

04/08/2022

Ch E.
 (PDE) Parabolic = ~~non steady state~~ ^{steady state}
 Date: ~~non steady state~~ ^{steady state}
 (PDE) Elliptical = ~~non steady state~~ ^{non steady state}
 (PDE) Hyperbolic = ~~non steady state~~ ^{Very rare} for Ch Eng
 Relevant for civil engineers.

Ex! $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$ ($\nabla^2 u = 0$)

$x = x_1, y = x_2, z = x_3$

$\nabla^2 \rightarrow$ Laplacian operator

$$a_{11} \frac{\partial^2 u}{\partial x_1^2} + a_{12} \frac{\partial^2 u}{\partial x_1 \partial x_2} + a_{13} \frac{\partial^2 u}{\partial x_1 \partial x_3}$$

$$+ a_{21} \frac{\partial^2 u}{\partial x_2 \partial x_1} + a_{12} \frac{\partial^2 u}{\partial x_2^2} + a_{13} \frac{\partial^2 u}{\partial x_2 \partial x_3} \Rightarrow A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$+ a_{31} \frac{\partial^2 u}{\partial x_3 \partial x_1} + a_{13} \frac{\partial^2 u}{\partial x_3 \partial x_2} + a_{23} \frac{\partial^2 u}{\partial x_3^2}$$

$$\lambda = 1, 1, 1$$

Elliptical PDE

② $\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$

$x = x_1, y = x_2, t = x_3$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\lambda = 1, 1, 0$$

parabolic PDE

③ $\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$

$x = x_1, y = x_2, t = x_3$

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 u}{\partial t^2} = 0$$

Hyperbolic PDE. \rightarrow Mixed sign.



Linear operatorIf $L(\alpha u + \beta v)$

$$= \alpha L(u) + \beta L(v)$$

 α, β are scalarsu, v are contin. funct.
thus, L is linear operator

$$\frac{d}{dx}(u+v) = \frac{du}{dx} + \frac{dv}{dx}$$

$\hookrightarrow L$

$$L = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

$$L = \frac{\partial}{\partial t} - \nabla^2$$

$$L = \frac{\partial^2}{\partial t^2} - \nabla^2$$

Linear operator.

if operator is linear \rightarrow Advantages, we can use principle of linear superposition \rightarrow Helps in solution of PDEs.

$$\# \text{ ODE: } \frac{d^2u}{dx^2} = x$$

(if $u=0$ then Homog.)

$$\text{at, } x=0, u=\underline{\underline{1}} \quad \rightarrow 3 \text{ sources of Non-homogeneity.}$$

$$x=1, u=\underline{\underline{2}} \quad u=u_1+u_2+u_3$$

1 about at a time
forcing others to be zero.

(if $u=1+\text{hom}$)
homog.)

$$\Rightarrow u_1 : \frac{d^2u_1}{dx^2} = x \quad u_2 : \frac{d^2u_2}{dx^2} = 0 \quad u_3 : \frac{d^2u_3}{dx^2} = 0$$

at $x=0 \quad \left\{ \begin{array}{l} u_1=0 \\ u_2=1 \\ u_3=0 \end{array} \right. \quad \text{at } x=0, u_2=1 \quad \text{at } x=0, u_3=0$

$$\frac{d^2}{dx^2}(u_1+u_2+u_3) = x \quad : \frac{d^2u_1}{dx^2} + \frac{d^2u_2}{dx^2} + \frac{d^2u_3}{dx^2} = x.$$

$$\text{at } x=0, u_1+u_2+u_3=\underline{\underline{1}}$$

$$\text{at } x=1, u_1+u_2+u_3=\underline{\underline{2}}.$$

$$u_1 : \frac{d u_1}{dx} = \frac{x^2}{2} + C_1$$

$$u_2 : \frac{d u_2}{dx} = C_2$$

$$u_1 = \frac{x^3}{6} + C_1 x + C_2$$

$$u_2 = C_2 x + C_3$$

$$C_2 = 0$$

$$u_1 = \frac{x^3}{6} + C_1 x$$

$$C_1 = 1$$

$$0 = \frac{1}{6} + C_1 \Rightarrow C_1 = -\frac{1}{6}$$

$$C_1 = -1$$

$$u_3: \frac{du_3}{dx} = c_1$$

$$u_3 = c_1 x + c_2$$

$$c_2 = 0$$

$$2 = c_1 + 0 \quad \boxed{c_1=2}$$

$$\boxed{u_3 = 2x}$$

If we directly solve the problem.

$$u = u_1 + u_2 + u_3$$

$$= \frac{x^3}{6} - \frac{x}{6} - x + 1 + 2x$$

$$= \frac{x^3}{6} - \frac{x}{6} + x + 1$$

$$\boxed{u = \frac{x^3}{6} - \frac{5x}{6} + 1}$$

$$\Rightarrow \frac{du}{dx} = \frac{x^2}{2}$$

$$u = \frac{x^3}{6} + c_2 \quad \Rightarrow \quad u = \frac{x^3}{6} + c_1 + 1$$

$$\boxed{c_2 = c_1}$$

$$\boxed{c_1 = 1}$$

$$\Rightarrow u = \frac{x^3}{6} + 1$$

$$\frac{du}{dx} = \frac{x^2}{2} + c_1$$

$$u = \frac{x^3}{6} + c_1 x + c_2$$

$$\boxed{c_2 = 1}$$

$$u = \frac{x^3}{6} + c_1 x + 1$$

$$2 = \frac{1}{6} + c_1 \cdot 0 + 1$$

$$\boxed{c_1 = \frac{5}{6}}$$

$$\boxed{u = \frac{x^3}{6} + \frac{5x}{6} + 1}$$

Φ_1 , Parabolic PDE (Principle of linear superposition)

