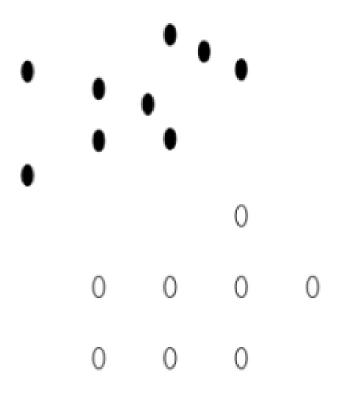
#### Lesson 6

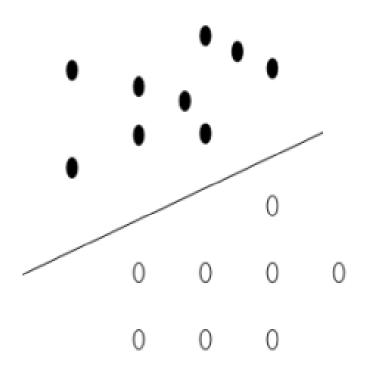
# Support vector machine (SVM)

Support vector machine (SVM in short) is a Discriminant based classification method where the task is to find a decision boundary separating sample in one class from the other. it is a binary in nature, means it considers two classes.

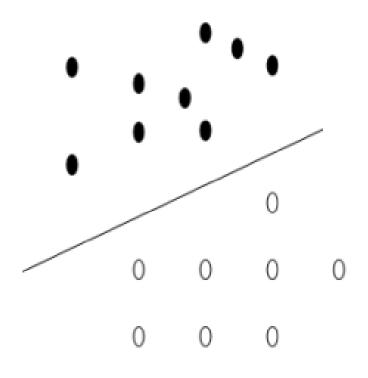
SVM is a vase topic. In this lesion, we will focus only on introductory understanding of SVM.



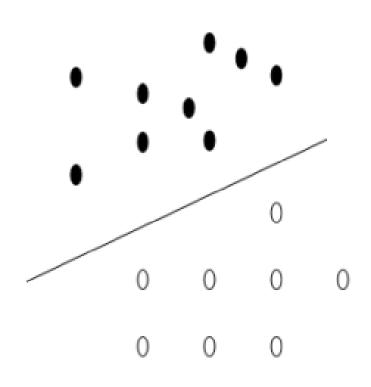
Let us say, we have samples in two different classes as shown in the figure. Black samples are in +ve class and white samples are in -ve class.

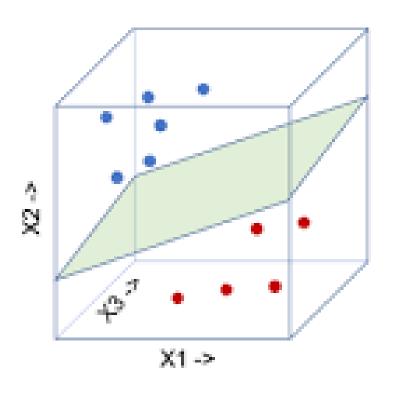


The task is to find best possible line separating samples in one class from the samples other class.



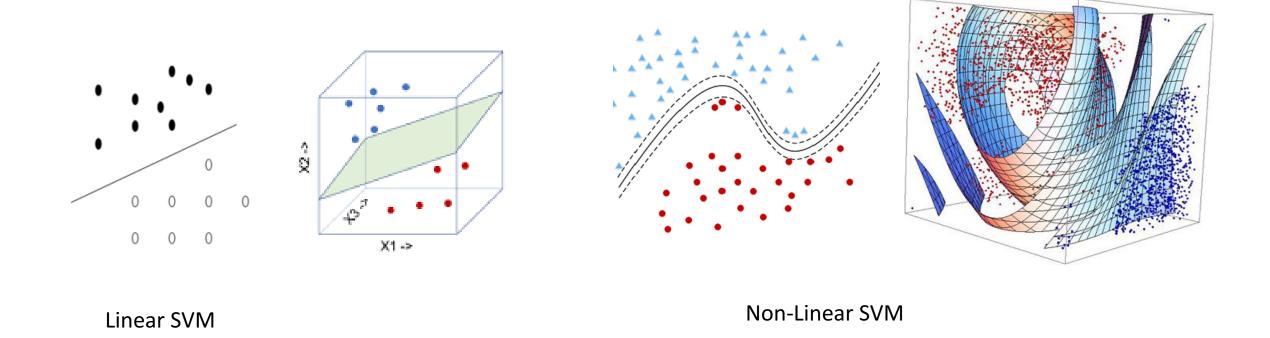
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In the 2D space, the decision boundary is a line,
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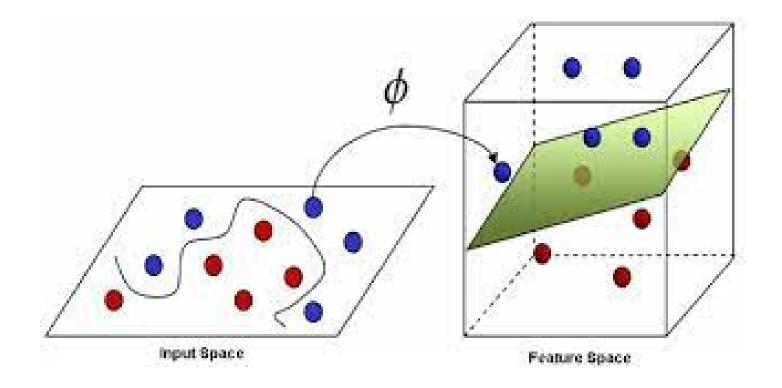
In the 3D space, the decision boundary is a hyperplane

