

SVL
SIMULATOR

J

John

Test Results > API

Sharing

Delete

Simulation Details

Iterations

1

1

0

1

Status:

Failed

Cause:

EgoCollision, Stuck

Start time:

21/07/2021, 18:37:26

Real time duration:

00 : 00 : 56.000

Simulation time duration:

00 : 00 : 33.990

Lincoln2017MKZ

Bridge type:

CyberRT

Connection:

Analysis

Visualization

https://wise.svlsimulator.com/test-results/ed8bee4f-0222-47d9-8429-c1c079571814

1/5

N/A

Sensors

IMU

[Simulator.Sensors.ImuSensor]

minX:

0 km

maxX:

615.749 km

minGyroX:

-0.002 °

maxGyroX:

0.001 °

minY:

0 km

maxY:

197.965 km

minGyroY:

-0.003 °

maxGyroY:

0 °

minZ:

0 km

maxZ:

10.64 km

minGyroZ:

-1 °

maxGyroZ:

0 °

Signal Sensor

[Simulator.Sensors.SignalSensor]

SignalsDetected:

0 counts

DetectedStates:

red,green misc

CAN Bus

[Simulator.Sensors.CanBusSensor]

GearUsed:

1

MaxSpeed:

5.279 m/s

MaxThrottle:

0 (user input)

MaxBrake:

0 (user input)

MaxSteering:

0 °

Wheel Car Control

[Simulator.Sensors.WheelControlSensor]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

MaxBrake:

0 (user input)

GPS

[Simulator.Sensors.GpsSensor]

Start Latitude:

37.788 °

Start Longitude:

-122.4 °

Start Altitude:

0.352 m

Start Northing:

Start Northing:

4,182,486.02 m East

Start Easting:

552,872.635 m North

Start Map Url:

open Google Maps

Latitude:

37.79 °

Longitude:

-122.393 °

Altitude:

10.554 m

Northing:

4,182,667.871 m East

Easting:

553,438.981 m North

Map Url:

open Google Maps

GPS INS Status

[**Simulator.Sensors.GpsInsSensor**]

Status:

3 misc

Position Type:

56 misc

Clock Sensor

[**Simulator.Sensors.ClockSensor**]

SimulationDuration:

33.99 seconds

RealtimeDuration:

34.024 seconds

Keyboard Car Control

[**Simulator.Sensors.KeyboardControlSensor**]

MaxSteer:

0 (user input)

MaxAccel:

0 (user input)

MaxBrake:

0 (user input)

3D Ground Truth

[`Simulator.Sensors.PerceptionSensor3D`]

MaxTracked:

3 counts

Apollo Car Control

[`Simulator.Sensors.ApolloControlSensor`]

MaxSteer:

0.285 (user input)

MaxAccel:

0.992 (user input)

MaxBrake:

0 (user input)

IsControlReceived:

true misc

GPS Odometry

[`Simulator.Sensors.GpsOdometrySensor`]

Start Latitude:

37.788 °

Start Longitude:

-122.4 °

Start Altitude:

0.352 m

Start Northing:

4,182,486.02 m East