

Sheet 4

Discussion of the sheet: Tue., 18.04.2023

1. Let $u : (0, 1) \rightarrow \mathbb{R}$ be a function that is continuously differentiable on $(0, 1/2)$ and $(1/2, 1)$ but such that $\lim_{x \uparrow 1/2} u(x) \neq \lim_{x \downarrow 1/2} u(x)$. Draw an example for such a function. Calculate the generalised/distributional derivative of u using the definition (that is, without just referring to the script or Wikipedia for the answer).

2. Show that the bilinear form $A(\cdot, \cdot)$ corresponding to the Poisson problem with mixed boundary conditions (Section 3.2.2 in the lecture notes) is indeed a continuous and coercive bilinear form on $H_D^1(\Omega)$. Moreover, show that the linear form $f(\cdot)$ given in Section 3.2.2 is a bounded linear form on $H_D^1(\Omega)$.

3. (**Fourier description of Sobolev spaces**) In some special domains, Sobolev spaces have a nice description in terms of Fourier series. Take $\Omega = (0, 1)$ and recall that any $f \in L^2(\Omega)$ can be written in a complex Fourier series

$$f(x) = \sum_{k \in \mathbb{Z}} c_k e^{i2\pi kx}, \quad c_k = \int_0^1 f(y) e^{i2\pi ky} dy.$$

a) Show that for any $m \geq 1$, the quantity

$$|f|_{\tilde{H}^m}^2 = \sum_{k \in \mathbb{Z}} k^{2m} |c_k|^2$$

is equivalent to the seminorm $|f|_{H^m}$ (that is, for some constant C , one has $|f|_{\tilde{H}^m} \leq C|f|_{H^m}$ and $|f|_{H^m} \leq C|f|_{\tilde{H}^m}$ for all $f \in H^m$).

b) Based on the above observation, give a 1 line proof of the Poincaré inequality.

c) Based on the above, how would you define $H^{1/2}(\Omega)$? How about $H^{-1}(\Omega)$?

d) With the preceding definitions, for which $s \in \mathbb{R}$ does the Dirac-delta at $1/2$ belong to $H^s(\Omega)$?

4. (**Hölder inequality and generalised Poincaré**) The Hölder inequality states that if $1/p + 1/q = 1$, then

$$\left| \int_{\Omega} f(x)g(x) dx \right| \leq \left(\int_{\Omega} |f(x)|^p dx \right)^{1/p} \left(\int_{\Omega} |g(x)|^q dx \right)^{1/q},$$

which is just Cauchy-Schwartz if $p = q = 2$. Use this to prove the following general form of Poincaré inequality in 1D, for arbitrary $p \in [1, \infty)$:

$$\int_0^1 |v(x)|^p dx \leq C_p \int_0^1 |v'(x)|^p dx$$

with some constant C_p , for all v in the more general Sobolev space

$$W_0^{1,p} = \left\{ v : \int_0^1 |v(x)|^p dx < \infty, \int_0^1 |v'(x)|^p dx < \infty, v(0) = v(1) = 0 \right\}.$$

Hint: Use the fundamental theorem of calculus $v(x) - v(0) = \int_0^x v'(y) dy$.

5. Let $\bar{H}^1(\Omega) := \{u \in H^1(\Omega) : \int_{\Omega} u \, dx = 0\}$. Show that $\bar{H}^1(\Omega)$ is a complete subspace of $H^1(\Omega)$. As a consequence, show that for any $f \in L^2(\Omega)$, the weak form of the pure Neumann problem

$$\begin{aligned} -\Delta u &= f & \text{in } \Omega \\ \nabla u \cdot n &= 0 & \text{on } \partial\Omega. \end{aligned}$$

has a unique solution in $\bar{H}^1(\Omega)$.

(Optional: What happened to the compatibility condition $\int_{\Omega} f = 0$? How come we don't need it?)

6. We now aim to implement the pure Neumann problem in 1D: Let $\Omega = (0, 1)$ and \mathcal{T} be a uniform mesh with $N + 1$ points. Take V_N to be the space of piecewise linear functions and $\bar{V}_N = V_N \cap \bar{H}^1$. Therefore the FEM reads as: $u_N \in \bar{V}_N$ s.t.

$$A(u_N, v_N) = \int_{\Omega} u'_N v'_N \, dx = \int_{\Omega} f v_N \, dx = \ell(v_N) \quad \forall v_N \in \bar{V}_N.$$

The idea is now to take the hat functions $\{\varphi_i : i = 1, \dots, N + 1\}$ as basis of V_N and enforce the condition $\int_0^1 u_N dx = 0$ separately.

