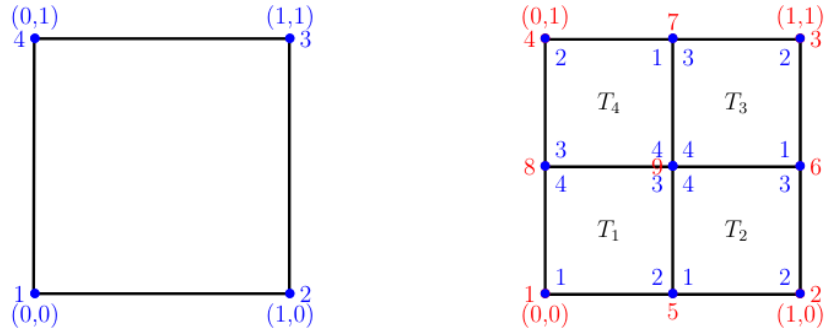


## Sheet 6

Discussion of the sheet: Tue., 02.05.2023

1. We now assemble a FEM system on four quadrilateral elements on  $\Omega = [0, 1]^2$  by hand.



Take quadrilateral Lagrangian finite elements on the reference element  $\Omega = [0, 1]^2$  as depicted on the left-hand side. Take the nodal basis of Sheet 5/Example 3b.

Moreover, let  $\mathcal{T}_h$  be a mesh consisting of 4 quadrilateral elements  $T_1, T_2, T_3, T_4$  depicted on the right-hand side that induces a global FEM space  $V_{\mathcal{T}}$ . The global numbering of the FEM basis  $\{\varphi_i : i = 1, \dots, 9\}$  is depicted in red, the local numberings on each element in blue.

- Compute the nodal basis functions  $\varphi_1, \varphi_2, \varphi_5, \varphi_6, \varphi_9$ .
  - Determine the affine linear map  $F_2 : \hat{T} \rightarrow T_2$  that maps  $F_2(0, 0) = v_5$ ,  $F_2(1, 0) = v_2$ ,  $F_2(1, 1) = v_6$ ,  $F_2(0, 1) = v_9$  (here  $v_i$  denote the vertices of the mesh numbered as depicted). Moreover, compute  $DF_2$  and  $\det(DF_2)$ .
  - Compute  $\int_{\Omega} \nabla \varphi_9 \cdot \nabla \varphi_9 dx$ .
2. We continue with the previous setting. Let

$$a(u, v) := \int_{\Omega} 6 \nabla u \cdot \nabla v \, dx \quad l(v) := \int_{\Omega} 16 v \, dx$$

and consider the problem: find  $u_h \in V_{\mathcal{T}}$  such that  $a(u_h, v_h) = l(v_h)$  for all  $v_h \in V_{\mathcal{T}}$ .

- Compute the element stiffness matrix and the element load vector for the element  $T_2$  of the triangulation. Note: here, all element stiffness matrices are the same!
- Compute the connectivity matrix  $C_{T_2}$  for the element  $T_2$ .

- c) Solve the problem with homogeneous Dirichlet boundary conditions (this leads to a  $1 \times 1$ -“matrix”).

3. We now aim to show that 1D-Lagrange finite elements reproduce exact nodal values. Let  $\Omega = (0, 1)$  and  $\mathcal{T}_h$  a mesh of intervals with nodes  $\{x_i : i = 1, \dots, n\}$ . Consider the 1D Poisson equation in the weak form, i.e., seek  $u \in H_0^1(\Omega)$  such that

$$\int_{\Omega} u' v' dx = \int_{\Omega} f v dx.$$

Denote the finite element approximation with  $P^1$ -Lagrangian finite elements by  $u_h$ .

- a) Define  $G_i(x) = \begin{cases} (1-x_i)x & 0 \leq x \leq x_i \\ x_i(1-x) & x_i \leq x \leq 1 \end{cases}$  and show that for any  $w \in H_0^1(\Omega)$  there holds

$$\int_{\Omega} G_i'(x) w'(x) dx = w(x_i).$$

- b) Use this to show that  $u(x_i) = u_h(x_i)$  by inserting the difference  $u - u_h$  into the weak formulation and using  $G_i$  as test function (Galerkin orthogonality).
4. Let  $T \subset \mathbb{R}^2$  be a triangle. Construct the so called polynomial bubble function  $b_T : T \rightarrow \mathbb{R}$ . This function is characterized by the conditions
- $0 \leq b_T \leq 1$ ,  $\max b_T = 1$ ,
  - $b_T \in P^k(T)$  for some  $k \in \mathbb{N}$ .
  - $b_T = 0$  on  $\partial T$ .