## Support vector machine – Linear or Non-linear

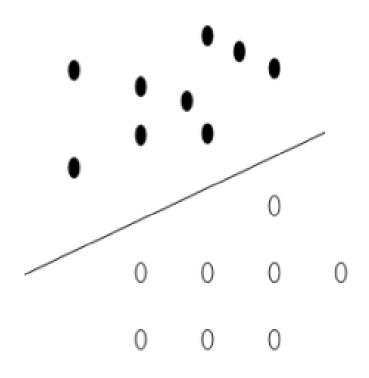


Depending on the nature of the samples, the decision boundary can be linear or non-linear, resulting to linear SVM or non-linear SVM.

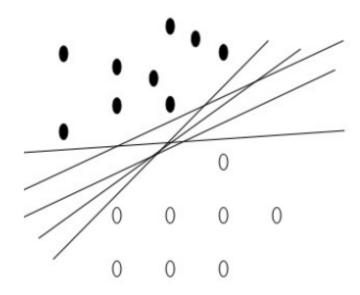
#### Non-Linear to Linear



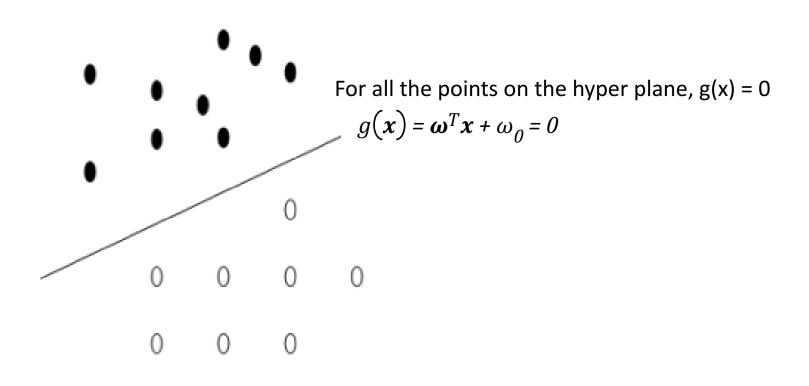
Finding a non-linear decision boundary is complex. Further, non-linear problems can be transformed to a linear problem. For example, ...... This lesson focusses on Linear SVM.



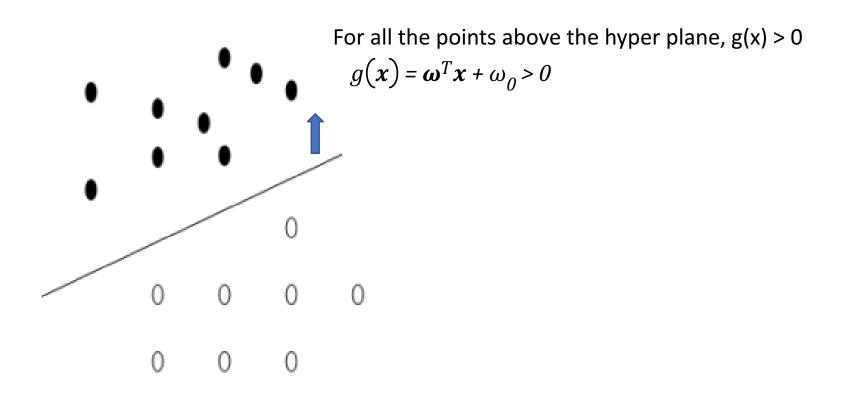
Given this example, As mentioned, the task is to find a separating line.

