## Mathematics of Neural Networks winter semester 2021/2022 exercise sheet 7

**Exercise 1:** (2 points) Use the extended Euclidean algorithm to compute a GCD g of the two polynomials

$$a(u) := u^4 + 3u^3 - 8u^2 - 12u + 16, \quad b(u) := u^4 + u^3 - 7u^2 - u + 6,$$

and two polynomials c, d, such that

$$ac + bd = q$$

holds true.

Hint: You can implement the extended Euclidean algorithm (See Algorithm 3.1 on page 122 of the lecture notes<sup>1</sup>) with the Python package sympy. Use sympy.quo(f, g) to obtain the quotient of polynomials f and g. The computed output has rational coefficients and thus has to be scaled.

Use the following skeleton:

```
2
   quo computes for given f,g the quotient q with
   f = q*g + r for some rest term r
   degree returns the degree of a given polynomial
5
 6
7
   expand returns a polynomial in standard representation
   expand(f) = \sum_{i=0}^n f_i x^i
8
   from sympy
                  import quo, degree, expand
10
   from sympy.abc import u
11
12
13
   def extended_euclidean_algorithm(a, b):
14
15
     TODO Implement the extended Euclidean algorithm
16
17
          with sympys div
18
19
     pass
20
21
   if __name__ == '__main__':
22
     a = u**4 + 3*u**3 - 8*u**2 - 12*u + 16
23
     b = u**4 + u**3 - 7*u**2 - u + 6
24
25
     r, c, d = extended_euclidean_algorithm(a, b)
```

<sup>&</sup>lt;sup>1</sup>version from 01.11.2021

```
27 | print('GCD<sub>\upsi</sub>=', r)

28 | print('c<sub>\upsi</sub>=', c)

29 | print('d<sub>\upsi</sub>=', d)

30 | print('Error<sub>\upsi</sub>in<sub>\upsi</sub>Bezout<sub>\upsi</sub>=', expand(a*c + b*d - r))
```

Exercise 2: (3+1 points)

- a) Compute a minimal Winograd algorithm for the full convolution  $\mathbf{z} = \mathbf{x} * \mathbf{f}$ , where  $\mathbf{x} \in \mathbb{R}^3$  and  $\mathbf{f} \in \mathbb{R}^2$ . Use the four points  $g_1 = 0$ ,  $g_2 = 1$ ,  $g_3 = -1$ , and  $g_4 = \infty$ .
- b) Give the matrices A, B, and C of the matrix form

$$\mathbf{z} = \mathbf{A}^{\!\mathsf{T}}((\mathbf{B}\mathbf{x}) \circ (\mathbf{C}\mathbf{f})).$$

Hint: In the lecture you developed a minimal algorithm for  $\mathbf{x} \in \mathbb{R}^2$  and  $\mathbf{f} \in \mathbb{R}^2$  (see page 124 of the lecture notes<sup>1</sup>). Extend this example to  $\mathbf{x} \in \mathbb{R}^3$  and  $\mathbf{f} \in \mathbb{R}^2$ .

Exercise 3: (2+1+2\* points)

a) Let  $\mathbf{x} \in \mathbb{R}^n$ ,  $\mathbf{f} \in \mathbb{R}^k$ , and  $\mathbf{y} \in \mathbb{R}^{n+k-1}$  be given. Prove that

$$\sum_{i=0}^{n-1} x_i \sum_{j=0}^{k-1} y_{i+j} f_j = \sum_{p=0}^{n+k-2} y_p \sum_{\ell=0}^p x_{\ell} f_{p-\ell},$$

where undefined entries  $x_{\ell}$  and  $f_{p-\ell}$  are zero.

b) Show that the full convolution of  $\mathbf{x} \in \mathbb{R}^n$  and  $\mathbf{f} \in \mathbb{R}^k$  is related to the computation of the valid cross-correlation of  $\mathbf{y} \in \mathbb{R}^{n+k-1}$  and  $\mathbf{f} \in \mathbb{R}^k$  or FIR filter F(n,k)

$$\begin{pmatrix} y_0 & y_1 & \cdots & y_{k-1} \\ y_1 & y_2 & \cdots & y_k \\ \vdots & \vdots & & \vdots \\ y_{n-1} & y_n & \cdots & y_{n+k-2} \end{pmatrix} \begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_{k-1} \end{pmatrix}$$

by computing the scalar product of the resulting vector with  $\mathbf{x} \in \mathbb{R}^n$  and using part a).

c) Use this result to derive a minimal algorithm for F(3,2) from a minimal algorithm for the full convolution of  $\mathbf{x} \in \mathbb{R}^3$  and  $\mathbf{f} \in \mathbb{R}^2$ .

Hint: A change of the summation order may be helpful for part c)

Exercise 4: (3 points) Compare the computation time for the different implementations of the evaluation of a convolutional layer. In addition to the already implemented methods evaluate\_scipy(), evaluate\_fft() and evaluate\_im2col() you can find an implementation of the Winograd approach for filters  $F \in \mathbb{R}^{3,3}$  called evaluate\_winograd() in layers.py. Compare them using a different number of images, corresponding height and width and channels for randomly generated input. For example you can try

- 100 and 20 for the number of inputs,
- 3 and 50 for the number of channels,
- 28 and 100 for the height/width of the input.

What can you oberserve?

You can use the following skeleton.

```
from time
              import process_time
 2
  from layers import *
 3
  0.00
 4
5
  TODO Test the evaluations for different numbers of inputs,
6
        channels, and different input dimensions
7
8 \mid n, c, h, w = None
9
10 m, fh, fw = 32, 3, 3
11 \mid tensor = (c, h, w)
12 | fshape = (m, fh, fw)
13 conv = Conv2DLayer(tensor, fshape)
14
15 # generate random input
16 \times = \text{np.random.randint}(0, 10, (n, c, h, w))
17
18 # test winograd
19 | print('----',')
20 | start = process_time()
  0.00
21
22 TODO Add the evaluation of the convolutional layer with
23
       the wingrad minimal algorithm
24 | " " "
25 time_winograd = process_time() - start
26 | print ('Timeusedubyuwinograd:', time_winograd, 'seconds')
27
28 # test im2col
29 | print('-----'m2col-----')
30 start = process_time()
31
  TODO Add the evaluation of the convolutional layer with
32
       the im2col method
33
34
35
  time_im2col = process_time() - start
36
  print('Time_used_by_im2col:', time_im2col, 'seconds')
37
38 # test
   print('----')
39
40 | start = process_time()
41 """
42 TODO Add the evaluation of the convolutional layer with
43
       the the fft method
  0.00
44
45 time_fft = process_time() - start
46 | print('Time_used_by_fft:', time_fft, 'seconds')
47
48 | # test
  | print('-----')
49
50 start = process_time()
  0.00
51
52 TODO Add the evaluation of the convolutional layer with
53
       the scipy convolutions
  .....
54
55 time_scipy = process_time() - start
56 | print('Time_used_by_scipy:', time_scipy, 'seconds')
```