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from collections import defaultdict
   class Graph:
       def __init__(self):
           self.graph = defaultdict(list)
       def add edge(self, u, v):
            """Add an edge to the graph."""
           self.graph[u].append(v)
       def dls(self, node, target, depth):
           Perform Depth-Limited Search (DLS) from the current node.
            :param node: Current node
            :param target: Target node
            :param depth: Maximum depth to explore
            :return: True if target is found, False otherwise
           if depth == 0:
               return node == target
           if depth > 0:
               for neighbor in self.graph[node]:
                    if self.dls(neighbor, target, depth - 1):
                        return True
           return False
       def iddfs(self, start, target, max_depth):
           Perform Iterative Deepening Depth-First Search (IDDFS).
            :param start: Starting node
            :param target: Target node to search for
            :param max depth: Maximum depth limit for IDDFS
            :return: True if target is found, False otherwise
           for depth in range(max_depth + 1):
               print(f"Searching at depth: {depth}")
                if self.dls(start, target, depth):
                    return True
           return False
   # Example Usage
   if __name__ == "__main__":
       g = Graph()
       # Construct the graph
       g.add_edge(0, 1)
       g.add edge(0, 2)
       g.add edge(1, 3)
       g.add_edge(1, 4)
       g.add_edge(2, 5)
       g.add_edge(2, 6)
       start node = 0
       target_node = 5
       max_depth = 3
       # Perform IDDFS
       if g.iddfs(start_node, target_node, max_depth):
           print(f"Target node {target node} found within depth {max depth}")
       else:
           print(f"Target node {target node} NOT found within depth {max depth}")
https://colab.research.google.com/drive/1c8qSvfCJYzwVp5fT5BEC1iS-ZBSUOa6c#scrollTo=8YeFVuH6ZnXR&printMode=true
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Searching at depth: 0
Searching at depth: 1
Searching at depth: 2
Target node 5 found within depth 3