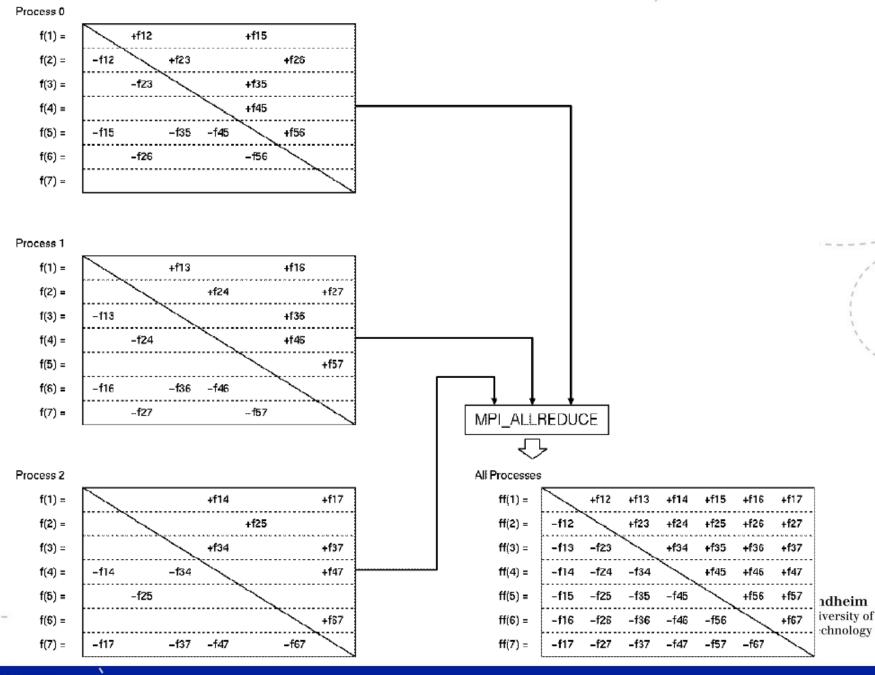




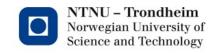
ex6/md1.f90







ex6/md2.f90

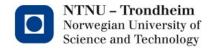


#### 7. MPMD Models

Wikipedia:

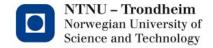
"Multiple Program, Multiple Data: multiple autonomous processors simultaneously operating at least 2 independent programs"

Different programs run in parallel and communicate with each other



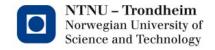
### An example

#### Process 0 Process 1 PROGRAM fluid PROGRAM struct INCLUDE 'mpif.h' INCLUDE 'mpif.h' CALL MPI INIT CALL MPI INIT CALL MPI COMM SIZE CALL MPI COMM SIZE CALL MPI COMM RANK CALL MPI COMM RANK DO itime = 1, n DO itime = 1, n Computation of Computation of Structural Analysis Fluid Dynamics CALL MPI SEND CALL MPI RECV CALL MPI RECV < CALL MPI SEND ENDDO ENDDO END END

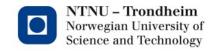


### Master/Worker Programs

- The master coordinates the execution of all the other processes
- The master has a list of jobs that must be processed
- Suitable if:
  - The processing time varies greatly from job to job
  - Neither block nor cyclic distribution gives a good load balancing
  - A heterogeneous environment where the performance of the machines is not uniform



ex7/master.f90 and ex7/worker.f90



#### More Information

- All examples are based on:
  - www.redbooks.ibm.com/redbooks/pdfs/sg245380.pdf
- Our Web-site:
  - http://www.hpc.ntnu.no/
- Send an e-mail to:
  - support-ntnu@notur.no
  - support-kongull@hpc.ntnu.no

