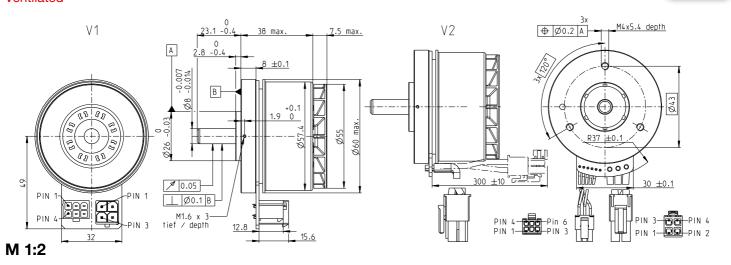
## **EC 60 flat** Ø60 mm, brushless, 200 Watt





Stock program Standard program Special program (on request)		Part Num	bers					
V1 with Hall sensors		625860	614949	625861				
V2 with Hall sensors and cables		647696	642221	647697				
Motor Data								
Values at nominal voltage								
1 Nominal voltage	V	12	24	48				
2 No load speed	rpm	3760	4300	4020				
3 No load current	mA	815	497	224				
4 Nominal speed	rpm	2790	3240	3020				
5 Nominal torque (max. continuous torque)	mNm	492	536	577				
6 Nominal current (max. continuous current)	Α	15.1	9.28	4.6				
7 Stall torque <sup>1</sup>	mNm	3340	4300	4870				
8 Stall current	Α	111	81.9	43.2				
9 Max. efficiency	%	83.8	85.2	86.3				
Characteristics								
10 Terminal resistance phase to phase	Ω	0.108	0.293	1.11				
11 Terminal inductance phase to phase	mH	0.0911	0.279	1.28				
12 Torque constant	mNm/A	30	52.5	113				
13 Speed constant	rpm/V	318	182	84.8				
14 Speed/torque gradient	rpm/mNm	1.14	1.01	0.837				
15 Mechanical time constant	ms	9.95	8.83	9.29				
16 Rotor inertia	gcm <sup>2</sup>	832	832	832				

## Comments **Specifications Operating Range** Thermal data Continuous operation n [rpm] Thermal resistance housing-ambient In observation of above listed thermal resistance 18 Thermal resistance winding-housing19 Thermal time constant winding 0.843 K/W 9.19 s (lines 17 and 18) the maximum permissible wind-7000 ing temperature will be reached during continuous 200 W 20 Thermal time constant motor 21 Ambient temperature 44 5 Ambient temperature Max. winding temperature Mechanical data (preloaded ball bearings) Max. speed Axial play at axial load operation at 25°C ambient. 22 Max. winding temperature 5000 = Thermal limit. 23 Max. speed 24 Axial play at axial load < 12.0 N > 12.0 N 4000 Short term operation 3000 The motor may be briefly overloaded (recurring). > 12.0 N 25 Radial play 26 Max. axial load (dynamic) 27 Max. force for press fits (static) (static, shaft supported) 28 Max. radial load, 5 mm from flange 2000 1000 12 N 170 N Assigned power rating 8000 N 112 N 200 3.9 600 11

Other specifications	
29 Number of pole pairs	7
30 Number of phases	3
31 Weight of motor	360 c
Values listed in the table are naminal	

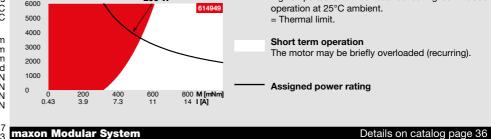
Connect	ion V1	V2 (sensors, AWG 24)
Pin 1	Hall sensor1	Hall sensor1
Pin 2	Hall sensor 2	Hall sensor 2
Pin 3	V <sub>Hall</sub> 4.524 VDC	Hall sensor 3
Pin 4	Hall sensor 3	GND
Pin 5	GND	V <sub>Hall</sub> 4.524 VDC
Pin 6	N.C.	N.C.
		<b>V2</b> (Motor, AWG 14)
Pin 1	Motor winding 1	Motor winding 1
Pin 2	Motor winding 3	Motor winding 2
Pin 3	Motor winding 2	Motor winding 3
Din 4	. 3	NC

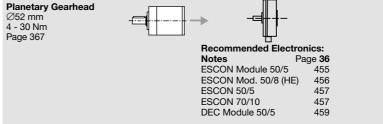
Wiring diagram for Hall sensors see p. 47 Connector Part number

43025-0600 76829-0104 Molex 171692-0104

Connection cable for V1

Connection cable Universal, L = 500 mm **651900** <sup>1</sup>Calculation does not include saturation effect (p. 57/162)





April 2019 edition / subject to change maxon EC motor 269