

Object Replication & Serialization

Chapter 3-5

GAME 311- Network Programming

Chapter 3 & 4

Objectives

- **Serialization**
 - Why can't we just memcpy everything between hosts?
 - Streams, endianness, and bits
- **Referenced data**
 - What happens when data points to other data?
- **Compression**
 - How to serialize efficiently
- **Maintainability**
 - Bug-resistant serialization
 - Data-driven serialization

Replicating Objects

- If we send each piece of data off one by one for the X, Y and paddle info like colour and size we could get offset in communication.
- All of a sudden we start accidentally mixing packets intended for the X location as the Y and data mixed up.
- The better option is to replicate entire objects at a time.
- Send all the information about one particular object as required.

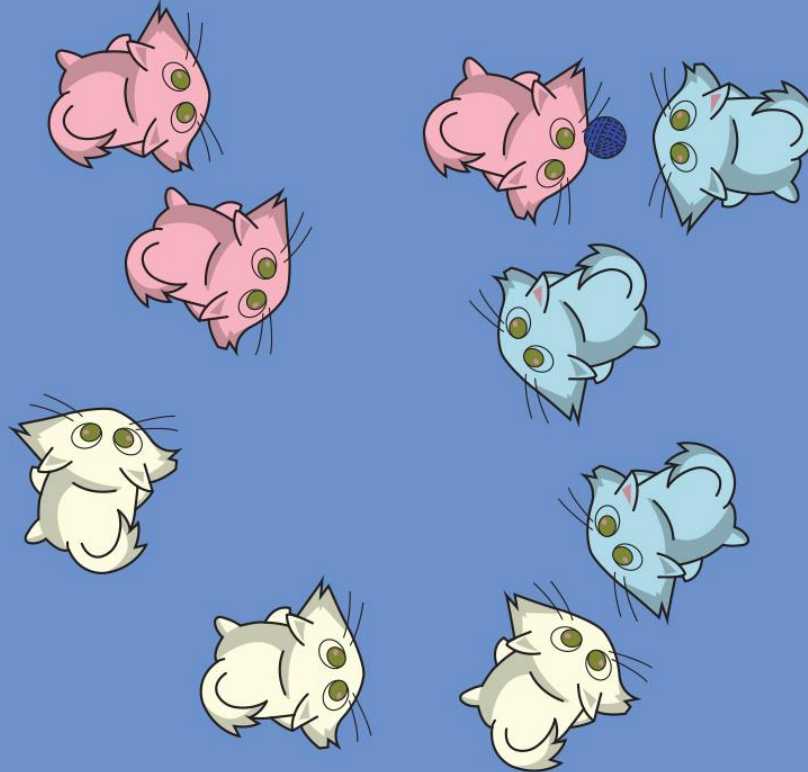
Case Study (RTS)

Turn 332:2

Sanjay 3

Josh 3

Zach 3



Replicating Objects

- Consider the following class of RoboCat

```
class RoboCat
{
public:
    RoboCat () {}
private:
    int mHealth;
    int mMeowCount;
};
```

- How can we send an instance to a remote host?

Send Code Review:

- Our send call is directly sending a char* (series of bytes)

```
// BOTH
void NetworkManager::SendData(const char* data)
{
    int messageLen = MAX_MESSAGE_SIZE;

    if (send(peerSocket, data, messageLen, 0) == SOCKET_ERROR)
    {
        int error = WSAGetLastError();

        if (error != WSAEWOULDBLOCK)
        {
            cout << "[Error] send error: " << WSAGetLastError() << endl;
            Shutdown();
        }
    }
}
```

Naïve Approach to Replication

```
void NaivelySendRoboCat( int inSocket, const RoboCat* inRoboCat)
{
    send( nSocket,
          reinterpret_cast< const char* >( inRoboCat ),
          sizeof( RoboCat ), 0 );
}

void NaivelyReceiveRoboCat( int inSocket, RoboCat* outRoboCat)
{
    recv( inSocket,
          reinterpret_cast< char* >( outRoboCat ),
          sizeof( RoboCat ), 0 );
}
```

- Will this work?
 - We can reinterpret_cast our entire objects memory footprint into a char*.