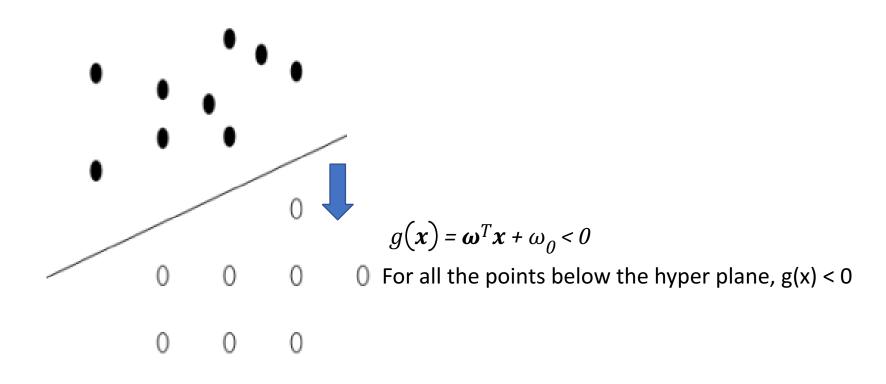


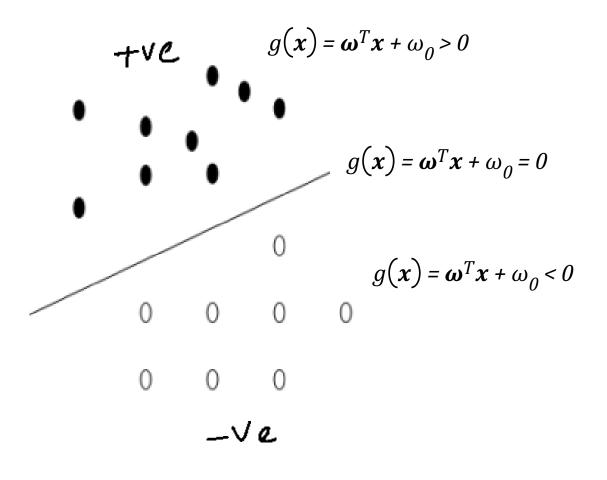
However, there are infinite number of lines which can separate the +ve samples from the –ve samples. Which one of them will be selected as the separating line. This lesson will explain how to choose the separating line.



To understand the process, let us begin with as separating hyperplane defined by the linear function g(x).

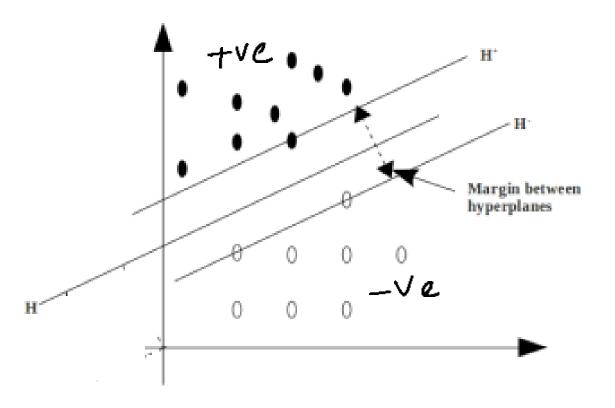






We choose the hyperplane that has the maximum separating margin

## What is Separating Margin?



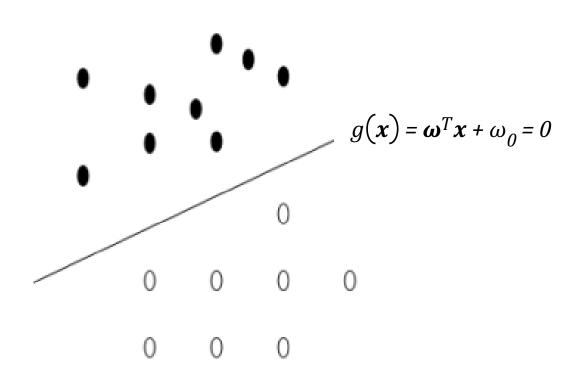
H is the separating hyperplane

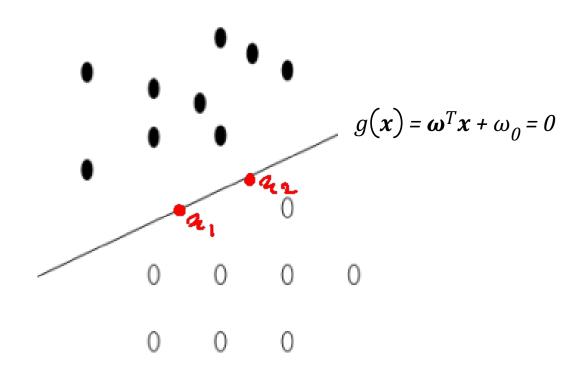
H<sup>+</sup> is the plane parallel to H and passing through the nearest +ve points to H

H<sup>-</sup> is the plane parallel to H and passing through the nearest -ve points to H

Separating margin is the distance between H<sup>+</sup> and H<sup>-</sup>

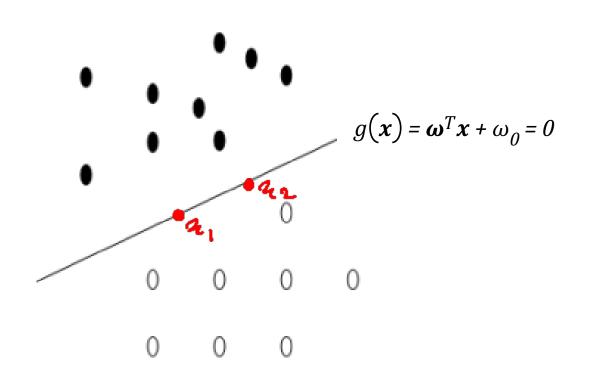
We choose H that has the maximum margin.