Define the stiffness matrix $\mathbf{A} \in \mathbb{R}^{(N+1) \times (N+1)}$ given as $\mathbf{A}_{ij} = A(\varphi_i, \varphi_j)$ and the load vector \mathbf{l} given as $\mathbf{l}_i = \ell(\varphi_i)$. Show that, provided $\sum_i \mathbf{l}_i = 0$, writing $u_N = \sum_i \mathbf{u}_i \varphi_i$ the FEM formulation leads to the linear system of equations

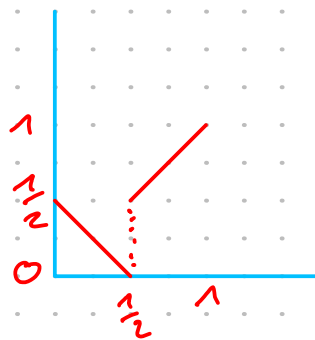
$$\begin{pmatrix} \mathbf{A} \\ \mathbf{P}^T \end{pmatrix} \cdot \mathbf{u} = \begin{pmatrix} \mathbf{l} \\ 0 \end{pmatrix},$$

where $\mathbf{P} \in \mathbb{R}^{N+1}$ is given as $\mathbf{P}_i := \int_{\Omega} \varphi_i dx$. Note that this implies that we get a solution to a symmetric $(N + 2) \times (N + 2)$ system:

$$\begin{pmatrix} \mathbf{A} & \mathbf{P} \\ \mathbf{P}^T & 0 \end{pmatrix} \cdot \begin{pmatrix} \mathbf{u} \\ 0 \end{pmatrix} = \begin{pmatrix} \mathbf{l} \\ 0 \end{pmatrix}.$$

1. Let $u : (0, 1) \rightarrow \mathbb{R}$ be a function that is continuously differentiable on $(0, 1/2)$ and $(1/2, 1)$ but such that $\lim_{x \uparrow 1/2} u(x) \neq \lim_{x \downarrow 1/2} u(x)$. Draw an example for such a function. Calculate the generalised/distributional derivative of u using the definition (that is, without just referring to the script or Wikipedia for the answer).

$$u = \begin{cases} -x + \frac{1}{2} & , x \in (0, \frac{1}{2}) \\ x & , x \in (\frac{1}{2}, 1) \end{cases}$$



$$\lim_{x \uparrow \frac{1}{2}} u = \lim_{x \uparrow \frac{1}{2}} \left(-\frac{1}{2} + \frac{1}{2} \right) = 0$$

$$\lim_{x \downarrow \frac{1}{2}} u = \lim_{x \downarrow \frac{1}{2}} x = \frac{1}{2}$$

Generalized derivative $\alpha = 1$

$$g(\varphi) = (-1)^{|\alpha|} u(D^\alpha \varphi) = -u(\varphi') = -\langle u, \varphi' \rangle_{D' \times D} = -\int_0^1 u \varphi' dx$$

$$\stackrel{!}{=} \langle g, \varphi \rangle_{D' \times D} = \int_0^1 g \varphi dx$$

$$\int_0^1 u \varphi' dx = \int_0^{\frac{1}{2}} \underbrace{\left(-x + \frac{1}{2} \right)}_f \underbrace{\varphi'}_{g'} dx + \int_{\frac{1}{2}}^1 \underbrace{x}_f \underbrace{\varphi'}_{g'} dx = \left[\int f g' = f g - \int f' g \right]$$

$$= \left(-x + \frac{1}{2} \right) \varphi \Big|_0^{\frac{1}{2}} - \int_0^{\frac{1}{2}} (-1) \varphi dx + x \varphi \Big|_{\frac{1}{2}}^1 - \int_{\frac{1}{2}}^1 \varphi dx$$

$$= \underbrace{\left(-\frac{1}{2} + \frac{1}{2} \right) \varphi\left(\frac{1}{2}\right)}_{=0} - \underbrace{\frac{1}{2} \varphi(0)}_{=0} + \int_0^{\frac{1}{2}} \varphi dx + \underbrace{\varphi(1) - \frac{1}{2} \varphi\left(\frac{1}{2}\right)}_{=0} - \int_{\frac{1}{2}}^1 \varphi dx$$