What About This RoboCat?

```
class RoboCat : public GameObject
{
public:
    RoboCat ()
    {
        mName[ 0 ] = '\0';
    }
    virtual void Update();

private:
    int32_t mHealth;
    int32_t mMeowCount;
    GameObject* mHomeBase;
    char mName[ 128 ];
    std::vector< int32_t > mMiceIndices;
    Vector3 mLocation;
    Quaternion mRotation;
};
```


Problems for Advanced RoboCat

- **mHomeBase** is a pointer:
 - Copying the value of a pointer doesn't copy the data.
- **mMiceIndices** is a complex data type:
 - Calling **memcpy** on the insides might not copy the data.
 - The vector on the remote host must be initialized to the proper size.

```
class RoboCat : public GameObject
{
public:
    RoboCat ()
    {
        mName[ 0 ] = '\0';
    }
    virtual void Update();

private:
    int32_t          mHealth;
    int32_t          mMeowCount;
    GameObject*      mHomeBase;
    char             mName[128];
    std::vector< int32_t > mMiceIndices;
    Vector3          mLocation;
    Quaternion       mRotation;
};
```

Problems for Advanced RoboCat

The virtual **Update()** requires a virtual function table pointer:

- **Copying the value of the function table pointer is pointless.**

mName is 128 bytes, unlikely all are used:

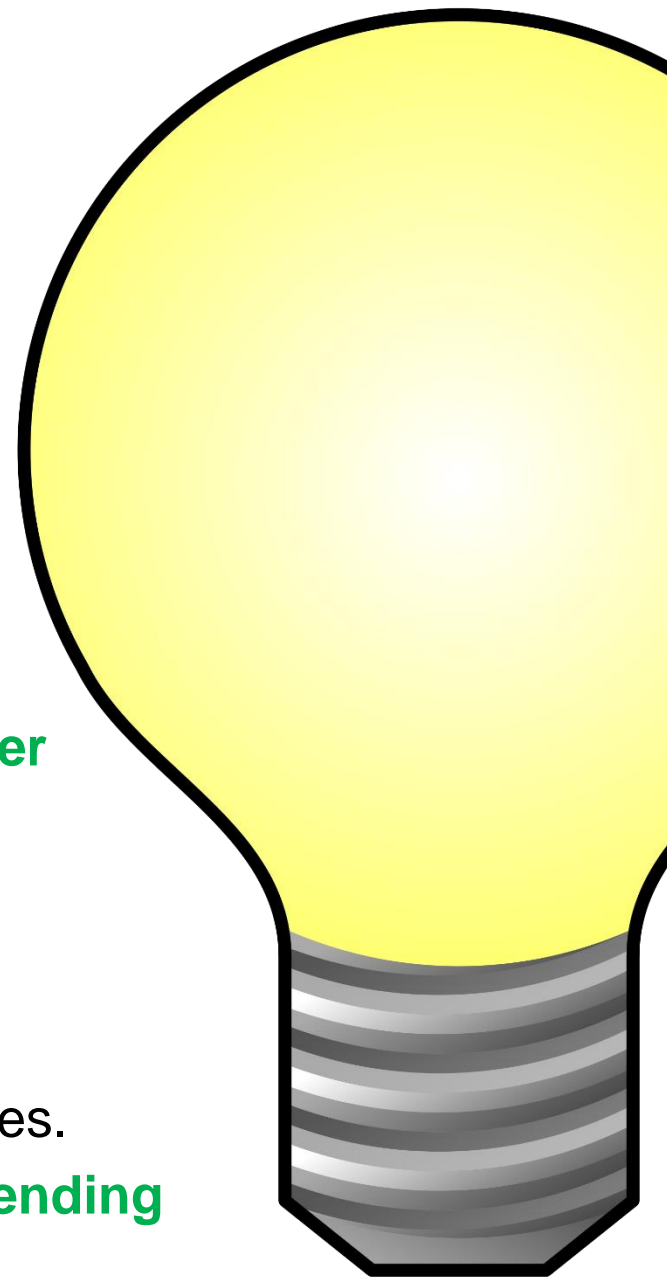
- **memcpy** will copy all 128 bytes regardless.

```
class RoboCat : public GameObject
{
public:
    RoboCat()
    {
        mName[ 0 ] = '\\0';
    }
    virtual void Update();

private:
    int32_t           mHealth;
    int32_t           mMeowCount;
    GameObject*       mHomeBase;
    char              mName[128];
    std::vector< int32_t > mMiceIndices;
    Vector3           mLocation;
    Quaternion        mRotation;
};
```

Solution

- Replicate each member variable **individually**:
 - Replicating **pointers**:
 - **Replicate the data they point to.**
 - Replicating **vectors**:
 - **replicate their size and data.**
 - Replicating objects with **virtual methods**:
 - **Replicate identifiers to hook up proper virtual function tables.**
 - Replicating **large arrays**:
 - **omit unused elements.**
 - But packets should be as big as possible:
 - Replicated variables usually < 1300 bytes.
 - **Combine member variables before sending them by serializing into a buffer.**



