

1) Divergence Theorem (Crauss divergence theorem)

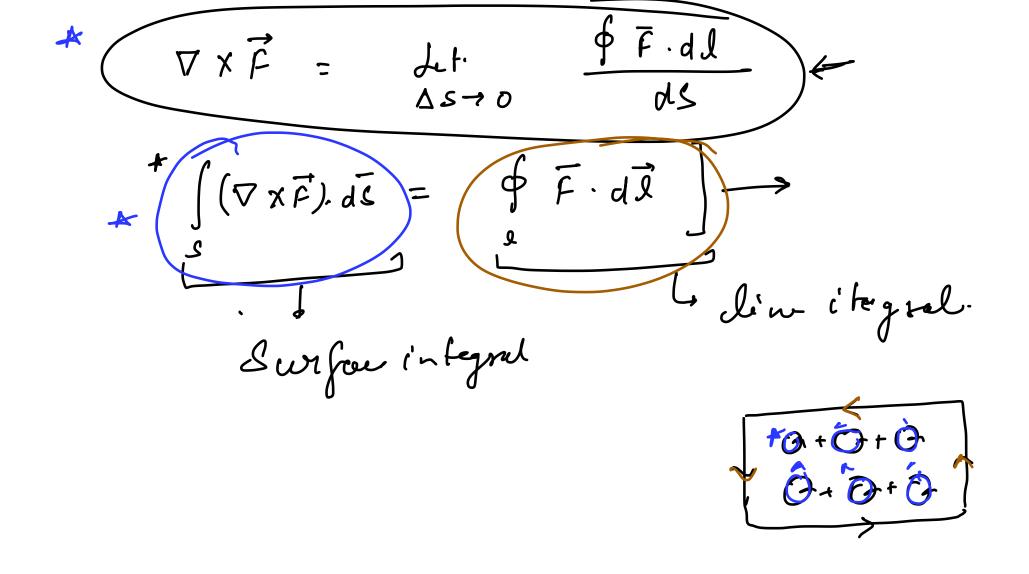
1 Cevel Theorem (Stoke's theorem)

$$\frac{\nabla \cdot \vec{F}}{\nabla \cdot \vec{F}} = \lim_{V \to 0} \oint_{V \to 0} \frac{\vec{F} \cdot d\vec{S}}{dV}$$

$$\int_{V} (\nabla \cdot \vec{F}) dV = \oint_{S} \vec{F} \cdot d\vec{S}$$

$$\int_{V} (\nabla \cdot \vec{F}) dV = \oint_{S} \vec{F} \cdot d\vec{S} = 0$$

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$$\int_{V} (\nabla \cdot \vec{F}) dV = \oint_{S} \vec{F} \cdot \vec{dS}$$

Gauss Theorem

 $\int_{S} (\nabla \times \vec{F}) \cdot \vec{dS} = \oint_{S} \vec{F} \cdot \vec{dI}$

Stoke's Theorem

Scalar and Vector

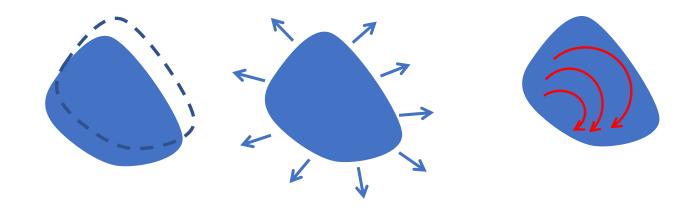
- Scalars are quantities that are fully described by a magnitude (or numerical value) alone. For example, length, speed, work, mass, density, etc.
- **Vectors** are quantities that are fully described by both a magnitude and a direction. For example, force, torque, momentum, acceleration, velocity, etc.

$$\vec{r} = a\hat{x} + b\hat{y} + c\hat{z}$$

$$= a\hat{i} + b\hat{j} + c\hat{k} = \langle a, b, c \rangle$$

- Vector possess both magnitudes as well as direction.
- They do not obey the ordinary laws of Algebra.
- Vector change if either the magnitude or direction change or both changes.

Gradient, Divergence and Curl



- A. In a smalltime *t* the center of the body will move.
- B. The body can expand or contract, changing its volume.
- C. The body can rotate.

