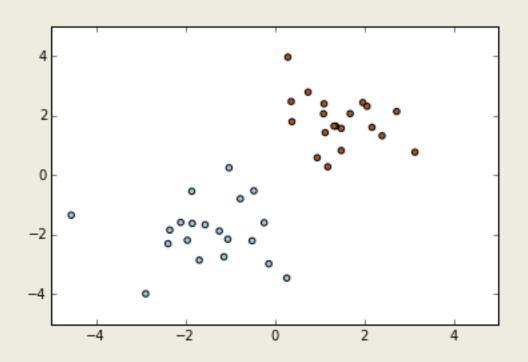
Data Science

Agenda

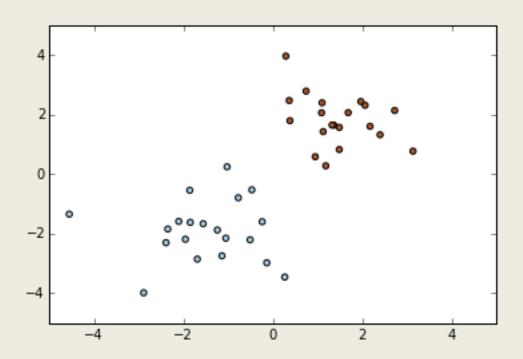
- Support Vector Machine
- Non-linear classification, Kernels
- Noisy examples
- SVM Practice in Python

Q: How would you build a classifier for this problem?



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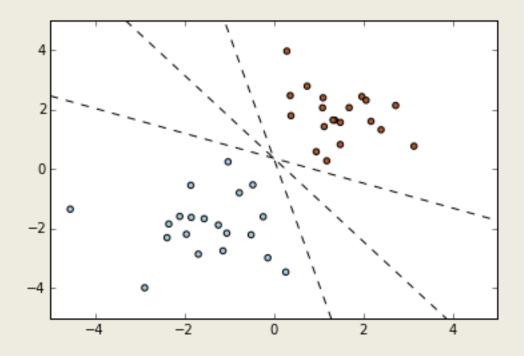
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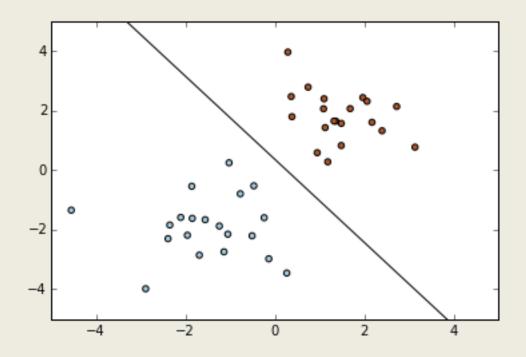
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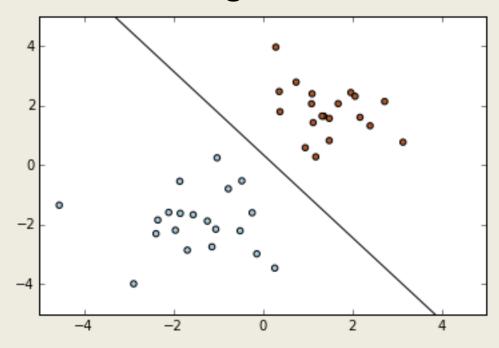


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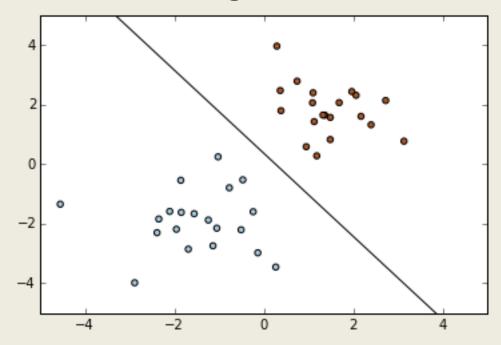


Q: How would you build a classifier for this problem?

A: A line can separate the classes (linearly separable)

Q: Which line is the best? Why?