What is the minimal polynomial degree  $k$  that is possible?

5. Write a code that evaluates the Legendre polynomials up to a fixed degree  $k$  at a point  $x \in [-1, 1]$  (i.e. a function `evalLegendre(x,k)`) by using the recursion formula

$$nL_n(x) = (2n-1)xL_{n-1}(x) - (n-1)L_{n-2}(x) \quad 2 \leq n \leq k$$

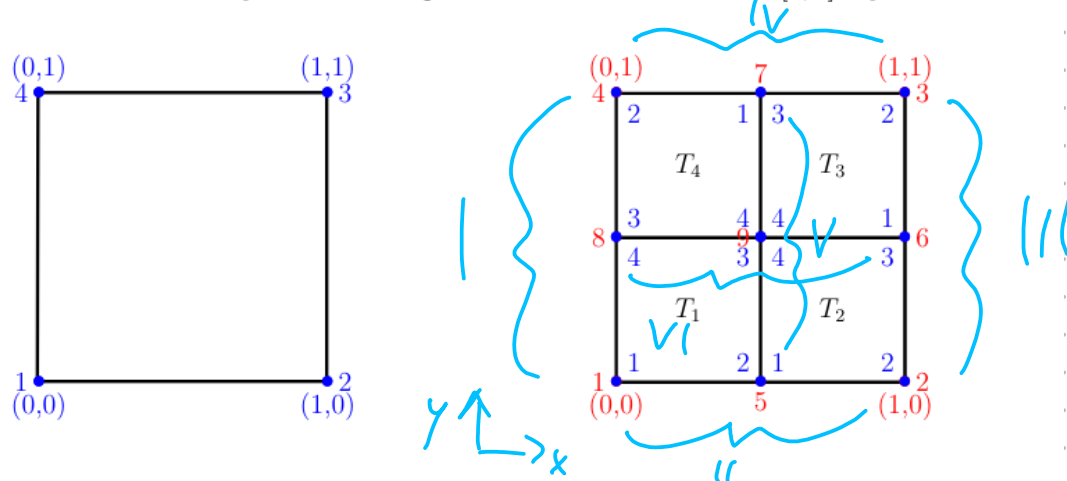
with  $L_0 = 1$  and  $L_1 = x$ . Do the same for the integrated Legendre polynomials  $N_i$ . Plot both polynomials!

Moreover, write a code that computes

$$\int_{-1}^1 f(x) N_i(x) dx$$

using Gaussian quadrature (e.g. use the provided routine `gauleg(m)` that provides  $m$  quadrature points and weights on  $[-1, 1]$ ). Test your code for different functions  $f$ ,  $i$ , and different quadrature orders  $m$ .

1. We now assemble a FEM system on four quadrilateral elements on  $\Omega = [0, 1]^2$  by hand.



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- b) Determine the affine linear map  $F_2 : \hat{T} \rightarrow T_2$  that maps  $F_2(0, 0) = v_5$ ,  $F_2(1, 0) = v_2$ ,  $F_2(1, 1) = v_6$ ,  $F_2(0, 1) = v_9$  (here  $v_i$  denote the vertices of the mesh numbered as depicted). Moreover, compute  $DF_2$  and  $\det(DF_2)$ .
- c) Compute  $\int_{\Omega} \nabla \varphi_9 \cdot \nabla \varphi_9 dx$ .

