CSC 381-34: Proj6 (C++)
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III. In Main
****
step 1: labelFile <-- open label file, argv[1]
propFile <-- open property file, argv[2]
output image header to outFile1
output image header to outFile2 // per text line
imageAry <-- dynamically allocated
lordImage(imageAry)
zeroFramed (imageAry)
CCAry <-- dynamically allocated

step 2: CC <-- get the next connected component from the property file
// CC a connectCC class object, therefore, all its properties are stored in the object CC
// by the class's constructor.

step 3: CClable <-- get the label of CC

Step 4: clearCC () // zero out the old cclable for next cc

loadCC (CClable, CCAry) // Extract the pixels with CClabel from imageAry to CCAry.

step 5: getChainCode(CC, CCAry)

step 6: repeat step 2 to step 5 until all connected components are processed.

step 7: close all files

****
IV. getChainCode(CC, CCAry)
****

step 1: minRow, minCol, maxRow, maxCol <-- get from CC's property

step 2: scan the CCAry from L to R & T to B within the bounding box

step 3: if CCAry(iRow, jCol) > 0
output iRow, jCol, CCAry(iRow, jCol) to outFile1 // see format specs above
output iRow, jCol, CCAry(iRow, jCol) to outFile2 // see format specs above
startP <-- (iRow, jCol)
currentP <-- (iRow, jCol)
lastQ <-- 4

step 4: nextQ <-- mod(lastQ+1, 8) // chain code for the outter boundry.

step 5: PchainDir <-- findNextP(currentP, nextQ, nextP) // nextP is assigned in the findNextP method.
currentP <-- flip the label of currentP from positive to negitive

step 6: output PchainDir to outFile1 // no spaces.
output PchainDir to outFile2 // with the readable format as given above

step 7: lastQ <-- nextDirTable[PchianDir]
currentP <-- nextP

step 8: repeat step 4 to step 7 until currentP == startP

****
III. findNextP(currentP, nextQ, nextP)
****

step 1: loadNeighborCoord(currentP)

step 2: chainDir <-- scan currentP's 8 neighbors within nighborCoord[] array from nextQ direction (mod 8) until a none zero neighbor with the same label as currentCC is found, chainDir is the index of neighborCoord[] which with the same label as currentP

step 3: nextP <-- nighborCoord[chainDir]

step 4: returns chainDir

SOURCE CODE

```
// Author: Swrajit Paul

#include <iostream>
#include <fstream>

using namespace std;

ifstream inFile;
ifstream inFiletwo;
ofstream outFile;
ofstream outFiletwo;

class image {

        public:

                int numRows;
                int numCols;
                int minVal;
                int maxVal;

                int** imageAry;
                int** CCAry;

           image() {

                        inFile >> numRows;
                        inFile >> numCols;
                        inFile >> minVal;
                        inFile >> maxVal;

                        outFile << numRows;
                        outFile << " ";
                        outFile << numCols;
                        outFile << " ";
                        outFile << minVal;
                        outFile << " ";
                        outFile << maxVal;
                        outFile << endl;

                        outFiletwo << numRows;
                        outFiletwo << " ";
                        outFiletwo << numCols;
                        outFiletwo << " ";
                        outFiletwo << minVal;
                        outFiletwo << " ";
                        outFiletwo << maxVal;
                        outFiletwo << endl;
```

```
                imageAry = new int*[numRows+2];
                for(int i = 0; i < numRows+2; i++){
                        imageAry[i] = new int[numCols+2]; }// set up the array with proper rows and cols
                for(int i = 0; i < numRows+2; i++) {
                        for(int j = 0; j < numCols+2; j++) {
                                imageAry[i][j] = 0; } }// initialize the array

                CCAry = new int*[numRows+2];
                for(int i = 0; i < numRows+2; i++){
                        CCAry[i] = new int[numCols+2];
                }// set up the array with proper rows and cols
                for(int i = 0; i < numRows+2; i++) {
                        for(int j = 0; j < numCols+2; j++) {
                                CCAry[i][j] = 0; } }// initialize the array
        }

        void loadImage(int** FramedAry) {
                // reads line by line from the input into zeroFramedAry
                for(int i = 1; i < numRows+1; i++) {
                        for(int j = 1; j < numCols+1; j++) {
                                inFile >> FramedAry[i][j]; } }

            }

            void zeroFramed(int** FramedAry) {
                for(int j = 0; j < numCols+2; j++) {
                        FramedAry[0][j] = 0;
                        FramedAry[numRows+1][j] = 0; }

                for(int j = 0; j < numRows+2; j++) {
                        FramedAry[j][0] = 0;
                        FramedAry[j][numCols+1] = 0; }
            }

};


class connectCC {

    public:

            int label;
            int numPixels;
            int minRow;
            int minCol;
            int maxRow;
            int maxCol;

        connectCC(int lab, int np, int minR, int minC, int maxR, int maxC, image im) {
              label = lab;
                numPixels = np;
                minRow = minR;
```

```
                minCol = minC;
                maxRow = maxR;
                maxCol = maxC;
                clearCC(im.CCAry, im.numRows+2, im.numCols+2);
                loadCC(label, im.CCAry, im);
        }

        void clearCC(int** CCAry, int row, int col){
                for(int i = 0; i < row; i++) {
                        for(int j = 0; j < col; j++) {
                                CCAry[i][j] = 0;
                        }
                }
        }

        void loadCC(int ccLable, int** CCAry, image im){
                for(int i = 0; i < im.numRows+2; i++) {
                        for(int j = 0; j < im.numCols+2; j++) {
                                if(im.imageAry[i][j] == ccLable)
                                        CCAry[i][j] = im.imageAry[i][j];
                        }
                }
        }

};

class chainCode{

        struct Point {
                int row;
                int col;
        };

        public:
                Point neighborCoord[8];
                Point startP;
                Point currentP;
                Point nextP;
                int lastQ;
                int nextQ;
                int nextDirTable[8] = {6, 0, 0, 2, 2, 4, 4, 6};;
                int nextDir;
                int PchainDir;
                int** imgAry;

                chainCode(connectCC CC, image im){
                        imgAry = im.CCAry;

                        getChainCode(im.CCAry, CC.minRow, CC.minCol, CC.maxRow, CC.maxCol);
                }

                void getChainCode(int** ary, int minR, int minC, int maxR, int maxC){
```

