

Sensors IMU minX: -125.222 km 0 km -0.003 ° maxGyroX: 0.001° 0 km maxY: 166.349 km minGyroY: -0.001 ° 0.001° minZ: 0 km maxZ: 10.583 km -0.736° maxGyroZ: 0° **Signal Sensor** SignalsDetected: 0 counts DetectedStates:

red,green,yellow misc **CAN Bus** GearUsed: MaxSpeed: 7.451 m/s MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxSteering: 0° **Wheel Car Control** MaxSteer: 0 (user input) MaxAccel: 0 (user input) MaxBrake: 0 (user input) **GPS** Start Latitude: 37.788° Start Longitude: -122.4° Start Altitude: 0.352 m Start Northing:

4,182,480.UZ III EdSl Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: 37.789° Longitude: -122.401° Altitude: 10.556 m Northing: 4,182,520.864 m East Easting: 552,748.762 m North Map Url: open Google Maps **GPS INS Status** Status: 3 misc Position Type: 56 misc **Clock Sensor** SimulationDuration: 70 seconds RealtimeDuration: 70.167 seconds **Keyboard Car Control**

MaxSteer: 0 (user input) MaxAccel: 0 (user input) MaxBrake: 0 (user input) **3D Ground Truth** MaxTracked: 22 counts **Apollo Car Control** MaxSteer: 0.029 (user input) MaxAccel: 0.974 (user input) MaxBrake: 0 (user input) IsControlReceived: true misc **GPS Odometry** Start Latitude: 37.788° Start Longitude: -122.4° Start Altitude: 0.352 m Start Northing: 4,182,486.02 m East Start Easting:

552,872.635 m North

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Callbacks