

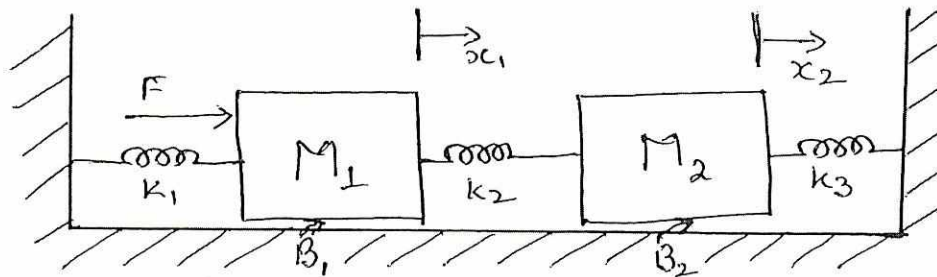
May 2018: END SEMESTER ASSESSMENT B.Tech. ECE VI Semester
ESA
UE15EC335 - CONTROL SYSTEMS

Time: 3 hours

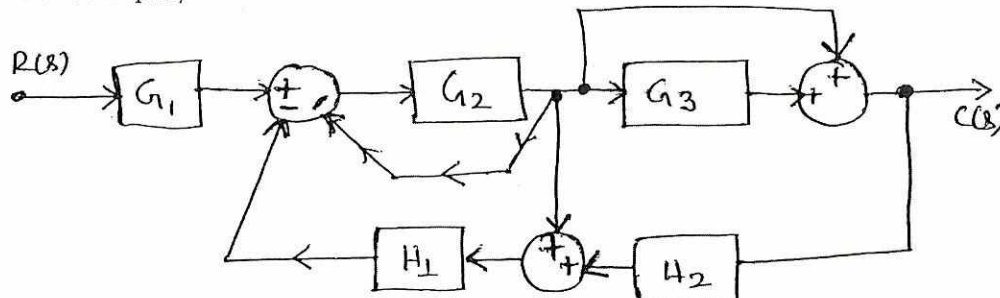
Answer All Questions

Max Marks: 100

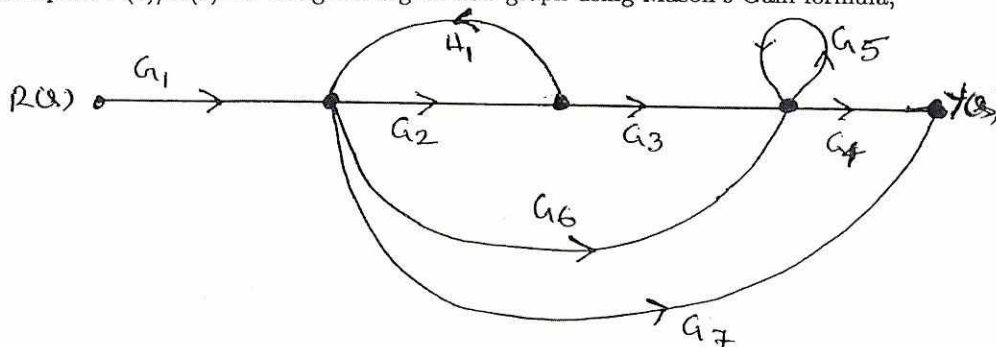
For the given physical system, draw the equivalent mechanical network. Derive the governing differential equations and express them in s -domain using Laplace Transforms assuming zero initial conditions. Draw the equivalent Force - Current and Force - Voltage Analogous circuits;

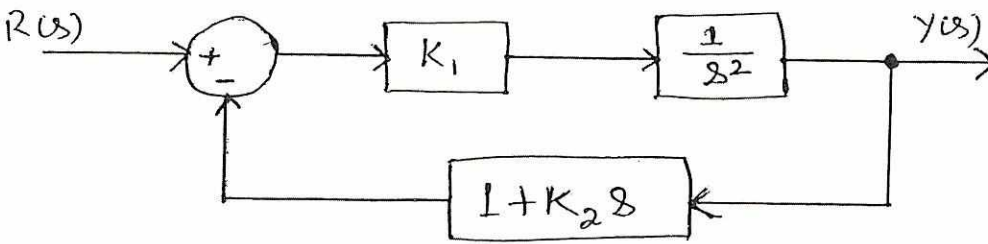
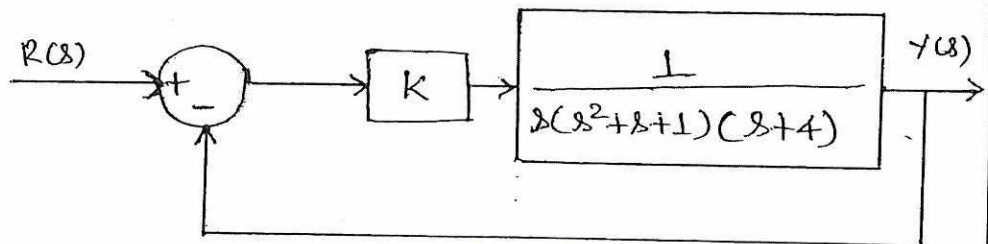


Evaluate $C(s)/R(s)$ for the given Block diagram architecture using Block Diagram Reduction Techniques;



Compute $Y(s)/R(s)$ for the given Signal-flow graph using Mason's Gain formula;



2	a	<p>Consider the control system shown below. Evaluate K_1 and K_2 such that the peak overshoot (M_p) is 25 % and peak time (t_p) is 4 Seconds;</p> 	5m
	b	<p>The open-loop transfer function for a system is given as;</p> $G(s)H(s) = \frac{K}{s^2(s+2)(s+3)}$ <p>It is desired to have a steady-state error of 10 for an input given by $1 + 10t + \frac{40}{2}t^2$. Evaluate the value of K to achieve this steady-state error.</p>	5m
	c	<p>Consider the control system given below. Applying Routh - Hurwitz Criterion, evaluate the value / range of K for which the closed-loop system is (i) Unstable, (ii) Marginally stable and (iii) Absolutely stable. Also compute the frequency of sustained oscillations when the system is marginally stable.</p> 	10m
3	a	<p>Sketch the Root Locus for a system whose open-loop transfer function is given by;</p> $G(s)H(s) = \frac{K}{s(s+3)(s^2+3s+3)}$ <p>Calculate the value / range of K for which the closed-loop system is (i) Unstable, (ii) Marginally stable and the frequency of sustained oscillations and (iii) Absolutely stable.</p>	10m
	b	<p>A unity-feedback system has the following open-loop transfer function;</p> $G(s)H(s) = \frac{242(s+5)}{s(s+1)(s^2+5s+121)}$ <p>Sketch the approximate Bode Magnitude and Phase plots. From the plots, evaluate ω_{gcf}, ω_{pcf}, Gain Margin and Phase Margin. Comment on the closed-loop stability.</p>	10m
4	a	<p>A feedback control system has the following open-loop transfer function;</p> $G(s)H(s) = \frac{40}{(s+4)(s^2+2s+2)}$ <p>Obtain the Nyquist Plot; comment on the closed-loop stability while applying Nyquist Stability Criterion. Also evaluate the Gain Margin.</p>	10m