$$= \int_0^{\frac{1}{2}} \varphi dx - \int_{\frac{1}{2}}^1 \varphi dx - \frac{1}{2} \varphi\left(\frac{1}{2}\right) \quad \left[\varphi(x) = \int \varphi \delta(x - \frac{0}{x}) dx \right]$$

$$= \int_0^1 (1 - 2H(x - \frac{1}{2})) \varphi - \delta(x - \frac{1}{2}) \varphi dx$$

$$-\int_0^1 u \varphi' dx = \int_0^1 \underbrace{\left[\delta(x - \frac{1}{2}) + 1 - 2H(x - \frac{1}{2}) \right]}_{\text{generalized derivative}} \varphi dx = \int_0^1 g \varphi dx$$

2. Show that the bilinear form $A(\cdot, \cdot)$ corresponding to the Poisson problem with mixed boundary conditions (Section 3.2.2 in the lecture notes) is indeed a continuous and coercive bilinear form on $H_D^1(\Omega)$. Moreover, show that the linear form $f(\cdot)$ given in Section 3.2.2 is a bounded linear form on $H_D^1(\Omega)$.

Coercive: $A(u, u) \geq \alpha \|u\|_V^2$

Continuous: $A(u, v) \leq \alpha \|u\|_V \|v\|_V$

Poisson with mixed boundary conditions:

$$A(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \, dx + \int_{\Gamma_R} \alpha \, \text{tr}(u) \, \text{tr}(v) \, ds$$

Continuity: ①

$$|A(u, v)| = \left| \int_{\Omega} \nabla u \cdot \nabla v \, dx + \int_{\Gamma_R} \alpha \, \text{tr}(u) \, \text{tr}(v) \, ds \right|$$

triangle ineq $\leq \left| \int_{\Omega} \nabla u \cdot \nabla v \, dx \right| + \left| \int_{\Gamma_R} \alpha \, \text{tr}(u) \, \text{tr}(v) \, ds \right|$

$\underbrace{\int_{\Omega} \nabla u \cdot \nabla v \, dx}_{L^2 \text{ inner prod}} \quad \underbrace{\int_{\Gamma_R} \alpha \, \text{tr}(u) \, \text{tr}(v) \, ds}_{L^2 \text{ inner prod}}$

Cauchy-Schwarz $\leq \|\nabla u\|_{L^2(\Omega)} \cdot \|\nabla v\|_{L^2(\Omega)} + \|\alpha\|_{\infty} \|\text{tr}(u)\|_{L^2(\Gamma_R)} \|\text{tr}(v)\|_{L^2(\Gamma_R)}$

$| (f, u)_{L^2} | \leq \|f\|_{L^2} \|u\|_{L^2}$

Theorem 3.13: $\|\text{tr}(u)\|_{L^2} = C \|u\|_{H^1(\Omega)}$

$\|u\|_{L^2} + \|\nabla u\|_{L^2}$ so it's bigger/eq

$$\leq \|u\|_{H^1_0(\Omega)} \|v\|_{H^1_0(\Omega)} + \|\alpha\|_{\infty} C_1 C_2 \|u\|_{H^1_0(\Omega)} \|v\|_{H^1_0(\Omega)}$$

$$= \underbrace{(1 + \|\alpha\|_{\infty} C_1 C_2)}_{=: \alpha} \|u\|_{H^1_0(\Omega)} \|v\|_{H^1_0(\Omega)}$$

$$f(u) = \int_{\Omega} f v \, dx + \int_{\Gamma_D} u \, \text{tr}(v) \, ds + \int_{\Gamma_R} g \, \text{tr}(v) \, ds$$

Coercivity: $A(u, u) \geq \alpha \|u\|_V^2$ (2)

$$\|u\|_{H_0^1(\Omega)}^2 = \|u\|_{L^2(\Omega)}^2 + \|\nabla u\|_{L^2(\Omega)}^2$$

