

1. a) Implement last week's first exercise in MATLAB, with $N = 4, 8, 16, 32$. Is there any change in the error in the nodal values, i.e., $|u(x_j) - u_j|$ for $j \in \{0, \dots, N\}$?
- b) Change the right-hand side of the equation from $1 + x$ to $2x^2 + 3x - 4/3$. Find again the exact solution and run the code with the new right-hand side. Calculate the errors

$$\max_{j \in \{0, \dots, N\}} |u(x_j) - u_j| \quad \begin{array}{l} -u'' = 1 + x \\ u(0) = u(1) = 0 \end{array} \quad \text{in } (0, 1)$$

for each $N = 4, 8, 16, 32$.

$$-u'' = 2x^2 + 3x - \frac{4}{3}$$

$$-u' = \frac{2}{3}x^3 + \frac{3}{2}x^2 - \frac{4}{3}x + C_1$$

$$-u = \frac{1}{6}x^4 + \frac{1}{2}x^3 - \frac{4}{6}x^2 + C_1x + C_2$$

$$u(0) = 0 \rightarrow C_2 = 0$$

$$u(1) = 0 \rightarrow \frac{1}{6} + \frac{1}{2} - \frac{4}{6} + C_1 = 0$$

$$\rightarrow C_1 = 0$$

$$u = -\frac{1}{6}x^4 - \frac{1}{2}x^3 + \frac{2}{3}x^2$$

(Resl in code)

2. (In very special cases the FEM and FDM are actually equivalent) Consider the 1-dimensional Poisson equation with Dirichlet boundary conditions. Take an equidistant grid $x_i = (i-1)/N$. Show that the finite difference method and the finite element method (with V_h being the space of piecewise linear continuous functions as in the introductory example) yield the same approximate function.

$$1D \text{ Poisson} : -u'' = f \text{ in } (0,1)$$

$$u(0) = u(1) = 0$$

$$x_i = \frac{i-1}{N}$$

$$FD: u'' = \frac{1}{h^2} (u_{i-1} - 2u_i + u_{i+1})$$

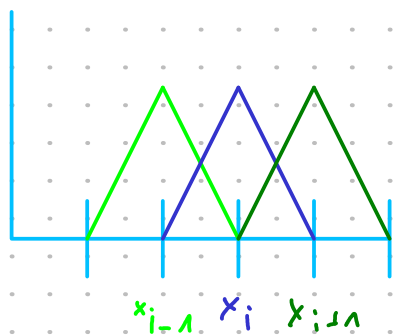
$$\rightarrow -\frac{1}{h^2} (u_{i-1} - 2u_i + u_{i+1}) = f$$

$$\text{solve } Au = f$$

$$\frac{1}{h^2} \begin{pmatrix} 2 & -1 & 0 & & 0 \\ -1 & 2 & -1 & & 0 \\ 0 & \ddots & \ddots & \ddots & 0 \\ 0 & \ddots & 0 & -1 & 2 & -1 \\ 0 & \ddots & 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} u_1 \\ \vdots \\ u_N \end{pmatrix} = \begin{pmatrix} f_1 \\ \vdots \\ f_N \end{pmatrix}$$

FEM:

nodal basis:



$$\varphi_i(x_i) := \delta_{ij}$$

$$\varphi_i(x) = \begin{cases} \frac{1}{h} (x - x_{i-1}) & x_{i-1} \leq x \leq x_i \\ \frac{1}{h} (x_{i+1} - x) & x_i \leq x \leq x_{i+1} \\ 0 & \text{else} \end{cases}$$

$$\varphi'_i(x) = \begin{cases} \frac{1}{h} & x_{i-1} \leq x \leq x_i \\ -\frac{1}{h} & x_i \leq x \leq x_{i+1} \\ 0 & \text{else} \end{cases}$$

stiffness matrix $A_{ij} = \int_{\Omega} \varphi'_j \varphi'_i dx = a(\varphi_j, \varphi_i)$

load vector $f_j = \int_{\Omega} f \varphi_j dx = (f, \varphi_j)$

$$A_{ii} = \int (\varphi'_i)^2 dx = \int_{x_{i-1}}^{x_i} \frac{1}{h^2} dx + \int_{x_i}^{x_{i+1}} \frac{1}{h^2} dx$$