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

$$\text{at } t=0, u = \underline{u_0}$$

$$\text{at } x=0, u \geq 0$$

$$\text{at } x \geq 1, u \geq 1$$

2 sources from

$$\therefore u = u_1 + u_2$$

$$u_1: \frac{\partial u_1}{\partial t} = \frac{\partial^2 u_1}{\partial x^2}$$

$$\text{at } t=0, u_1 = u_0$$

$$\left. \begin{array}{l} \text{at } x=0 \\ = 1 \end{array} \right\} u_1 = 0$$

well behaved/well-posed problem

solvable directly

$$u_2: \frac{\partial u_2}{\partial t} = \frac{\partial^2 u_2}{\partial x^2}$$

$$\text{at } t=0, u_2 = 0$$

$$\text{at } x=0, u_2 = 0$$

$$\text{at } x=1, u_2 = 1$$

ill posed problem
initial value is 0
at one BC's

BC's not known

All BC's are homogeneous

\Rightarrow ILL POSED PROB

To be split

into (1) time dependent

(2) T.P.D. independent

pioneerpaper.co

$$u(x, t) = u_2^S(x) + u_2^T(x, t)$$

Steady state part

$$u_2^S + u_2^T = \frac{\partial^2}{\partial x^2} (u_2^S + u_2^T)$$

$$\frac{\partial u_2^T}{\partial t} = \frac{\partial^2 u_2^S}{\partial x^2} + \frac{\partial^2 u_2^T}{\partial x^2}$$

$$\text{at } x=0, u_2^S=0 \quad \text{at } x=0, u_2^T=0$$

$$\text{at } x=1, u_2^S=1 \quad \text{at } x=1, u_2^T=0$$

$$\text{at } t=0, u_2 \approx u_2^S + u_2^T = 1$$

$$u_2^T = -u_2^S(x)$$

$$= -x$$

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} \quad ; \quad \text{at } t=0, u=u_0,$$

$$x=0, \frac{\partial u}{\partial x} + \alpha u = u_{02}$$

$$x=1, \frac{\partial u}{\partial x} = u_{03}.$$

$u = u_1 + u_2 + u_3$ (Formulate problems s.t. there exist one

NH at ~~all~~ ~~one~~ time),

$$u_1 = \frac{\partial u_1}{\partial t} + \frac{\partial^2 u_1}{\partial x^2} \quad \text{at } t=0, u_1=u_{01},$$

$$x=0, \frac{\partial u_1}{\partial x} + \alpha u_1 = 0$$

$$x=1, \frac{\partial u_1}{\partial x} = 0$$

$$u_2 = \frac{\partial u_2}{\partial t} = \frac{\partial^2 u_2}{\partial x^2}$$

$$\text{at } t=0, u_2=0 \quad \text{at } t=\infty, \frac{\partial u_2}{\partial x} + u_2 = 0$$

$$\text{at } x=1, \frac{\partial u_2}{\partial x} \approx 0 \quad \text{ILL posed}$$

$$u_3 : \frac{\partial u_3}{\partial t} = \frac{\partial^2 u_3}{\partial x^2} ; \quad \text{at } x=0, \frac{\partial u_3}{\partial x} + \alpha u_3 = 0$$

$$\text{at } x=1, \frac{\partial u_3}{\partial x} = u_{03}.$$

$$u_2 = u_2^S(x) + u_2^T(x, t)$$

$$\text{at } t=\infty, u_3=0$$

ILL posed

$$\text{at } x=0, \frac{du_2^S}{dx} + \frac{\partial u_2^T}{\partial x} + \alpha_1 u_2^S + \alpha_2 u_2^T = u_{02}$$

$$u_2^S : \frac{\partial^2 u_2^S}{\partial x^2} = 0$$

$$\frac{du_2^S}{dx} + \alpha_1 u_2^S = u_{02} \text{ at } x=0$$

$$u_2^T : \frac{\partial^2 u_2^T}{\partial x^2} = 0$$

$$\text{at } x=0, \frac{\partial u_2^T}{\partial x} + u_{02} = 0$$

$$\text{at } x=1, \frac{\partial u_2^T}{\partial x} = 0$$

$$\frac{du_2^T}{dx} + \frac{\partial u_2^T}{\partial x} = 0$$

of the form

Defines
standard
value
problem.

$$\frac{d^2y}{dx^2} + \lambda y = 0 ; \quad \lambda \text{ is a scalar.}$$

subject to at $x=0 \quad y=0$
 $x=1 \quad y=0$

pioneerpaper.co
 Page _____
 Date _____

$$L = \frac{d^2}{dx^2}$$

$$\Rightarrow Ly + \lambda y = 0$$

$$Ly = -\lambda y$$

Equivalent to
 Discrete. $Ax = \lambda x$ ← Eigen value
 domain. problem.
 in cont. domain.

Case 1: $\frac{d^2y}{dx^2} + \lambda y = 0$

Sq. vector matrix λ : Eigen value

Sub to $y=0$ at $x=0$

⇒ Standard value prob.

