

Golden Hyperbolic Swirl-Angle and Tangential Swirl Speed in Swirl-String Theory (SST)

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Abstract

This paper introduces a hyperbolic, kinematics-only construction used to define a distinguished “golden layer” for tangential swirl motion in Swirl-String Theory (SST). We adopt a hyperbolic definition of the golden ratio, $\phi := e^{\text{asinh}(1/2)}$, based on standard inverse-hyperbolic identities. [1] Defining the *golden hyperbolic swirl-angle* $\xi_g := \frac{3}{2} \text{asinh}(1/2)$, we prove the closed identity $\tanh(\xi_g) = e^{-\text{asinh}(1/2)} = \phi^{-1}$ using standard hyperbolic-function relations. [2] We then define a dimensionless tangential swirl fraction $\beta := \|\mathbf{v}\|/v_\circlearrowleft \in [0, 1]$, where $v_\circlearrowleft = \|\mathbf{v}_\circlearrowleft\|$ is the SST canonical reference swirl speed. [6] A *hyperbolic swirl-angle* ξ is introduced purely as a bijective re-parameterization of β via $\beta = \tanh \xi$. [2] At the golden layer $\xi = \xi_g$, the tangential fraction is fixed to $\beta_g = \phi^{-1}$, implying $\|\mathbf{v}\|_g = v_\circlearrowleft/\phi$ and $\Omega_g = v_\circlearrowleft/(\phi r_c)$. Numerical evaluation is given using the SST constants $v_\circlearrowleft = 1.093\,845\,63 \times 10^6 \text{ m s}^{-1}$ and $r_c = 1.408\,970\,17 \times 10^{-15} \text{ m}$. [6]

1 Introduction and motivation

Hyperbolic functions provide a natural coordinate system for any quantity constrained to the open interval $[0, 1)$, because $\tanh : \mathbb{R} \rightarrow (-1, 1)$ is smooth, monotone, and saturating. [2] In many areas of mathematical physics, a bounded “fraction” β is therefore re-parameterized by a hyperbolic angle ξ such that $\beta = \tanh \xi$; this is a coordinate choice, not a dynamical assumption. [2, 3]

In SST, a canonical tangential swirl-speed scale v_\circlearrowleft and a core length scale r_c are treated as fundamental constants in the theory’s kinematic and energetic bookkeeping. [6] When discussing tangential swirl fractions $\beta = \|\mathbf{v}\|/v_\circlearrowleft$, it is therefore useful to introduce a *hyperbolic swirl-angle* ξ as a compact, analytic parameterization of β .

This paper adds one further ingredient: a hyperbolic definition of the golden ratio and a corresponding *golden swirl-angle* ξ_g at which $\tanh \xi_g = \phi^{-1}$. Standard properties of ϕ are classical and widely documented; here we emphasize a hyperbolic-first presentation. [4, 5]

2 Definitions and notation

2.1 SST kinematic quantities

Let $\mathbf{v}_\circlearrowleft$ denote the SST canonical characteristic swirl velocity vector, and define the reference speed

$$v_\circlearrowleft \equiv \|\mathbf{v}_\circlearrowleft\|. \quad (1)$$

Let \mathbf{v} denote a local tangential swirl velocity (e.g. associated with a swirl-string segment). Define the dimensionless tangential fraction

$$\boxed{\beta \equiv \frac{\|\mathbf{v}\|}{v_\circ} \in [0, 1].} \quad (2)$$

The interval restriction $\beta < 1$ is definitional: v_\circ is used as the sector reference scale. [6]

2.2 Hyperbolic swirl-angle

We introduce a *hyperbolic swirl-angle* ξ by the bijection

$$\boxed{\beta = \tanh \xi, \quad \xi = \operatorname{artanh}(\beta).} \quad (3)$$

The functions \tanh and artanh and their standard identities are classical. [2]