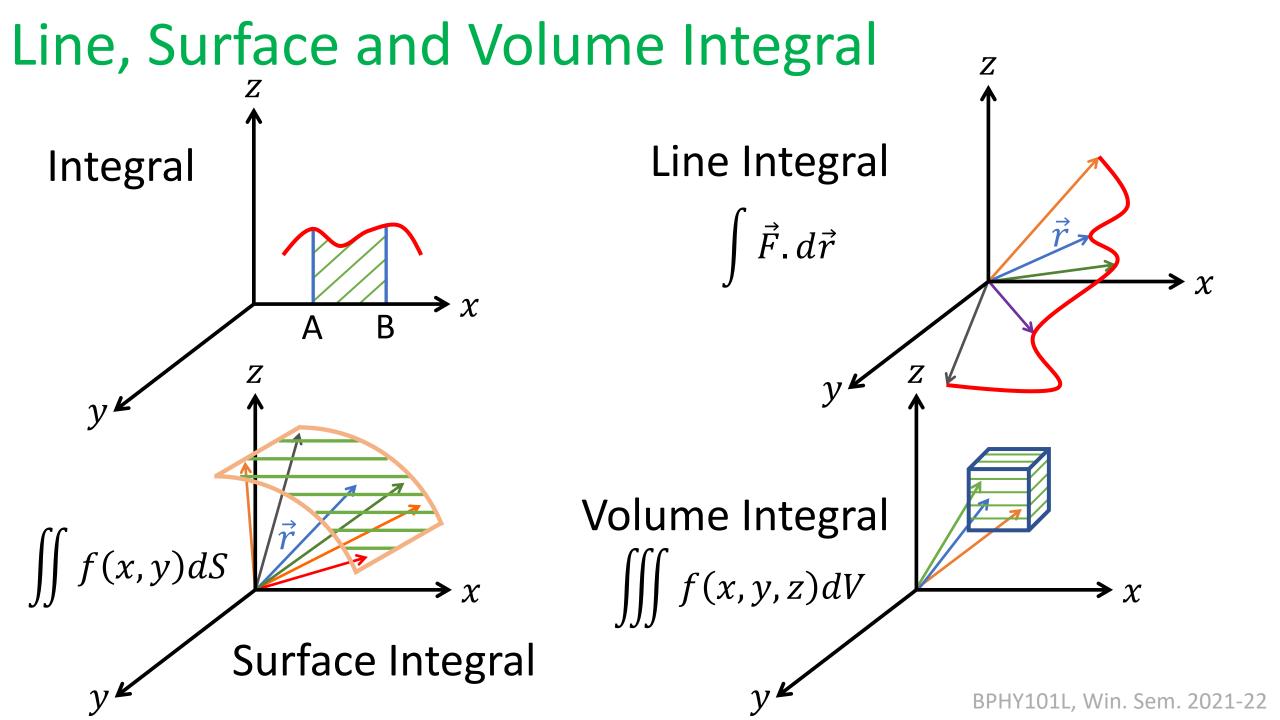
Gradient: the derivative of a function with respect to distance along the direction in which the function changes most rapidly.

$$\nabla = \frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}$$

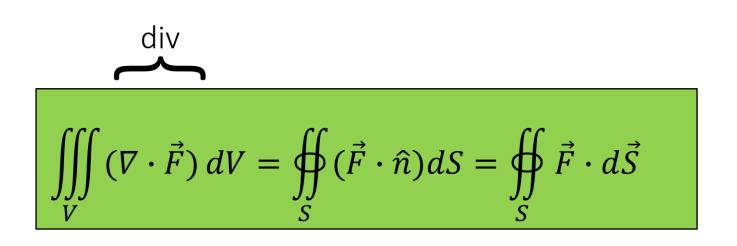
Divergence:
$$\nabla f(x, y, z) = \left(\frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}\right) f(x, y, z)$$

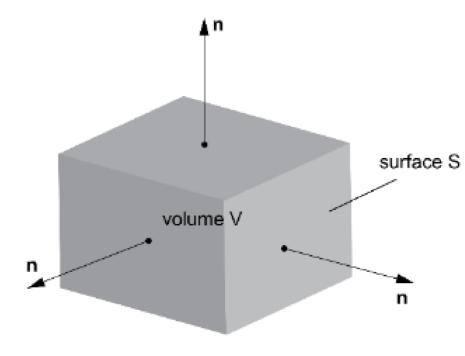
Curl:
$$\nabla \times f(x, y, z) = \left(\frac{\partial}{\partial x}\hat{x} + \frac{\partial}{\partial y}\hat{y} + \frac{\partial}{\partial z}\hat{z}\right) \times f(x, y, z)$$

$$= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & f \end{vmatrix} = \left(\frac{\partial f}{\partial y} - \frac{\partial f}{\partial z}\right)\hat{x} + \left(\frac{\partial f}{\partial z} - \frac{\partial f}{\partial x}\right)\hat{y} + \left(\frac{\partial f}{\partial x} - \frac{\partial f}{\partial y}\right)\hat{z}$$



Divergence (Gauss') Theorem





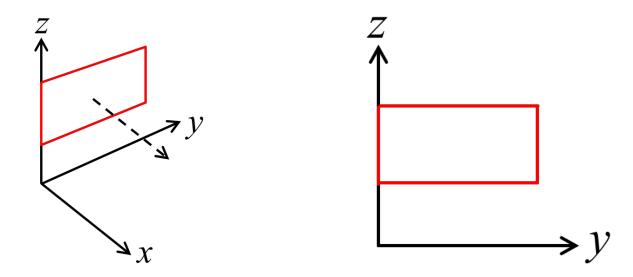
Integral of divergence of vector field (\vec{F}) over volume V inside closed boundary S **equals** outward flux of vector field (\vec{F}) through closed surface S

$$\nabla \cdot \vec{F} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) \cdot \left(F_x, F_y, F_z\right) = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

Curl (Stokes') Theorem

$$\iiint\limits_{S} (\nabla \times \vec{F}) \cdot d\vec{S} = \iint\limits_{S} ((\nabla \times \vec{F}) \cdot \hat{n}) dS = \oint\limits_{\partial S} \vec{F} \cdot d\vec{l}$$

Integral of curl of vector field (\vec{F}) over surface S equals line integral of vector field (\vec{F}) over closed boundary dS defined by surface S



Problem:1 $\vec{F} = 4xz\hat{\imath} - y^2\hat{\jmath} + yz\hat{k}$, Find $div\vec{F}$, and $curl\vec{F}$

Problem:2 $\vec{F} = (2x + yz)\hat{\imath} + xz\hat{\jmath} + xy\hat{k}$, Find $div\vec{F}$, and $curl\vec{F}$

Problem:3 F = xyz, Find ∇F