## My Article

## Sybe van Hijum

## Today

Blablabla said Nobody [2]. Maar kees zei [1]

**Definition 1** (Timed Automata). An extended timed automaton is a 7-tuple  $A = \langle L, C, Act, s_0, \rightarrow, I_c \rangle$  where

- L is a finite set of locations, typically denoted by l
- C is in finite set of clocks, typically denoted by c
- Act is a finite set of actions
- $-s_0 \in L$  is the initial location
- $\rightarrow \subseteq L \times G(C) \times Act \times 2^C \times L$  is the (non-deterministic) transition relation. We noramlly write  $l \xrightarrow{g,a,r} l$ ' for a transition., where l is the source location, g is the guard over the clocks, a is the action, and r is the set of clocks reset.
- $I_C: L \to G(C)$  is a function mapping locations to downwards closed clock invariants.

**Definition 2** (Network of timed automata). Let  $Act = \{ch!, ch? | ch \in Chan\} \cup \{\tau\}$  be a finite set of actions, and let C be a finite set of clocks. Then the parallel composition of extended timed automata  $A_i = (L_i, C, Act, S_0^i, \rightarrow_i, I_C^i)$  for all  $1 \leq i \leq n$ , where  $n \in \mathbb{N}$ , is a network of timed automata, denoted  $A = A_1 ||A_2||...||A_n$ .

## References

[1] S. C. C. Blom, J. C. van de Pol, and M. Weber. Ltsmin: Distributed and symbolic reachability. In T. Touili, B. Cook, and P. Jackson, editors, Computer Aided Verification, Edinburgh, volume 6174 of Lecture Notes in Computer Science, pages 354–359, Berlin, July 2010. Springer Verlag.

[2] A. E. Dalsgaard, A. W. Laarman, K. G. Larsen, M. C. Olesen, and J. C. van de Pol. Multi-core reachability for timed automata. In M. Jurdzinski and D. Nickovic, editors, 10th International Conference on Formal Modeling and Analysis of Timed Systems, FORMATS 2012, London, UK, volume 7595 of Lecture Notes in Computer Science, pages 91–106, London, September 2012. Springer Verlag.