

## k224413 Syeda Fakhira Saghir - Lab 2

Q1

```
class Environment:
    def __init__(self):
        # components are a part of the environment
        import random
        # 0 VULNERABLE 1 SAFE
        # critical components
        self.components=['A','B','C','D','E','F','G','H','I']
        self.vulnerability=[]
        for i in range(len(self.components)):
            self.vulnerability.append(random.randint(0,1))
            if self.vulnerability[i]==1:
                print(f'component {self.components[i]} is safe ✓' )
            else :
                print(f'component {self.components[i]} is vulnerable ⚠')

class SecurityAgent:
    def __init__(self):
        self.patch_list=[]
        pass

    def scanComponent(self,percept,component):
        if percept == 1:
            print("warning! vulnerable component detected ⚠")
            self.patch_list.append(component)
        else:
            print("success! component is safe ✓")

    def patchComponents(self, Env):
        for component in self.patch_list:
            print(f'patching {component}')
            index = env.components.index(component)
            env.vulnerability[index] = 0
            print(f'patched {component}')

def run_agent(agent, env):
    for i in range(len(env.components)):
```

```

    agent.scanComponent(env.vulnerability[i],env.components[i])
agent.patchComponents(env)

```

```

agent = SecurityAgent()
env= Environment()
run_agent(agent,env)
for i in range(len(env.components)):
    if env.vulnerability[i]==1:
        print(f'component {env.components[i]} is unsafe ⚠')
    else:
        print(f'component {env.components[i]} is safe ✓')

```

```

...else:
    print(f'component {env.components[i]} is safe ✓')

```

```

component A is safe ✓
component B is safe ✓
component C is safe ✓
component D is vulnerable ⚠
component E is safe ✓
component F is vulnerable ⚠
component G is safe ✓
component H is vulnerable ⚠
component I is vulnerable ⚠
warning! vulnerable component detected ⚠
warning! vulnerable component detected ⚠
warning! vulnerable component detected ⚠
success! component is safe ✓
warning! vulnerable component detected ⚠
success! component is safe ✓
warning! vulnerable component detected ⚠
success! component is safe ✓
success! component is safe ✓
patching A
patched A
patching B
patched B
patching C
patched C
patching E
patched E
patching G
patched G
component A is safe ✓
component B is safe ✓
component C is safe ✓
component D is safe ✓
component E is safe ✓
component F is safe ✓
component G is safe ✓
component H is safe ✓
component I is safe ✓

```

Q2

# Q2

```

class Environment:
    def update_servers(self):
        for i in range(len(self.tasks)):
            if self.tasks[i] <= 4:
                self.servers[i]="Underloaded"
            elif self.tasks[i]>=6:
                self.servers[i]="Overloaded"
            else:
                self.servers[i]="Balanced"

    def __init__(self, n):
        self.tasks={}
        self.servers = {}
        import random
        for i in range(n):
            self.tasks[i]=random.randint(0,10)
        self.update_servers()

    def get_percept(self):
        return self.servers

class LoadBalancerAgent:
    def __init__(self):
        pass

    def balanceLoad(self, env):
        for i in range(len(env.servers)):
            if env.servers[i] == "Overloaded":
                balanced = False
                for j in range(len(env.servers)):
                    if env.servers[j] == "Underloaded" and i != j:
                        transfer = min(env.tasks[i] - 6, 4 -
env.tasks[j])+1

                        if transfer > 0:
                            env.tasks[i] -= transfer
                            env.tasks[j] += transfer
                            env.update_servers()
                            print(f"{transfer} tasks are transferred from
server {i} to server {j}")
                            balanced = True