Poincaré-Friedrichs: $\|u\|_{L^2(\Omega)} \leq C \|\nabla u\|_{L^2(\Omega)}$

$$\leq C \|\nabla u\|_{L^2(\Omega)} + \|\nabla u\|_{L^2(\Omega)}^2$$

$$= (C+1) \|\nabla u\|_{L^2(\Omega)}^2$$

$$\leq (C+1) \|\nabla u\|_{L^2(\Omega)}^2 + (C+1) \|\alpha^{1/2} u\|_{L^2(\Omega)}^2$$

$$= (C+1) \left(\int_{\Omega} \nabla u \cdot \nabla u \, dx + \int_{\Gamma_R} \alpha^{1/2} u \alpha^{1/2} u \, ds \right)$$

$$= (1+c) A(u, u)$$

$$\rightarrow \|u\|_{H_0^1(\Omega)}^2 \leq (1+c) A(u, u)$$

$$A(u, u) \geq \underbrace{\frac{1}{1+c}}_{\alpha} \|u\|_{H_0^1(\Omega)}^2$$

3

$$f(v) = \int_{\Omega} f v dx + \int_{\Gamma_N} v_N v(v) ds + \int_{\Gamma_R} v_R v(v) ds$$

$$|f(v)| \leq \|v\|_{L^2(\Omega)} \|f\|_{L^2(\Omega)} + \|v_N\|_{L^2(\Gamma_N)} \|v(v)\|_{L^2(\Gamma_N)} \\ + \|v_R\|_{L^2(\Gamma_R)} \|v(v)\|_{L^2(\Gamma_R)}$$

Theorem 3.13 (trace inequality)

$$\|v\|_{L^2} \leq \|v\|_{H^1_0}$$

$$\leq \|v\|_{H^1_0(\Omega)} \|f\|_{L^2(\Omega)} + \|v_N\|_{L^2(\Gamma_N)} C_1 \|v\|_{H^1_0(\Omega)} \\ + \|v_R\|_{L^2(\Gamma_R)} C_2 \|v\|_{H^1_0(\Omega)}$$

$$= \left(\|f\|_{L^2(\Omega)} + \underbrace{C_1 \|v_N\|_{L^2(\Gamma_N)} + C_2 \|v_R\|_{L^2(\Gamma_R)}}_{\geq 0} \right) \|v\|_{H^1_0(\Omega)}$$

3. **(Fourier description of Sobolev spaces)** In some special domains, Sobolev spaces have a nice description in terms of Fourier series. Take $\Omega = (0, 1)$ and recall that any $f \in L^2(\Omega)$ can be written in a complex Fourier series

$$f(x) = \sum_{k \in \mathbb{Z}} c_k e^{i2\pi kx}, \quad c_k = \int_0^1 f(y) e^{i2\pi ky} dy.$$

- a) Show that for any $m \geq 1$, the quantity

$$|f|_{\tilde{H}^m}^2 = \sum_{k \in \mathbb{Z}} k^{2m} |c_k|^2$$

is equivalent to the seminorm $|f|_{H^m}$ (that is, for some constant C , one has $|f|_{\tilde{H}^m} \leq C|f|_{H^m}$ and $|f|_{H^m} \leq C|f|_{\tilde{H}^m}$ for all $f \in H^m$).

- b) Based on the above observation, give a 1 line proof of the Poincaré inequality.
 c) Based on the above, how would you define $H^{1/2}(\Omega)$? How about $H^{-1}(\Omega)$?
 d) With the preceding definitions, for which $s \in \mathbb{R}$ does the Dirac-delta at $1/2$ belong to $H^s(\Omega)$?

4. (Hölder inequality and generalised Poincaré) The Hölder inequality states that if $1/p + 1/q = 1$, then

$$\left| \int_{\Omega} f(x)g(x) dx \right| \leq \left(\int_{\Omega} |f(x)|^p dx \right)^{1/p} \left(\int_{\Omega} |g(x)|^q dx \right)^{1/q}, \quad (1)$$

which is just Cauchy-Schwartz if $p = q = 2$. Use this to prove the following general form of Poincaré inequality in 1D, for arbitrary $p \in [1, \infty)$:

To prove
$$\int_0^1 |v(x)|^p dx \leq C_p \int_0^1 |v'(x)|^p dx$$

with some constant C_p , for all v in the more general Sobolev space

$$W_0^{1,p} = \left\{ v : \int_0^1 |v(x)|^p dx < \infty, \int_0^1 |v'(x)|^p dx < \infty, v(0) = v(1) = 0 \right\}.$$

Hint: Use the fundamental theorem of calculus $v(x) - v(0) = \int_0^x v'(y) dy$.

