

PDC CLASS TEST

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1.

a) order of system = 6 (order of system = $2 \times 3 = 6$)

Dynamical equation

$$y_1 = \frac{dx_1}{dt}$$

$$y_2 = \frac{dx_2}{dt}$$

$$y_3 = \frac{dx_3}{dt}$$

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \\ y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ y_1 \\ y_2 \\ y_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\frac{dy_1}{dt} = -a(x_1 - x_2)$$

$$\frac{dy_2}{dt} = -b(x_2 - x_1) - b(x_2 - x_3)$$

$$\frac{dy_3}{dt} = -a(x_3 - x_2)$$

Dynamical variables: $x_1, x_2, x_3, y_1, y_2, y_3$

b) For equilibrium solutions

$$Ax = 0$$

$$\frac{d}{dt} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} -a & a & 0 \\ b & -2b & b \\ 0 & a & -a \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow -ax_1 + ax_2 = 0$$

$$x_1 = x_2 \quad (a \neq 0)$$

$$ax_2 - ax_3 = 0$$

$$x_2 = x_3 \quad (a \neq 0)$$

$$b(x_1 - 2x_2 + x_3) = 0$$

$$b \neq 0$$

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equilibrium solution

$$x_1 = x_2 = x_3 = \text{constant (or zero)}$$

c)
$$\frac{d}{dt} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ -a & a & 0 & 0 & 0 & 0 \\ b & -2b & b & 0 & 0 & 0 \\ 0 & a & -a & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

from Wolframalpha we get

$$\lambda_1 = 0 \quad V_1 = [1 \ 1 \ 1 \ 0 \ 0 \ 0]^T$$

$$\lambda_2 = -i\sqrt{a} \quad V_2 = \left[\frac{-i}{\sqrt{a}} \ 0 \ \frac{i}{\sqrt{a}} \ -1 \ 0 \ 0 \right]^T$$

$$\lambda_3 = i\sqrt{a} \quad V_3 = \left[\frac{i}{\sqrt{a}} \ 0 \ \frac{-i}{\sqrt{a}} \ -1 \ 0 \ 0 \right]^T$$

$$\lambda_4 = -\sqrt{a-2b}$$

$$\lambda_5 = \sqrt{a-2b}$$

$$V_4 = \left[\frac{-1}{\sqrt{a-2b}} \ \frac{2b}{a\sqrt{a-2b}} \ \frac{1}{\sqrt{a-2b}} \ 1 \ \frac{-2b}{a} \ 1 \right]^T$$

$$V_5 = \left[\frac{1}{\sqrt{a-2b}} \ -\frac{2b}{a\sqrt{a-2b}} \ \frac{1}{\sqrt{a-2b}} \ 1 \ \frac{-2b}{a} \ 1 \right]^T$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ y_1 \\ y_2 \\ y_3 \end{bmatrix} = \sum_{i=1}^6 c_i e^{\lambda_i t} V_i$$

d)

let $a < 0, b < 0$

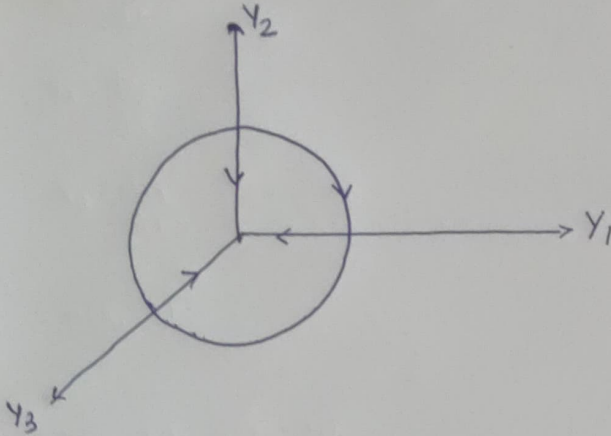
so all eigen values are imaginary.

solution will be in the form of $\text{Real} + j \text{Imaginary}$.

so the phase portrait must be centre solutions.

let $a > 0, b > 0$

All eigen values can be imaginary based on $a > b$.



2. Constant yeast decay rate = β .

Let growth parameter be = α .

$$\frac{dx}{dt} = \alpha x(1-x)$$

Since constant decay rate,

It should be subtracted from growing rate.

$$\frac{dx}{dt} = \alpha x(1-x) - \beta$$

$$f(x) = \alpha x - \alpha x^2 - \beta$$

$$\frac{dx}{dt} = 0 \quad (\text{for equilibrium})$$

$$-\alpha x^2 + \alpha x - \beta = 0$$

$$x^2 - x + \frac{\beta}{\alpha} = 0$$

$$x = \frac{1 \pm \sqrt{1 - \frac{4\beta}{\alpha}}}{2}$$

$$x_e = f(x)$$

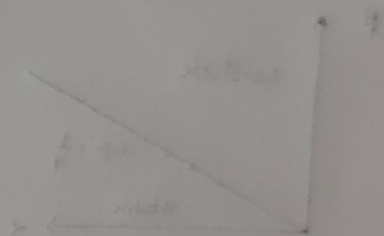
for bifurcation

$$\left. \frac{df}{dx} \right|_{x_e} = 0$$

$$\frac{\partial f}{\partial x} = \alpha - 2\alpha x$$

$$\left. \frac{df}{dx} \right|_{x_e} = \alpha \left(1 - 2 \left(\frac{1 \pm \sqrt{1 - \frac{4\beta}{\alpha}}}{2} \right) \right)$$

$$= \alpha \left[1 - \left[1 \pm \sqrt{1 - \frac{4\beta}{\alpha}} \right] \right]$$



for λ stable

$$\frac{\partial F}{\partial n/\alpha} < 0$$

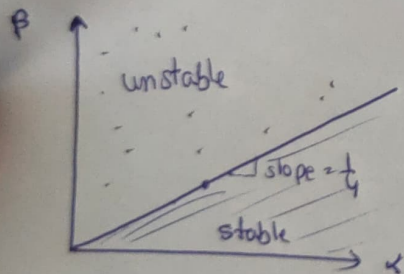
α is always +ve

so $1 - (1 + \sqrt{1 - 4\beta/\alpha}) > 0$ is ~~not~~ unstable
 < 0 is stable

$$\sqrt{1 - 4\beta/\alpha} > 0 \text{ stable}$$

$$1 > \frac{4\beta}{\alpha}$$

$$\alpha > 4\beta$$



$q = \text{the part that is lost}$

$x = \text{the amount that is lost}$

$$(x-1)x = \frac{1\beta}{1\beta}$$

the part that is lost

the part that is lost

$$q = (x-1)x = \frac{1\beta}{1\beta}$$

$$q = x - x^2 = (x-1)x$$

$$(x-1)x = \frac{1\beta}{1\beta}$$

$$0 = q - x = x - x^2$$

$$0 = q - x = x - x^2$$

$$\frac{1\beta}{1\beta} = 1 - x$$

$$1 - x = \frac{1\beta}{1\beta}$$

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