Custom Read and Write

```
void RoboCat::Write( OutputMemoryStream& outputStream ) const
{
    outputStream.Write( mHealth );
    outputStream.Write( mMeowCount );
    //no solution for mHomeBase yet
    outputStream.Write( mName, sizeof( mName ) );
    //no solution for mMiceIndices
    outputStream.Write( mLocation, sizeof( mLocation ) );
    outputStream.Write( mRotation, sizeof( mRotation ) );
}

void RoboCat::Read( InputMemoryStream& inputStream )
{
    inputStream.Read( mHealth );
    inputStream.Read( mMeowCount );
    //no solution for mHomeBase yet
    inputStream.Read( mName, sizeof( mName ) );
    //no solution for mMiceIndices
    inputStream.Read( mLocation, sizeof( mLocation ) );
    inputStream.Read( mRotation, sizeof( mRotation ) );
}
```

Putting It All Together

```
void SendRoboCat( int inSocket, const RoboCat* inRoboCat )
{
    OutputMemoryStream stream;
    inRoboCat->Write( stream );
    send( inSocket, stream.GetBufferPtr(),
          stream.GetLength(), 0 );
}

void ReceiveRoboCat( int inSocket, RoboCat* outRoboCat )
{
    char* temporaryBuffer =
        static_cast< char* >( std::malloc( kMaxPacketSize ) );
    int receivedByteCount =
        recv( inSocket, temporaryBuffer, kMaxPacketSize, 0 );

    if( receivedByteCount > 0 )
    {
        InputMemoryStream stream( temporaryBuffer,
                                   static_cast< uint32_t >( receivedByteCount ) );
        outRoboCat->Read( stream );
    } else {
        std::free( temporaryBuffer );
    }
}
```

Maintainability

- Read and Write for data type must remain in sync with each other:
 - Changing the order or compression in one method requires changing the other.
 - Opportunity for bugs.
- Read and Write must remain in sync with data type!
 - Adding or removing member variable
 - Changing data type of member variable
 - Including changing precision required
 - All opportunities for bugs
- **Tradeoff:** Improving maintainability can mean decreasing performance.

Referenced Data

- Pointer member variables **reference** other data.
- **Container** member variables, like **vector**, also reference other data.
- Data can be referenced by only one object, or by multiple objects:

```
class RoboCat : public GameObject
{
public:
    RoboCat ()
    {
        mName[ 0 ] = '\0';
    }
    virtual void Update();

private:
    int32_t mHealth;
    int32_t mMeowCount;
    GameObject* mHomeBase;
    char mName[128];
    std::vector< int32_t > mMiceIndices;
    Vector3 mLocation;
    Quaternion mRotation;
};
```

Problems for Advanced RoboCat

If multiple RoboCats have the same HomeBase, that HomeBase is referenced by multiple objects

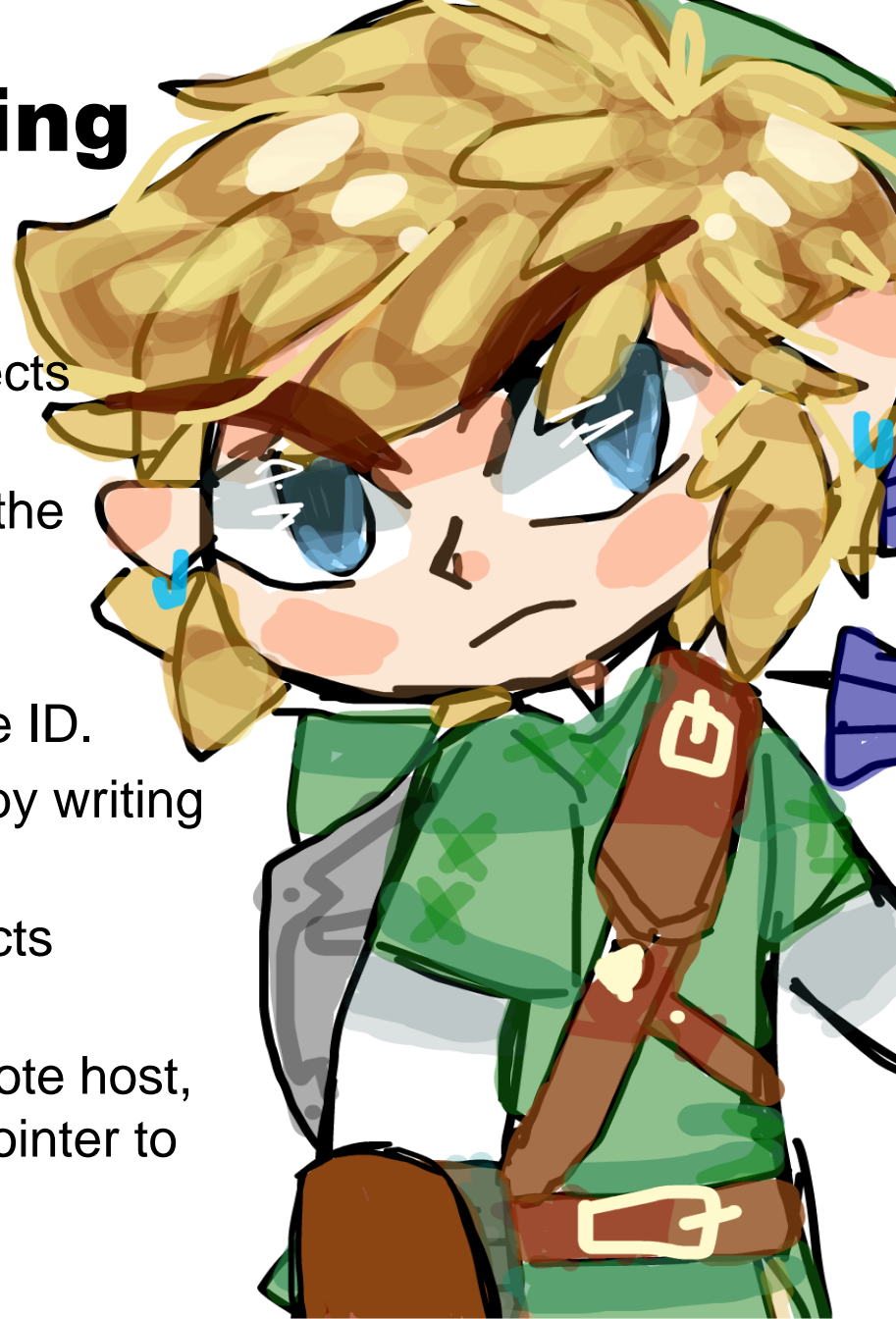
Each RoboCat has a unique vector of mice indices it is tracking; each vector is referenced/owned by only a single RoboCat.

```
class RoboCat : public GameObject
{
public:
    RoboCat()
    {
        mName[ 0 ] = '\0';
    }
    virtual void Update();

private:
    int32_t mHealth;
    int32_t mMeowCount;
    GameObject* mHomeBase;
    char mName[128];
    std::vector< int32_t > mMiceIndices;
    Vector3 mLocation;
    Quaternion mRotation;
};
```


