# Machine Learning 101

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# **Linear regression**

### 1 Introduction

Linear regression is a fundamental method in machine learning and statistics for modeling the relationship between a dependent variable and one or more independent variables. Ordinary Least Squares (OLS) is a common approach used to fit linear regression models by minimizing the sum of squared residuals.

# 2 Least Squares Method

The least squares method involves finding the parameters of a linear model such that the sum of the squared differences between the observed values and the predicted values is minimized. Mathematically:

$$J(\beta) = \sum_{i=1}^{m} (y_i - \hat{y}_i)^2$$
 (1)

where:

- y<sub>i</sub> are the actual values.
- $\hat{y}_i = \beta_0 + \beta_1 x_i$  is the predicted value.
- *m* is the number of observations.

### 2.1 Objective

Minimize  $J(\beta)$  to determine the optimal parameters  $\beta_0$  and  $\beta_1$ .

<sup>\*</sup>Amygdala AI, is an international volunteer-run research group that advocates for AI for a better tomorrow http://amygdalaai.org/.

# 3 Ordinary Least Squares (OLS)

OLS extends the least squares method for multiple variables. For a dataset X (design matrix) and target vector y, the model is:

$$\hat{\mathbf{y}} = X\boldsymbol{\beta} \tag{2}$$

The OLS solution minimizes:

$$J(\beta) = \|y - X\beta\|^2 \tag{3}$$

The closed-form solution is given by:

$$\beta = (X^T X)^{-1} X^T y \tag{4}$$

## 4 Toy Problem

Consider a dataset with two observations:

- Inputs  $X = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$
- Outputs  $y = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

Adding a bias term, the design matrix becomes:

$$X = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \tag{5}$$

Using the OLS formula:

$$\beta = (X^T X)^{-1} X^T y \tag{6}$$

### 4.1 Solution

- 1. Compute  $X^T X$ :  $\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}^T \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$
- 2. Compute  $X^T y$ :  $\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}^T \begin{bmatrix} 2 \\ 3 \end{bmatrix}$
- 3. Compute  $\beta$ :  $\begin{bmatrix} 3 & 5 \\ 5 & 13 \end{bmatrix}^{-1} \begin{bmatrix} 5 \\ 8 \end{bmatrix}$

# 5 Challenges of OLS

- **Multicollinearity:** When predictors are highly correlated,  $X^TX$  becomes near-singular.
- Outliers: OLS is sensitive to outliers, as they disproportionately influence the cost function.
- Overfitting: When the model has too many predictors, it may fit noise in the data rather than the underlying trend.

### 6 Gradient Descent Variants

#### 6.1 Batch Gradient Descent

Updates  $\beta$  based on all training examples:

$$\beta := \beta - \alpha \nabla J(\beta) \tag{7}$$

#### 6.2 Stochastic Gradient Descent (SGD)

Updates  $\beta$  based on a single example:

$$\beta := \beta - \alpha (y^{(i)} - \hat{y}^{(i)}) x^{(i)}$$
(8)

#### 6.3 Mini-batch Gradient Descent

Combines aspects of batch and stochastic gradient descent, updating  $\beta$  using a subset of examples.

# 7 Linear Regression with SGD: Step-by-Step

- 1. Initialize  $\beta$  to random values.
- 2. For each iteration:
  - (a) Shuffle the dataset.
  - (b) For each training example:
    - Compute prediction:  $\hat{y} = x^T \beta$
    - Compute error:  $e = \hat{y} y$
    - Update parameters:  $\beta := \beta \alpha ex$

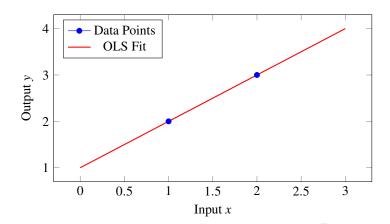


Figure 1: OLS fit for a toy problem.

### 8 Visualization

## 8.1 OLS Fit Example

# 9 Introduction to Linear Regression

Linear regression is a supervised learning algorithm used for modeling the relationship between a dependent variable *y* and one or more independent variables *x*. It aims to fit a linear equation to observed data.

The linear model is given by:

$$\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n \tag{9}$$

where:

- ŷ is the predicted value of the dependent variable.
- $\theta_0, \theta_1, \dots, \theta_n$  are the model parameters.
- $x_1, x_2, \dots, x_n$  are the independent variables.

# 10 Cost Function for Linear Regression

The cost function quantifies the error between the predicted values  $(\hat{y})$  and the actual values (y). For linear regression, we use the Mean Squared Error (MSE) as the cost function:

$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (\hat{y}^{(i)} - y^{(i)})^2$$
 (10)

where:

- *m* is the number of training examples.
- $\hat{y}^{(i)} = \theta^T x^{(i)}$  is the prediction for the *i*-th example.
- $y^{(i)}$  is the actual value for the *i*-th example.

The factor  $\frac{1}{2}$  is included to simplify the derivative during gradient computation.

#### 10.1 Deriving the Gradient of the Cost Function

To optimize  $J(\theta)$ , we compute its gradient with respect to  $\theta_i$ :

$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^{m} (\hat{y}^{(i)} - y^{(i)}) x_j^{(i)}$$
(11)

where  $x_j^{(i)}$  is the *j*-th feature of the *i*-th example. This gradient guides us in updating  $\theta$  to minimize the cost function.

## 11 Stochastic Gradient Descent (SGD)

Gradient Descent is an optimization algorithm that minimizes the cost function  $J(\theta)$  by iteratively updating the model parameters.

