INDIAN INSTITUTE OF TECHNOLOGY, KHARAGPUR
Mid-Autumn Semester 2018-19

Date of Examination : 24-09-2018 Session (FN/AN) AN Duration 2 hrs
Subject No. : CH20001 Subject Name : Fluid Mechanics
Department/Center/School : Chemical Engineering
Specific charts, graph paper, log book etc., required: No
Special Instructions (if any) : Assume any data you feel are missing

Q1. A hot water tank is 28°C hotter at the top than at the bottom. A thermostat maintains the water at the bottom of the tank at 60°C, with temperature changing linearly with height. The tank is 1.5 m tall, and vented at the top. Assume that the density varies according to the relationship: $\frac{\rho(T)}{\rho(T_B)} = 1 - 0.0004(T - T_B)$, where T and T_B are the temperatures in Kelvin. The density of water at 60°C is 983.21 kg/m^3. Find

(i) the pressure distribution in the tank as a function of height
(ii) the pressure distribution in the tank if the entire tank is held at 60°C. **2+1=3 Marks**

Q2. For the velocity field, $\vec{V} = ax\hat{\imath} + ay\hat{\jmath} - 2az\hat{k}$, calculate

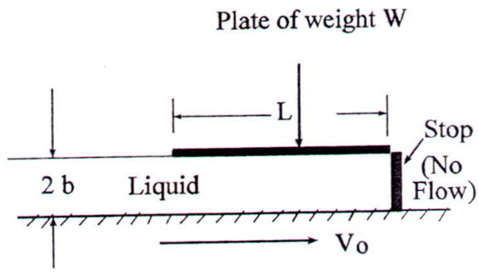
i) acceleration
ii) the position of a particle at time t, if the coordinates of the particle was (x_0, y_0, z_0) at t = 0.
iii) Vorticity **1+1+1=3 Marks**

Q3. For the velocity field, $\vec{V} = \frac{1}{t_0+t}x\hat{\imath} + v_0\hat{\jmath}$,

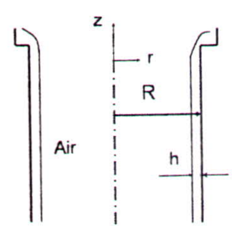
i) write the equation for streamline passing through (x_0, y_0) at time t
ii) write the equation for pathline of the fluid element that was at the position $(x_0 y_0)$ at time t = 0
iii) show that the pathline forms a tangent to the streamline at (x_0, y_0) **2+2+1=5 Marks**

Q4. The viscosity of a body fluid is found to be 6.5 cp at shear rate of 10 s^{-1}, and 4.7 cp at shear rate of 80 s^{-1}. What is the viscosity of the fluid when it is subjected to a shear stress of 100 dyne / cm^2 assuming the fluid to follow a) Power law, b) Bingham plastic model? **2+2=4 Marks**

Q5. The lower plate of a lubricated thrust bearing moves to the right at velocity V_0 . The stop at the right prevents any liquid flow beyond that point. Find the weight W that can be supported by the fluid (of viscosity μ and of density ρ) Assume the plate to be wide so that the end effects can be neglected. It can be assumed further that even if two unequal pressures act at the two ends (x=0 and x=L) of the plate it will not topple and the whole plate can be assumed to be acted on by an average of the two pressures at the two ends. **8 Marks**



Q6. A wetted wall column is used to measure mass transfer coefficients. A liquid of density ρ and viscosity μ flows down the inside of a tube of radius R, as shown in the figure. After an initial region, the flow becomes fully developed and the thickness of the liquid layer is constant and equal to h. Simplify the Navier-Stokes and continuity equations to obtain $v_z(r)$ for laminar flow in the film. **7 Marks**



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§B.4 THE EQUATION OF CONTINUITY[a]

$$[\partial\rho/\partial t + (\nabla \cdot \rho \mathbf{v}) = 0]$$

Cartesian coordinates (x, y, z):

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho v_x) + \frac{\partial}{\partial y}(\rho v_y) + \frac{\partial}{\partial z}(\rho v_z) = 0 \tag{B.4-1}$$

Cylindrical coordinates (r, θ, z):

$$\frac{\partial \rho}{\partial t} + \frac{1}{r}\frac{\partial}{\partial r}(\rho r v_r) + \frac{1}{r}\frac{\partial}{\partial \theta}(\rho v_\theta) + \frac{\partial}{\partial z}(\rho v_z) = 0 \tag{B.4-2}$$

Spherical coordinates (r, θ, ϕ):

$$\frac{\partial \rho}{\partial t} + \frac{1}{r^2}\frac{\partial}{\partial r}(\rho r^2 v_r) + \frac{1}{r \sin\theta}\frac{\partial}{\partial \theta}(\rho v_\theta \sin\theta) + \frac{1}{r \sin\theta}\frac{\partial}{\partial \phi}(\rho v_\phi) = 0 \tag{B.4-3}$$

[a] When the fluid is assumed to have constant mass density ρ, the equation simplifies to $(\nabla \cdot \mathbf{v}) = 0$.

