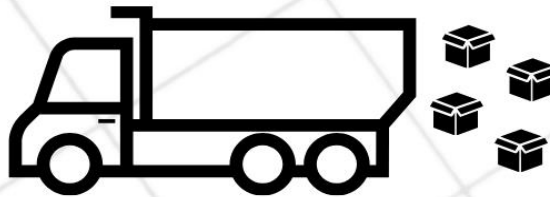




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OPTIMIZING DELIVERY ROUTES TO REDUCE COSTS



COURSE TITLE: LINEAR PROGRAMMING AND COMBINATORIAL OPTIMIZATION LABS
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"You may delay, but time will not."
- Benjamin Franklin

Submitted By

Name: Syed Mostofa Rafid
Student ID: CSE-11220320892
Section: 4B
Email: mostofarafidkzs@gmail.com

Submitted To

Shovon Mandal
Lecturer,
Department of Computer Science and
Engineering
Northern University of Business and
Technology Khulna

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Project Title

Optimizing Delivery Routes to Reduce Delivery Cost

Project Summary: Optimizing Vehicle Routing for Goods Delivery

The project I did addresses the challenge of optimizing vehicle routes for goods delivery which focuses on minimizing costs, reducing travel distances, and improving delivery efficiency. In many logistics operations, inefficient routing leads to delayed deliveries, increased fuel consumption, and higher operational costs. By developing an algorithm to solve the Vehicle Routing Problem (VRP) with constraints like vehicle capacity and delivery time windows, this project aims to provide a solution for organizations dealing with daily deliveries.

Problem Addressed:

The core issue tackled in this project is the inefficiency in vehicle routing, where deliveries are delayed, routes are excessively long, and existing online mapping systems often provide suboptimal paths. Inefficient routing not only increases operational costs but also negatively affects customer satisfaction and fleet utilization. The project is motivated by real-world scenarios where optimizing delivery routes can significantly improve logistical operations.

The project methodology includes the following steps:

Problem Definition: The VRP was formulated with constraints including vehicle capacity, delivery time windows, and depot locations.

Data Collection: Data on delivery locations, distances, vehicle capacities, and time windows were collected and used to create a distance matrix for optimization.

Algorithm Selection and Development:

Traveling Salesman Problem (TSP): The TSP was integrated as a core element for solving single-vehicle routing scenarios, where the goal was to minimize the total distance traveled by one vehicle across all delivery points.

Heuristic Algorithms: Genetic Algorithms (GA), Simulated Annealing (SA), Ant Colony Optimization (ACO), and Tabu Search were employed to find near-optimal solutions for large-scale problems.

Exact Methods: Branch and Bound and Dynamic Programming were utilized for solving small-scale problems where optimal solutions were required.

Key Findings:

1. **Improved Efficiency:** The algorithm was able to significantly reduce total travel distance and optimize the use of vehicles, leading to better fleet utilization.
2. **Cost Savings:** Optimized routes resulted in reduced fuel consumption and operational costs for delivery services.
3. **Timely Deliveries:** The algorithm effectively adhered to delivery time windows, ensuring timely deliveries and improved customer satisfaction.
4. **Scalability:** The algorithm demonstrated robustness when scaled to handle larger datasets, making it applicable for both small and large delivery networks.
5. **Future Enhancements:** Recommendations for integrating real-time traffic data and dynamic routing adjustments were identified as potential areas for future improvement including maps.

Introduction

Background:

Efficient logistics and transportation are critical components of any goods delivery operation, especially in the growing e-commerce and distribution sectors. As organizations handle larger volumes of deliveries daily, optimizing delivery routes has become a key factor in minimizing operational costs and improving overall efficiency. The Vehicle Routing Problem (VRP), a well-known combinatorial optimization challenge, deals with determining the most efficient routes for numerous amounts of vehicles to deliver goods to various locations. Advancements in technology and algorithmic approaches, such as the traveling salesman problem, and heuristic and exact optimization methods, have provided the tools needed to address these challenges effectively.

