view_frames Result Recorded at time: 1759045402.6775706 map Broadcaster: default authority Average rate: $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 odom Broadcaster: default authority Average rate: $5\overline{0.207}$ Buffer length: 4.82 Most recent transform: 14.62 Oldest transform: 9.8 base_link Broadcaster: default authority Average rate: $10\overline{0}00.0$ Average rate: 20.208 Average rate: 20.208 Average rate: 20.208 Average rate: 20.208 Buffer length: 4.8 Buffer length: 4.8 Buffer length: 4.8 Buffer length: 0.0 Buffer length: 4.8 Most recent transform: 0.0 Most recent transform: 14.6 Most recent transform: 14.6 Most recent transform: 14.6 Most recent transform: 14.6 Oldest transform: 0.0 Oldest transform: 9.8 Oldest transform: 9.8 Oldest transform: 9.8 Oldest transform: 9.8 $front_right_wheel$ lidar link front left wheel rear left wheel rear right wheel