Limit checks. From standard expansions, $\tanh \xi \sim \xi$ as $\xi \rightarrow 0$, so $\beta \approx \xi$ for small tangential fractions. [2] As $\beta \rightarrow 1^-$, one has $\xi = \operatorname{artanh}(\beta) \rightarrow +\infty$, consistent with the open interval $[0, 1)$. [2]

3 Hyperbolic definition of the golden ratio

We adopt a hyperbolic-first definition:

$$\boxed{\phi \equiv e^{\operatorname{asinh}(0.5)}, \quad \operatorname{asinh}(0.5) \equiv \operatorname{asinh}\left(\frac{1}{2}\right).} \quad (4)$$

The defining inverse-hyperbolic identity used here is standard: $\operatorname{asinh}(x) = \ln(x + \sqrt{x^2 + 1})$. [1]

Lemma 1 (Algebraic corollary). *The hyperbolic definition (4) implies the familiar algebraic relation*

$$\phi^2 = \phi + 1, \quad \text{hence} \quad \phi = \frac{1 + \sqrt{5}}{2}. \quad (5)$$

Proof. Let $t := e^{\operatorname{asinh}(0.5)} > 0$. Since $\operatorname{asinh}(0.5) = \operatorname{asinh}(1/2)$, we have $\sinh(\operatorname{asinh}(0.5)) = 1/2$. [1, 2] Using $\sinh(\operatorname{asinh}(0.5)) = \frac{t-t^{-1}}{2}$, [2] we obtain

$$\frac{t-t^{-1}}{2} = \frac{1}{2} \implies t - \frac{1}{t} = 1 \implies t^2 - t - 1 = 0 \implies t^2 = t + 1.$$

By definition $\phi = t$, so $\phi^2 = \phi + 1$. The quadratic solution gives $\phi = (1 + \sqrt{5})/2$ since $\phi > 0$. Classical properties of ϕ are standard. [4, 5] \square

4 Golden hyperbolic swirl-angle identity

Define the *golden hyperbolic swirl-angle*

$$\boxed{\xi_g \equiv \frac{3}{2} \operatorname{asinh}(0.5) = \frac{3}{2} \operatorname{asinh}\left(\frac{1}{2}\right).} \quad (6)$$

Theorem 1 (Golden swirl-angle implies golden tangential fraction). *With $\phi = e^{(\operatorname{asinh}(1/2))}$ and ξ_g defined by (6), the following identity holds:*

$$\boxed{\tanh(\xi_g) = e^{-\operatorname{asinh}(0.5)} = \phi^{-1}.} \quad (7)$$

Proof. Let $t := e^{\operatorname{asinh}(0.5)}$. From Lemma (5) we have $t^2 = t + 1$. Using the standard identity $\tanh y = \frac{e^{2y}-1}{e^{2y}+1}$, [2] with $y = \xi_g = \frac{3}{2}\operatorname{asinh}(0.5)$,

$$\tanh(\xi_g) = \frac{e^{3\operatorname{asinh}(0.5)} - 1}{e^{3\operatorname{asinh}(0.5)} + 1} = \frac{t^3 - 1}{t^3 + 1}.$$

Since $t^2 = t + 1$, we obtain $t^3 = t(t + 1) = t^2 + t = 2t + 1$. Therefore

$$\tanh(\xi_g) = \frac{(2t + 1) - 1}{(2t + 1) + 1} = \frac{2t}{2t + 2} = \frac{t}{t + 1} = \frac{t}{t^2} = \frac{1}{t} = e^{-\operatorname{asinh}(0.5)}.$$

Finally, $\phi = e^{\operatorname{asinh}(0.5)}$ by (4), hence $\tanh(\xi_g) = \phi^{-1}$. \square