Case 2: $y=0$ is always a trivial soln. but we aren't looking for a trivial solution

$$\lambda > 0$$

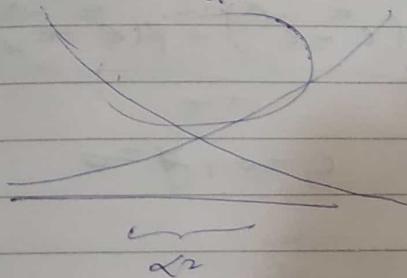
$$\frac{d^2y}{dx^2} \Rightarrow$$

$$y=0$$

Trivial solution

Case 3: $\lambda = -ve = -\alpha^2$

$$\frac{d^2y}{dx^2} - \alpha^2 y = 0 ; \quad y = c_1 e^{\alpha x} + c_2 e^{-\alpha x}$$



$$0 = c_1 + c_2 \quad \text{--- (1)}$$

$$0 = c_1 e^\alpha + c_2 e^{-\alpha}$$

$$y = c_1 \underbrace{(e^{\alpha x} - e^{-\alpha x})}_{\text{ane.}}$$

Case 4: $\lambda = +ve = \alpha^2$

$$\frac{d^2y}{dx^2} + \alpha^2 y = 0$$

$$\Rightarrow y = c_1 \sin(\alpha x) + c_2 \cos(\alpha x)$$

$$0 = c_2$$

$$y = c_1 \sin(\alpha x)$$

$$0 = c_1 \sin(x), \text{ if } c_1 \neq 0.$$

Trivial soln
 (0)

For $c_1 \neq 0 \Rightarrow \alpha \neq 0$ we must take α for soln.

$$\alpha_n = n\pi, n=1, 2, \dots, \infty - \{0\}$$

Case 5: $\frac{d^2y}{dx^2} + \lambda y = 0$ sub to at $x=0 \quad \frac{dy}{dx} = 0$

at $x=1, y=0$

Case 6: $\lambda = 0$

$$y = c_1 x + c_2$$

$y=0$ Trivial soln

$$\lambda \neq 0$$

Case 7: $\lambda = -ve = -\alpha^2$

$$\frac{d^2y}{dx^2} - \alpha^2 y = 0$$

at $x=0, y \neq 0$

$$\frac{dy}{dx} = c_1 \alpha e^{\alpha x} - c_2 \alpha e^{-\alpha x}$$

$$\begin{aligned} 0 &= c_1 \alpha - c_2 \alpha \\ \Rightarrow c_1 &= c_2 \end{aligned}$$

$$y = c_1 (e^{\alpha x} + e^{-\alpha x})$$

$$0 = c_1 x (e^{\alpha x} + e^{-\alpha x}) \Rightarrow c_1 x_2 = 0$$

Eigenfunkt.

$$y_n = C_n \cos((2n+1)\frac{\pi}{2}x)$$

Convex

$$\frac{d^2y}{dx^2} + \lambda y = 0 ; \text{ sub to at } x=0, y \neq 0 \quad n=1, 2, \dots \infty$$

$$\text{at } x=1, \left[\frac{dy}{dx} + \beta y = 0 \right] \quad (\rightarrow \text{scalar})$$

$$\text{Concave: } \lambda \geq 0$$

$y \neq 0$ is soln

$$\text{Concave: } \lambda - \nu e = -\alpha^2$$

$$y(x) = c_1 e^{\alpha x} + c_2 e^{-\alpha x}$$

$$0 = c_1 + c_2 \Rightarrow c_1 = -c_2$$

$$y(x) = c_1 (e^{\alpha x} - e^{-\alpha x})$$

$$Ke^{\beta x} = c_1 (e^{\alpha x} - e^{-\alpha x})$$

$$c_1 = \frac{Ke^{-\beta x}}{e^{\alpha x} - e^{-\alpha x}}$$

$$c_1 \left(\alpha e^{\alpha x} + \alpha e^{-\alpha x} \right) + \beta c_1 (e^{\alpha x} - e^{-\alpha x})$$

$$c_1 \left[\underbrace{\alpha (e^{\alpha x} + e^{-\alpha x})}_{\text{+ve}} + \beta (e^{\alpha x} - e^{-\alpha x}) \right] = 0$$

$$c_1 \neq 0, \beta \neq 0$$

$$\text{Concave: } \lambda^2 + \nu e > \alpha^2$$

$$y \sim c_1 \sin(\alpha x) + c_2 \cos(\alpha x)$$

$$0 \neq c_2$$

$$y \sim c_1 \sin(\alpha x)$$

$$c_1 \alpha \cos(\alpha x) + \beta c_1 \sin(\alpha x) \Big|_{x=1} = 0$$

$$c_1 (\alpha \cos \alpha + \beta \sin \alpha) = 0$$

$$c_1 (\alpha + \beta \tan \alpha) = 0$$

$$\text{For } c_1 \neq 0 \Rightarrow \boxed{\alpha + \beta \tan \alpha = 0} \quad \begin{array}{l} \text{Transcendental equation in } \alpha, \\ \rightarrow \text{NR method} \end{array}$$