5.3b)  $N_1 = (1-x)(1-y), N_2 = x(1-y), N_3 = y(1-x), N_4 = xy$

line I:  $x=0 \rightarrow x-0=0$

line II:  $y=0 \rightarrow y-0=0$

line III:  $x=1 \rightarrow x-1=0$

line IV:  $y=1 \rightarrow y-1=0$

line V:  $x=\frac{1}{2} \rightarrow x-\frac{1}{2}=0$

line VI:  $y=\frac{1}{2} \rightarrow y-\frac{1}{2}=0$

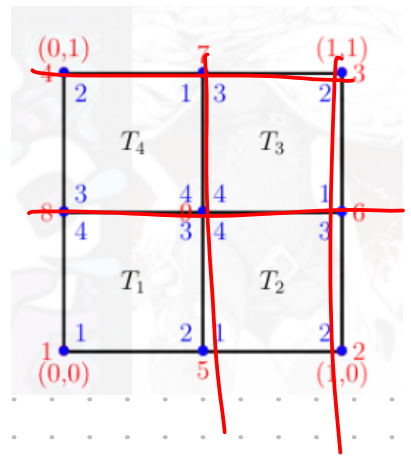
$\varphi_1$ :  $\varphi_1(0,0)=1, \varphi_1(0,\frac{1}{2})=0, \varphi_1(\frac{1}{2},0)=0, \varphi_1(\frac{1}{2},\frac{1}{2})=0$

Combine lines to calculate  $\varphi_i$ :

$$\varphi_1 = (y-1)(x-\frac{1}{2})(x-1)(y-\frac{1}{2}) \cdot C$$

$$\varphi_1(0,0) = 1 \rightarrow \frac{1}{4} \cdot C = 1 \rightarrow C = 4$$

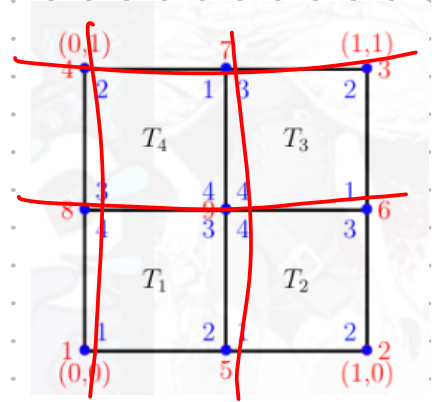
$$\rightarrow \varphi_1 = 4(y-1)(x-\frac{1}{2})(x-1)(y-\frac{1}{2})$$



$$\varphi_2 = x(y-1)(x-\frac{1}{2})(y-\frac{1}{2}) \cdot C$$

$$\varphi_2(1,0) = 1 \rightarrow \frac{1}{4} C = 1 \rightarrow C = 4$$

$$\varphi_2 = x(y-1)(x-\frac{1}{2})(y-\frac{1}{2}) \cdot 4$$

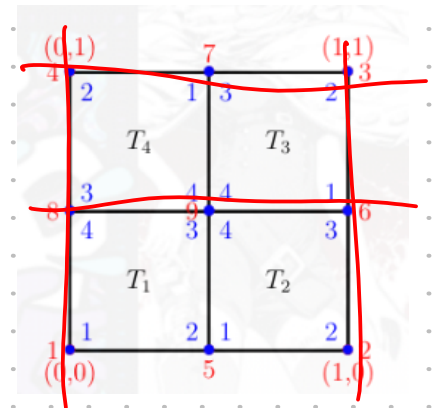


$$\varphi_5 = x(x-1)(y-1)(y-\frac{1}{2}) \cdot C$$

$$\varphi_5(\frac{1}{2}, 0) = 1 \rightarrow \frac{1}{2}(-\frac{1}{2})(-1)(-\frac{1}{2}) C = 1$$

$$\rightarrow -\frac{1}{8} C = 1 \rightarrow C = 8$$

$$\varphi_5 = x(x-1)(y-1)(y-\frac{1}{2}) \cdot 8$$

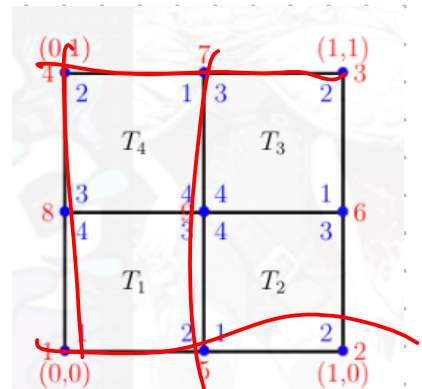


$$\varphi_6 = x y (y-1)(x-\frac{1}{2}) \cdot C$$

$$\varphi_6(1, \frac{1}{2}) = 1 \rightarrow \frac{1}{2}(-\frac{1}{2})(\frac{1}{2}) C = 1$$

$$-\frac{1}{8} C = 1 \rightarrow C = 8$$

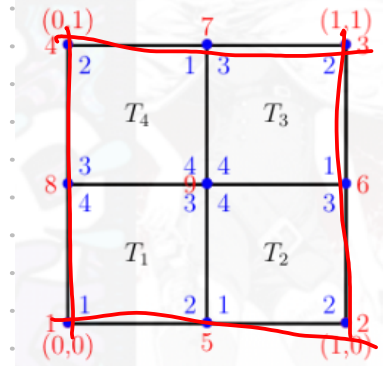
$$\varphi_6 = x y (y-1)(x-\frac{1}{2}) \cdot 8$$



