Detection and Pattern Recognition

Matrix Computation and optimization: .

Metrix Cookbook, Convex optimization - Online - Google it

Slide 1.0

Introduction

1.1 Signal processing, ML and

Slide 1.16.1

1.2 Detection

Baseband - no need to care about carrier.

Binary detection = hypothesis Test

*) 2 hypothesis

· null hypothesis Ho

· alternative hypothesis H, I + I | target | murder

*) unknown true state H ∈ {Ho, H,]

Given :

*) a noisy measurement vector x

*) a probabilistic signal model for x: P(x|Ho)

P(X|Ho) = prob. density f. ". (DDF) of x conditioned on Ho=Ho

P(x (H,) = ... on H= H,

P(H=Ho), P(H=H,)=1-P(H=Ho)

Motation:

P() for PDF for continuous valued RV

P() for Prob discrete "

Phobability Mass F. r. (PMF)

Task:
Design a detector $\hat{H}(X) \in \{H_0, H_1\}$ for H.

estimate for actual task.

Performance measures for H:

TNR: True Negative Rate PTN = PTO (TN)

= P(Ĥ +Ho) = P(Ĥ = Ho | H = Ho)

cond prob

P (A=Ho, H= Ho) joint prob.

FPR: False positive rate Prp = P(H=Ho) H=Ho)

FNR: False negative rate PFN = P (H= Ho/H= HI)

TPR: True positive rate PTP = P(H=H, |H=H)