

Sensors IMU minX: -44.301 km 0 km minGyroX: 0 ° maxGyroX: 0.008° -93.467 km maxY: 0 km minGyroY: -0 ° maxGyroY: 0.005° minZ: -3.341 km maxZ: 0 km -0.794° maxGyroZ: 0° **Signal Sensor** SignalsDetected: 0 counts DetectedStates:

misc **CAN Bus** GearUsed: MaxSpeed: 5.032 m/s MaxThrottle: 0 (user input) MaxBrake: 0 (user input) MaxSteering: 0° **Wheel Car Control** MaxSteer: 0 (user input) MaxAccel: 0 (user input) MaxBrake: 0 (user input) **GPS** Start Latitude: 37.417° Start Longitude: -122.016° Start Altitude: 0.352 m Start Northing:

4,141,5// III EaSt Start Easting: 587,068.651 m North Start Map Url: open Google Maps Latitude: 37.416° Longitude: -122.017° Altitude: -3.341 m Northing: 4,141,483.534 m East Easting: 587,025.7 m North Map Url: open Google Maps **GPS INS Status** Status: 3 misc Position Type: 56 misc **Clock Sensor** SimulationDuration: 62 seconds RealtimeDuration: 62.051 seconds **Keyboard Car Control**

MaxSteer: 0 (user input) MaxAccel: 0 (user input) MaxBrake: 0 (user input) **3D Ground Truth** MaxTracked: 2 counts **Apollo Car Control** MaxSteer: 0.013 (user input) MaxAccel: 1 (user input) MaxBrake: 0 (user input) IsControlReceived: true misc **GPS Odometry** Start Latitude: 37.417° Start Longitude: -122.016° Start Altitude: 0.352 m Start Northing: 4,141,577 m East

Start Easting:

587,068.651 m North

Start Map Url:

open Google Maps

Latitude:

37.416 °

Longitude:

-122.017°

Altitude:

-3.341 m

Northing:

4,141,483.534 m East

Easting:

587,025.7 m North

Map Url:

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Callbacks