

ASSIGNMENT-4

PROBLEM STATEMENT-1

Consider the following BVP representing a dimensionless form of the diffusion with chemical reaction in a catalyst pore.

$$\frac{d^2C}{dx^2} = 4C$$

At $x = 0$ (the mouth of the pore), the dimensionless concentration, $c = 1$.

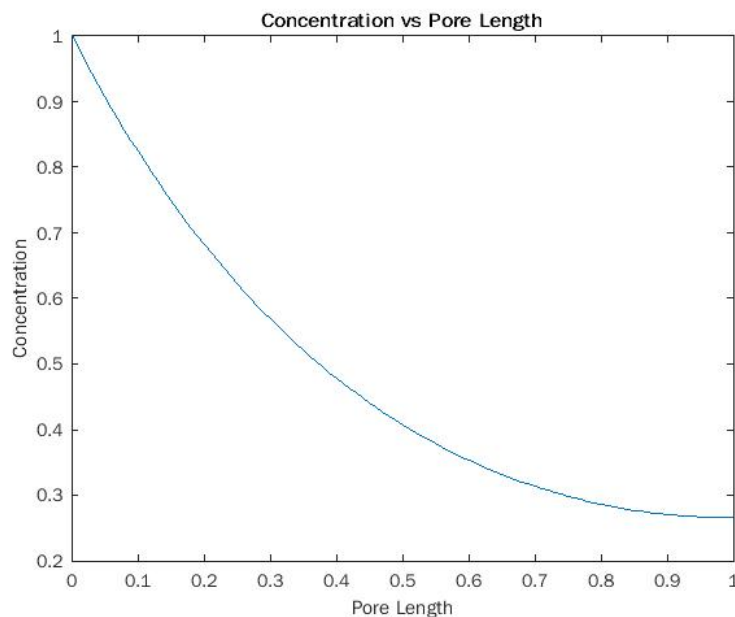
At $x = 1$ (the pore end), the gradient of the concentration, $dc/dx = 0$.

Solve the BVP using (a) Shooting Method (your code) and (b) MATLAB function `bvp4c`. Plot the concentration profile along pore length x and compare the results.

SHOOTING METHOD (MATLAB Code)

```
%SHOOTING METHOD
f= @(x,y1,y2) [ y2];      % c=y1, dc/dx = dy1/dx = y2
g = @(x,y1,y2)[4*y1];     % dy2/dx = 4y1
y1(1)=1;                  % x=0, c=1, y1=1
y2(1)=-1.925;             % guess at x=0
h=0.01;                   % step height
x=[0:h:1];                % length of pore
for i=1:1/h
    y1(i+1)= y1(i) + h*f(x(i),y1(i),y2(i)); % EULER METHOD TO SOLVE THE SYSTEM OF
    y2(i+1)= y2(i) + h*g(x(i),y1(i),y2(i));
    EQUATIONS
end
plot(x,y1);
```

Plot



MATLAB FUNCTION bvp4c

```
f= @(x,y) [ y(2) ; 4*y(1)]; % define function
                        % c=y1, dc/dx = dy1/dx = y2
                        % dy2/dx = 4y1

bc = @(ya, yb) [ya(1)-1; yb(2)]; % boundary condition
                        % x=0, c=1; x=1, dc/dx=0

xmesh = linspace(0 , 1 , 100); % steps

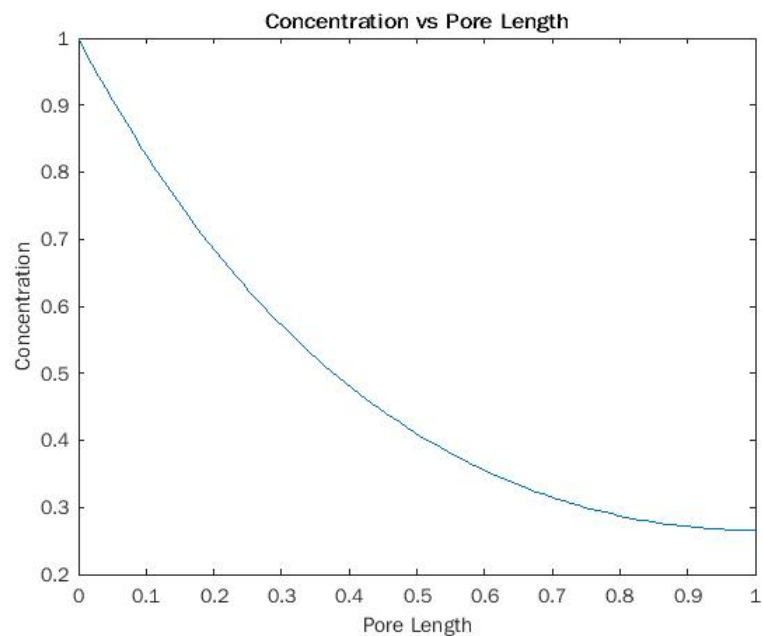
solinit = bvpinit(xmesh, [0 1]);

sol=bvp4c(f, bc,solinit);

c = sol.y;

plot( sol.x, c(1,:));
```

Plot



CONCLUSION

PROBLEM STATEMENT-2

Consider the following BVP representing steady state Heat Transfer in a rod of length $L = 10$ m.