Let $f(x) = |v'(x)|$, $g(x) = 1$, $\Omega = [0, 1]$

in (1)

$$\left| \int_{\Omega} |v'(x)| dx \right| \leq \left(\int_{\Omega} |v'(x)|^p dx \right)^{1/p} \quad | \quad 1^p$$

$$\left| \int_{\Omega} |v'(x)| dx \right|^p \leq \int_{\Omega} |v'(x)|^p dx$$

↑
Close but not quite

5. Let $\bar{H}^1(\Omega) := \{u \in H^1(\Omega) : \int_{\Omega} u \, dx = 0\}$. Show that $\bar{H}^1(\Omega)$ is a complete subspace of $H^1(\Omega)$. As a consequence, show that for any $f \in L^2(\Omega)$, the weak form of the pure Neumann problem

$$\begin{aligned} -\Delta u &= f & \text{in } \Omega \\ \nabla u \cdot n &= 0 & \text{on } \partial\Omega. \end{aligned}$$

has a unique solution in $\bar{H}^1(\Omega)$.

(Optional: What happened to the compatibility condition $\int_{\Omega} f = 0$? How come we don't need it?)

Complete subspace: every Cauchy sequence of points in space M has a limit that is also in M

$(u_n)_{n \in \mathbb{N}} \subseteq \bar{H}^1(\Omega)$... Cauchy sequence

To show: $\exists v \in \bar{H}^1(\Omega) : \lim_{n \rightarrow \infty} u_n = v$

i) $u_n \in \bar{H}^1(\Omega) \subseteq H^1(\Omega)$

H^1 is a Banachspace - so it's complete & normed

$\rightarrow \exists v \in H^1(\Omega) : \lim_{n \rightarrow \infty} u_n = v$

$$\rightarrow v \in H^1(\Omega)$$

ii) show $v \in \bar{H}^1(\Omega)$ (i.e. show $\int_{\Omega} v \, dx = 0$)

$$\left| \int_{\Omega} v \, dx \right| = \left| \int_{\Omega} v \, dx - \underbrace{\int_{\Omega} u_n \, dx}_{=0 [u_n \in \bar{H}^1(\Omega)]} \right| = \left| \int_{\Omega} v - u_n \, dx \right| = \sqrt{\left(\int_{\Omega} v - u_n \, dx \right)^2}$$

$$\left| \left(\int_{\Omega} v \, dx \right)^2 \leq C \int_{\Omega} |v|^2 \, dx \right| \leq \sqrt{C} \sqrt{\int_{\Omega} |v - u_n|^2 \, dx} = C \|v - u_n\|_{L^2}$$

$$\leq C \|v - u_n\|_{H^1} = 0$$

$$\rightarrow \left| \int_{\Omega} v \, dx \right| = 0 \rightarrow \int_{\Omega} v \, dx = 0$$

$$\textcircled{2} \quad -\Delta v = f \quad | \cdot v | \int$$

$$-\int_{\Omega} \Delta v v \, dx = \int_{\Omega} f v \, dx \quad \left| \begin{array}{l} \text{Integration by parts} \\ \text{S. 29} \end{array} \right.$$

$$-\int_{\partial\Omega} \underbrace{\nabla v \cdot \underline{n}}_{=0 \text{ (boundary conditions)}} v \, ds + \int_{\Omega} \nabla v \cdot \nabla v \, dx = \int_{\Omega} f v \, dx$$

$$A(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \, dx = \int_{\Omega} f v \, dx = (f, v)$$

Lax-Milgram: A , cont. , coercive and $|$ bounded?

A continuous?

$$\begin{aligned} |A(u, v)| &= \left| \int_{\Omega} \nabla u \cdot \nabla v \, dx \right| \stackrel{\text{C.S.}}{\leq} \|\nabla u\|_{L^2(\Omega)} \|\nabla v\|_{L^2(\Omega)} \\ &\leq \|u\|_{H^1(\Omega)} \|v\|_{H^1(\Omega)} \quad \checkmark \end{aligned}$$

A coercive?

$$\|u\|_{H^1(\Omega)}^2 = \|u\|_{L^2(\Omega)}^2 + \|\nabla u\|_{L^2(\Omega)}^2$$

Poincaré - Inequality (Lemma 3.10): $\|u\|_{L^2(\Omega)} \leq C \left(\|\nabla u\|_{L^2(\Omega)} + \left| \int_{\Omega} u \, dx \right| \right)$

$$\leq C^2 \left(\|\nabla u\|_{L^2(\Omega)}^2 + \underbrace{\left| \int_{\Omega} u \, dx \right|^2}_{=0, u \in \bar{H}^1(\Omega)} \right) + \|\nabla u\|_{L^2(\Omega)}^2$$

$$\geq (1 + C^2) \|\nabla u\|_{L^2(\Omega)}^2 = (1 + C^2) A(u, u) \rightarrow A(u, u) \geq \frac{1}{1 + C^2} \|u\|_{H^1(\Omega)}^2 \quad \checkmark$$