A: Minimizes the generalization error. Maximizes the margin

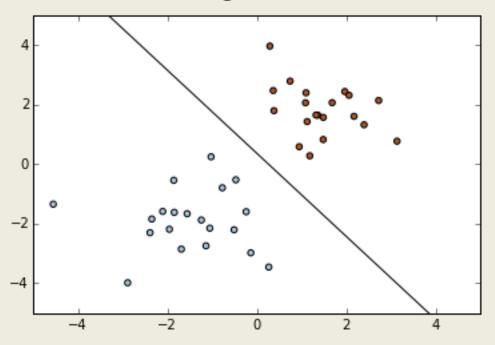


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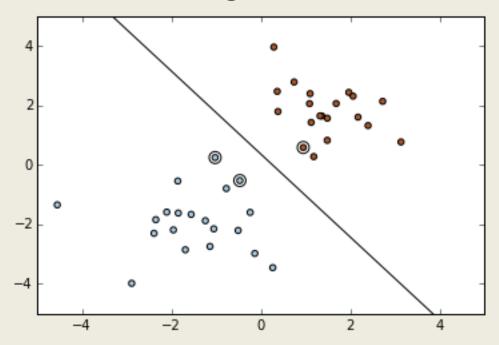
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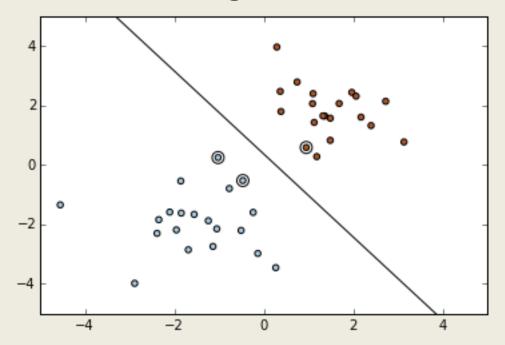
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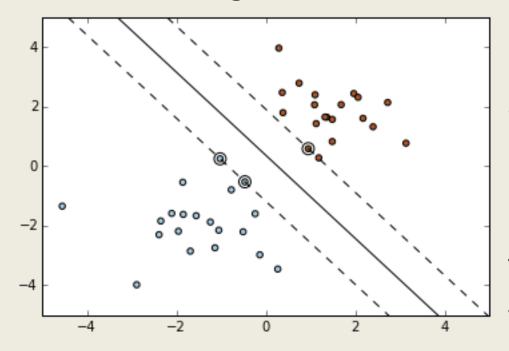
These points are called the **Support Vectors**

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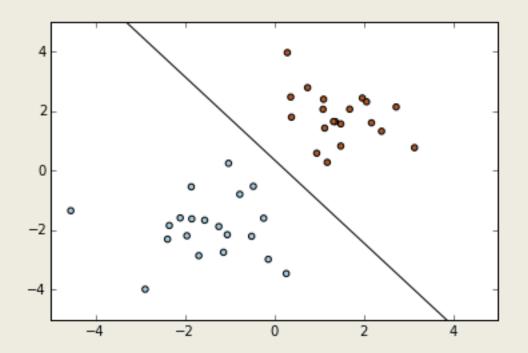