$$\frac{d^2T}{dx^2} + h'(T_\infty - T) + \sigma(T_\infty^4 - T^4) = 0$$

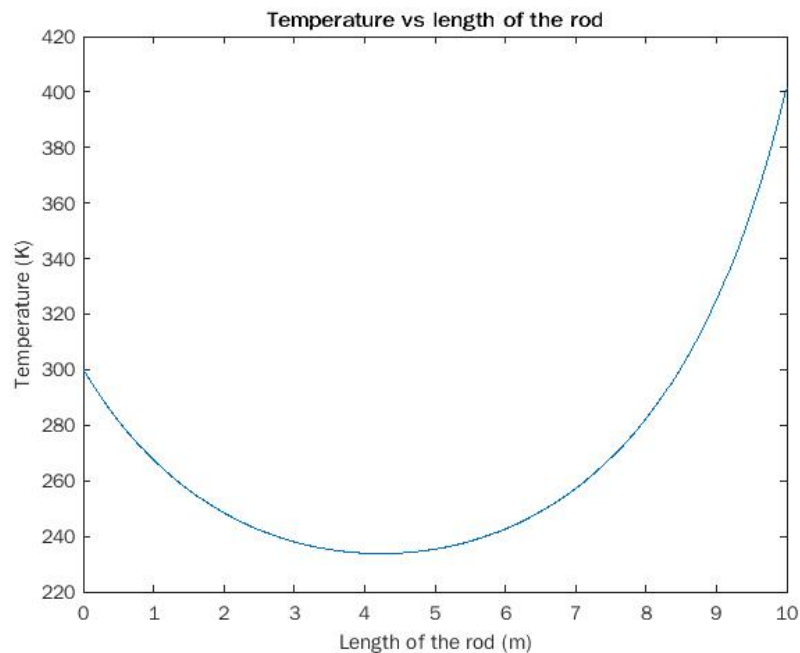
Given: $h' = 0.05 \text{ m}^{-2}$, $\sigma = 2.7 \times 10^{-9} \text{ K}^{-3} \text{ m}^{-2}$, $T_\infty = 200 \text{ K}$, $T(0) = 300 \text{ K}$, $T(10) = 400 \text{ K}$.

Solve the BVP using (a) Shooting Method (your code) and (b) MATLAB function `bvp4c`. Plot the temperature distribution along the length of the rod and compare the results.

SHOOTING METHOD (MATLAB code)

```
h= 0.05;
T0=300;
TL=400;
Tinf=200;
sigma= 2.7*10^-9;
f= @(x,y1,y2) [ y2]; % T=y1, dy1/dx = y2
g = @(x,y1,y2)[(-h*(Tinf-y1) - sigma*(Tinf^4 - (y1)^4))]; %dy2/dx=(-h*(Tinf-y1)-sigma*(Tinf^4-y1^4))
y1(1)=300; % x=0, T(0)=300
y2(1)=-41.72; % guess at x=0
h=0.01; % step height
x=[0:h:10]; % Length of the rod
for i=1:10/h
    y1(i+1)= y1(i) + h*f(x(i),y1(i),y2(i)); % EULER METHOD FOR SOLVING SYSTEM OF EQUATIONS
    y2(i+1)= y2(i) + h*g(x(i),y1(i),y2(i));
end
plot(x,y1);
```

Plot



MATLAB FUNCTION bvp4c

```
h= 0.05;
T0=300;
TL=400;
Tinf=200;
sigma= 2.7*10^-9;
f= @(x,y) [ y(2) ; (-h*(Tinf-y(1)) - sigma*(Tinf^4 - (y(1))^4))]; % T=y1, dy1/dx = y2
                                     %dy2/dx=(-h*(Tinf-y1)-sigma*(Tinf^4-y1^4))

bc = @(ya, yb) [ya(1)-T0; yb(1) - TL]; % boundary condition
                                     % x=0, T=T0; x=10, T=TL

xmesh = linspace(0 , 10 , 100); % mesh

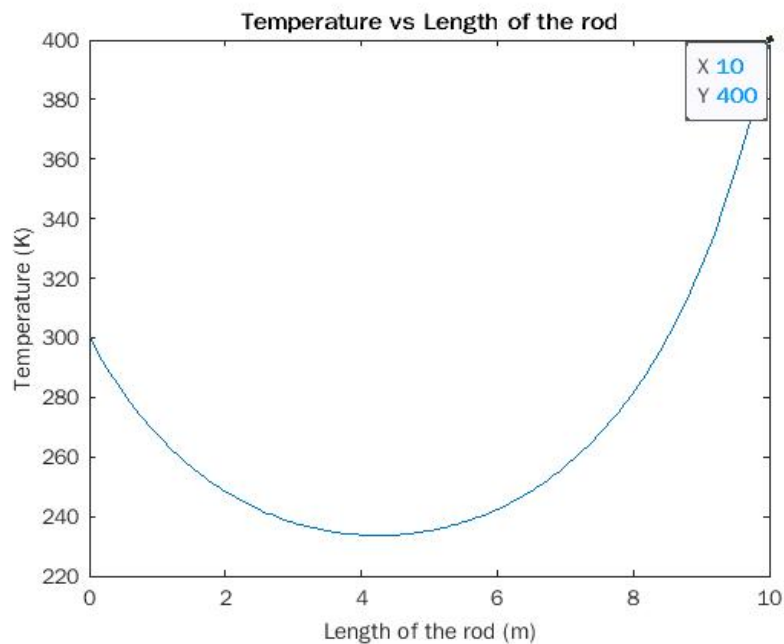
solinit = bvpinit(xmesh, [0 10]);

sol=bvp4c(f, bc,solinit);

T = sol.y;

plot( sol.x, T(1,:));
```

Plot



CONCLUSION