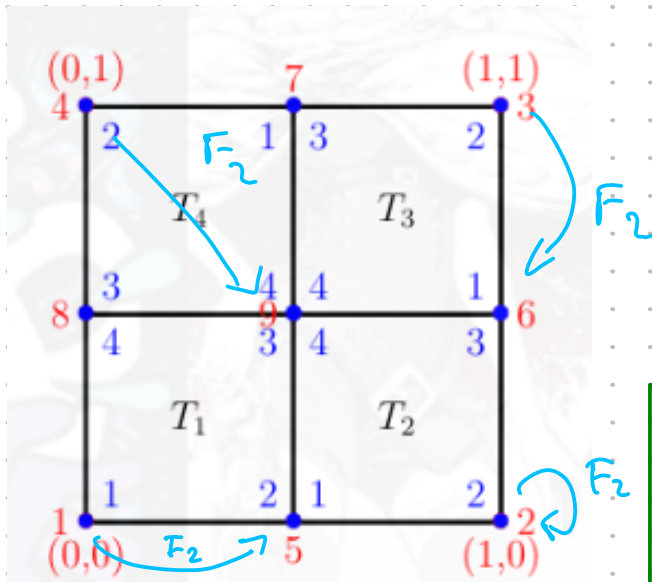
$$\varphi_9 = xy(x-1)(y-1) \subset$$

$$\varphi_9\left(\frac{1}{2}, \frac{1}{2}\right) = 1 \rightarrow \frac{1}{16} \subset = 1 \rightarrow 16$$

$$\varphi_9 = xy(x-1)(y-1) 16$$



- b) Determine the affine linear map  $F_2 : \hat{T} \rightarrow T_2$  that maps  $F_2(0,0) = v_5$ ,  $F_2(1,0) = v_2$ ,  $F_2(1,1) = v_6$ ,  $F_2(0,1) = v_9$  (here  $v_i$  denote the vertices of the mesh numbered as depicted). Moreover, compute  $DF_2$  and  $\det(DF_2)$ .



$$F_2(x) = \begin{pmatrix} 1 - \frac{1}{2} & \frac{1}{2} - \frac{1}{2} \\ 0 - 0 & \frac{1}{2} - 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} \frac{1}{2} \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} \frac{1}{2} \\ 0 \end{pmatrix}$$

$$DF_2 = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}, \det(DF_2) = \frac{1}{4}$$

- c) Compute  $\int_{\Omega} \nabla \varphi_9 \cdot \nabla \varphi_9 dx$ .

$$\nabla \varphi_9 = \begin{pmatrix} 16y(2x-1)(y-1) \\ 16x(x-1)(y-1) \end{pmatrix}$$

$$\nabla \varphi_9 \cdot \nabla \varphi_9 = 256 y^2 (2x-1)^2 (y-1)^2 + 256 x^2 (x-1)^2 (2y-1)^2$$

$$\int_{\Omega} \star = \int_0^1 \int_0^1 \star dy dx = \star = \frac{256}{45}$$

2. We continue with the previous setting. Let

$$a(u, v) := \int_{\Omega} 6 \nabla u \cdot \nabla v \, dx \quad l(v) := \int_{\Omega} 16v \, dx$$

and consider the problem: find  $u_h \in V_T$  such that  $a(u_h, v_h) = l(v_h)$  for all  $v_h \in V_T$ .