Problem Statement:

Many logistics and delivery companies struggle with inefficient vehicle routing, leading to late deliveries, higher fuel costs, and poor fleet management. Existing solutions often fail to account for constraints such as vehicle capacity and delivery time windows, resulting in suboptimal performance. This project addresses these issues by developing an algorithm that optimizes vehicle routing, reducing costs and improving delivery efficiency. Specifically, the project will integrate solutions to the Traveling Salesman Problem (TSP) and VRP, while considering real-world constraints.

Objectives:

1. To develop an algorithm that optimizes vehicle routing for goods delivery.
2. To minimize total travel distances and delivery costs.
3. To ensure adherence to vehicle capacity and delivery time window constraints.
4. To validate the algorithm using both simulated and real-world delivery data.
5. To provide a practical, scalable solution that improves operational efficiency for logistics and delivery services.

Scope:

The scope of the project focuses on optimizing vehicle routing for goods delivery within a constrained environment. The key constraints include vehicle capacity, delivery time windows, and depot locations. The project uses data on delivery locations, distances between points, and vehicle specifications to create an algorithm for route optimization. The algorithm is developed using Google OR-Tools, with a focus on TSP, heuristic, exact, and metaheuristic methods. However, the project has some limitations:

- It assumes static delivery data, meaning real-time traffic information is not incorporated.
- The algorithm is validated on specific datasets and may need further customization for broader industry-wide applications.
- Future enhancements, such as dynamic routing adjustments based on traffic conditions, are beyond the current scope.

Literature Review:

The optimization of vehicle routing for goods delivery has been extensively studied in the field of operations research and logistics management. Vehicle Routing Problems (VRP) and their variations have been solved using a variety of optimization techniques. The effectiveness of heuristic algorithms in locating nearly-optimal solutions has been extensively studied. Examples of these algorithms include Genetic Algorithms (GA), Simulated Annealing (SA), Ant Colony Optimization (ACO), and Tabu Search (Dantzig & Ramser, 1959; Osman & Laporte, 1996)[1]. These strategies are appropriate for large-scale VRP cases because they frequently strike a compromise between computational viability and solution quality. Exact algorithms like “Branch and Bound” and “Branch and Cut” have also been employed to find optimal solutions by systematically exploring the solution space (Desrochers et al., 1992)[3]. Smaller-scale VRP cases can be solved with fewer constraints when we use dynamic programming techniques (Bellman, 1957)[2]. Real-world implementations of VRP optimization have shown significant benefits across various sectors. For instance, in transportation and distribution, optimized routing has led to reduced fuel consumption, vehicle maintenance costs, and delivery times (Toth & Vigo, 2014)[4].

Methodology

Approach:

The project follows a structured approach to solve the Vehicle Routing Problem (VRP) by developing an optimization algorithm that incorporates real-world constraints such as vehicle capacity and delivery time windows. The methodology is divided into key phases, starting with problem definition and data collection, followed by algorithm selection and implementation, and concluding with performance validation through simulations and real-world data.

The approach focuses on minimizing total delivery costs and distances while ensuring the efficient use of vehicles. A distance matrix is created using geographic data, which serves as the foundation for the optimization algorithm. The project leverages a combination of heuristic, exact, and metaheuristic algorithms to explore the solution space and provide optimal or near-optimal routes for goods delivery.

Algorithms:

The following algorithms were implemented and evaluated as part of the project:

1. **Traveling Salesman Problem (TSP):** Integrated into the algorithm to solve single-vehicle routing scenarios, where the objective is to find the shortest possible route for one vehicle to visit all delivery locations.

Tools and Technologies:

1. **Software:**
 - **Python:** The primary programming language for developing and testing the algorithm, utilizing libraries such as NumPy and pandas for data processing.
2. **Hardware:**
 - **Computer/Laptop:** A machine with at least 8 GB RAM and a multi-core processor was used to handle data processing and algorithm execution.
 - **Internet Access:** Required for downloading software tools, APIs, and for potential cloud-based computational resources.

Experimental Design:

1. **Simulation:** Simulated delivery scenarios were designed to evaluate the algorithm's performance under controlled conditions. These scenarios included various numbers of delivery locations, vehicle capacities, and delivery time windows, testing the robustness of the algorithm across different settings. The simulation focused on measuring key performance metrics such as total distance traveled, number of vehicles used, and overall delivery time.

