≡   **SVL**
SIMULATOR

Ⓙ John ▾

Test Results › API

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Simulation Details   ▼

Iterations | 1 | 1 | 0 |

1

Status:

Failed

Cause:

EgoCollision

Start time:

22/07/2021, 13:20:29

Real time duration:

00 : 01 : 16.000

Simulation time duration:

00 : 00 : 15.350

Lincoln2017MKZ

Bridge type:

CyberRT

Connection:

Analysis   Visualization

N/A

Sensors

IMU   [Simulator.Sensors.ImuSensor]

minX:

  0 km

maxX:

  668.809 km

minGyroX:

  -0.001 °

maxGyroX:

  0.002 °

minY:

  0 km

maxY:

  108.949 km

minGyroY:

  -0.001 °

maxGyroY:

  0.002 °

minZ:

  0 km

maxZ:

  10.64 km

minGyroZ:

  -0.707 °

maxGyroZ:

  0.707 °

Signal Sensor   [Simulator.Sensors.SignalSensor]

SignalsDetected:

0 counts

DetectedStates:

green misc

CAN Bus   [Simulator.Sensors.CanBusSensor]

GearUsed:

1

MaxSpeed:

7.55 m/s

MaxThrottle:

0 (user input)

MaxBrake:

0 (user input)

MaxSteering:

0 °

Wheel Car Control   [Simulator.Sensors.WheelControlSensor]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

MaxBrake:

0 (user input)

GPS   [Simulator.Sensors.GpsSensor]

Start Latitude:

37.788 °

Start Longitude:

-122.4 °

Start Altitude:

0.352 m

Start Northing:

Start Northing:

4,182,486.02 m East

Start Easting:

552,872.635 m North

Start Map Url:

open Google Maps

Latitude:

37.789 °

Longitude:

-122.392 °

Altitude:

10.557 m

Northing:

4,182,564.427 m East

Easting:

553,542.793 m North

Map Url:

open Google Maps

GPS INS Status   [Simulator.Sensors.GpsInsSensor]

Status:

3 misc

Position Type:

56 misc

Clock Sensor   [Simulator.Sensors.ClockSensor]

SimulationDuration:

15.35 seconds

RealtimeDuration:

15.388 seconds

Keyboard Car Control   [Simulator.Sensors.KeyboardControlSensor]

MaxSteer:

   0 (user input)

MaxAccel:

   0 (user input)

MaxBrake:

   0 (user input)

3D Ground Truth   [Simulator.Sensors.PerceptionSensor3D]

MaxTracked:

   2 counts

Apollo Car Control   [Simulator.Sensors.ApolloControlSensor]

MaxSteer:

   0.085 (user input)

MaxAccel:

   0.983 (user input)

MaxBrake:

   0 (user input)

IsControlReceived:

   true misc

GPS Odometry   [Simulator.Sensors.GpsOdometrySensor]

Start Latitude:

   37.788 °

Start Longitude:

   -122.4 °

Start Altitude:

   0.352 m

Start Northing:

   4,182,486.02 m East