Let us take two points  $x_1$  and  $x_2$  lying on g(x)

$$g(x_1) = g(x_2) = 0$$

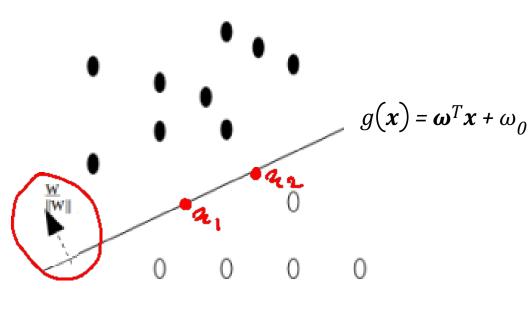


Let us take two points  $x_1$  and  $x_2$  lying on g(x)

$$g(x_1) = g(x_2) = 0$$

$$\Rightarrow \boldsymbol{\omega}^T \boldsymbol{x}_1 + \omega_0 = \boldsymbol{\omega}^T \boldsymbol{x}_1 + \omega_0$$

$$\Rightarrow \boldsymbol{\omega}^T (\boldsymbol{x}_1 - \boldsymbol{x}_1) = 0$$



Let us take two points  $x_1$  and  $x_2$  lying on g(x)

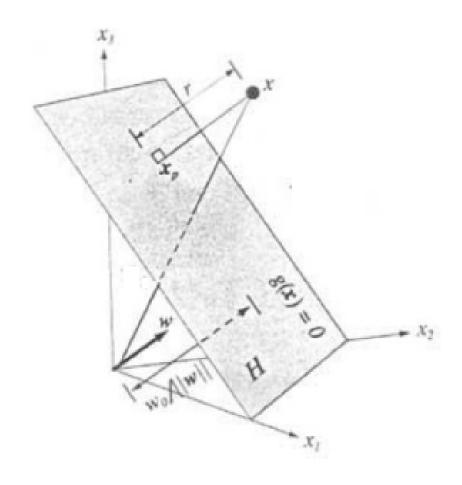
$$g(x_1) = g(x_2) = 0$$

$$\Rightarrow \boldsymbol{\omega}^T \boldsymbol{x}_1 + \omega_0 = \boldsymbol{\omega}^T \boldsymbol{x}_1 + \omega_0$$

$$\Rightarrow \boldsymbol{\omega}^T (\boldsymbol{x}_1 - \boldsymbol{x}_1) = 0$$

It means  $\omega$  is orthogonal (90°/perpendicular) the vector ( $\mathbf{x_1} - \mathbf{x_2}$ ).

It means  $\omega$  is orthogonal (90°/perpendicular) to g(x).



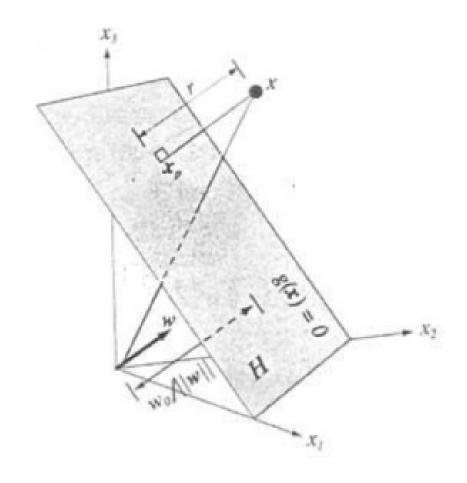
Let x be a point in space.

Let r be the distance of the point x from the hyperplane g(x), and  $x_p$  be the corresponding projection point of x on g(x).

Now, vector x can be defined by the sum of the vector  $x_p$  and vector r.

$$x = x_p + r$$

$$\Rightarrow x = x_p + r \frac{\omega}{\|\omega\|}$$



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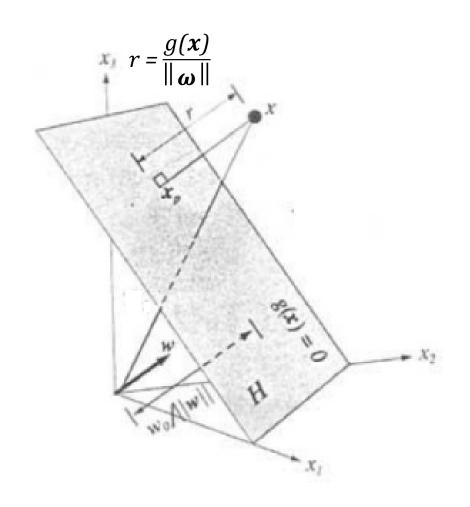
$$x = x_p + r$$

$$\Rightarrow x = x_p + r \frac{\omega}{\|\omega\|}$$

If you substitute x in g(x).