$$y_n = c_1 \sin(\alpha_n x) \rightarrow \text{Eigenfunkt.}$$

$$\text{Concave: } \lambda^2 + \nu e < \alpha^2$$

$$\frac{d^2y}{dx^2} + \alpha^2 y = 0$$

$$y = c_1 \sin(\alpha x) + c_2 \cos(\alpha x)$$

$$\frac{dy}{dx} = c_1 \alpha \cos(\alpha x) - c_2 \alpha \sin(\alpha x)$$

$$0 = c_1 \alpha \cos(\alpha x), c_1 \neq 0, \alpha \neq 0$$

$$y = c_2 \cos(\alpha x)$$

$$0 = c_2 \cos \alpha$$

$$\cos \alpha = 0 \Rightarrow \alpha = (2n+1)\frac{\pi}{2}$$

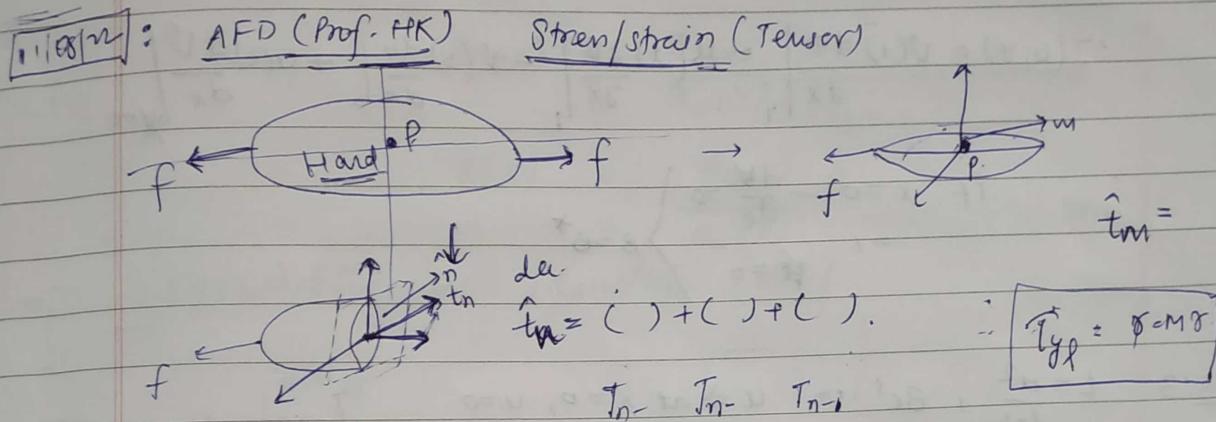
$$\text{Concave: } \lambda^2 + \nu e < \alpha^2$$

$$\begin{aligned} \frac{dy}{dx} - \beta y &= 0 \\ dy &= \beta y dx \\ y &= K e^{\beta x} \end{aligned}$$



$\frac{d^2}{dx^2} + \lambda y = 0$ } Std. eigenvalue prob
 Sub to Ham BC's } common in solution of PDE's
 w.r.t. boundary cond.

<u>BC</u>	<u>Evalue</u>	<u>Efunkt.</u>
Dirichlet	$n\pi$	$\sin(n\pi x)$
Neumann + Dirichlet	$(2n-1)\frac{\pi}{2}$	$\cos((2n-1)\pi x)$
Dirichlet + Robin mix	$\alpha_n + \beta \tan(\alpha_n) = 0$ P roots	$\sin(\alpha_n x)$



24/08/22 AMT

For operator $L = \frac{a_0 d^2}{dx^2} + a_1 \frac{d}{dx} + a_2$

$$L^* = \frac{a_0 d^2}{dx^2} + (2a_0 - a_1) \frac{d}{dx} + (a_0'' - a_1' + a_2)$$

$$\langle v, Lu \rangle = J(u, v) + \langle u, L^* v \rangle$$

if $L = L^*$
 $\& B = B^*$

$L \rightarrow$ self adjoint operator.

Ex: 1 $L = \frac{d^2}{dx^2}$, BC's on $u \Rightarrow$ at $x=0$ } $u=0$
 $x=1$ } B .

$$\begin{aligned} L^* &= ? \quad B^* = ? \\ \langle v, Lu \rangle &= \int_0^1 v \frac{d^2 u}{dx^2} dx = \int_0^1 v \frac{du}{dx} \Big|_0^1 - \int_0^1 \frac{dv}{dx} \frac{du}{dx} dx \\ &= \int_0^1 v \frac{du}{dx} \Big|_0^1 - \frac{dv}{dx} u \Big|_0^1 + \int_0^1 v \frac{d^2 u}{dx^2} dx \end{aligned}$$

$$= \left[v \frac{du}{dx} - u \frac{dv}{dx} \right]_0^1 + \langle u, L^* v \rangle \quad L^* = L = \frac{d^2}{dx^2}$$



REDMI NOTE 5 PRO
MI DUAL CAMERA

$$J(u, v) = v(1) \frac{du}{dx} \Big|_0 - u(1) \frac{dv}{dx} \Big|_0 - v(0) \frac{du}{dx} \Big|_0 + u(0) \frac{dv}{dx} \Big|_0$$

if $x=0 \Rightarrow \left. v = 0 \right\} B^*$

In this particular problem.
 $\begin{cases} B = B^* \\ L = L^* \end{cases}$

Ex: 2 $L = \frac{d^2}{dx^2}; B \text{ is on } u \Rightarrow \text{at } x=0, \frac{du}{dx} = 0$
 $= 1, u = 0 \quad \boxed{B}$

— Same as previous —

$$J(u, v) = v(1) \frac{du}{dx} \Big|_0 - u(1) \frac{dv}{dx} \Big|_0 - v(0) \frac{du}{dx} \Big|_0 + u(0) \frac{dv}{dx} \Big|_0$$

if $x=0 - \frac{dv}{dx} = 0$
 $= 1, v = 0 \quad \boxed{B = B^*}$

Ex: 3 $L = \frac{d^2}{dx^2}, B \text{ is on } u \Rightarrow \text{at } x=0, u = 0$
 $= 1, \frac{du}{dx} + \beta u = 0 \quad \boxed{B}$

$\leftarrow B^* \therefore \left[\frac{v du}{dx} - u \frac{dv}{dx} \right]_0^1 + \langle u, L^* v \rangle$
 $L^* = L = \frac{d^2}{dx^2}$
 $B = B^*$

$$J(u, v) = v(1) \frac{du}{dx} \Big|_0 - u(1) \frac{dv}{dx} - v(0) \frac{du}{dx} \Big|_0 + u(0) \frac{dv}{dx} \Big|_{x=0}$$

$$J(u, v) = v(1) + (-\beta)u(x=1) - u(1) \frac{dv}{dx} \Big|_{x=1} - v(0) \frac{du}{dx} \Big|_{x=0}$$

$\begin{cases} L = L^* \\ B = B^* \end{cases} \therefore = \text{CCO} \left[\frac{dv}{dx} \Big|_{x=1} + \beta v \Big|_{x=1} \right] - v(x_0) \frac{du}{dx} \Big|_{x=0}$

\hookrightarrow self adjoint

operator at $x=0, v=0$

at $x=1, \frac{dv}{dx} + \beta v = 0 \quad \boxed{B^*}$



\rightarrow Generalised second order operator.