$$= \left. \frac{x}{h^2} \right|_{x_{i-1}=(i-2)h}^{x_i=(i-1)h} + \left. \frac{x}{h^2} \right|_{x_i=(i-1)h}^{x_{i+1}=ih} = \frac{h}{h^2} (i-1-i+2) + \frac{h}{h^2} (i-i+1)$$

$$\left[\begin{array}{l} h = \frac{1}{N} \quad x_i = \frac{i-1}{N} \\ x_i = (i-1)h \\ x_{i-1} = (i-2)h \\ x_{i+1} = (i)h \end{array} \right]$$

$$\rightarrow A_{ii} = \frac{2}{h}$$

$$A_{i,i+1} = \int \varphi'_i \varphi'_{i+1} = \int_{x_{i-1}}^{x_i} \frac{1}{h} \cdot 0 dx + \int_{x_i}^{x_{i+1}} \left(-\frac{1}{h}\right) \left(\frac{1}{h}\right) dx = -\left. \frac{x}{h^2} \right|_{x_i=(i-1)h}^{x_{i+1}=ih} = -\frac{h}{h^2} (i-i+1)$$

$$\rightarrow A_{i,i+1} = -\frac{1}{h}$$

$$A_{i,i-1} = \int \varphi'_i \varphi'_{i-1} = \int_{x_{i-1}}^{x_i} \left(\frac{1}{h}\right) \left(-\frac{1}{h}\right) dx + \int_{x_i}^{x_{i+1}} \left(-\frac{1}{h}\right) \cdot 0 dx = -\left. \frac{x}{h^2} \right|_{x_{i-1}=(i-2)h}^{x_i=(i-1)h} = -\frac{h}{h^2} (i-1-i+2)$$

$$\rightarrow A_{i,i-1} = -\frac{1}{h}$$

$$A_{ij} = 0, \quad j > i+1$$

$$f_j = \int_{\Omega} f \begin{cases} \frac{1}{h} (x - (i-2)h) & x_{i-1} < x < x_i \\ \frac{1}{h} (i h - x) & x_i < x < x_{i+1} \\ 0 & \text{else} \end{cases}$$

$$f_j = \begin{cases} f\left(\frac{x^2}{2h} - (i-2)x\right) & x_i = (i-1)h \\ f\left(i x - \frac{x^2}{2h}\right) & x_{i+1} = ih \\ 0 & \text{else} \end{cases} = \begin{cases} f\left(\frac{(i-1)^2 h^2}{2h} - (i-2)(i-1)h - \left(\frac{(i-1)^2 h^2}{2h} - (i-2)^2 h\right)\right) \\ f\left(i^2 h - \frac{i^2 h^2}{2h} - ((i-1)hi - \frac{(i-1)^2 h^2}{2h})\right) \\ 0 \end{cases}$$

$$f_j \propto h$$

Divide by h :

$$\tilde{A} u = f \Rightarrow \frac{1}{h^2} \begin{pmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & \ddots & \ddots & \ddots \\ 0 & \ddots & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} u_1 \\ \vdots \\ u_N \end{pmatrix} = \begin{pmatrix} f_1 \\ \vdots \\ f_N \end{pmatrix} \quad \checkmark$$

3. Give a compatibility condition on the function g so that the Poisson equation with Neumann boundary conditions

$$\begin{aligned} -u'' &= f & \text{in } (0, 1) \\ u'(0) &= g(0) \\ u'(1) &= g(1) \end{aligned}$$

(1)

has a solution. What additional constraint can be added for the uniqueness of the solution u ?