(bounded?)

$$|L(v)| \leq \|v\|_{L^2(\Omega)} \|f\|_{L^2(\Omega)} \leq \|f\|_{L^2(\Omega)} \|v\|_{H^1(\Omega)} \quad \checkmark$$

By Lax - Milgram there exists a unique solution

6. We now aim to implement the pure Neumann problem in 1D: Let $\Omega = (0, 1)$ and \mathcal{T} be a uniform mesh with $N + 1$ points. Take V_N to be the space of piecewise linear functions and $\bar{V}_N = V_N \cap \bar{H}^1$. Therefore the FEM reads as: $u_N \in \bar{V}_N$ s.t.

$$A(u_N, v_N) = \int_{\Omega} u'_N v'_N dx = \int_{\Omega} f v_N dx = \ell(v_N) \quad \forall v_N \in \bar{V}_N.$$

The idea is now to take the hat functions $\{\varphi_i : i = 1, \dots, N + 1\}$ as basis of V_N and enforce the condition $\int_0^1 u_N dx = 0$ separately.

Define the stiffness matrix $\mathbf{A} \in \mathbb{R}^{(N+1) \times (N+1)}$ given as $\mathbf{A}_{ij} = A(\varphi_i, \varphi_j)$ and the load vector \mathbf{l} given as $\mathbf{l}_i = \ell(\varphi_i)$. Show that, provided $\sum_i \mathbf{l}_i = 0$, writing $u_N = \sum_i \mathbf{u}_i \varphi_i$ the FEM formulation leads to the linear system of equations

$$\begin{pmatrix} \mathbf{A} \\ \mathbf{P}^T \end{pmatrix} \cdot \mathbf{u} = \begin{pmatrix} \mathbf{l} \\ 0 \end{pmatrix}, \quad \textcircled{1}$$

where $\mathbf{P} \in \mathbb{R}^{N+1}$ is given as $\mathbf{P}_i := \int_{\Omega} \varphi_i dx$. Note that this implies that we get a solution to a symmetric $(N + 2) \times (N + 2)$ system:

$$\begin{pmatrix} \mathbf{A} & \mathbf{P} \\ \mathbf{P}^T & 0 \end{pmatrix} \cdot \begin{pmatrix} \mathbf{u} \\ 0 \end{pmatrix} = \begin{pmatrix} \mathbf{l} \\ 0 \end{pmatrix}.$$

⑦

$$(u_N) = \left(\sum_{i=1}^{N+1} v_i \varphi_i \right) = \sum_{i=1}^{N+1} v_i (\varphi_i) = \sum_{i=1}^{N+1} v_i \cdot \mathbf{l}_i$$

||

$$A(u_N, v_N) = \sum_{j=1}^{N+1} v_j \sum_{i=1}^{N+1} v_i A(\varphi_j, \varphi_i) = \sum_{i=1}^{N+1} v_i \sum_{j=1}^{N+1} v_j A_{ij}$$

KVC:

$$\sum_{j=1}^{N+1} v_j A_{ij} = \mathbf{l}_i \Leftrightarrow \mathbf{A} \mathbf{v} = \mathbf{l}$$

$$\mathbf{P}^T \mathbf{v} = \sum_i \mathbf{P}_i v_i = \sum_i \underbrace{\int_0^1 \varphi_i(x) dx}_{\mathbf{P}_i \text{ (definition)}} v_i \in \mathbb{R}, \text{ just a number}$$

$$= \int_0^1 \sum_i v_i \varphi_i(x) dx = \int_0^1 u_N dx = 0$$

$$u_N \in \bar{H}^1 \rightarrow \int_0^1 u_N dx = 0$$

$$\rightarrow \mathbf{P}^T \mathbf{v} = 0$$

$$\rightarrow \begin{pmatrix} \mathbf{A} \\ \mathbf{P}^T \end{pmatrix} \cdot \mathbf{u} = \begin{pmatrix} \mathbf{l} \\ 0 \end{pmatrix}$$