REDMI NOTE 5 PRO

MI DUAL CAMERA $+ a_1(x) \frac{du}{dx} + a_2(x) u$

$$L u = -\lambda a_3 u \quad [\text{Generalized Eigenvalue Problem}]$$

$a_0 u'' + a_1 u' + a_2 u + \lambda a_3 u = 0 \quad \dots \quad (1)$

Equation (1) can be re-written

$$\frac{d}{dx} \left[P(x) \frac{du}{dx} \right] + Q(x)u + \lambda R(x)u = 0 \quad \dots \quad (2)$$

where, $P(x) = e^{\int \frac{a_1(x)}{a_0(x)} dx}$

$$Q(x) = \frac{a_2(x)}{a_0(x)} P.$$

$$R(x) = \frac{a_3(x)}{a_0(x)} P$$

Eqs (1) & (2) are identical. [P.T]

$$\frac{d}{dx} \left[e^{\int \frac{a_1(x)}{a_0(x)} dx} \frac{du}{dx} \right] + \frac{a_2(x) P u + \lambda \frac{a_3(x) P u}{a_0(x)}}{a_0(x)} = 0$$

$$+ \frac{a_2(x)}{a_0(x)} e^{\int \frac{a_1(x)}{a_0(x)} dx} u + \lambda \frac{a_3(x)}{a_0(x)} e^{\int \frac{a_1(x)}{a_0(x)} dx} u = 0$$

$$\frac{a_1(x)}{a_0(x)} e^{\int \frac{a_1(x)}{a_0(x)} dx} \frac{du}{dx} + e^{\int \frac{a_1(x)}{a_0(x)} dx} \frac{d^2 u}{dx^2} + \frac{a_2(x)}{a_0(x)} e^{\int \frac{a_1(x)}{a_0(x)} dx} u + \lambda \frac{a_3(x)}{a_0(x)} e^{\int \frac{a_1(x)}{a_0(x)} dx} u = 0$$

$$a_0(x) u'' + a_1 u' + a_2 u + \lambda a_3 u = 0 \rightarrow [a_0 u'' + a_1 u' + a_2 u + \lambda a_3 u = 0]$$

M.T

$$\ln P = \int \frac{a_1}{a_0} dx \Rightarrow \frac{1}{P} \frac{dP}{dx} = \frac{a_1}{a_0} \Rightarrow \frac{dP}{dx} = \frac{a_1}{a_0} P.$$

$$\frac{d}{dx} \left[P \frac{du}{dx} \right] + Q u + \lambda R u = 0$$

$$L = \frac{d}{dx} \left[P \frac{du}{dx} \right] + Q.$$

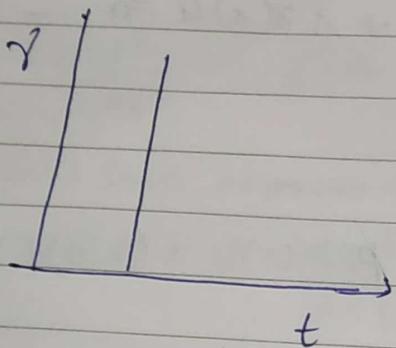
$$\alpha_0 = P_j \quad \alpha_1 = P'_j \quad \alpha_2 = 2$$

$$L^* = \frac{P d^2}{dx^2} + (2P' - P') \frac{d}{dx} + (P'' - P' + 2)$$

Date: / /

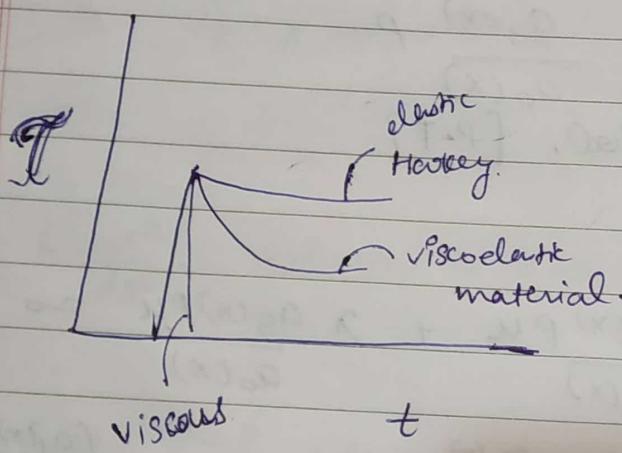
$$= P \frac{d^2}{dx^2} + P' \frac{d}{dx} + 2.$$

[#24/08/21] AFD : Prof. HK.



Time (strain) dependence

elastic solid	simple liquid	complex fluid
---------------	---------------	---------------



→ Draw these on cartesian coordinate and study their behaviour. Do the study on graphs.

$$\rightarrow G(t) = \frac{T(t)}{\gamma}$$

$$M(t) = -\frac{dG}{dt}$$

memory function

Visco
Liquid. viscoelastic material elastic solid.

$$\int T(t) dt = \int M(t) \gamma dt$$

$$(t-t') = s$$

Measures for viscoelastic

(1) Stress Relaxation.

(2) Creep

(3) Stress Oscillation.