5 SST golden layer for tangential swirl kinematics

Combining the SST kinematic mapping (3) with Theorem (7), the golden layer is defined by $\xi = \xi_g$ and yields the fixed fraction

$$\boxed{\beta_g \equiv \tanh(\xi_g) = \phi^{-1}.} \quad (8)$$

Thus, for any SST sector employing the hyperbolic swirl-angle coordinate ξ , the golden layer implies the tangential speed scale

$$\boxed{\|\mathbf{v}\|_g = \beta_g v_{\circlearrowleft} = \frac{v_{\circlearrowleft}}{\phi}.} \quad (9)$$

If r_c denotes the SST core length scale, a corresponding angular-frequency scale can be introduced by dimensional normalization,

$$\boxed{\Omega \equiv \frac{v_{\circlearrowleft}}{r_c}, \quad \Omega_g \equiv \frac{\|\mathbf{v}\|_g}{r_c} = \frac{1}{\phi} \frac{v_{\circlearrowleft}}{r_c} = \frac{\Omega}{\phi}.} \quad (10)$$

This step is purely dimensional: it does not assert a specific dynamical equation for Ω . The constants v_{\circlearrowleft} and r_c are taken from SST canon. [6]

Dimensional consistency. Equation (9) has units of speed, and (10) has units of s^{-1} , since r_c has units of length. [6]

6 Numerical evaluation using SST constants

We evaluate ϕ , ξ_g , and the corresponding kinematic scales using

$$v_{\circlearrowleft} = 1.093\,845\,63 \times 10^6 \text{ m s}^{-1}, \quad r_c = 1.408\,970\,17 \times 10^{-15} \text{ m},$$

as specified in SST canon. [6]

Using the hyperbolic definitions and standard functions, [1, 2] we obtain

$$\phi = e^{(\operatorname{asinh}(1/2))} \approx 1.618033988749895, \quad (11)$$

$$\operatorname{asinh}(0.5) = \operatorname{asinh}(1/2) \approx 0.4812118250596035, \quad (12)$$

$$\xi_g = \frac{3}{2} \operatorname{asinh}(0.5) \approx 0.7218177375894053, \quad (13)$$

$$\beta_g = \tanh(\xi_g) \approx 0.6180339887498948 = \phi^{-1}. \quad (14)$$

Therefore,

$$\|\mathbf{v}\|_g = \frac{v_\odot}{\phi} \approx 6.760337777855416 \times 10^5 \text{ m s}^{-1}, \quad (15)$$

$$\Omega = \frac{v_\odot}{r_c} \approx 7.763440655383073 \times 10^{20} \text{ s}^{-1}, \quad (16)$$

$$\Omega_g = \frac{\Omega}{\phi} \approx 4.798070194669498 \times 10^{20} \text{ s}^{-1}. \quad (17)$$

7 Interpretation and mainstream-facing remarks

7.1 What is “new” here

The hyperbolic function identities and the classical properties of ϕ used above are not new. [1, 2, 4] The SST-specific contribution is the *interpretive packaging*:

- introduce ξ as a *hyperbolic swirl-angle* coordinating the SST tangential fraction β ,
- define the golden layer ξ_g and note that $\beta_g = \phi^{-1}$ becomes an SST-internal, dimensionless marker,
- express the associated speed and frequency scales in terms of SST canonical constants v_\odot and r_c . [6]

7.2 Why use the hyperbolic coordinate at all

The mapping $\beta = \tanh \xi$ has two practical advantages: (i) it automatically enforces $\beta \in [0, 1)$ for all real ξ ; [2] (ii) it linearizes certain algebraic manipulations because exponentials appear directly in \tanh identities. [2] In SST, this makes it convenient to talk about “layers” in ξ rather than repeatedly carrying bounded fractions β .

7.3 Analogy (age 10)

Imagine a speed slider that can never go above 100%. The hyperbolic swirl-angle is like a special knob behind the slider: turning the knob by equal steps changes the slider smoothly, and there is one special knob position that always lands exactly at the same famous fraction (about 62%), the golden one.

Acknowledgements

The numerical values used for v_\odot and r_c are taken from the SST canon. [6]

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