(2)

$$(1) \quad -u'' = f \rightarrow -\int_0^1 u'' v \, dx = \int_0^1 f v \, dx \quad [\int u'v = uv - \int uv']$$

$$\rightarrow -\int_0^1 u'' v \, dx = -uv \Big|_0^1 + \int_0^1 u'v' \, dx = \int_0^1 f v \, dx$$

$$-u'(1)v(1) + u'(0)v(0) = \int_0^1 f v - u'v' \, dx$$

$$[\text{let } v = 1 \in H_1 \Rightarrow v' = 0]$$

$$u'(0) - u'(1) = g(0) - g(1) = \int_0^1 f \, dx \quad \text{compatibility condition}$$

$$(2) \quad \text{let } g(x) = \text{const}$$

$$\Rightarrow \int_0^1 f(x) \, dx = 0$$

If u is a weak solution $u+c$ is too

Hence, add another condition by, e.g., constraining

$$\text{a point: } \boxed{u(a) = b}$$

In contrast to the Dirichlet problem (where the boundary conditions are incorporated into the vector space), the boundary conditions are "hidden" in the bilinear form. However, this formulation may not be solvable! E.g. testing with the constant function $1 \in H^1(\Omega)$ gives

$$0 = \int_0^1 f \, dx,$$

which may not hold for arbitrary functions f . Moreover, provided $\int f \, dx = 0$, solutions may not be unique as, if u is a weak solution, $u+c$ for an arbitrary constant $c \in \mathbb{R}$ is a solution as well. In order to guarantee unique solvability, additional conditions need to be imposed. A common condition is to only look for functions u with vanishing mean, i.e., $\int_0^1 u \, dx = 0$.

4. Derive a weak formulation for the problem

$$\begin{aligned} -u'' + u &= f && \text{in } (0, 1) \\ u(0) - 2u'(0) &= 0 \\ u(1) + 2u'(1) &= 0 \end{aligned}$$

with Robin boundary conditions.

$$-u'' + u = f \quad \rightarrow \quad \int_{\Omega} -u'' v + u v \, dx = \int_{\Omega} f v \, dx$$

$$[\int u' v = uv - \int u v']$$

$$-u' v \Big|_0^1 + \int_{\Omega} u' v' + u v \, dx = \int_{\Omega} f v \, dx$$

$$= (-u'(1)v(1) + u'(0)v(0)) + \int_{\Omega} u' v' + u v \, dx = a(u, v)$$

$$u(0) - 2u'(0) = 0 \rightarrow u'(0) = \frac{1}{2} u(0)$$

$$u(1) + 2u'(1) = 0 \rightarrow u'(1) = -\frac{1}{2} u(1)$$

$$= \left(\frac{1}{2} u(1)v(1) + \frac{1}{2} u(0)v(0) \right) + \int_{\Omega} u' v' + u v \, dx$$

→ weak formulation

$$a(u, v) = \int_{\Omega} u' v' + u v \, dx + \frac{1}{2} (u(1)v(1) + u(0)v(0)) = \int_{\Omega} f v \, dx = (f, v)$$

5. Let $b, c > 0$. Find the bilinear form on H_0^1 associated to the equation

$$\begin{aligned} -u'' + bu' + cu &= f & \text{in } (0, 1) \\ u(0) = u(1) &= 0 \end{aligned}$$

Is it symmetric? Is it coercive?

$$\int_0^1 -u''v + bu'v + cuv \, dx = \int_0^1 f v \, dx$$

$$\left[\int u'v = \int uv - \int uv' \right]$$

$$0 [v(0) = v(1) = 0]$$

$$-\cancel{u}v \Big|_0^1 + \int u'v' + bu'v + cuv \, dx = \int_0^1 f v \, dx$$

$$\rightarrow a(u, v) = \int u'v' + bu'v + cuv \, dx = \int_0^1 f v \, dx = (f, v)$$

bilinear form

Definition 2.2. Let V be a vector space. A bilinear form $A(\cdot, \cdot)$ on V is a mapping $A : V \times V \rightarrow \mathbb{R}$ which is linear in u and in v .
A bilinear form is called **symmetric** if $A(u, v) = A(v, u)$ for all $u, v \in V$.