REDMI NOTE 5 PRO
MI DUAL CAMERA

Generalized Sturm-Liouville operator,

$$L = \int_{(x)}^{a_0} \frac{d^2}{dx^2} + a_1 \frac{d}{dx} + a_2$$

$$L = L^*$$

$$Lu = -\lambda u$$

$$\text{at } x=a, \alpha_1 \frac{du}{dx} + \alpha_2 u = 0$$

$$x=b, \beta_1 \frac{dy}{dx} + \beta_2 y = 0 \quad \left. \right\} B$$

$$J(u, v) = \left[v a_0 u' - v' a_0 u - v a_1 u' + a_1 v u \right]_a^b$$

$$a_0 = p$$

$$a_1 = p'$$

$$a_2 = q$$

$$a_3 = r$$

$$\Rightarrow -[a_0 v u' - a_0 v' u]_a^b$$

$$\Rightarrow a_0 v(b) u'(b) - a_0 v'(b) u(b)$$

$$- a_0 v(a) u'(a) + a_0 v'(a) u(a)$$

$$\Rightarrow a_0(b) * (-u(b)) \left[\frac{\beta_2}{\beta_1} v(b) + v'(b) \right]$$

$$\Rightarrow a_0(a) * \left\{ \frac{\alpha_2}{\alpha_1} v(a) + v'(a) \right\} u(a)$$

$$\Rightarrow \text{at } x=a$$

$$\alpha_1 \frac{dv}{dx} + \alpha_2 v = 0$$

$$\text{at } x=b$$

$$\beta_1 \frac{dv}{dx} + \beta_2 v = 0$$

$$\Rightarrow \boxed{B = B^*}$$

$$\boxed{L = L^*}$$

$\rightarrow L$ is self adjoint.

Theorem # 1: For Sturm-Liouville operator (S-L)
 ↳ Infinite eigen values.

Definition of orthogonal function:

$\phi_m(x)$ & $\phi_n(x)$ are orthogonal to each other w.r.t weight function $\sigma(x)$. if $\langle \phi_m, \phi_n \rangle = 0$.

$$\Rightarrow \int_x \phi_m \phi_n \sigma(x) dx = 0$$

if $f(x, y)$

$$\int_{(X,Y)} \phi_m \phi_n \sigma(x, y) dx dy = 0$$

similarly for (x, y, z)



Theorem 2 : If λ_m & λ_n are corresponding eigen functions.

y_m & y_n are orthogonal function w.r.t $\delta(x)$.

$$\Rightarrow Ly = -\lambda \gamma y \Rightarrow Ly_n = -\lambda_n \gamma y_n \quad \dots \textcircled{1}$$

Eigen value problem.

$$Ly_m = -\lambda_m \gamma y_m \quad \dots \textcircled{2}$$

Take inner product of eq(1) w.r.t y_m

$$\begin{bmatrix} \langle v, Lu \rangle = \langle u, L^* v \rangle \\ + J(u, v) \end{bmatrix}$$

" " " " eq₂ w.r.t y_n .

& subtract.

$$\Rightarrow \int y_m (Ly_n) dx - \int y_n (Ly_m) dx = (\lambda_m - \lambda_n) \int y_m y_n \gamma dx$$

$$\int y_n L^* y_m dx + J(y_m, y_n) - \int y_n (Ly_m) dx = (\lambda_m - \lambda_n) \int y_m y_n \gamma dx$$

$$L = L^* \& J(u, v) = 0$$

$$\Rightarrow \begin{cases} (\lambda_m - \lambda_n) \int y_m y_n \gamma dx = 0 \\ \neq 0 \end{cases} \quad \boxed{\int y_m y_n \gamma dx = 0}$$

Summary: * Characteristics of PDEs

* Various BC's

* Definition of well & ill-posed problem.

↳ convert into

well posed problem.

* Special ODEs (\Rightarrow corresponding eigenvalue problem).

* Finding out adjoint operator & BCs of adjoint problem.

* Definition of S-L operator

* Definition/Theorems.

Solving PDE's using separation of variables

→ Cartesian co-ord/ Parabolic PDE.

Well posed Problem

$$\text{Ex: } \frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$$

$$f C_p \frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

at $t=0$, $u=u_0$
 $x=0$, $u=u_0$
 $x=b$, $T=T_0$

at $t=0$, $T=T_0$

$x=a$, $T=T_1$

$x=b$, $T=T_1$



REDMI NOTE 5 PRO
MI DUAL CAMERA

$$\Rightarrow \frac{x dT}{dt} = T \frac{d^2 x}{dx^2}$$

$$\Rightarrow \frac{1}{T} \frac{dT}{dt} = \frac{1}{x} \frac{d^2 x}{dx^2} = \text{const} = -\lambda$$

$\begin{matrix} 1 \\ \downarrow \\ \text{+ve} & \text{-ve} & \text{zero} \end{matrix}$

$$\Rightarrow \frac{d^2 x}{dx^2} + \lambda x = 0$$

$$\left[\frac{d^2 x}{dx^2} + \lambda^2 x = 0 \right] \quad \text{at } \begin{cases} x=0 \\ x=L \end{cases} \quad \left[x_n = C_n \sin(n\pi x) \right]$$

$$x_n = n\pi, n=1, 2, \dots, \infty$$

$$\Rightarrow \frac{1}{T_n} \frac{dT_n}{dt} = -n^2 \pi^2$$

$$T_n = C_1 \exp(-n^2 \pi^2 t)$$

$$x = \sum_{n=1}^{\infty} x_n$$

$$= \sum_{n=1}^{\infty} C_n \sin(n\pi x)$$

$$U_n = T_n x_n$$

$$\boxed{U(x, t) = \sum_{n=1}^{\infty} U_n = \sum C_n \exp(-n^2 \pi^2 t) \sin(n\pi x)}$$