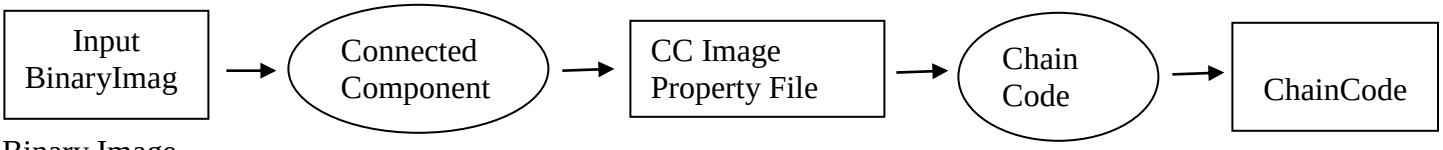
```
bool flag = false;

for(int i= minR; i <= maxR; i++) {

        for(int j = minC; j <= maxC; j++){

                if(ary[i][j] > 0){

                        flag = true;

                        // set starting point
                startP.row = i;
                startP.col = j;

                // set current point
                currentP.row = i;
                currentP.col = j;

                lastQ = 4;
                if(ary[i][j]!=1)
                        outFiletwo << "###" <<endl;
                outFile << ary[i][j] << " " << i-1 << " " << j-1 << " ";
                outFiletwo << ary[i][j] << " " << i-1 << " " << j-1 << " ";
                int count = 0;
                        while (true){

                                nextQ = (lastQ+1) % 8;

                                PchainDir = findNextP(currentP, nextQ, nextP);
                                count++;
                        outFile << PchainDir << " ";
                        if(count == 20){
                                outFiletwo << endl;
                                count = 0;
                                }
                                outFiletwo << PchainDir << " ";
                                nextQ = PchainDir -1;

                                if(nextQ < 0){
                                nextQ += 8;
                                }

                                lastQ = nextDirTable[nextQ];
                                currentP.row = nextP.row;
                        currentP.col = nextP.col;

                        if((currentP.row == startP.row) && (currentP.col == startP.col)){
                                        break;
                                }
                        }
                        if(flag == true){
                                break;
```

```
                                        }
                                }

        }

        if(flag == true){
                        break;
                }
        }
        outFile << endl;
        outFiletwo << endl;
}
void loadNeighborsCoord(Point current) {
        neighborCoord[0].row = current.row;
        neighborCoord[0].col = current.col+1;

        neighborCoord[1].row = current.row-1;
        neighborCoord[1].col = current.col+1;

        neighborCoord[2].row = current.row-1;
        neighborCoord[2].col = current.col;

        neighborCoord[3].row = current.row-1;
        neighborCoord[3].col = current.col-1;

        neighborCoord[4].row = current.row;
        neighborCoord[4].col = current.col-1;

        neighborCoord[5].row = current.row+1;
        neighborCoord[5].col = current.col-1;

        neighborCoord[6].row = current.row+1;
        neighborCoord[6].col = current.col;

        neighborCoord[7].row = current.row+1;
        neighborCoord[7].col = current.col+1;
}

int findNextP(Point currentP, int nextQ, Point p){
        int chainDir;
        loadNeighborsCoord(currentP);
        chainDir = getChainDir(currentP, nextQ);
        nextP.row = neighborCoord[chainDir].row;
        nextP.col = neighborCoord[chainDir].col;
        return chainDir;
}

int getChainDir(Point current, int nextQ){
        int chainDir;
        int counter = nextQ;
        while(true){
                int i = neighborCoord[counter].row;
```

```
                        int j = neighborCoord[counter].col;

                        if( imgAry[i][j]> 0){
                                chainDir = counter;
                                break;
                        }
                        counter++;
                        counter = counter % 8;
                }
                return chainDir;
        }
        void prettyPrint() {

        }
};


int main(int argc, char *argv[]){
        inFile.open(argv[1]);

        inFiletwo.open(argv[2]);

        outFile.open(argv[3]);

        outFiletwo.open(argv[4]);

        image img;
        img.loadImage(img.imageAry);
        img.zeroFramed(img.imageAry);

        int temp;
        inFiletwo >> temp;
        inFiletwo >> temp;
        inFiletwo >> temp;
        inFiletwo >> temp;
        // skipping lines

        inFiletwo >> temp;

        for(int i=0; i < temp; i++){

                int label, numPixels, minRow, minCol, maxRow, maxCol;
                inFiletwo >> label;
                inFiletwo >> numPixels;
                inFiletwo >> minRow;
                inFiletwo >> minCol;
                inFiletwo >> maxRow;
                inFiletwo >> maxCol;

                connectCC ConCC(label, numPixels, minRow, minCol, maxRow, maxCol, img);

                chainCode chainC(ConCC, img);
```

```
 }

        inFile.close();
        inFiletwo.close();
        outFile.close();
        outFiletwo.close();
        return 0;
}
```