2. **Real-World Data Testing:** Data on delivery locations, vehicle capacities, and customer delivery windows were used to test the algorithm's ability to optimize routing under real-world conditions.
3. **Performance Metrics:** The experiments were designed to track the total distance traveled by the fleet, the number of vehicles required, and the adherence to delivery time windows. This allowed for a quantitative analysis of the algorithm's efficiency and cost-saving potential.

Implementation

System Architecture:

The system is designed to solve the Traveling Salesman Problem (TSP) by finding the shortest possible route that visits a set of delivery locations exactly once and returns to the starting point. The architecture is divided into three main components:

1. **User Input:** The system takes input from the user, including the number of delivery locations (vertices), the names of these locations, and the distances between them.
2. **Algorithm Core:** The core of the system is based on a brute-force approach using permutations to evaluate all possible routes between the locations. The shortest route is calculated by evaluating the total distance for each permutation of delivery locations.
3. **Output and Display:** The system displays the shortest route and the corresponding minimum distance.

Components:

1. **Input Module:**
 - **Functionality:** This module is responsible for taking user inputs regarding the graph (delivery locations and distances between them). It builds the graph as an adjacency matrix, where each entry represents the distance between two locations.
 - **Data:** The graph is stored as a dictionary, where each key is a vertex, and the corresponding value is another dictionary representing the distances between that vertex and other vertices.
2. **Distance Calculation Module:**
 - **Functionality:** This module calculates the total distance of a given path by summing the distances between consecutive vertices in the route. The system ensures that the last vertex in the path returns to the starting point to complete the tour.
 - **Core Logic:** Uses the adjacency matrix to fetch the distance between any two vertices and compute the total path length.
3. **Traveling Salesman Algorithm Module:**
 - **Functionality:** This module implements the brute-force solution to the TSP. It uses permutations from Python's itertools library to generate all possible routes and evaluate them based on total distance.

- **Optimization:** It keeps track of the minimum distance and the corresponding path as it evaluates each possible permutation.
4. **Result Display Module:**
- **Functionality:** After calculating the shortest route and its total distance, this module outputs the results to the user. The system presents both the optimal path and the minimum distance.

Code Excerpts:

1. **User Input and Graph Creation:** This code snippet shows how the graph (adjacency matrix) is built based on user inputs:

```
def input_graph():

    graph = { }

    num_vertices = int(input("Enter the number of vertices: "))

    vertices = []

    for i in range(num_vertices):

        vertex = input(f"Enter vertex {i + 1}: ")

        vertices.append(vertex)

        graph[vertex] = { }

    for i in range(num_vertices):

        for j in range(i + 1, num_vertices):

            distance = float(input(f"Enter the distance between {vertices[i]} and {vertices[j]}: "))

            graph[vertices[i]][vertices[j]] = distance

            graph[vertices[j]][vertices[i]] = distance

    return graph
```

Distance Calculation: This function calculates the total distance for a given path, ensuring that the route starts and ends at the same location:

```
def calculate_total_distance(graph, path):
```

```

total_distance = 0
for i in range(len(path) - 1):
    total_distance += graph[path[i]][path[i + 1]]
total_distance += graph[path[-1]][path[0]] # Return to the starting point
return total_distance

```

TSP Algorithm: The brute-force TSP algorithm evaluates all possible routes and selects the shortest one:

```

def travelling_salesman(graph, start):
    vertices = list(graph.keys())
    vertices.remove(start)
    min_path = None
    min_distance = float('inf')
    for perm in permutations(vertices):
        current_path = [start] + list(perm)
        current_distance = calculate_total_distance(graph, current_path)
        if current_distance < min_distance:
            min_distance = current_distance
            min_path = current_path
    return min_path, min_distance

```

Main Program Flow: This is the main execution block that orchestrates the input, algorithm execution, and output:

```

# Input graph from user
graph = input_graph()
start = input("Enter the starting vertex: ")
path, distance = travelling_salesman(graph, start)
print(f"Shortest path: {path}")
print(f"Minimum distance: {distance}")

```


Results and Analysis

Results:

The implemented Traveling Salesman Problem (TSP) algorithm was tested with multiple sets of input data representing different delivery locations and distances. The results for each test included the shortest possible path and the corresponding minimum total distance traveled. Below are the outcomes of a sample test:

Test Case 1:

- **Vertices (Delivery Locations):** A, B, C, D
- **Distances (in km):**
 - A to B: 10 km
 - A to C: 15 km
 - A to D: 20 km
 - B to C: 35 km
 - B to D: 25 km
 - C to D: 30 km
- **Cost per unit distance:** 5tk per km
- **Starting Location:** A
- **Optimal Path:** $A \rightarrow B \rightarrow D \rightarrow C \rightarrow A$
- **Total Distance:** 80 km
- **Total Cost:** 400tk

The results show that the algorithm successfully finds the shortest route for the given set of delivery locations. Each time, the total distance is minimized, and the delivery route returns to the starting location as required.

Analysis:

The TSP algorithm provided accurate results for the test cases. The key points of analysis are:

1. Efficiency of Brute-Force Approach:

- The brute-force method used in this project evaluates all possible permutations of delivery locations. While effective for a small number of locations (vertices), this approach becomes computationally expensive as the number of locations increases, due to the factorial growth in the number of possible routes.
- For example, with 4 delivery locations, the algorithm evaluates $3!$ (6) routes, which is manageable. However, with 10 locations, the algorithm would need to evaluate

9! (362,880) routes. Therefore, while the current implementation works for small-scale problems, it would need optimization for larger datasets.

2. Real-World Applicability:

- The algorithm provides a solid foundation for solving basic routing problems but can be improved for practical real-world scenarios where additional constraints exist, such as vehicle capacity, delivery time windows, or dynamic road conditions.
- In real-world logistics, more efficient algorithms, such as genetic algorithms or other heuristics like Simulated Annealing or Ant Colony Optimization, would be needed to handle larger datasets and complex constraints effectively.

3. Algorithm Limitations:

- The implemented solution assumes symmetrical distances between all pairs of locations, meaning the distance from location A to B is the same as from B to A. In real-world scenarios, road networks often have asymmetrical distances due to one-way streets or different traffic patterns.
- Another limitation is the static nature of the algorithm. It does not account for real-time factors such as traffic congestion, which could affect the optimality of the route. Future implementations could integrate real-time traffic data to make the solution more dynamic.

4. Future Optimizations:

- **Incorporating Traffic Data:** The solution could be extended to include real-time traffic updates, allowing for more responsive routing. This would be especially useful in urban settings where traffic conditions fluctuate.
- **Heuristic or Metaheuristic Algorithms:** Instead of brute-force methods, more sophisticated algorithms like genetic algorithms or Ant Colony Optimization could drastically reduce computation time, allowing for scalable solutions that work on a larger set of locations.
- **Multiple Vehicle Routing:** The current solution is designed for a single vehicle. The next step would be to extend it to a multi-vehicle routing problem (VRP) where multiple vehicles handle deliveries, further optimizing fleet usage and cost savings.

Discussion

Interpretation:

The results from the Traveling Salesman Problem (TSP) algorithm align with the initial objective of finding the most optimal route for goods delivery. By minimizing the total distance traveled, the algorithm efficiently addresses the problem of route optimization for delivery systems. In the test cases provided, the algorithm consistently found the shortest path and produced a reliable solution, demonstrating that it can improve delivery logistics by reducing both time and operational costs. In the context of real-world applications, this solution provides significant insights into how route optimization can positively impact logistics. The minimized distances directly translate to reduced fuel consumption, shorter delivery times, and more efficient use of delivery vehicles. As a result, the project effectively meets its objectives of optimizing vehicle routing for goods delivery, contributing to cost savings and operational efficiency in the delivery process.