- Compute the element stiffness matrix and the element load vector for the element  $T_2$  of the triangulation. Note: here, all element stiffness matrices are the same!
- Compute the connectivity matrix  $C_{T_2}$  for the element  $T_2$ .

c) Solve the problem with homogeneous Dirichlet boundary conditions (this leads to a  $1 \times 1$ -matrix).

$$A_{T_2}(\varphi_i, \varphi_j) = 6 \cdot \int_{T_2} \nabla \varphi_i \cdot \nabla \varphi_j \, dx$$

Use transformation theorem on the reference element:

$$A_{T_2}^{T_2} = 6 \int_{\hat{T}} \nabla N_i (DF_2)^{-1} (DF_2)^{-T} \nabla N_k \underbrace{|\det(DF_2)|}_{\frac{1}{4}} \, dx$$

$$\begin{aligned} N_1 &= (1-x)(1-y), & N_2 &= x(1-y), & N_3 &= xy, & N_4 &= y(1-x), \\ \nabla N_1 &= (y-1, x-1), & \nabla N_2 &= (1-y, -x), & \nabla N_3 &= (y, x), & \nabla N_4 &= (-y, 1-x). \end{aligned}$$

$$(DF_2)^{-1} = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}^{-1} = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} = (DF_2)^{-T}$$

$$A_{T_2}^{T_2} = \frac{6}{4} \int_0^1 \int_0^1 \begin{pmatrix} y-1 \\ x-1 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} y-1 \\ x-1 \end{pmatrix} \, dx \, dy$$

$$= 6 \int_0^1 \int_0^1 \begin{pmatrix} y-1 \\ x-1 \end{pmatrix} \begin{pmatrix} y-1 \\ x-1 \end{pmatrix} \, dx \, dy$$

$$= 6 \int_0^1 \int_0^1 (y-1)^2 + (x-1)^2 \, dx \, dy = 4$$

$$A_{T_2}^{T_2} = 6 \int_0^1 \int_0^1 (y-1)(1-y) + (x-1)(1-x) \, dx \, dy = -1$$

$$A_{T_2}^{T_2} = 6 \int_0^1 \int_0^1 (y-1)y + (x-1)x \, dx \, dy = -2$$

$$A_{14}^{T_2} = 6 \int_0^1 \int_0^1 (y-1)(-1) + (x-1)(x) dx dy = -1$$

$$A_{21}^{T_2} = 4, A_{23}^{T_2} = -1, A_{24}^{T_2} = -2, A_{33}^{T_2} = 4, A_{34}^{T_2} = -1, A_{44}^{T_2} = 4$$

$$A^{T_2} = \begin{pmatrix} 4 & -1 & -2 & -1 \\ -1 & 4 & -1 & -2 \\ -2 & -1 & 4 & -1 \\ -1 & -2 & -1 & 4 \end{pmatrix}$$

element (act vector

$$f_i^T = \int_{\hat{\Gamma}} \hat{f} N_i \underbrace{|\det(D_F)|}_{16} dx$$

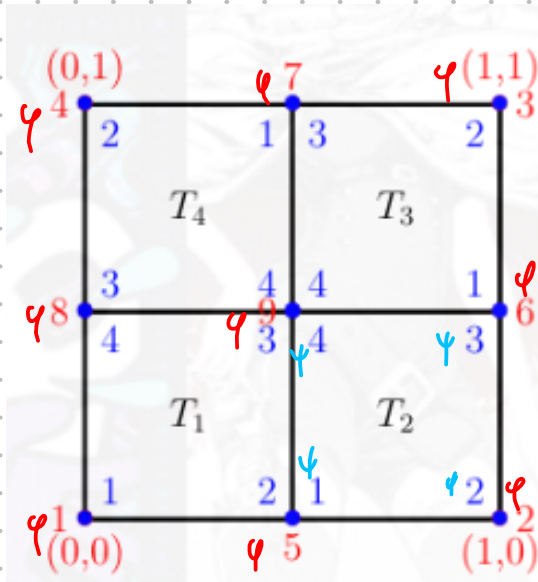
$$f_1^{T_2} = \frac{16}{4} \int_0^1 \int_0^1 (1-x)(1-y) dx dy = 1$$

$$f_2^{T_2} = 1, f_3^{T_2} = 1, f_4^{T_2} = 1$$

$$f^{T_2} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$



b) Compute the connectivity matrix  $C_{T_2}$  for the element  $T_2$ .



$$\begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \end{pmatrix}^T = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \psi_3 \\ \psi_4 \\ \psi_5 \\ \psi_6 \\ \psi_7 \\ \psi_8 \\ \psi_9 \end{pmatrix}$$

$C_{T_2}^T$

c) Solve the problem with homogeneous Dirichlet boundary conditions (this leads to a  $1 \times 1$ -“matrix”).

