

Sensors IMU minX: 0 km maxX: 702.336 km -0.002 ° maxGyroX: 0.002° -0.034 km maxY: 68.949 km minGyroY: -0.002 ° 0.001° minZ: 0 km maxZ: 10.64 km -0.711 ° maxGyroZ: 0.707° **Signal Sensor** SignalsDetected: 0 counts DetectedStates:

green misc **CAN Bus** GearUsed: MaxSpeed: 7.122 m/s MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxSteering: 0° **Wheel Car Control** MaxSteer: 0 (user input) MaxAccel: 0 (user input) MaxBrake: 0 (user input) **GPS** Start Latitude: 37.788° Start Longitude: -122.4° Start Altitude: 0.352 m Start Northing:

4,182,486.UZ III EdSL Start Easting: 552,872.635 m North Start Map Url: open Google Maps Latitude: 37.788° Longitude: -122.392° Altitude: 10.556 m Northing: 4,182,486.086 m East Easting: 553,576.32 m North Map Url: open Google Maps **GPS INS Status** Status: 3 misc Position Type: 56 misc **Clock Sensor** SimulationDuration: 68 seconds RealtimeDuration: 68.077 seconds **Keyboard Car Control**

MaxSteer: 0 (user input) MaxAccel: 0 (user input) MaxBrake: 0 (user input) **3D Ground Truth** MaxTracked: 19 counts **Apollo Car Control** MaxSteer: 0.337 (user input) MaxAccel: 0.992 (user input) MaxBrake: 0 (user input) IsControlReceived: true misc **GPS Odometry** Start Latitude: 37.788° Start Longitude: -122.4° Start Altitude: 0.352 m Start Northing: 4,182,486.02 m East Start Easting:

552,872.635 m North

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Callbacks