$$\text{at } t=0, U=U_0$$

$$U_0 = \sum C_n \sin(n\pi x)$$

Multiply both sides by $\sin(m\pi x) dx$

$$U_0 \sin(m\pi x) dx = \sum_{n=1}^{\infty} C_n \int_0^L \sin(m\pi x) \sin(n\pi x) dx$$

$$= C_1 \int \sin(m\pi x) \sin(\pi x) dx + C_2 \int \sin(m\pi x) \sin(2\pi x) dx$$

$$= C_n \int \sin^2(n\pi x) dx$$

$$\Rightarrow U_0 \int_0^L \sin(m\pi x) dx = C_n \int_0^L \sin^2(n\pi x) dx$$

\downarrow
 $m \rightarrow n$

$$\Rightarrow U_0 \int_0^L \sin(n\pi x) dx = C_n / 2 \Rightarrow U_0 \left(\frac{1 - \cos(n\pi)}{n\pi} \right) = C_n / 2$$

$$\boxed{U(x, t) = \sum_{n=1}^{\infty} U_n = 2U_0 \sum \frac{(1 - \cos(n\pi))}{n\pi} \exp(-n^2 \pi^2 t) \sin(n\pi x)}$$



- 2 Dimensional Parabolic
well posed problem.

$$\left[\begin{array}{l} \frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} \\ \text{at } t=0, \quad u=u_0 \\ x=0, \quad \frac{\partial u}{\partial x}=0 \\ x=1, \quad u=0 \end{array} \right]$$

$$u = X(x)T(t)$$

$$\frac{1}{T} \frac{dT}{dt} = \frac{1}{X} \frac{d^2X}{dx^2} = -\alpha_n^2$$

$$\frac{d^2X}{dx^2} + \alpha_n^2 X = 0$$

$$\left. \begin{array}{l} \text{at } x=0 \Rightarrow \frac{dX}{dx} = 0 \\ = L \Rightarrow X=0 \end{array} \right\} \begin{array}{l} \alpha_n = (2n-1)\pi/2 \\ X_n = C_1 \cos(\alpha_n x) \end{array}$$

$$\Rightarrow \frac{1}{T_n} \frac{dT_n}{dt} = -\alpha_n^2$$

$$T_n = C_2 \exp(-\alpha_n^2 t)$$

$$\begin{aligned} u_n &= X_n T_n \\ &= C_n \exp(-\alpha_n^2 t) \end{aligned}$$

$$u = \sum_{n=1}^{\infty} u_n = \sum C_n \exp(-\alpha_n^2 t) \cos(\alpha_n x)$$

$$\cdot \cos(\alpha_n x)$$

$$u_0 = \sum C_n \cos(\alpha_n x)$$

multiply both sides by $\cos(\alpha_m x) dx$ & integrate over x

$$\int_{m \rightarrow n}^{m \rightarrow 1} u_0 \cos(\alpha_m x) dx = \sum_{n=1}^{\infty} \int_0^1 C_n \cos(\alpha_n x) \cos(\alpha_m x) dx$$

$$= C_n \underbrace{\int_0^1 \cos^2(\alpha_n x) dx}_{1/2}$$

$$u_0 \int_0^1 \cos(\alpha_n x) dx = \frac{C_n}{2}$$

$$u(x,t) = \alpha u_0 \sum_{n=1}^{\infty} \frac{\sin \alpha_n t}{\alpha_n} \exp(-\alpha_n^2 t) \cos(\alpha_n x)$$

$$\alpha_n = (2n-1)\pi/2$$

$n=1, 2, 3, \dots \infty$

* $\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}$, at $t=0$, $u=u_0$
 $x=0, u=0$
 $x=1, \frac{\partial u}{\partial x} + \beta u = 0$.

$$u = X(x)T(t); \quad \frac{1}{T} \frac{dT}{dt} = \frac{1}{X} \frac{d^2X}{dx^2} = -\alpha^2$$

$$\frac{d^2X}{dx^2} + \alpha^2 X = 0$$

$$\text{at } x=0, X=0$$

$$x=1, \frac{dX}{dx} + \beta X = 0$$

$$X_n = C_n \sin(\alpha_n x) \Rightarrow \alpha_n + \beta \tan \alpha_n = 0$$

↳ Eigen values are roots of this eqn.

$$T_n = C_n \exp(-\alpha_n^2 t); \quad u_n = T_n X_n \\ = C_n \exp(-\alpha_n^2 t) \sin(\alpha_n x)$$

$$u_0 \int_0^1 \sin(\alpha_n x) dx = C_n \int_0^1 \sin^2(\alpha_n x) dx$$

$$u(x,t) = \sum_{n=1}^{\infty} C_n \exp(-\alpha_n^2 t) \sin(\alpha_n x)$$

$$u_0 \left(\frac{1 - \cos \alpha_n}{\alpha_n} \right) = \frac{C_n}{2} \int_0^1 2 \sin^2(\alpha_n x) dx \\ \approx \frac{C_n}{2} \int_0^1 [1 - \cos(2\alpha_n x)] dx$$

$$u_0 = \sum_{n=1}^{\infty} C_n \sin(\alpha_n x)$$

$$= \frac{C_n}{2} \left[1 - \int_0^1 \cos(2\alpha_n x) dx \right] \\ = \frac{C_n}{2} \left[1 - \left\{ \frac{\sin(2\alpha_n x)}{2\alpha_n} \right\}_0^1 \right] \Rightarrow \frac{C_n}{2} \left[1 - \left\{ \frac{\sin(2\alpha_n)}{2\alpha_n} \right\} \right]$$

$$u_0 \left(\frac{1 - \cos \alpha_n}{\alpha_n} \right) = \frac{C_n}{2} \left[1 - \frac{2 - \tan \alpha_n}{1 + \tan^2 \alpha_n} \left(\frac{1}{2\alpha_n} \right) \right]$$