INPUT



Binary Image

26 40 0 1

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0
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0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0
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0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0
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0 0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0 0 0 0 0 0 0 0

Connected Components

26 40 0 3

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0
0 0 0 0 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 0 0 0 0
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0 0 0 0 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 0 0 0
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0 0 0 0 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 0
0 0 0 0 2 2 2 2 2 2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 1 1 0
0 0 0 0 2 2 2 2 2 2 0 0 0 0 3 3 3 3 0 0 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0
0 0 0 0 2 2 2 2 2 2 0 0 0 0 3 3 3 3 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 0 0 0 0 0 0

0 0 0 0 2 2 2 2 2 2 0 0 0 0 3 3 3 3 0 0 0 0 0 0 0 0 0 0 0 1 1 1 0 0 0 0 0 0 0 0
0 0 0 0 2 2 2 2 2 2 0 3 3 3 3 3 3 3 3 3 3 0 0 0 0 0 0 0 0 1 1 1 0 0 0 0 0 0 0 0
0 0 0 0 2 2 2 2 2 2 0 3 3 3 3 3 3 3 3 3 3 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 0 0
0 0 0 0 2 2 2 2 2 2 0 3 3 3 3 3 3 3 3 3 3 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 0 0 0
0 0 0 0 2 2 2 2 2 2 0 3 3 3 3 3 3 3 3 3 3 0 0 0 0 1 1 1 1 1 1 1 1 1 1 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 0 0 0 0 0 0 1 1 1 1 1 1 1 0 0 0 0 0 0
0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0 0 1 1 1 1 1 0 0 0 0 0 0
0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3 0 0 0 0 1 1 1 0 0 0 0 0 0 0
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0 0 0 0 0 0 0 0 0 0 0 3 3 3 3 3 3 3 3 3 3 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

Property File

26 40 0 3
3
1
128
1 23
18 37
2
78
2 4
14 9
3
208
8 5
24 24

OUTPUT

Outfile One

26 40 0 3
1 1 30 5 5 5 5 5 5 5 0 0 0 0 0 7 6 6 5 4 4 4 4 4 7 7 0 7 7 7 7 1 1 1 1 0 1 1 4 4 4 4 4 3 2 2 1 0 0 0 0 0 3 3 3 3 3 3 3
2 2 4 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 0 0 0 0 0 2 2 2 2 2 2 2 2 2 2 2 2 2 4 4 4 4 4
3 8 14 6 6 5 4 4 6 6 6 6 5 4 4 4 4 4 6 6 6 6 6 0 0 0 0 0 7 6 6 0 0 0 0 0 0 0 0 0 0 2 2 2 1 0 0 0 2 2 2 2 4 4 4 3 2 2 2 2
4 4 3 2 2 4 4 4

Outfile Two

26 40 0 3
1 1 30 5 5 5 5 5 5 5 0 0 0 0 0 7 6 6 5 4 4 4
4 4 7 7 0 7 7 7 7 1 1 1 1 0 1 1 4 4 4 4
4 3 2 2 1 0 0 0 0 0 3 3 3 3 3 3 3
###
2 2 4 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 0 0 0 0 0 2 2
2 2 2 2 2 2 2 2 2 2 4 4 4 4 4
###
3 8 14 6 6 5 4 4 6 6 6 6 5 4 4 4 4 4 6 6 6 6
6 0 0 0 0 0 7 6 6 0 0 0 0 0 0 0 0 0 0 2 2
2 1 0 0 0 2 2 2 2 4 4 4 3 2 2 2 2 4 4 3
2 2 4 4 4