## 11.1 Types of Gradient Descent

- Batch Gradient Descent: Uses the entire training dataset to compute the gradient at each iteration.
- Stochastic Gradient Descent (SGD): Uses a single training example to compute the gradient and update the parameters at each iteration.
- Mini-Batch Gradient Descent: Uses a small batch of training examples to compute the gradient at each iteration.

#### 11.2 SGD Update Rule

For each training example  $(x^{(i)}, y^{(i)})$ , the parameters are updated as follows:

$$\theta_j := \theta_j - \alpha \frac{\partial J(\theta)}{\partial \theta_j} \tag{12}$$

Substituting the gradient, we get:

$$\theta_j := \theta_j - \alpha(\hat{y}^{(i)} - y^{(i)}) x_i^{(i)} \tag{13}$$

where  $\alpha$  is the learning rate.

### 11.3 Advantages of SGD

- Faster updates as it uses only one example per iteration.
- Useful for large datasets.
- Can escape local minima due to its noisy updates.

#### 11.4 Challenges of SGD

- Noisy updates can lead to fluctuations around the minimum.
- Requires careful tuning of the learning rate.
- Can take longer to converge compared to batch methods.

# 12 Toy Problem: Linear Regression with SGD

Let us solve a toy problem using SGD.

## 12.1 Problem Setup

Consider a dataset with one feature:

x	y
1	2
2	4
3	6
4	8

Table 1: Sample dataset.

## 12.2 SGD Steps

- 1. **Initialize Parameters:** Start with  $\theta_0 = 0$  and  $\theta_1 = 0$ .
- 2. Compute Predictions: Use  $\hat{y} = \theta_0 + \theta_1 x$ .
- 3. **Update Parameters:** For each example  $(x^{(i)}, y^{(i)})$ :

$$\theta_0 := \theta_0 - \alpha(\hat{\mathbf{y}}^{(i)} - \mathbf{y}^{(i)}) \tag{14}$$

$$\theta_1 := \theta_1 - \alpha(\hat{y}^{(i)} - y^{(i)}) x^{(i)} \tag{15}$$

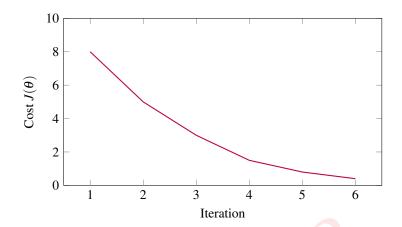


Figure 2: SGD convergence trajectory.

#### 12.3 Visualization of SGD

## 13 Assumptions of Linear Regression

Linear regression relies on several assumptions to ensure the validity of its results. These assumptions, their verification methods, and remedies for violations are detailed below:

- 1. **Linearity:** The relationship between the independent variables (predictors) and the dependent variable (target) is linear.
  - **Verification:** Plot the observed data against the predicted values to check for a linear pattern.
  - **Remedies:** If the relationship is non-linear, consider applying transformations to the variables (e.g., log, square root) or using non-linear models.
- Independence: Observations are independent, and residuals are not autocorrelated.
  - **Verification:** Use the Durbin-Watson test to detect autocorrelation in residuals.
  - **Remedies:** If autocorrelation exists, consider using time-series models or adding lagged variables.
- 3. **Homoscedasticity:** The variance of residuals is constant across all levels of the independent variables.
  - **Verification:** Create a residual vs. fitted values plot. Homoscedasticity is indicated by a random scatter with no discernible pattern.

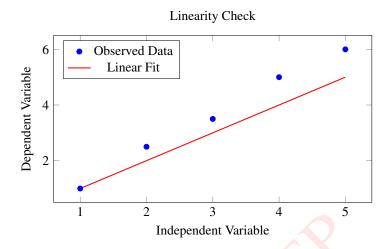


Figure 3: Checking the linear relationship between predictors and the target.

• **Remedies:** Use weighted least squares or transform the dependent variable if heteroscedasticity is present.

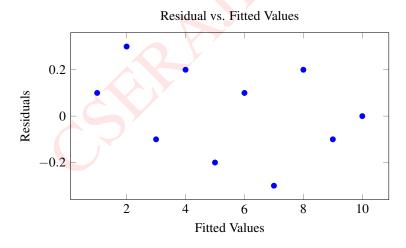


Figure 4: Residual plot to verify homoscedasticity. A random scatter indicates homoscedasticity.

- 4. Normality of Residuals: Residuals are normally distributed.
  - Verification: Use a Q-Q plot or the Shapiro-Wilk test to assess normality.
  - **Remedies:** Apply transformations to the target variable or use robust regression techniques if normality is violated.

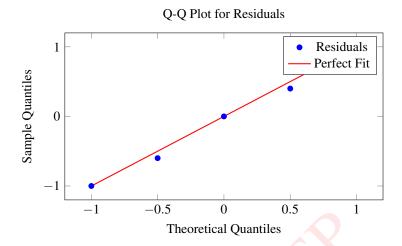


Figure 5: Q-Q plot to verify normality of residuals. Points close to the red line indicate normality.

- 5. **No Multicollinearity:** Independent variables are not highly correlated with each other.
  - **Verification:** Calculate the Variance Inflation Factor (VIF). A VIF greater than 10 indicates multicollinearity.
  - **Remedies:** Remove or combine highly correlated predictors, or use regularization techniques like ridge or lasso regression.
- 6. **Exogeneity:** Independent variables are uncorrelated with the error term.
  - Verification: Use the Hausman test to check for endogeneity.
  - Remedies: Include instrumental variables to address endogeneity.