Global stiffness matrix and load vector

$$A = \sum_{T \in \mathcal{T}} C_T A C_T^T$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 4 & -1 & -2 & -1 \\ -1 & 4 & -1 & -2 \\ -2 & -1 & 4 & -1 \\ -1 & -2 & -1 & 4 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{pmatrix} =$$

$$\dots A = \begin{pmatrix} 4 & 0 & -1 & 0 & -1 & 0 & 0 & 0 & -2 \\ 0 & 4 & 0 & 0 & 0 & -1 & 0 & 0 & -2 \\ -1 & 0 & 1 & 2 & -1 & -2 & -1 & 0 & -4 \\ 0 & 0 & -1 & 4 & 0 & 0 & -1 & 0 & -2 \\ -1 & -1 & -2 & 0 & 0 & 0 & 0 & 0 & -2 \\ 0 & -1 & -1 & 0 & 0 & 0 & 0 & 0 & -2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -2 & -2 & -4 & -2 & -2 & -2 & -2 & 0 & 16 \end{pmatrix}$$

↑  
entry corresponding to  $\psi_9$

$$f = \sum_{T \in \mathcal{T}} C_T f_T = (1, 1, 3, 1, 2, 2, 2, 0, 4)^T$$

← to  $\psi_9$



after removing Dirichlet entries

lines and columns corresponding to nodal functions with nodes on the Dirichlet boundary can be omitted

$$A = [16], \quad f = [4] \rightarrow v = A^{-1}f = \frac{1}{16} \cdot 4$$

$$v = \frac{1}{4}$$

3. We now aim to show that 1D-Lagrange finite elements reproduce exact nodal values. Let  $\Omega = (0, 1)$  and  $\mathcal{T}_h$  a mesh of intervals with nodes  $\{x_i : i = 1, \dots, n\}$ . Consider the 1D Poisson equation in the weak form, i.e., seek  $u \in H_0^1(\Omega)$  such that

$$\int_{\Omega} u'v' dx = \int_{\Omega} fv dx.$$

Denote the finite element approximation with  $P^1$ -Lagrangian finite elements by  $u_h$ .

- a) Define  $G_i(x) = \begin{cases} (1-x_i)x & 0 \leq x \leq x_i \\ x_i(1-x) & x_i \leq x \leq 1 \end{cases}$  and show that for any  $w \in H_0^1(\Omega)$  there holds

$$G_i' = \begin{cases} (1-x_i) & 0 \leq x \leq x_i \\ -x_i & x_i \leq x \leq 1 \end{cases} \quad \int_{\Omega} G_i'(x)w'(x) dx = w(x_i).$$

- b) Use this to show that  $u(x_i) = u_h(x_i)$  by inserting the difference  $u - u_h$  into the weak formulation and using  $G_i$  as test function (Galerkin orthogonality).

$$\begin{aligned} \int_{\Omega} G_i' w'(x) dx &= \int_0^{x_i} (1-x_i) \cdot w'(x) dx + \int_{x_i}^1 -x_i w'(x) dx \\ &= (1-x_i) \int_0^{x_i} w'(x) dx - x_i \int_{x_i}^1 w'(x) dx \\ &= (1-x_i) [w(x) \Big|_0^{x_i}] - x_i [w(x) \Big|_{x_i}^1] \\ &= (1-x_i) (w(x_i) - \cancel{w(0)}) - x_i (\cancel{w(1)} - w(x_i)) \\ &= w(x_i) - \cancel{x_i w(x_i)} + \cancel{x_i w(x_i)} \\ &= w(x_i) \end{aligned}$$

Can not use integration by parts here because  $w$  &  $G_i$  are not in  $H^1 \rightarrow$  not enough differentiability. However, we know the derivatives of  $G_i \rightarrow$  fundamental theorem of calculus.

b) Use this to show that  $u(x_i) = u_h(x_i)$  by inserting the difference  $u - u_h$  into the weak formulation and using  $G_i$  as test function (Galerkin orthogonality).