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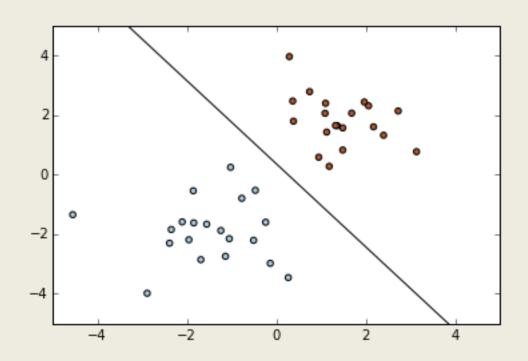
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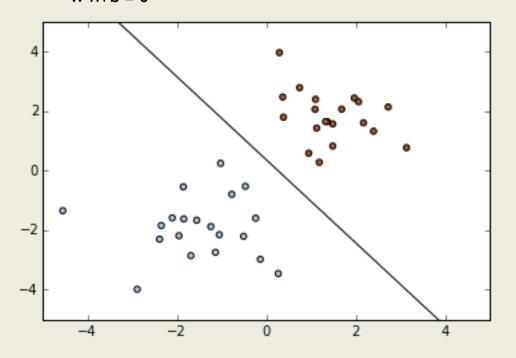
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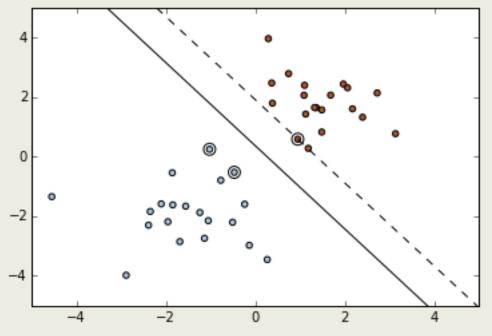
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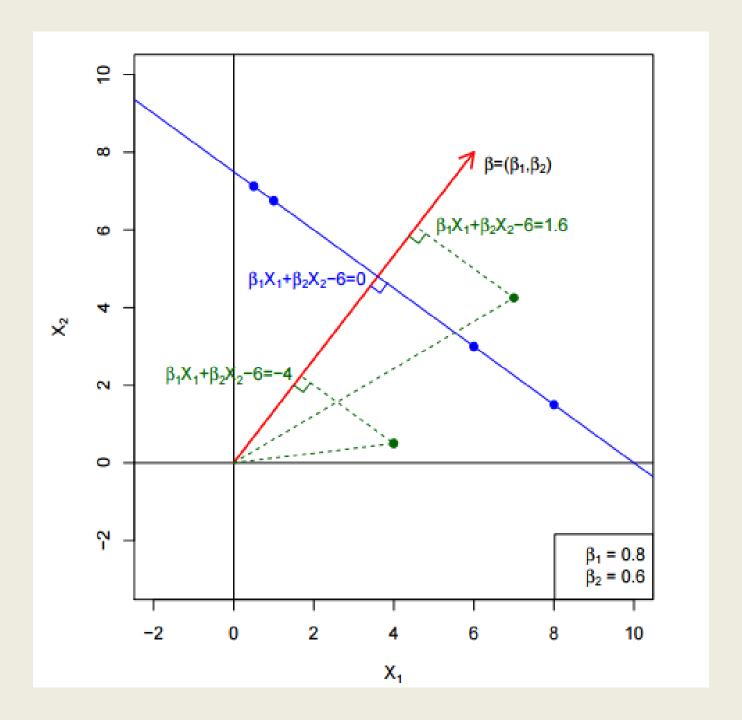


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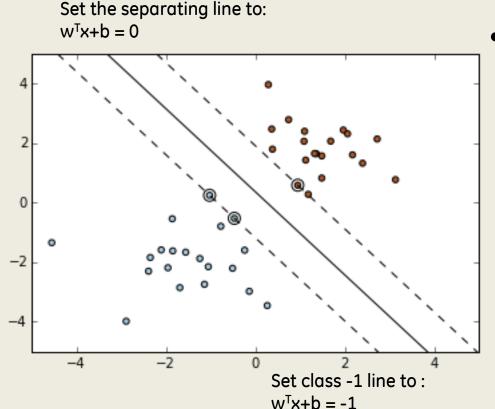
 $w^Tx+b=0$ Set class 1 line to: $w^Tx+b=1$ Set class -1 line to: $w^{T}x+b = -1$