Linking

- Data referenced by multiple objects should not be embedded:
 - Results in multiple copies of the object when deserialized.
- Use linking:
 - Assign object needs a unique ID.
 - Serialize pointers to objects by writing the object's ID:
 - Serialize referenced objects separately/earlier.
 - When deserializing on a remote host, replace an object ID with a pointer to a deserialized object.



Fixed Point

- Games use **floating-point** numbers for most math.
- Floating point numbers are 32 bits.
- Values often don't require 32 bits of precision.
 - Leave as floats for fast calculation at run time.
 - Convert to smaller precision **fixed-point** numbers during serialization.
- Fixed-point numbers are integers with an implied constant division.

Fixed-Point Example

RobotCat:mLocation

- World extends from –2000 games units to 2000 game units.
- mX and mZ position values only need to be accurate to within 0.1 game units.
- How many possible relevant values are there for mX then?
$$\frac{(\text{MaxValue} - \text{MinValue})}{\text{Precision}} + 1$$
$$\frac{(2000 - -2000)}{0.1} + 1$$
$$= 40001$$

```
class RoboCat : public GameObject
{
public:
    RoboCat()
    {
        mName[ 0 ] = '\0';
    }
    virtual void Update();

private:
    int32_t           mHealth
    int32_t           mMeowC
    GameObject*       mHomeB
    char              mName[
    std::vector< int32_t > mMiceI
    Vector3           mLocat
    Quaternion        mRotat
};
```

Fixed-Point Example

RobotCat:mLocation

$$\frac{(\text{MaxValue} - \text{MinValue})}{\text{Precision} + 1} \\ (2000 - -2000) / 0.1 + 1 = 40001$$

- There are only 40,001 possible values for mX.
- All values representable with only 16 bits.

```
class RoboCat : public GameObject
{
public:
    RoboCat()
    {
        mName[ 0 ] = '\0';
    }
    virtual void Update();

private:
    int32_t           mHealth
    int32_t           mMeowC
    GameObject*       mHomeB
    char              mName[
    std::vector< int32_t > mMiceI
    Vector3           mLocat
    Quaternion        mRotat
};
```

Bit Streams

- Not all data requires a multiple of 8 bits:
 - For example, a boolean value can be stored in a single bit!
- Bandwidth is expensive: Use as few bits as possible.
- Current streams support only byte-level precision.
- Bit Streams
 - Manager which takes in a variable and adds only the actual bits used to the stream.
 - Each time we write a value into a stream, we should be able to specify bit count.
 - Consider writing 13 as a 5-bit number and then 52 as a 6-bit number.

Chapter 3 & 4 Summary

- Explain the issues with floating point numbers
- Serialize an object with pointers
- Efficiently compress data for transmission.
- Explain the important data transmitted with an object for replication