$$\Rightarrow g(x) = \omega^T x_p + r \frac{\omega^T \omega}{\|\omega\|} + \omega_0$$

$$\Rightarrow g(x) = \omega^T x_p + \omega_0 + r \frac{\omega^T \omega}{\|\omega\|} \qquad \Rightarrow g(x) = r \frac{\omega^T \omega}{\|\omega\|} \Rightarrow r = \frac{g(x)}{\|\omega\|}$$

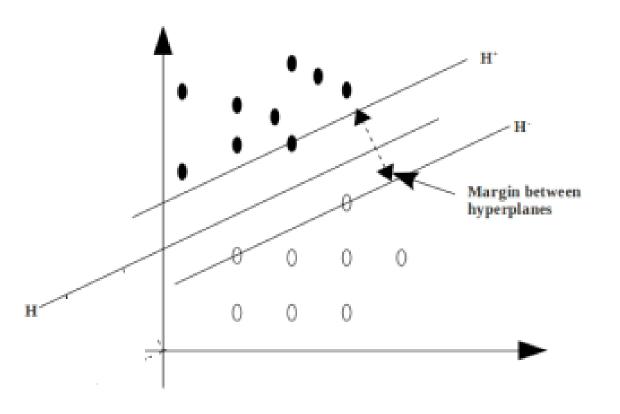


Distance of 
$$x_p$$
 from g(x)=0 is  $r = \frac{g(x)}{\|\omega\|}$ 

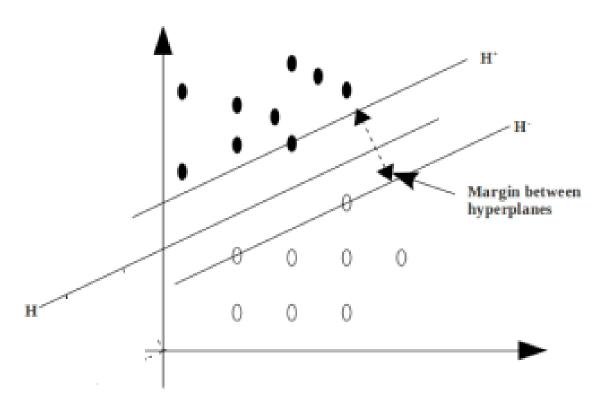
So, the distance of origin from g(x)=0 is

$$\Rightarrow r_0 = \frac{\boldsymbol{\omega}^T \mathbf{0} + \omega_0}{\|\boldsymbol{\omega}\|}$$

$$\Rightarrow r_0 = \frac{\omega_0}{\|\boldsymbol{\omega}\|}$$



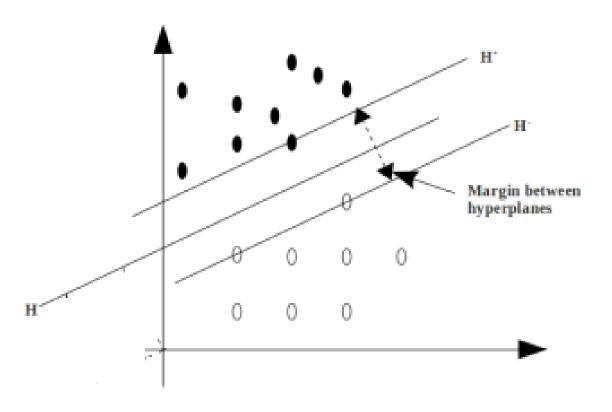
What is the Margin between H+ and H-?



To define the expression for H+ and H-, let us make the following assumptions.

Given a datapoint  $< x_{i'} y_i >$  where  $y_i \in \{ + ve, -ve \}$  is the class label of  $x_{i'}$ 

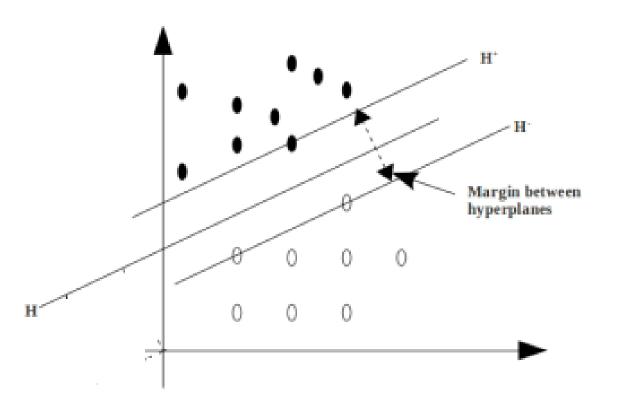
let us replace -ve by +1, and -ve by -1.