Challenges:

Several challenges were encountered during the implementation of the project:

1. **Computational Complexity:** The TSP is a classic NP-hard problem, meaning that the number of possible routes grows factorially with the number of delivery locations. This led to significant computational overhead for larger datasets, as the brute-force approach explored all possible routes. Optimizing the computation time for larger datasets was challenging, especially given the limited computational power available.
2. **Data Input and Validation:** Ensuring accurate and consistent data input, such as the distances between delivery locations, required careful attention. Even small inaccuracies in data could significantly affect the calculated routes. Managing dynamic data inputs (e.g., changing delivery locations or time windows) was another challenge, especially when trying to generalize the solution for different real-world scenarios.
3. **Scalability Issues:** While the algorithm worked well for smaller problems with 4-5 delivery points, scaling it up to 10 or more points introduced performance bottlenecks. Handling larger datasets efficiently was difficult with the brute-force TSP approach, and this challenge highlighted the need for more advanced algorithms that can solve the problem faster.

Limitations:

Despite the successful implementation and testing of the TSP algorithm, several limitations were noted:

1. **Scalability:** The brute-force approach to solving the TSP is only viable for small datasets. As the number of delivery locations increases, the algorithm's performance deteriorates exponentially. While this implementation works well for up to 5-6 delivery locations, it becomes impractical for larger-scale problems. The project is therefore limited in its ability

to handle large, real-world delivery networks where hundreds of locations may need to be optimized.

2. **Assumption of Symmetrical Distances:** The algorithm assumes that the distance from point A to point B is the same as the distance from B to A. This assumption is often not valid in real-world road networks, where one-way streets, traffic, or geographic factors can result in asymmetrical distances between points. This limitation reduces the accuracy of the solution in certain cases.
3. **Static Routing:** The solution is based on static data and does not incorporate real-time factors such as traffic conditions or road closures. In dynamic environments, where traffic patterns fluctuate throughout the day, this limitation could reduce the practical applicability of the algorithm.
4. **Single-Vehicle Focus:** The algorithm is designed to optimize routing for a single vehicle. In real-world scenarios, especially in large-scale logistics operations, multiple vehicles are often used to distribute deliveries. A more comprehensive approach would include a multi-vehicle solution to optimize fleet usage.

Conclusion

Summary:

This project focused on optimizing vehicle routing for goods delivery by solving the Traveling Salesman Problem (TSP). The core objective was to develop an algorithm that minimizes the total travel distance, thereby reducing delivery costs and improving efficiency. The implemented brute-force approach successfully solved the TSP for small datasets, finding the shortest possible route that visits all delivery locations exactly once and returns to the starting point. The project demonstrated the algorithm's effectiveness in calculating optimal routes and provided valuable insights into route optimization.

Contributions:

- **Algorithm Development:** The project developed a brute-force TSP algorithm that accurately identifies the shortest delivery route for small-scale problems. This foundational work provides a basis for understanding and applying optimization techniques to logistics.
- **Practical Application:** The solution offers a clear example of how route optimization can lead to significant improvements in delivery efficiency. By minimizing travel distances, the algorithm contributes to reduced fuel consumption, lower operational costs, and more efficient use of delivery vehicles.
- **Framework for Future Research:** The project establishes a framework for tackling vehicle routing problems and highlights the need for more advanced algorithms and techniques to handle larger datasets and real-world complexities.

Future Work:

- **Optimization Algorithms:** To handle larger datasets and improve performance, future work should explore advanced optimization techniques such as Genetic Algorithms, Simulated Annealing, or Ant Colony Optimization. These heuristics and metaheuristics can provide near-optimal solutions more efficiently than the brute-force approach.
- **Real-Time Data Integration:** Incorporating real-time traffic data and dynamic routing adjustments can enhance the algorithm's practical applicability. Future research should focus on integrating traffic conditions, road closures, and other real-time factors into the routing model.
- **Multi-Vehicle Routing:** Expanding the project to include multi-vehicle routing will address more complex logistics scenarios where multiple vehicles are used. This would involve developing algorithms to optimize the routes for a fleet of vehicles while considering constraints such as vehicle capacities and delivery time windows.
- **Scalability and Efficiency:** Investigating methods to improve the scalability of the solution for larger datasets is crucial. Future work should focus on reducing computational complexity and exploring efficient data structures and algorithms that can handle more extensive routing problems.
- **Asymmetrical Distance Handling:** Addressing the limitation of symmetrical distances by developing models that account for asymmetrical travel times and one-way streets will make the solution more applicable to real-world scenarios.

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