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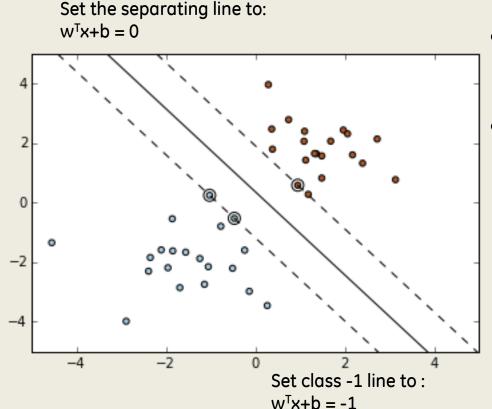
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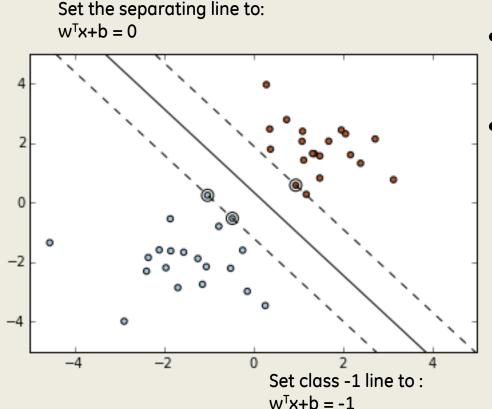
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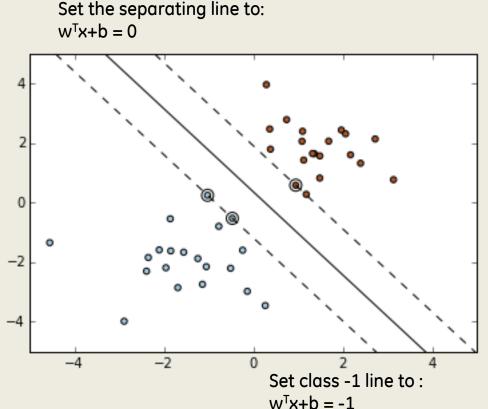
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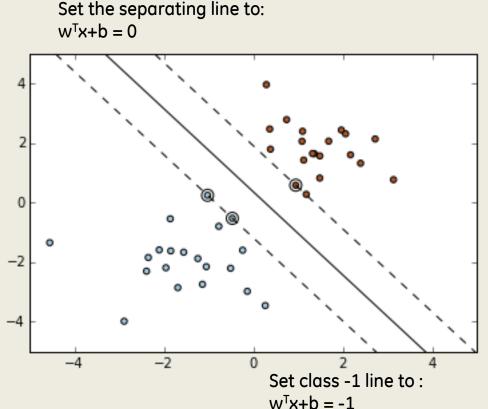
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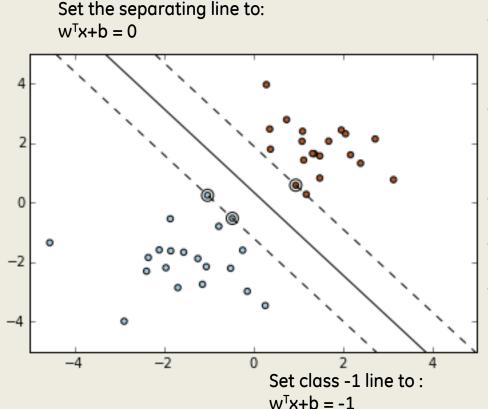
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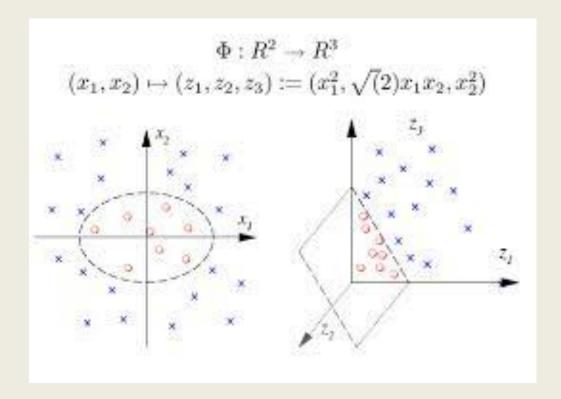
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- Classify: $f(x) = sign(w^Tx + b)$