```

```
        if env.servers[i] != "Overloaded":
            break
    if not balanced:
        print(f"Balancing not possible at the moment for server
{i}")

def runAgent(agent, env):
    print(f"servers before balancing \n{env.servers}\n")
    print(f"tasks before balancing \n{env.tasks}\n")
    agent.balanceLoad(env)
    print(env.servers)
    print(f"servers after balancing \n{env.servers}\n")
    print(f"tasks after balancing \n{env.tasks}\n")

env = Environment(5)
agent = LoadBalancerAgent()
runAgent(agent, env)
```

```
agent = LoadBalancerAgent()
runAgent(agent, env)
```

```
servers before balancing
{0: 'Underloaded', 1: 'Underloaded', 2: 'Underloaded', 3: 'Overloaded', 4: 'Overloaded'}
```

```
tasks before balancing
{0: 0, 1: 2, 2: 2, 3: 10, 4: 8}
```

```
5 tasks are transferred from server 3 to server 0
3 tasks are transferred from server 4 to server 1
{0: 'Balanced', 1: 'Balanced', 2: 'Underloaded', 3: 'Balanced', 4: 'Balanced'}
servers after balancing
{0: 'Balanced', 1: 'Balanced', 2: 'Underloaded', 3: 'Balanced', 4: 'Balanced'}
```

```
tasks after balancing
{0: 5, 1: 5, 2: 2, 3: 5, 4: 5}
```

```
runAgent(agent, env)
```

```
↩ servers before balancing
{0: 'Overloaded', 1: 'Overloaded', 2: 'Balanced', 3: 'Overloaded', 4: 'Underloaded'}
```

```
tasks before balancing
{0: 9, 1: 9, 2: 5, 3: 8, 4: 2}
```

```
3 tasks are transferred from server 0 to server 4
Balancing not possible at the moment for server 1
Balancing not possible at the moment for server 3
{0: 'Overloaded', 1: 'Overloaded', 2: 'Balanced', 3: 'Overloaded', 4: 'Balanced'}
servers after balancing
{0: 'Overloaded', 1: 'Overloaded', 2: 'Balanced', 3: 'Overloaded', 4: 'Balanced'}
```

```
tasks after balancing
{0: 6, 1: 9, 2: 5, 3: 8, 4: 5}
```

### Q3

```
class environment:
    def __init__(self,n):
        self.tasks={}
        import random
        for i in range(n):
            self.tasks[i]=random.choice(["Completed","Failed"])

    def get_percept(self):
        return self.tasks

class BackupManagementAgent:
    def __init__(self):
        pass

    def retryFailedTasks(self, env):
```

```

for i in range(len(env.tasks)):
    if env.tasks[i] == "Failed":
        env.tasks[i] = "Completed"
        print(f"Task {i} is completed ✅")
    else:
        print(f"Task {i} is already completed ⚠️")

def runAgent(agent, env):
    print(f"tasks before retrying \n{env.tasks}\n")
    agent.retryFailedTasks(env)
    print(f"tasks after retrying \n{env.tasks}\n")

env=environment(10)
agent=BackupManagementAgent()
runAgent(agent,env)

tasks before retrying
{0: 'Completed', 1: 'Failed', 2: 'Failed', 3: 'Failed', 4: 'Completed', 5: 'Failed', 6: 'Completed', 7: 'Completed', 8: 'Completed', 9: 'Completed'}

Task 0 is already completed ⚠️
Task 1 is completed ✅
Task 2 is completed ✅
Task 3 is completed ✅
Task 4 is already completed ⚠️
Task 5 is completed ✅
Task 6 is already completed ⚠️
Task 7 is already completed ⚠️
Task 8 is already completed ⚠️
Task 9 is already completed ⚠️
tasks after retrying
{0: 'Completed', 1: 'Completed', 2: 'Completed', 3: 'Completed', 4: 'Completed', 5: 'Completed', 6: 'Completed', 7: 'Completed', 8: 'Completed', 9: 'Comple

```

#### Q4

```

# Task # 4 (utility based agent)
# A cybersecurity exercise is being conducted for a company's security
system, which consists
# of nine critical components (A through I). Each component of the system
can either be Safe
# or have Vulnerabilities of varying severity. The company wants to ensure
that its system
# remains secure, but it only has access to a basic security service that
can patch Low Risk
# Vulnerabilities. High Risk Vulnerabilities require purchasing a premium
security service to
# patch.
# In this scenario, the goal is to simulate how a Utility-Based Security
Agent scans and
# patches the system based on the vulnerabilities detected and the
available resources

