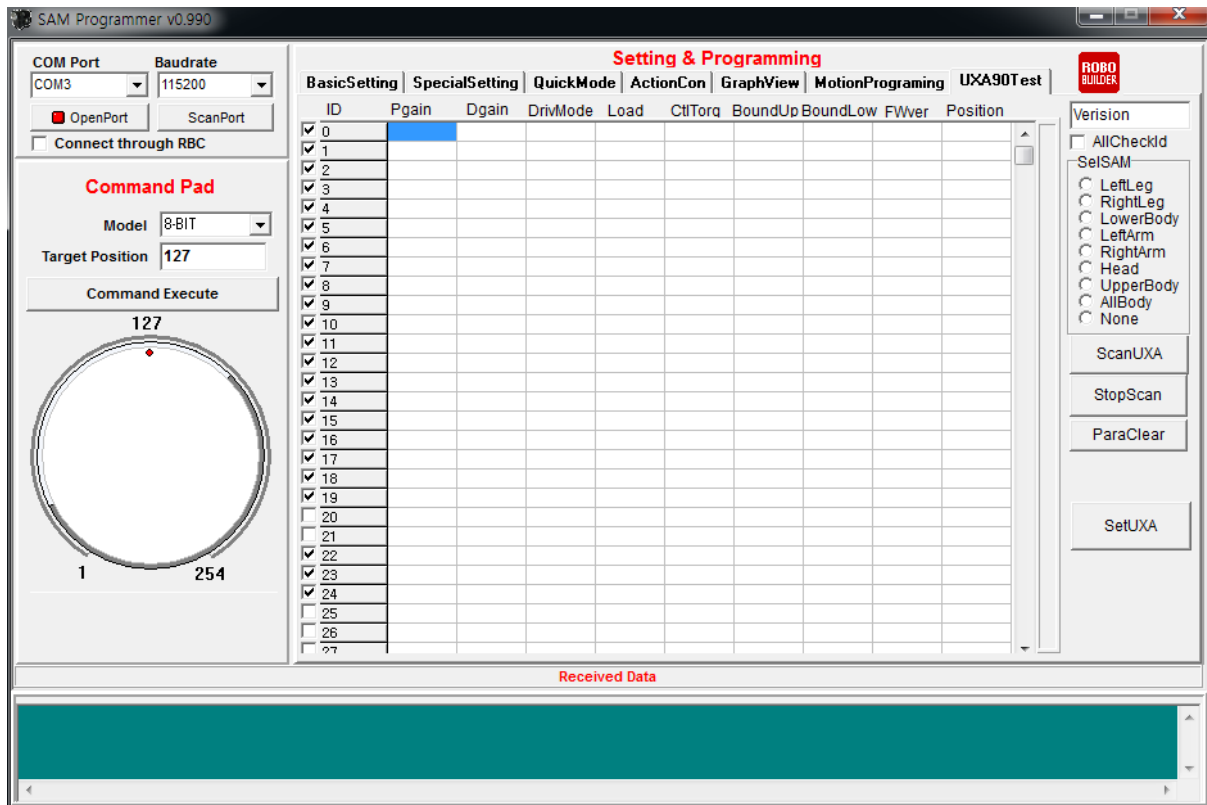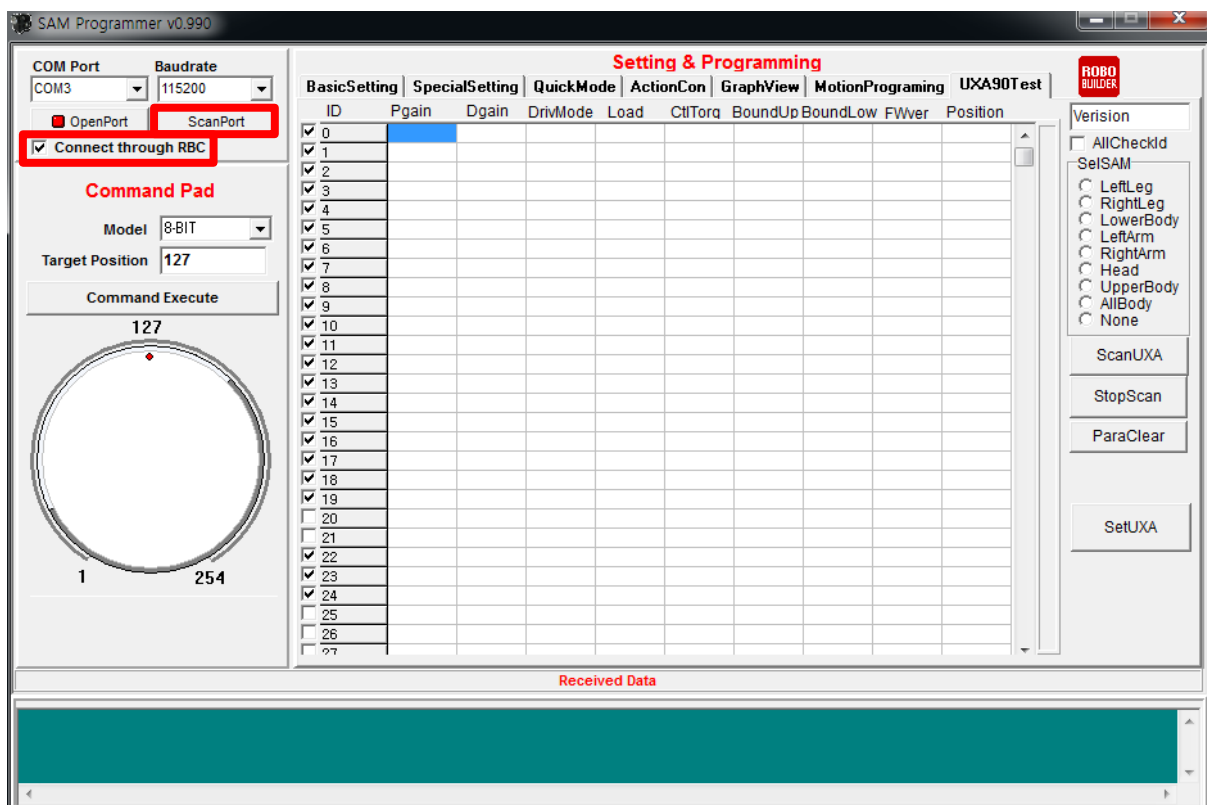# ●SAM Programmer v0.990●