- Objective:
 - Minimize $||w||^2/2$
 - S.T. $y_i(w^Tx_i + b) >= 1$
- It turns out that we can reformulate this problem to:
 - $-\operatorname{\mathsf{Max}} \Sigma_{\mathbf{i}}\alpha_{\mathbf{i}}\text{-}1/2\ \Sigma_{\mathbf{i}\mathbf{j}}\alpha_{\mathbf{i}}\alpha_{\mathbf{j}}y_{\mathbf{i}}y_{\mathbf{j}}x_{\mathbf{i}}{}^{\mathrm{T}}x_{\mathbf{j}}$
 - s.t. $\alpha_i >= 0$ and $\Sigma_i \alpha_i y_i = 0$
- Then $w = \sum_{i} \alpha_{i} y_{i} x_{i}$
- It turns out that $\alpha_i = 0$ for non support vectors
- Now we can classify by: $f(x) = sign(\Sigma_i \alpha_i y_i < x_i, x >)$
- Note that this is line Nearest Neighbors where the neighbors have been selected for you

Q: What happens if our data is not linearly separable?

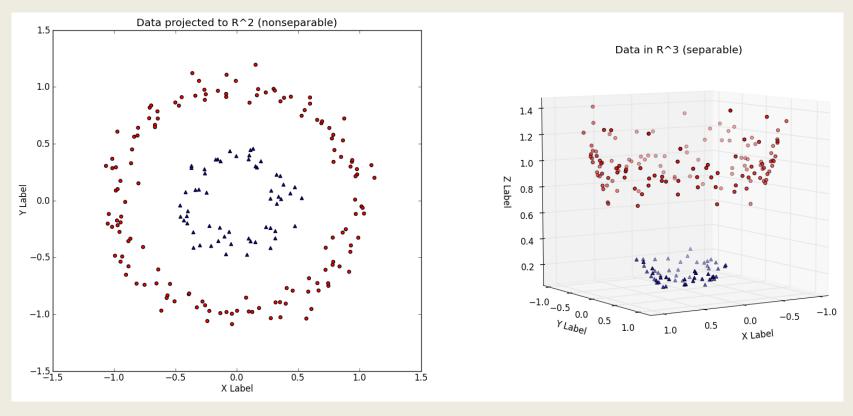
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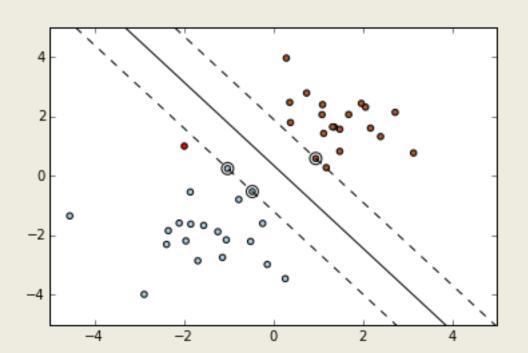
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 - Gaussian: $K(x_1,x) = \exp(-||x_1-x||^2/(2\sigma^2))$
 - Linear: $K(x_1,x) = \langle x_1,x \rangle$
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- Our new classifier is now $f(x) = sign(\Sigma_i \alpha_i y_i K(x_i, x))$

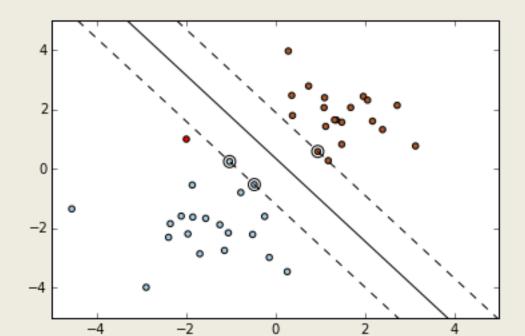
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A: We introduce the idea of a slack variable:

- $-\zeta_i$ is a slack variable
- Now solve min $||w||^2 + C\Sigma_i \zeta_i$
- Now the constraint is $y_i(w^Tx_i + b) >= 1-\zeta_i$ where $\zeta_i >= 0$



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- We can classify new points with $f(x) = sign(\Sigma_i \alpha_i y_i K(x_i, x))$

Questions?