```

```
# (limited patching service).
# • Initial System Check:
# ◦ Initialize the system environment with random vulnerabilities (Safe,
Low Risk
# Vulnerable, and High Risk Vulnerable).
# ◦ Display the initial state of the system, showing which components are
Safe
# and which have Vulnerabilities.
```

```
# • System Scan:
# ◦ The security agent will scan each component.
# ◦ If a component is Vulnerable, the agent logs a warning.
# ◦ If it is Safe, a success message is logged.
# • Patching Vulnerabilities:
# ◦ The agent will patch all Low Risk Vulnerabilities.
# ◦ The agent will log a message for High Risk Vulnerabilities indicating
the need
# for premium service to patch them.
```

```
# • Final System Check:
# ◦ Display the system's final state to confirm that all Low Risk
Vulnerabilities
# have been patched.
# ◦ The High Risk Vulnerabilities will remain unresolved unless the
premium
# service is purchased.
```

```
class Environment:
    def displayEnvironment(self):
        for i in range(len(self.components)):
            if self.vulnerability[i]=='Safe':
                print(f'{self.components[i]} : safe ✓' )
            elif self.vulnerability[i]=='Low Risk Vulnerable':
                print(f'{self.components[i]} : Low Risk Vulnerable ⚠')
            else:
                print(f'{self.components[i]} : High Risk Vulnerable ✖')
    def __init__(self):
        # components are a part of the environment
        import random
        # 0 VULNERABLE 1 SAFE
```

```

# critical components
self.components=['A','B','C','D','E','F','G','H','I']
self.vulnerability={}
for i in range(len(self.components)):
    self.vulnerability[i]=random.choice(['Safe', 'Low Risk Vulnerable',
"High Risk Vulnerable"])
self.displayEnvironment()

class SecurityAgent:
    def __init__(self):
        self.patch_list=[]
        pass

    def scanComponent(self,env):
        for i in range(len(env.components)):
            if env.vulnerability[i]=='Safe':
                print(f'success {env.components[i]} is safe ✅' )
            elif env.vulnerability[i]=='Low Risk Vulnerable':
                print(f'warning!! component {env.components[i]} is Low Risk
Vulnerable ⚠️')
                self.patch_list.append(env.components[i])
            else:
                print(f'WARNING!!!! component {env.components[i]} is High Risk
Vulnerable ❌')
                self.patch_list.append(env.components[i])

    def patchComponents(self, env):
        for i in range(len(env.components)):
            if env.vulnerability[i]=='Low Risk Vulnerable':
                print(f'patching {env.components[i]} \n patched
{env.components[i]}')
                env.vulnerability[i]=='Safe'
            else:
                print(f'premium service needed to patch {env.components[i]}')

    def final_check(self,env):
        for i in range(len(env.components)):
            if env.vulnerability[i]=='Safe':
                print(f'{env.components[i]} is safe ✅' )

```



```

        elif env.vulnerability[i]=='Low Risk Vulnerable':
            print(f'component {env.components[i]} is Low Risk Vulnerable and
has not been patched')

        else:
            print(f'WARNING!!!! component {env.components[i]} needs premium
service')

def runAgent(agent, env):
    for i in range(len(env.components)):
        agent.scanComponent(env)
        agent.patchComponents(env)

agent = SecurityAgent()
env= Environment()
runAgent(agent,env)
for i in range(len(env.components)):
    if env.vulnerability[i]==1:
        print(f'component {env.components[i]} is unsafe ⚠')
    else:
        print(f'component {env.components[i]} is safe ✓')

```

```

A : High Risk Vulnerable ❌
B : High Risk Vulnerable ❌
C : Low Risk Vulnerable ⚠️
D : Low Risk Vulnerable ⚠️
E : High Risk Vulnerable ❌
F : Low Risk Vulnerable ⚠️
G : Low Risk Vulnerable ⚠️
H : Low Risk Vulnerable ⚠️
I : safe ✓

WARNING!!!! component A is High Risk Vulnerable ❌
WARNING!!!! component B is High Risk Vulnerable ❌
warning!! component C is Low Risk Vulnerable ⚠️
warning!! component D is Low Risk Vulnerable ⚠️
WARNING!!!! component E is High Risk Vulnerable ❌
warning!! component F is Low Risk Vulnerable ⚠️
warning!! component G is Low Risk Vulnerable ⚠️
warning!! component H is Low Risk Vulnerable ⚠️
success I is safe ✓

WARNING!!!! component A is High Risk Vulnerable ❌
WARNING!!!! component B is High Risk Vulnerable ❌
warning!! component C is Low Risk Vulnerable ⚠️
warning!! component D is Low Risk Vulnerable ⚠️
WARNING!!!! component E is High Risk Vulnerable ❌
warning!! component F is Low Risk Vulnerable ⚠️
warning!! component G is Low Risk Vulnerable ⚠️
warning!! component H is Low Risk Vulnerable ⚠️
success I is safe ✓

WARNING!!!! component A is High Risk Vulnerable ❌
WARNING!!!! component B is High Risk Vulnerable ❌
warning!! component C is Low Risk Vulnerable ⚠️
warning!! component D is Low Risk Vulnerable ⚠️
WARNING!!!! component E is High Risk Vulnerable ❌
warning!! component F is Low Risk Vulnerable ⚠️
warning!! component G is Low Risk Vulnerable ⚠️
warning!! component H is Low Risk Vulnerable ⚠️