Preparation : ①UXA-90 and PC are connected by an USB cable. ②UXA-90 is in sitting position while power is on.
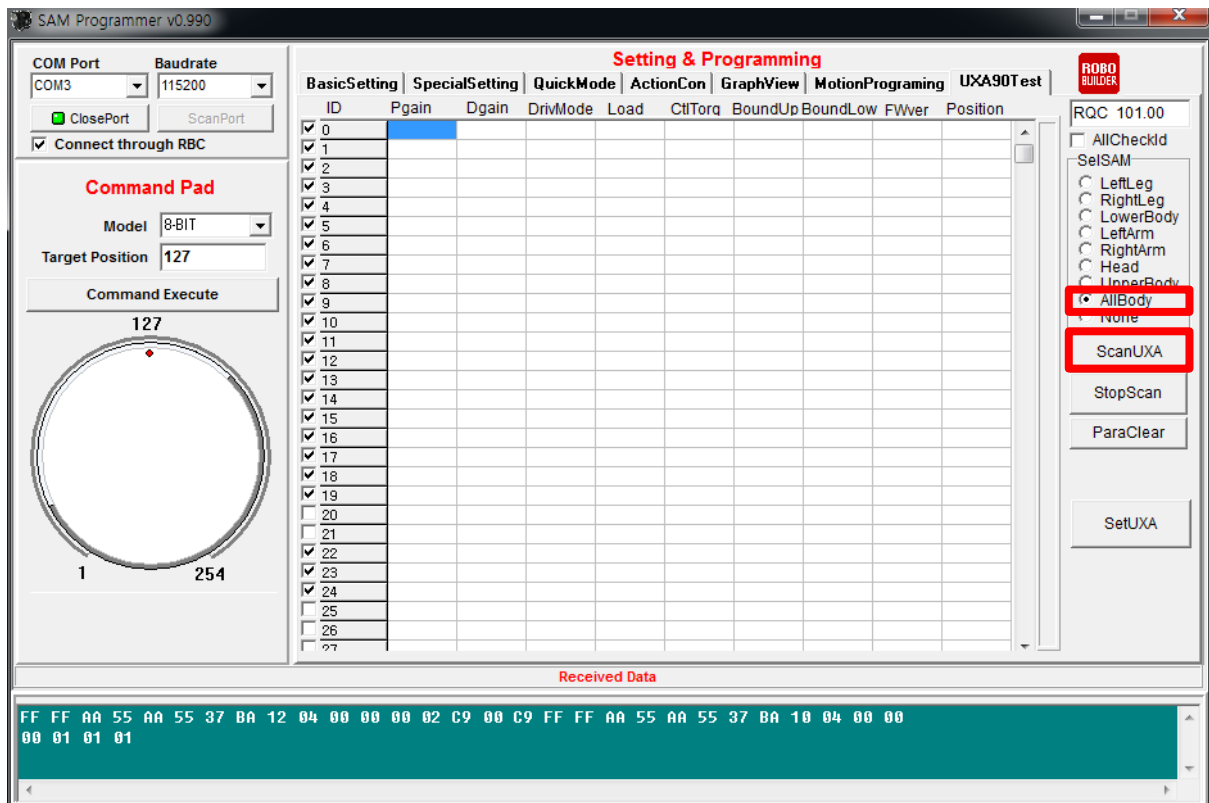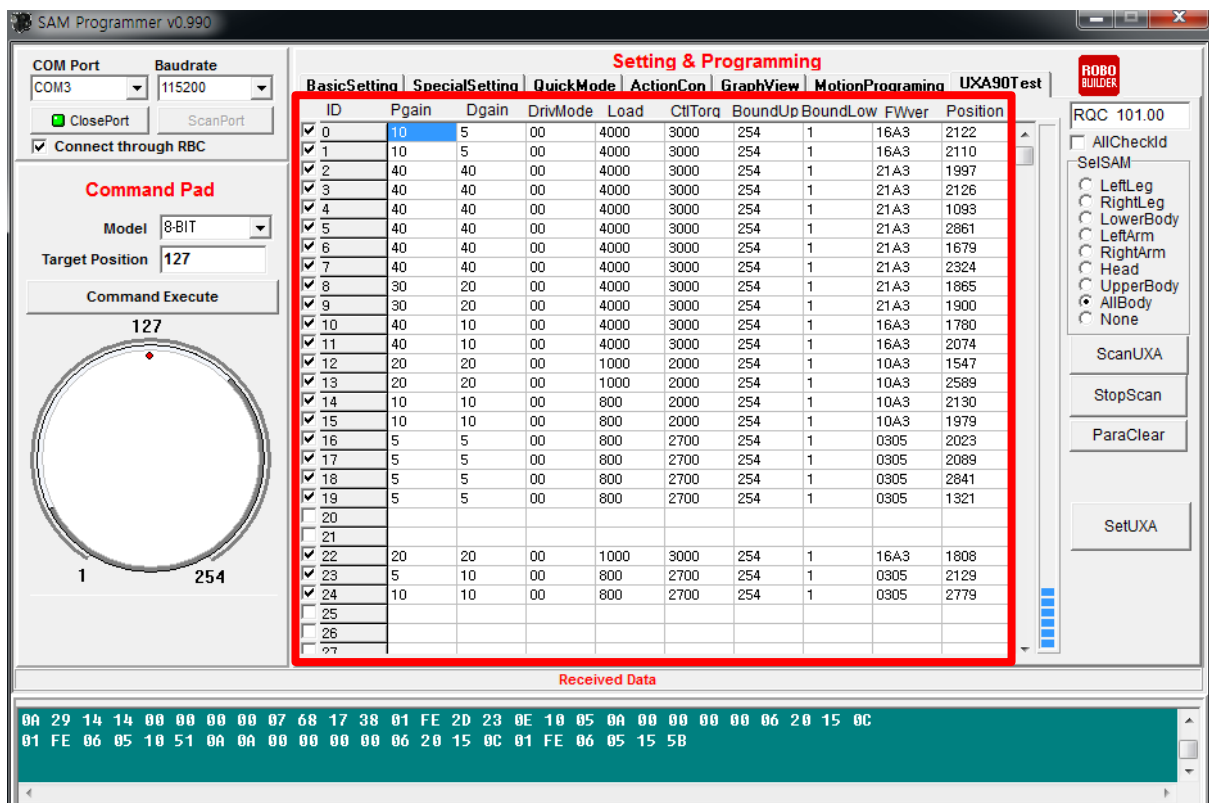
1. Run "SAM Programmer v0.990".

2. Check "Connect through RBC" and click "Scan Port" to connect with the robot.

3. "Closeport" will appear once the connection is successfully done. Check "AllBody" and click "Scan UXA" to scan all of UXA-90's servo motors.

4. You can scan all of the servo motors' data if UXA-90 is in a normal condition. **(Please follow this process and send us a captured image of the scanned data as below).**

5. But if UXA-90 is not in a normal condition, you will see pop-up message "Try Again", then if you press "OK", the scan will go on and will find servo motors that do not function.