class accessorycommunication.model

«enumeration» RequestCommand

NOOP GET PROTOCOL VERSION

GET_FEATURES
TURN_CAR
ADJUST_SPEED
ROTATE CAM

GET_BATTERY_STATE

Attributes

- + messageld: byte {readOnly}
- + payloadLength: short {readOnly}
- ~ RequestCommand(byte, short)

CarFeatures

- + adjustableSpeed: boolean {readOnly}
- + batteryPower: boolean {readOnly}
- + cameraPanMax: float (readOnly)
- + cameraPanMin: float {readOnly}
- + cameraTiltMax: float {readOnly}
- + cameraTiltMin: float {readOnly}+ driveBackward: boolean {readOnly}
- + CarFeatures(float, float, float, float, boolean, boolean, boolean)
- + supportPanCamera(): boolean+ supportTiltCamera(): boolean

«enumeration» **ResponseMessage**

REQUEST OK

ERROR

BATTERY_NEAR_EMPTY

PROTOCOL_VERSION FEATURES

BATTERY_STATE

Attributes

- + messageld: byte {readOnly}
 + payloadLength: short {readOnly}
- map: SortedMap<Byte, ResponseMessage> = new TreeMap<Byt... {readOnly}
- ~ ResponseMessage(byte, short)
- + get(byte): ResponseMessage

«enumeration» Frontd

UNDEFINED_ERROR INVALID_COMMAND_ERROR

UNKOWN_COMMAND_ERROR PROCESS_COMMAND_ERROR

Attributes

- errorld: short {readOnly} map: SortedMap<Short, Errorld> = newTreeMap<Sho... {readOnly}</p>
- Errorld(short)aet(short): Errorld