To define the expression for H+ and H-, let us make the following assumptions.

Given a datapoint  $\langle x_{i'}y_{i}\rangle$  where  $y_{i}\in\{+ve,-ve\}$  is the class label of  $x_{i'}$ 

- Let us replace -ve by +1, and -ve by -1.
- Now, each data point will satisfy the following  $\boldsymbol{\omega}^T \boldsymbol{x_i} + \omega_0 \ge 1$ ,  $\forall y_i = +1$   $\boldsymbol{\omega}^T \boldsymbol{x_i} + \omega_0 \le -1$ ,  $\forall y_i = -1$



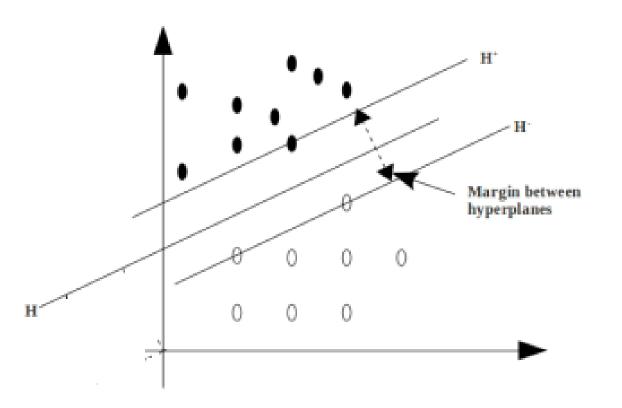
To define the expression for H+ and H-, let us make the following assumptions.

Given a datapoint  $\langle x_i, y_i \rangle$  where  $y_i \in \{ + ve, -ve \}$  is the class label of  $x_i$ ,

- let us replace -ve by +1, and -ve by -1.
- Now, each data point will satisfy the following  $\boldsymbol{\omega}^T \boldsymbol{x_i} + \omega_0 \ge 1$ ,  $\forall y_i = +1$   $\boldsymbol{\omega}^T \boldsymbol{x_i} + \omega_0 \le -1$ ,  $\forall y_i = -1$

The above two expression can be merged to form a single expression

$$y_i(\boldsymbol{\omega}^T \boldsymbol{x}_i + \boldsymbol{\omega}_0) \ge 1, \ \forall \ \boldsymbol{x}_i$$



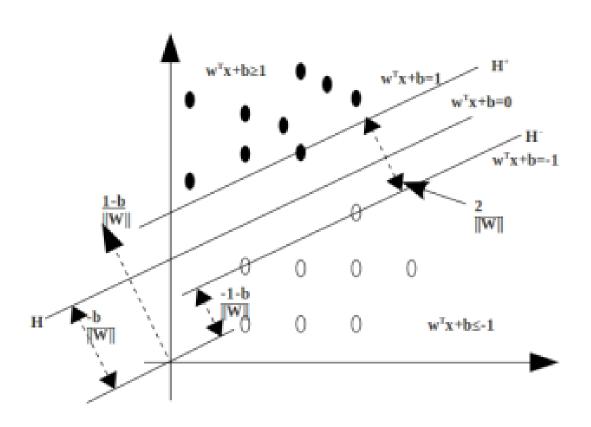
To define the expression for H+ and H-, let us make the following assumptions.

Given a datapoint  $\langle x_i, y_i \rangle$  where  $y_i \in \{ + ve, -ve \}$  is the class label of  $x_i$ ,

- let us replace -ve by +1, and -ve by -1.
- Now, each data point will satisfy the following  $\boldsymbol{\omega}^T \boldsymbol{x_i} + \omega_0 \ge 1$ ,  $\forall y_i = +1$   $\boldsymbol{\omega}^T \boldsymbol{x_i} + \omega_0 \le -1$ ,  $\forall y_i = -1$

The above two expression can be merged to form a single expression

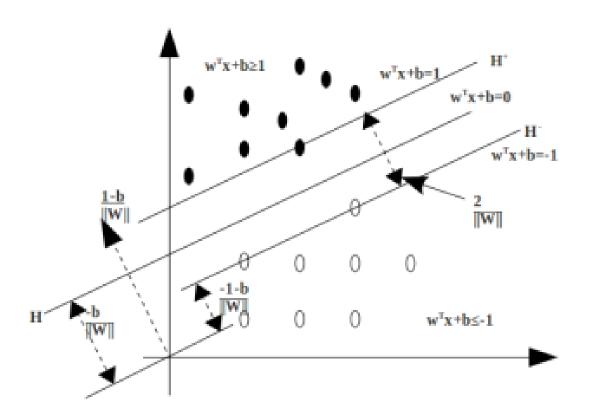
$$y_{i}(\boldsymbol{\omega}^{T}\boldsymbol{x}_{i} + \boldsymbol{\omega}_{0}) \geq 1, \ \forall \ \boldsymbol{x}_{i}$$
$$y_{i}(\boldsymbol{\omega}^{T}\boldsymbol{x}_{i} + \boldsymbol{\omega}_{0}) - 1 \geq 0, \ \forall \ \boldsymbol{x}_{i}$$