$$\int u'v' + bu'v + cuv \, dx \stackrel{?}{=} \int v'u' + bv'u + cvv \, dx$$

$\hookrightarrow bu'v \neq bv'u \quad \leftarrow \rightarrow$ not symmetric

Definition 2.5. A bilinear form $A(\cdot, \cdot) : V \times V \rightarrow \mathbb{R}$ is called **coercive** (or **elliptic**), if there is a constant $\alpha_1 \in \mathbb{R}$ such that

$$A(u, u) \geq \alpha_1 \|u\|_V^2 \quad \forall u \in V. \quad (2.3)$$

$A(\cdot, \cdot)$ is called **continuous**, if there is a constant $\alpha_2 \in \mathbb{R}$ such that

$$A(u, v) \leq \alpha_2 \|u\|_V \|v\|_V \quad \forall u, v \in V. \quad (2.4)$$

$$\left[\|u\|_{L^2}^2 = \|u\|_{L^2}^2 + \|u'\|_{L^2}^2 \right]$$

$$a(u, u) = \int_0^1 u' u' + b u' u + c u u \, dx$$

$$= \|u'\|_{L^2}^2 + c \|u\|_{L^2}^2 + \int_0^1 b u' u \, dx$$

$$\left[\int_0^1 b u u' \, dx = \left| \begin{array}{l} y = u(x), \frac{dy}{dx} = u' \\ u'(x) \, dx = dy \end{array} \right| \int_{u(0)}^{u(1)} b y \, dy = b \frac{y^2}{2} \Big|_{u(0)}^{u(1)} = \frac{b}{2} (\underbrace{u(1)^2}_{\text{red}} - \underbrace{u(0)^2}_{\text{red}}) = 0 \right]$$

$$a(u, u) = \|u'\|_{L^2}^2 + c \|u\|_{L^2}^2$$

$$\|u'\|_{L^2}^2 + c \|u\|_{L^2}^2 \stackrel{c > 0}{\geq} \|u'\|_{L^2}^2$$

For coercivity, we employ the Poincaré-Friedrich inequality (denoting the constant there by C_P) to derive

$$\|u\|_{H^1(\Omega)}^2 = \|u\|_{L^2(\Omega)}^2 + \|\nabla u\|_{L^2(\Omega)}^2 \leq (C_P^2 + 1) \|\nabla u\|_{L^2(\Omega)}^2 = (C_P^2 + 1) A(u, u).$$

$$[\|u\|_{L^1}^2 \leq \alpha \|u'\|_{L^2}^2]$$

$$a(u, u) \geq \|u'\|_{L^2}^2 \geq \underbrace{\frac{1}{\alpha}}_{:= \alpha} \|u\|_{L^1}^2$$

$$a(u, u) \geq \alpha \|u\|_{L^1}^2$$

6. a) Let $X = \{u \in C^4([0, 1]) : u(0) = u(1) = u'(0) = u'(1) = 0\}$. Show that

$$A(u, v) = \int_0^1 \Delta^2(u) v dx$$

is a symmetric bilinear form on $X \times X$. (Here, Δ^2 denotes the operator $\Delta(\Delta u)$.)

- b) Let $T = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$. Is

$$A(u, v) = u^T T v$$

a coercive bilinear form on $\mathbb{R}^2 \times \mathbb{R}^2$ (with the Euclidean norm)?

Definition 2.2. Let V be a vector space. A **bilinear form** $A(\cdot, \cdot)$ on V is a mapping $A : V \times V \rightarrow \mathbb{R}$ which is linear in u and in v .

A bilinear form is called **symmetric** if $A(u, v) = A(v, u)$ for all $u, v \in V$.

a)

$$1D : \Delta u = u'' \Rightarrow \Delta^2 u = u^{(4)}$$

Linearity:

$$1) A(u+v, w) \stackrel{?}{=} A(u, w) + A(v, w)$$

$$\begin{aligned} A(u+v, w) &= \int_0^1 (u+v)^{(4)} w dx = \int_0^1 (u^{(4)} + v^{(4)}) w dx \\ &= \int_0^1 u^{(4)} w dx + \int_0^1 v^{(4)} w dx \\ &= A(u, w) + A(v, w) \end{aligned}$$

$$2) A(\alpha u, \beta v) = \alpha \beta A(u, v)$$

$$\begin{aligned} A(\alpha u, \beta v) &= \int_0^1 (\alpha u)^{(4)} \beta v = \int_0^1 \alpha u^{(4)} \beta v \\ &= \alpha \beta \int_0^1 u^{(4)} v \\ &= \alpha \beta A(u, v) \end{aligned}$$

