

SVL

SIMULATOR

J

John

Test Results > API

Sharing

Delete

Simulation Details

Iterations

1

1

0

1

Status:

Failed

Cause:

EgoCollision, Stuck

Start time:

21/07/2021, 18:39:58

Real time duration:

00 : 02 : 30.000

Simulation time duration:

00 : 00 : 17.750

Lincoln2017MKZ

Bridge type:

CyberRT

Connection:

Analysis

Visualization

N/A

Sensors

IMU

[Simulator.Sensors.ImuSensor]

minX:
0 km

maxX:
670.873 km

minGyroX:
-0.001 °

maxGyroX:
0 °

minY:
0 km

maxY:
68.949 km

minGyroY:
-0.001 °

maxGyroY:
0 °

minZ:
0 km

maxZ:
10.64 km

minGyroZ:
-0.707 °

maxGyroZ:
0.707 °

Signal Sensor

[Simulator.Sensors.SignalSensor]

SignalsDetected:

0 counts

DetectedStates:

green misc

CAN Bus

[Simulator.Sensors.CanBusSensor]

GearUsed:

1

MaxSpeed:

9.989 m/s

MaxThrottle:

0 (user input)

MaxBrake:

0 (user input)

MaxSteering:

0 °

Wheel Car Control

[Simulator.Sensors.WheelControlSensor]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

MaxBrake:

0 (user input)

GPS

[Simulator.Sensors.GpsSensor]

Start Latitude:

37.788 °

Start Longitude:

-122.4 °

Start Altitude:

0.352 m

Start Northing:

Start Northing:

4,182,486.02 m East

Start Easting:

552,872.635 m North

Start Map Url:

open Google Maps

Latitude:

37.788 °

Longitude:

-122.392 °

Altitude:

10.555 m

Northing:

4,182,498.523 m East

Easting:

553,544.857 m North

Map Url:

open Google Maps

GPS INS Status

[**Simulator.Sensors.GpsInsSensor**]

Status:

3 misc

Position Type:

56 misc

Clock Sensor

[**Simulator.Sensors.ClockSensor**]

SimulationDuration:

17.75 seconds

RealtimeDuration:

17.807 seconds

Keyboard Car Control

[**Simulator.Sensors.KeyboardControlSensor**]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

MaxBrake:

0 (user input)

3D Ground Truth

[`Simulator.Sensors.PerceptionSensor3D`]

MaxTracked:

12 counts

Apollo Car Control

[`Simulator.Sensors.ApolloControlSensor`]

MaxSteer:

0.073 (user input)

MaxAccel:

0.991 (user input)

MaxBrake:

0 (user input)

IsControlReceived:

true misc

GPS Odometry

[`Simulator.Sensors.GpsOdometrySensor`]

Start Latitude:

37.788 °

Start Longitude:

-122.4 °

Start Altitude:

0.352 m

Start Northing:

4,182,486.02 m East