§B.6 EQUATION OF MOTION FOR A NEWTONIAN FLUID WITH CONSTANT ρ AND μ

$$[\rho D\mathbf{v}/Dt = -\nabla p + \mu \nabla^2 \mathbf{v} + \rho \mathbf{g}]$$

Cartesian coordinates (x, y, z):

$$\rho\left(\frac{\partial v_x}{\partial t} + v_x\frac{\partial v_x}{\partial x} + v_y\frac{\partial v_x}{\partial y} + v_z\frac{\partial v_x}{\partial z}\right) = -\frac{\partial p}{\partial x} + \mu\left[\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2}\right] + \rho g_x \tag{B.6-1}$$

$$\rho\left(\frac{\partial v_y}{\partial t} + v_x\frac{\partial v_y}{\partial x} + v_y\frac{\partial v_y}{\partial y} + v_z\frac{\partial v_y}{\partial z}\right) = -\frac{\partial p}{\partial y} + \mu\left[\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2}\right] + \rho g_y \tag{B.6-2}$$

$$\rho\left(\frac{\partial v_z}{\partial t} + v_x\frac{\partial v_z}{\partial x} + v_y\frac{\partial v_z}{\partial y} + v_z\frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} + \mu\left[\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2}\right] + \rho g_z \tag{B.6-3}$$

Cylindrical coordinates (r, θ, z):

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} + v_z\frac{\partial v_r}{\partial z} - \frac{v_\theta^2}{r}\right) = -\frac{\partial p}{\partial r} + \mu\left[\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}(r v_r)\right) + \frac{1}{r^2}\frac{\partial^2 v_r}{\partial \theta^2} + \frac{\partial^2 v_r}{\partial z^2} - \frac{2}{r^2}\frac{\partial v_\theta}{\partial \theta}\right] + \rho g_r \tag{B.6-4}$$

$$\rho\left(\frac{\partial v_\theta}{\partial t} + v_r\frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\theta}{\partial \theta} + v_z\frac{\partial v_\theta}{\partial z} + \frac{v_r v_\theta}{r}\right) = -\frac{1}{r}\frac{\partial p}{\partial \theta} + \mu\left[\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}(r v_\theta)\right) + \frac{1}{r^2}\frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{\partial^2 v_\theta}{\partial z^2} + \frac{2}{r^2}\frac{\partial v_r}{\partial \theta}\right] + \rho g_\theta \tag{B.6-5}$$

$$\rho\left(\frac{\partial v_z}{\partial t} + v_r\frac{\partial v_z}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_z}{\partial \theta} + v_z\frac{\partial v_z}{\partial z}\right) = -\frac{\partial p}{\partial z} + \mu\left[\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial v_z}{\partial r}\right) + \frac{1}{r^2}\frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2}\right] + \rho g_z \tag{B.6-6}$$

Spherical coordinates (r, θ, ϕ):

$$\rho\left(\frac{\partial v_r}{\partial t} + v_r\frac{\partial v_r}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_r}{\partial \theta} + \frac{v_\phi}{r \sin\theta}\frac{\partial v_r}{\partial \phi} - \frac{v_\theta^2 + v_\phi^2}{r}\right) = -\frac{\partial p}{\partial r}$$
$$+ \mu\left[\frac{1}{r^2}\frac{\partial^2}{\partial r^2}(r^2 v_r) + \frac{1}{r^2 \sin\theta}\frac{\partial}{\partial \theta}\left(\sin\theta\frac{\partial v_r}{\partial \theta}\right) + \frac{1}{r^2 \sin^2\theta}\frac{\partial^2 v_r}{\partial \phi^2}\right] + \rho g_r \qquad \text{(B.6-7)}^a$$

$$\rho\left(\frac{\partial v_\theta}{\partial t} + v_r\frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\theta}{\partial \theta} + \frac{v_\phi}{r \sin\theta}\frac{\partial v_\theta}{\partial \phi} + \frac{v_r v_\theta - v_\phi^2 \cot\theta}{r}\right) = -\frac{1}{r}\frac{\partial p}{\partial \theta}$$
$$+ \mu\left[\frac{1}{r^2}\frac{\partial}{\partial r}\left(r^2\frac{\partial v_\theta}{\partial r}\right) + \frac{1}{r^2}\frac{\partial}{\partial \theta}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial \theta}(v_\theta \sin\theta)\right) + \frac{1}{r^2 \sin^2\theta}\frac{\partial^2 v_\theta}{\partial \phi^2} + \frac{2}{r^2}\frac{\partial v_r}{\partial \theta} - \frac{2\cot\theta}{r^2 \sin\theta}\frac{\partial v_\phi}{\partial \phi}\right] + \rho g_\theta \tag{B.6-8}$$

$$\rho\left(\frac{\partial v_\phi}{\partial t} + v_r\frac{\partial v_\phi}{\partial r} + \frac{v_\theta}{r}\frac{\partial v_\phi}{\partial \theta} + \frac{v_\phi}{r \sin\theta}\frac{\partial v_\phi}{\partial \phi} + \frac{v_\phi v_r + v_\theta v_\phi \cot\theta}{r}\right) = -\frac{1}{r \sin\theta}\frac{\partial p}{\partial \phi}$$
$$+ \mu\left[\frac{1}{r^2}\frac{\partial}{\partial r}\left(r^2\frac{\partial v_\phi}{\partial r}\right) + \frac{1}{r^2}\frac{\partial}{\partial \theta}\left(\frac{1}{\sin\theta}\frac{\partial}{\partial \theta}(v_\phi \sin\theta)\right) + \frac{1}{r^2 \sin^2\theta}\frac{\partial^2 v_\phi}{\partial \phi^2} + \frac{2}{r^2 \sin\theta}\frac{\partial v_r}{\partial \phi} + \frac{2\cot\theta}{r^2 \sin\theta}\frac{\partial v_\theta}{\partial \phi}\right] + \rho g_\phi \tag{B.6-9}$$