probably
not
needed
to
show
for
exercise

Symmetry: $A(u, v) \stackrel{?}{=} A(v, u)$

$$A(u, v) = \int_0^1 u^{(4)} v \, dx \quad [\int u'v = uv - \int uv']$$

$$= u^{(3)} v \Big|_0^1 - \int_0^1 u^{(3)} v^{(1)} \, dx$$

$$= u^{(3)} v \Big|_0^1 - u^{(2)} v^{(1)} \Big|_0^1 + \int_0^1 u^{(2)} v^{(2)} \, dx$$

$$= u^{(3)} v \Big|_0^1 - u^{(2)} v^{(1)} \Big|_0^1 + u^{(1)} v^{(2)} \Big|_0^1 - \int_0^1 u^{(1)} v^{(3)} \, dx$$

$$= u^{(3)} v \Big|_0^1 - u^{(2)} v^{(1)} \Big|_0^1 + u^{(1)} v^{(2)} \Big|_0^1 - uv^{(3)} \Big|_0^1 + \int_0^1 uv^{(4)} \, dx$$

With $u(0) = u'(0) = u(1) = u'(1) = 0$

and $v(0) = v'(0) = v(1) = v'(1) = 0$

$$= \cancel{u^{(3)} v \Big|_0^1} - \cancel{u^{(2)} v^{(1)} \Big|_0^1} + \cancel{u^{(1)} v^{(2)} \Big|_0^1} - \cancel{uv^{(3)} \Big|_0^1} + \int_0^1 uv^{(4)} \, dx$$

$$= \int_0^1 uv^{(4)} \, dx = A(v, u)$$

\rightarrow It is a symmetric bilinear form

b) Let $T = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$. Is

$$A(u, v) = u^T T v$$

a coercive bilinear form on $\mathbb{R}^2 \times \mathbb{R}^2$ (with the Euclidean norm)?

Definition 2.5. A bilinear form $A(\cdot, \cdot) : V \times V \rightarrow \mathbb{R}$ is called **coercive** (or **elliptic**), if there is a constant $\alpha_1 \in \mathbb{R}$ such that

$$A(u, u) \geq \alpha_1 \|u\|_V^2 \quad \forall u \in V. \quad (2.3)$$

$A(\cdot, \cdot)$ is called **continuous**, if there is a constant $\alpha_2 \in \mathbb{R}$ such that

$$A(u, v) \leq \alpha_2 \|u\|_V \|v\|_V \quad \forall u, v \in V. \quad (2.4)$$

$$\begin{aligned} A(u, u) &= (u_1 \ u_2) \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \\ &= (u_1 \ u_2) \begin{pmatrix} u_2 \\ -u_1 \end{pmatrix} = u_1 u_2 - u_2 u_1 = 0 \end{aligned}$$

$$0 \geq \alpha \underbrace{\|u\|_2^2}_{\geq 0}$$

$$\text{let } \alpha = 0 :$$

$$0 \geq 0 \quad \checkmark \quad \text{coercive}$$

from lecture
 $\alpha > 0$

Then

$$0 \geq \underbrace{\alpha}_{>0} \underbrace{\|u\|_2^2}_{\geq 0} \quad \text{?}$$

not coercive (must hold $\forall u \in V$)

Linearity:

$$\begin{aligned} 1) \quad A(u+v, w) &= (u_1+v_1 \ u_2+v_2) \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} \\ &= (u_1+v_1 \ u_2+v_2) \begin{pmatrix} w_2 \\ -w_1 \end{pmatrix} \\ &= (u_1+v_1)w_2 - (u_2+v_2)w_1 \\ &= u_1 w_2 - u_2 w_1 + v_1 w_2 - v_2 w_1 \\ &= A(u, w) + A(v, w) \quad \checkmark \end{aligned}$$

$$\begin{aligned}
 2) \quad A(u, v) &= \begin{pmatrix} u_1 & u_2 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \\
 &= \begin{pmatrix} u_1 & u_2 \end{pmatrix} \begin{pmatrix} v_2 \\ -v_1 \end{pmatrix} \\
 &= u_1 v_2 - u_2 v_1 \\
 &= d/d(u_1 v_2 - u_2 v_1) \\
 &= d/d A(u, v) \quad \checkmark \text{ Linear}
 \end{aligned}$$

→ Is coercive bilinear