

## Progress Report

**Name:** Swarnadwip Sarkar  
**Course:** Control Design Onramp with Simulink  
**Progress:** **100%** complete (as of 7 May 2025)

### Chapters

1. Course Overview **100%**
2. Control System Plants **100%**
3. Linearizing the Plant with Model Linearizer **100%**
4. Feedback Control with PID **100%**
5. PID Tuning **100%**
6. Project - Robotic Leg Control **100%**
7. Conclusion **100%**