H: 
$$g(x) = \omega^T x + \omega_0 = 0$$

H+: 
$$g(x) = \omega^T x + \omega_0 = 1$$

H-: 
$$g(x) = \omega^T x + \omega_0 = -1$$



H: 
$$g(x) = \omega^T x + \omega_0 = 0$$

H+: 
$$g(x) = \omega^T x + \omega_0 = 1$$

H-: 
$$g(x) = \omega^T x + \omega_0 = -1$$

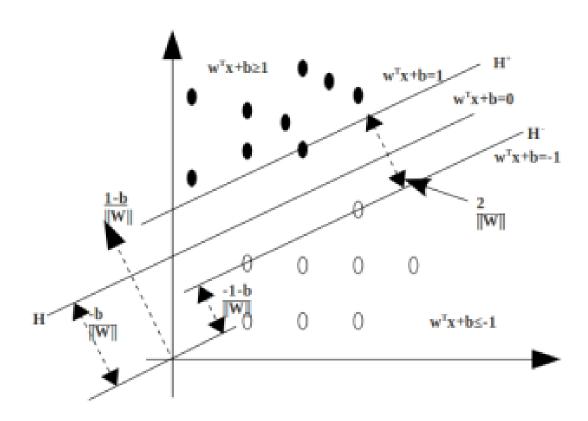
Margin = 
$$r_{H^+} - r_{H^-}$$

$$= \frac{\omega_0 - 1}{\|\boldsymbol{\omega}\|} - \frac{\omega_0 + 1}{\|\boldsymbol{\omega}\|}$$

$$= \frac{\omega_0 - 1 - \omega_0 - 1}{\|\boldsymbol{\omega}\|}$$

$$= \frac{\omega_0 - 2}{\|\boldsymbol{\omega}\|}$$

$$\Rightarrow Margin = \frac{-2}{\|\boldsymbol{\omega}\|}$$



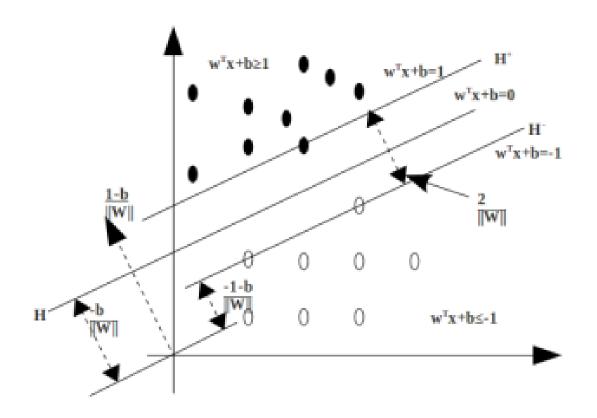
As we are interested in the absolute value, we consider the margin as  $\frac{2}{\|\boldsymbol{\omega}\|}$ 

H: 
$$g(x) = \omega^T x + \omega_0 = 0$$

H+: 
$$g(x) = \omega^T x + \omega_0 = 1$$

H-: 
$$g(x) = \omega^T x + \omega_0 = -1$$

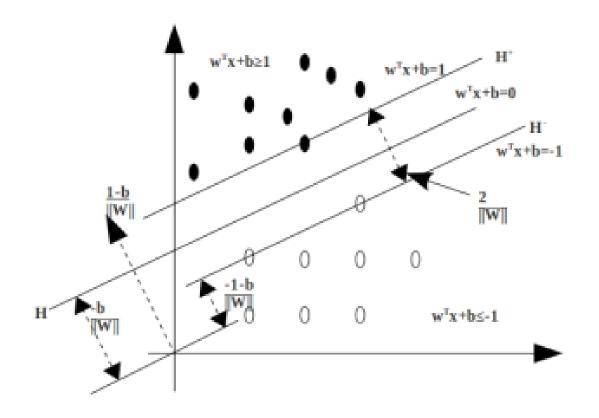
$$\begin{aligned} \operatorname{Margin} &= r_{H^+} - r_{H^-} \\ &= \frac{\omega_0 - 1}{\|\boldsymbol{\omega}\|} - \frac{\omega_0 + 1}{\|\boldsymbol{\omega}\|} \\ &= \frac{\omega_0 - 1 - \omega_0 - 1}{\|\boldsymbol{\omega}\|} \\ \Rightarrow \operatorname{Margin} &= \frac{-2}{\|\boldsymbol{\omega}\|} \end{aligned}$$



