☰   **SVL** SIMULATOR   Ⓙ John ▾

Test Results › API

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Simulation Details   ▾

Iterations | 1 | 1 | 0 |

| 1 |

Status:

Failed

Cause:

EgoCollision

Start time:

21/07/2021, 17:59:42

Real time duration:

00 : 00 : 25.000

Simulation time duration:

00 : 00 : 18.700

Lincoln2017MKZ

Bridge type:

CyberRT

Connection:

[Analysis] [Visualization]

N/A

Sensors

IMU [Simulator.Sensors.ImuSensor]

minX:

-120.358 km

maxX:

0 km

minGyroX:

-0.003 °

maxGyroX:

0.001 °

minY:

0 km

maxY:

166.349 km

minGyroY:

-0.002 °

maxGyroY:

0.001 °

minZ:

0 km

maxZ:

10.582 km

minGyroZ:

-0.716 °

maxGyroZ:

0 °

Signal Sensor [Simulator.Sensors.SignalSensor]

SignalsDetected:

0 counts

DetectedStates:

misc

CAN Bus   [Simulator.Sensors.CanBusSensor]

GearUsed:

1

MaxSpeed:

5.989 m/s

MaxThrottle:

0 (user input)

MaxBrake:

0 (user input)

MaxSteering:

0 °

Wheel Car Control   [Simulator.Sensors.WheelControlSensor]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

MaxBrake:

0 (user input)

GPS   [Simulator.Sensors.GpsSensor]

Start Latitude:

37.788 °

Start Longitude:

-122.4 °

Start Altitude:

0.352 m

Start Northing:

Start Northing:

  4,182,486.02 m East

Start Easting:

  552,872.635 m North

Start Map Url:

  open Google Maps

Latitude:

  37.789 °

Longitude:

  -122.401 °

Altitude:

  10.559 m

Northing:

  4,182,622.535 m East

Easting:

  552,753.626 m North

Map Url:

  open Google Maps

GPS INS Status   [Simulator.Sensors.GpsInsSensor]

Status:

  3 misc

Position Type:

  56 misc

Clock Sensor   [Simulator.Sensors.ClockSensor]

SimulationDuration:

  18.7 seconds

RealtimeDuration:

  18.874 seconds

Keyboard Car Control   [Simulator.Sensors.KeyboardControlSensor]

MaxSteer:

   0 (user input)

MaxAccel:

   0 (user input)

MaxBrake:

   0 (user input)

3D Ground Truth   [Simulator.Sensors.PerceptionSensor3D]

MaxTracked:

   22 counts

Apollo Car Control   [Simulator.Sensors.ApolloControlSensor]

MaxSteer:

   0.032 (user input)

MaxAccel:

   0.979 (user input)

MaxBrake:

   0 (user input)

IsControlReceived:

   true misc

GPS Odometry   [Simulator.Sensors.GpsOdometrySensor]

Start Latitude:

   37.788 °

Start Longitude:

   -122.4 °

Start Altitude:

   0.352 m

Start Northing:

   4,182,486.02 m East