$$\int_0^1 G_i'(x) w'(x) dx = w(x_i)$$

Galerkin orthogonality:  $A(u - u_h, v_h) = 0$

$$A(u, v) = \int_{\Omega} u' v' dx$$

$$\rightarrow A(u - u_h, G_i) = \int_{\Omega} \underbrace{(u - u_h)'}_{w'(x)} G_i' dx$$

$$= u(x_i) - u_h(x_i) = 0$$

$$\rightarrow u(x_i) = u_h(x_i)$$

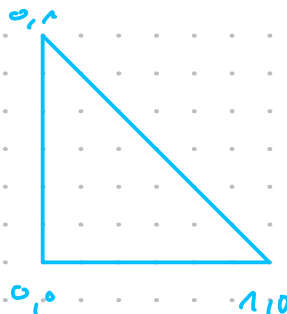
4. Let  $T \subset \mathbb{R}^2$  be a triangle. Construct the so called polynomial bubble function  $b_T : T \rightarrow \mathbb{R}$ . This function is characterized by the conditions

- $0 \leq b_T \leq 1$ ,  $\max b_T = 1$ ,
- $b_T \in P^k(T)$  for some  $k \in \mathbb{N}$ .
- $b_T = 0$  on  $\partial T$ .

What is the minimal polynomial degree  $k$  that is possible?

reference triangle

$$b_{\hat{T}}(x, y) = C \cdot xy(1-x-y)$$



$$\rightarrow b_{\hat{T}} \in P^3(T)$$

$$\rightarrow b_{\hat{T}}|_{\partial \hat{T}} = 0 \quad \checkmark$$

$\max b_{\hat{T}} \stackrel{!}{=} 1 \rightarrow$  find  $C$  so that this holds

$$\begin{aligned} \nabla b_{\hat{T}} &= 0 = \nabla (C \cdot (xy - x^2y - y^2x)) \\ &= C \cdot \begin{pmatrix} y - 2xy - y^2 \\ x - 2yx - x^2 \end{pmatrix} = 0 \end{aligned}$$

4 possibilities:  $\left. \begin{array}{l} x=0, y=0 \\ x=1, y=0 \\ x=0, y=1 \\ x=\frac{1}{3}, y=\frac{1}{3} \end{array} \right\} \text{ covered by } b_{\hat{T}}|_{\partial \hat{T}} = 0$

Check if  $(\frac{1}{3}, \frac{1}{3})$  is indeed a maximum

$$L|_{b_f}(x, y) = \begin{pmatrix} -2y & 1-2x-2y \\ 1-2y-2x & -2x \end{pmatrix}$$

$$L|_{b_f}\left(\frac{1}{3}, \frac{1}{3}\right) = \begin{pmatrix} -\frac{2}{3} & -\frac{1}{3} \\ -\frac{1}{3} & -\frac{2}{3} \end{pmatrix}$$

$$\det L\left(L|_{b_f}\left(\frac{1}{3}, \frac{1}{3}\right)\right) = \left(-\frac{2}{3} - \lambda\right)^2 - \frac{1}{9} = 0$$

$$= \left(-\frac{2}{3} - \lambda\right)\left(-\frac{2}{3} - \lambda\right) - \frac{1}{9} = 0$$

$$= \frac{4}{9} + \frac{4}{3}\lambda + \lambda^2 - \frac{1}{9} = 0$$

$$= \lambda^2 + \frac{4}{3}\lambda + \frac{1}{3} = 0$$

$$\lambda_{1,2} = -\frac{6}{9} \pm \sqrt{\frac{36}{81} - \frac{12}{81}}$$

$$\lambda_{1,2} = -\frac{6}{9} \pm \frac{2}{3} \rightarrow \lambda_1 = -\frac{1}{3}, \lambda_2 = -1$$

negative definite  
→ maximum

$$b_T(\frac{1}{3}, \frac{1}{3}) \stackrel{!}{=} 1 \rightarrow c \cdot \frac{1}{3} \cdot \frac{1}{3} (1 - \frac{1}{3} - \frac{1}{3}) = 1$$

$$\frac{c}{27} = 1 \rightarrow c = 27$$

$$b_T(x, y) = 27 \cdot x \cdot y \cdot (1 - x - y)$$

Using an affine linear map, this function can be applied to any 3 points in 2D space without changing the polynomial degree  
 i.e.  $b_T(\alpha) = b_T(F_T^{-1}(x)) \in P^1(T)$