Task is to find the hyperplane (g(x)=0) that maximizes the margin  $\frac{2}{\|x\|}$ 

$$Margin = \frac{2}{\|\boldsymbol{\omega}\|}$$

$$\Rightarrow Margin = \frac{1}{\|\boldsymbol{\omega}\|}$$



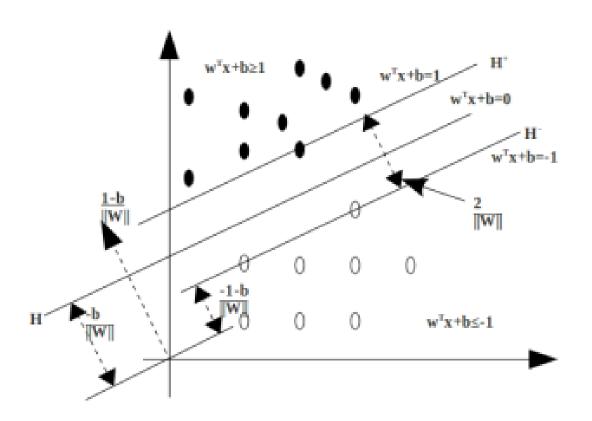
Task is to find the hyperplane (g(x)=0) that maximizes the margin  $\frac{2}{\|\mathbf{g}\|}$ 

$$Margin = \frac{2}{\|\boldsymbol{\omega}\|}$$

$$\Rightarrow Margin = \frac{1}{\|\boldsymbol{\omega}\|}$$

Maximizing  $\frac{2}{\|\boldsymbol{\omega}\|}$  is equivalent to minimizing  $\frac{\|\boldsymbol{\omega}\|}{2}$ 

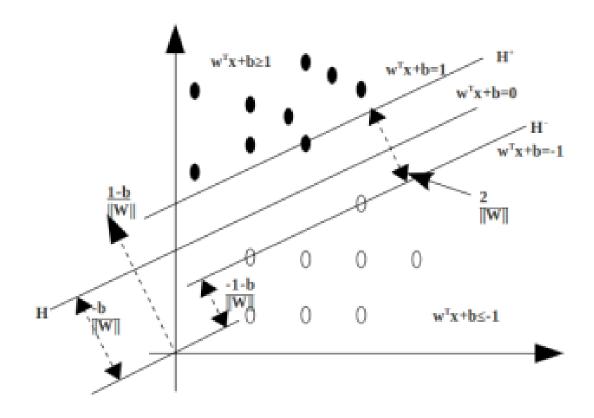
Minimizing  $\frac{\|\omega\|}{2}$  is equivalent to minimizing  $\frac{\omega^T\omega}{2}$ 



Now, we need to solve the following optimization

Minimize objective function 
$$\frac{\omega^T \omega}{2}$$

Subject to the constraint  $y_i(\omega^T x_i + \omega_0) \ge 1$ ,  $\forall x_i$ 



Objective function is to minimize  $\frac{\omega^T \omega}{2}$ 

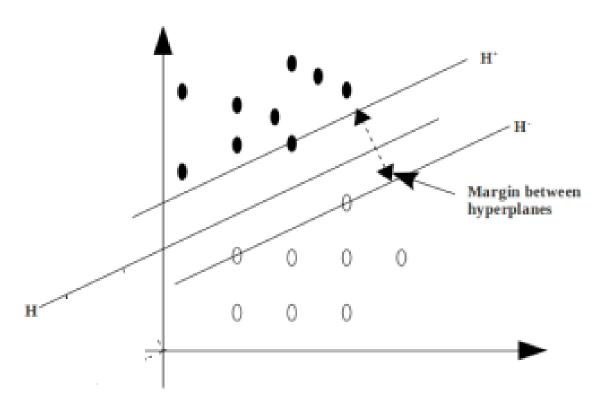
Subject to 
$$y_i(\boldsymbol{\omega}^T \boldsymbol{x}_i + \omega_0) \ge 1, \ \forall \ \boldsymbol{x}_i$$

To find the parameters  $\omega$  and where  $\omega_{\it 0}$ , solve the following optimization function

$$L_p = \frac{\omega^T \omega}{2} - \sum_{i=1}^n \lambda_i \left( y_i (\omega^T x_i + \omega_0) - 1 \right)$$

where  $\lambda_i$  are Lagrange multipliers

#### What are the support vectors?



$$L_p = \frac{\omega^T \omega}{2} - \sum_{i=1}^n \lambda_i \left( y_i (\omega^T x_i + \omega_0) - 1 \right)$$

In order to find the parameters, we need to solve this objective function.

#### Summary

- What is separating hyperplane?
- How to define separating hyperplane?
- What are Support Vector Machine?
- How to classify a new example using SVM