Assignment 2 Optimisation for Computer Science Group 33

Sven Celin & Gabriela Ožegović

December 2019

1 Tasks

1. The size of the matrices is:

 $W^0: N_H \times 3$ $W^1: 4 \times N_H$

 $b^0: N_H$ $b^1: 4 \times 1$

 N_H is the number of hidden layers.

3 is input dimension.

4 is output dimension.

1 because it is a vector.

$$\begin{split} N_{O} &= 4, N_{I} = 3 \\ \begin{bmatrix} z_{1}^{(1)} \\ \vdots \\ z_{N_{H}}^{(1)} \end{bmatrix} &= \begin{bmatrix} W_{1,1}^{(0)} & \dots & W_{1,N_{I}}^{(0)} \\ \vdots & \ddots & \vdots \\ W_{N_{H},1}^{(0)} & \dots & W_{N_{H},N_{I}}^{(0)} \end{bmatrix} \begin{bmatrix} a_{1}^{(0)} \\ \vdots \\ a_{N_{I}}^{(0)} \end{bmatrix} + \begin{bmatrix} b_{1}^{(0)} \\ \vdots \\ b_{N_{H}}^{(0)} \end{bmatrix} \\ \begin{bmatrix} z_{1}^{(2)} \\ \vdots \\ z_{N_{O}}^{(2)} \end{bmatrix} &= \begin{bmatrix} W_{1,1}^{(1)} & \dots & W_{1,N_{H}}^{(1)} \\ \vdots & \ddots & \vdots \\ W_{N_{O},1}^{(1)} & \dots & W_{N_{O},N_{H}}^{(1)} \end{bmatrix} \begin{bmatrix} a_{1}^{(1)} \\ \vdots \\ a_{N_{H}}^{(1)} \end{bmatrix} + \begin{bmatrix} b_{1}^{(1)} \\ \vdots \\ b_{N_{O}}^{(1)} \end{bmatrix} \end{split}$$

- 2. N/A
- 3. Parameters are initialized in method initNormalDistribution. There was an idea to make normal distribution for values of the $W^{(0)}, W^{(1)}, b^{(0)}, b^{(1)}$ for values $\mu = 0$ and $\sigma = 0.05$.
- 4. Forward pass is implemented in neural network with one hidden layer. Dimensions of that hidden layer are N_H and after passing trough Softmax and Softplus functions we get a and z.
- 5. Backward pass using back-propagation method is implemented in back-prop function. After passing trough back-propagation function we get derivatives of the parameters and we use them to check results with \tilde{y} .
- 6. We make list of vectors from y and \tilde{y} and after that we iterate trough that list of vector pairs. For 1000 iterations we search for steepest descent function. Step we choose is $k^k = 0.01$.

7.

$$\mathcal{A} = \frac{1}{S} \sum_{n=1}^{S} \delta(y^{s}, \tilde{y}^{s}) \quad \text{with } \delta(u, v) = \begin{cases} 1 & \text{if } u = v \\ 0 & \text{else,} \end{cases}$$

We train data $W^{(0)}, W^{(1)}, b^{(0)}, b^{(1)}$. Using them we run forward feed from where we get \tilde{y} . \tilde{y} is result of one pair of the vectors. Then we compare \tilde{y} with y test in every iteration in vector list. From that we get accuracy.

- 8. We train parameters $W^{(1)}$, $b^{(1)}$ using x-train and y-train. After training the parameters we put last feed forward where we check accuracy of x-test and y-test and we get numbers that signifies difference.
- 9. We created 3D scatter plot in drawPlot method that gives us visual representation of trained and real model.

Dots which are colored with red are x^s dots with corresponding $x^s = 0$ true values. Dots which are colored with blue are x^s dots with corresponding $y^s = 1$ true values. Dots which are colored with green are x^s dots with corresponding $y^s = 2$ true values. Dots which are colored with yellow are x^s dots with corresponding $y^s = 3$ true values. In case of correct value there would be plus signs matching the points in correct places.

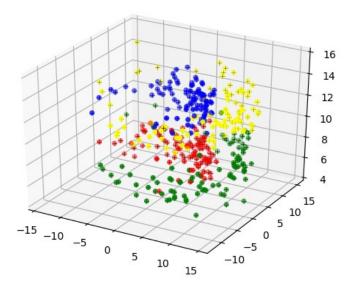


Figure 1: Graph