

VGG Net

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Ex 10.2: Narrow vs Wide Kernels

1. A stack of  $S$   $3 \times 3 \times C \times C$  ~~channels~~ kernels

$$N_{p,1} \approx S \cdot (3^2 C^2) \text{ parameters}$$

$$\begin{aligned} \text{effective kernel size / receptive fields} &: 3 + (3-1)(S-1) \\ &= 2S+1 \end{aligned}$$

2. Single ~~25~~  $(2S+1) \times (2S+1) \times C \times C$  ~~Reke~~ kernels

$$N_{p,2} \approx (2S+1)^2 C^2$$

$$\frac{N_{p,1}}{N_{p,2}} = \frac{9S}{(2S+1)^2} = \begin{array}{cccc} S=1 & 2 & 3 & 4 \\ 100\% & 72\% & 55\% & 44\% \end{array}$$

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10-37 — Residual block is a must when we have a deep architecture

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## 10.4 Networks and Modules for object detection

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## 10.5 Networks and modules for image segmentation

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10-46 — V-Net.  $\hat{=}$  3D U-net

## 10.6 Networks and modules for generative tasks

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11.

Future topics and outlooks11.1Important but unaddressed topics

XAI - Visualization - Grad CAM and guided-CAM for change in weights etc for the ~~for~~ feature maps.

t-SNE

Causal inference → next big thing

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Adversarial N/w and attack