

## **Helpful resources:**

- Adafruit Barometric Pressure Sensor: <a href="https://www.adafruit.com/product/1893">https://www.adafruit.com/product/1893</a>
- I2C cable: <a href="https://www.adafruit.com/product/3955">https://www.adafruit.com/product/3955</a>
- FeatherS2: <a href="https://unexpectedmaker.com/shop/feathers2-esp32-s2">https://unexpectedmaker.com/shop/feathers2-esp32-s2</a>
- Swarm GitHub: <a href="https://github.com/Swarm-Technologies/Getting-Started">https://github.com/Swarm-Technologies/Getting-Started</a>
- Code with Mu: <a href="https://codewith.mu/">https://codewith.mu/</a>
- Swarm Developer Tools: https://swarm.space/developertools/

## **Installation Instructions:**

- Download a copy of "Example-Barometric-Pressure" from <u>Swarm's Github</u> repository
- Remove the cover from the eval kit
- 3. Connect the sensor to the eval kit using a JST 4-PH cable plugged into J4 (I2C Header)
- 4. Connect your FeatherS2 to your computer using a USB-C cable and open the storage folder
- 5. Create a backup of all the files stored on the FeatherS2 in case you need to revert back to the previous project that was being used
- Delete all of the files located on the FeatherS2
- Copy the contents of the root folder from the "Example-Barometric-Pressure" repository to the FeatherS2
- 8. The code.py file is used to take a measurement of the sensor once every ~30 minutes. The timestamp of the measurement, barometric pressure, altitude, and temperature is logged and formatted into a \$TD message for transmission to the Hive. The frequency of sensor measurements can be changed in the code.py file in line 128. The code also uses the RGB LED on the eval kit to display the RSSI range with the colors red, yellow, and green depending on the type of Swarm Modem being used.

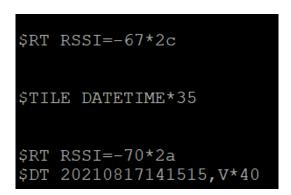


- a. Please note that the sensor utilizes your local sea level pressure for more accurate measurements. Your local sea level pressure can be found using local weather station data, or from weather websites. This value can be changed in line 143 of the code.py file
- 9. Unplug the USB-C cable from the FeatherS2 and power on your eval kit
- 10. Connect the FeatherS2 to your PC using the USB-C cable. Start a serial terminal session using the following settings:

Parameter	Value
Baud Rate	115200
Data Bits	8 Bits
Parity	None
Stop bits	1 Bit
Flow Control	None

Note: The FeatherS2's COM port can be found under the device manager.

11. You will see the device's RSSI values printed in the terminal session along with the Swarm Modem startup information. You will also see the datetime values once the Swarm Modem has acquired its date and time



12. Unplug the USB-C cable from the FeatherS2



- 13. Mount the eval kit onto its tripod and place it in an area with a clear view of the sky. Monitor the RGB LED and ensure that it is green
- 14. The eval kit will queue a message onto the Swarm Modem every ~30 minutes (default) formatted as *timestamp*, *pressure*, *altitude*, *temp*
- 15. The messages queued on the Swarm Modem will transmit when a satellite is in range and the device is powered on. Please ensure that the device is placed in a location where it has a clear view of the sky and there are no objects placed close to the antenna. Satellite passes over your location can be checked using Swarm's pass checker
- 16. Once a message has been transmitted, it will show on the Hive under the device ID for the Swarm Modem that is installed in the eval kit
- 17. The data can then be pulled from the Hive using Swarm's REST API