## Class Exercise (Kalman Filter) Introduction to Data Assimilation

## Exercise 8b (KF with a Linear Advection Equation )

Consider a one-dimensional linear advection model on a periodic domain of length 360 m ( $L_a = -180 \le x_{axis} < L_b = 180$ ). The model has a constant advection speed,  $\mu$ =1 m/s, the grid spacing is  $\Delta x$  = 1 m and the time step  $\Delta t$  = 1 s.

The true initial state  $\mathbf{x_0^t}$  is sampled from a normal distribution with mean equal to a square wave (use sqrwv.m in D2L), variance equal to zero and spatial de-correlation length of 45 m. Yes, we assume here that the true state,  $\mathbf{x^t}$  is without system noise.

The initial forecast states  $\mathbf{x}_0^f$ , however are generated by drawing a sample from a normal distribution with mean  $\mathbf{x}_0^t$ , variance equal to 0.5 and spatial de-correlation length of 45 m similar to the length scale of  $\mathbf{x}_0^t$ .

- 1) Construct  $\mathbf{x}_0^t$ ,  $\mathbf{x}_0^f$  and  $\mathbf{P}_0^f = \mathbf{Q}$ . Use gcorr.m (and gauss.m) can be found in D2L -- to generate the correlation matrix,  $\boldsymbol{\rho}$ . Also use mvnrnd.m to draw the sample.
- 2) Construct a time-independent state transition matrix **M** using Lax-Wendorff scheme to solve the advection equation:

$$\begin{split} \frac{\partial a}{\partial t} &= -\mu \frac{\partial a}{\partial x} \\ a_i^{k+1} &= a_i^k - \frac{\mu \Delta t}{2\Delta x} \left( a_{i+1}^k - a_{i-1}^k \right) + 2 \left( \frac{\mu \Delta t}{2\Delta x} \right)^2 \left( a_{i+1}^k + a_{i-1}^k - 2a_i^k \right) \end{split}$$

where *k* and *i* denote time and position, respectively.

- 3) Construct the observation operator assuming that there are a) zero measurements, b) 1 measurement at grid point 10 and c) 4 measurements at grid points 10, 100, 190 and 280. Assume a measurement error variance of 0.01 (and a diagonal error covariance, **R**).
- 4) Find an optimal estimate  $\mathbf{x}_{k=1,300}^a$  using a Kalman Filter and using measurements in (3) and assuming for now that  $\mathbf{Q} = \mathbf{0}$ . Plot your results (truth, forecast, analysis and observation/s) for all grid points and for iteration 5, iteration 150, and iteration 300. Provide comments on your results.
- 5) Do (4) but now assume  $\mathbf{Q} = \sigma^2 \boldsymbol{\rho}$ .

Note: This is a continuation of Exercise 8a (fonts in red are the new tasks).