REDMI NOTE 5 PRO
MI DUAL CAMERA

$$= \frac{C_n}{2} \left[1 - \frac{4 \tan \alpha_n}{\alpha_n (1 + \tan^2 \alpha_n)} \right] = \frac{C_n}{2} \left[1 - \frac{1}{\alpha_n} \left(\frac{-\alpha_n \beta}{1 + \alpha_n^2 \beta^2} \right) \right]$$

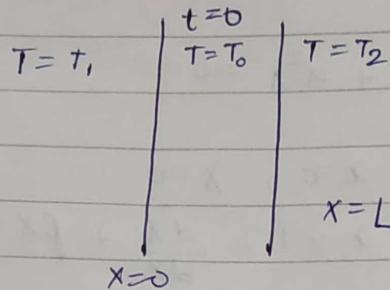


$$\frac{C_n}{2} \left[1 + \frac{1}{\beta} \frac{\beta^2 + \alpha_n^2}{\beta^2 + \alpha_n^2} \right] = \frac{C_n}{2} \left[\frac{\beta^2 + \alpha_n^2}{\beta^2 + \alpha_n^2} \right]$$

$$C_n = 24_0 \left(\frac{1 - \cos \alpha_n}{\alpha_n} \right) \frac{\beta^2 + \alpha_n^2}{\beta^2 + \beta + \alpha_n^2}$$

$$\Rightarrow u(x, t) = 24_0 \sum_{n=1}^{\infty} \left(\frac{1 - \cos \alpha_n}{\alpha_n} \right) \left(\frac{\beta^2 + \alpha_n^2}{\beta^2 + \beta + \alpha_n^2} \right) \sin(\alpha_n n) \exp(-\alpha_n^2 t)$$

\Rightarrow 2D heat Conduction problem.



$$\text{Biot no. } (Bi) = \frac{hL}{K} < 0.1$$

If K is high ~~low~~ $eg\ K$ would be ODE.

K = Thermal conductivity.

$$\Rightarrow \rho C_p \frac{\partial T}{\partial t} = k \frac{\partial^2 T}{\partial x^2}$$

at $t=0, T=T_0$

$x=0, T=T_1$

$x=L, T=T_2 \Rightarrow$

$$\Theta = \frac{T - T_1}{T_1}; \quad x^* = \frac{x}{L}$$

idea is
for BC should
be handle.

$$\rho C_p \frac{\partial \Theta}{\partial t} = \frac{k}{L^2} \frac{\partial^2 \Theta}{\partial x^2}$$

$$\Rightarrow \frac{L^2 (\rho C_p)}{k} \frac{\partial \Theta}{\partial t} = \frac{\partial^2 \Theta}{\partial (x^*)^2} \Rightarrow \frac{L^2}{x^*} \frac{\partial \Theta}{\partial t} = \frac{\partial^2 \Theta}{\partial x^*^2}$$

Thermal diffusivity.

$$\frac{t \alpha}{L^2} = \tau$$

Dimensionless
no.

$$\frac{\partial \Theta}{\partial \tau} = \frac{\partial^2 \Theta}{\partial x^*^2}$$

$$\text{at } \tau=0, \Theta = \frac{T_0 - T_1}{T_1} = \Theta_0$$

$$\text{at } x^*=0, \Theta = 0$$

$$x^*=1, \Theta = \frac{T_2 - T_1}{T_1} = \Theta_1$$

ILL POSED
PROBLEM.

$$\Theta_1 = 2\Theta_0$$

$$\Theta_1: \frac{\partial \Theta_1}{\partial \tau} = \frac{\partial^2 \Theta_1}{\partial x^*^2}$$

$$\Theta = \Theta_1 + \Theta_2$$

$$\text{at } \tau=0, \Theta_1 = \Theta_0, \Theta_2 = 0$$

REDMI NOTE 5 PRO
MI DUAL CAMERA

$$x^*=1, \Theta_1 = 0$$

$$\Theta_2: \frac{\partial \Theta_2}{\partial \tau} = \frac{\partial^2 \Theta_2}{\partial x^*^2}$$

$$\theta_2 = \theta_2^S(x^*) + \theta_2^T(x^*, t) ; \quad \theta_2^S : \frac{\partial^2 \theta_2^S}{\partial x^{*2}} = 0$$

Page: / Date: /

$\theta_2^T : \frac{\partial \theta_2^T}{\partial t} - \frac{\partial^2 \theta_2^T}{\partial x^{*2}} = -\theta_{10} x^*$

at $x^* = 0, \theta_2^S = 0$ at $t = 0, \theta_2^T = \theta_{10} x^*$

$x^* = 1, \theta_2^S = \theta_{10}$ at $x^* = 0 \Rightarrow \theta_2^T = 0$

$\theta_2^S = C_1 x^*$
 $\theta_{10} = C_1$
 $\boxed{\theta_2^S = \theta_{10} x^*}$

$\theta_2^T(x^*, t) = \sum C_n \exp(-n^2 \pi^2 t) \sin(n \pi x^*)$

$$C_n = -2 \theta_{10} \int_0^1 x^* \sin(n \pi x^*) dx$$

$$C_n = -2 \theta_{10} \int_0^1 x^* \sin(n \pi x^*) dx$$

$$\theta_2(x^*, t) = \theta_{10} x^* + \sum_{n=1}^{\infty} C_n \exp(-n^2 \pi^2 t) \sin(n \pi x^*)$$

$$\boxed{\theta = \theta_1 + \theta_2} \\ (x^*, t)$$

01/09/2021
 Tomorrow: 9:00 clock.
 class test - I
 syllabus TPell today
 1 hr



REDMI NOTE 5 PRO
MI DUAL CAMERA