```

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```
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```

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✓ 0s completed at 15:36

```
1s warning!! component D is Low Risk Vulnerable Δ
WARNING!!!! component E is High Risk Vulnerable X
warning!! component F is Low Risk Vulnerable Δ
warning!! component G is Low Risk Vulnerable Δ
warning!! component H is Low Risk Vulnerable Δ
success I is safe ✓
premium service needed to patch A
premium service needed to patch B
patching C
  patched C
patching D
  patched D
premium service needed to patch E
patching F
  patched F
patching G
  patched G
patching H
  patched H
premium service needed to patch I
component A is safe ✓
component B is safe ✓
component C is safe ✓
component D is safe ✓
component E is safe ✓
component F is safe ✓
component G is safe ✓
component H is safe ✓
component I is safe ✓
```

## Q5

```
#Task # 5 (Goal based agent)
# In a hospital, a delivery robot is tasked with delivering medicines to
patients, assisting
# nurses, and performing other related activities in an efficient manner.
The goal of the robot is
# to automatically move through hospital corridors, pick up medicines,
deliver them to the
# correct patient rooms, and perform various tasks such as scanning
patient IDs or alerting
# staff.
# • Components:
# ○ Agent: The hospital delivery robot, which can move around, interact
with
# patient rooms, pick up medicines, deliver them, and alert nurses or
doctors
# when needed.
# • Environment: The hospital layout, including:
```

```

# ○ Corridors
# ○ Patient rooms
# ○ Nurse stations
# ○ Medicine storage areas
# ● Actions:
# ○ Move to a location (room, station, etc.).
# ○ Pick up medicine from storage.
# ○ Deliver medicine to the patient's room.
# ○ Scan patient ID for verification.
# ○ Alert staff for critical situations.
# ● Perceptions:
# ○ Room numbers (where the robot should deliver the medicine).
# ○ Patient schedules (timing for when patients need their medicines).
# ○ Medicine type (specific medicines to be delivered to patients).
# ○ Staff availability (alerts if staff assistance is needed).
# Goal-Based Agent Approach:
# Goal: Deliver medicine to patients based on a schedule and room number,
while ensuring all
# deliveries are correctly made. The robot must scan the patient's ID
before delivering and
# alert nurses or doctors if needed.
import random

class Environment:
    def __init__(self):
        self.locations = ['Corridor', 'Medicine Storage', 'Nurse Station',
'room_1', 'room_2', 'room_3']
        self.patients = {
            'room_1': {'id': 'P1', 'medicine': 'panadol', 'schedule': '1:00
AM'},
            'room_2': {'id': 'P2', 'medicine': 'Arinac', 'schedule': '2:00
PM'},
            'room_3': {'id': 'P3', 'medicine': 'Softin', 'schedule': '11:00
AM'}
        }
        self.staffAvaliability = random.choice([True, False])

    def getInfo(self, roomKey):
        return self.patients.get(roomKey)

```

```

class Agent:
    def __init__(self):
        self.location = 'Medicine Storage'
        self.medicineToDeliver = None

    def move(self, destination):
        print(f"moving from {self.location.replace('_', ' ')} to {destination.replace('_', ' ')}")
        self.location = destination

    def collectMedicine(self, medicine):
        if self.location == 'Medicine Storage':
            self.medicineToDeliver = medicine
            print(f"collected {medicine}.")
        else:
            print("medicine unavailable. go to medicine storage.")

    def verifyPatient(self, expectedId):
        print(f"scanned patient id: {expectedId}.")
        return True # assuming successful verification for now

    def deliverMedicine(self, room, patientInfo):
        if self.location == room:
            if self.verifyPatient(patientInfo['id']):
                if self.medicineToDeliver == patientInfo['medicine']:
                    print(f"successfully delivered {self.medicineToDeliver} to {self.location.replace('_', ' ')} ✅")
                    self.medicineToDeliver = None
                else:
                    print(f"carrying the wrong medicine. expected {patientInfo['medicine']} ❌")
            else:
                print("id mismatch! ❌")
        else:
            print("wrong room 🚫")

def runAgent(agent, env):
    for room, patientInfo in env.patients.items():
        agent.move('Medicine Storage')
        agent.collectMedicine(patientInfo['medicine'])

```

```

agent.move(room)
if not env.staffAvailability:
    print("alert! assistance required from medical staff ⚠")
agent.deliverMedicine(room, env.getInfo(room))

env = Environment()
agent = Agent()
runAgent(agent, env)

```

```

➡ moving from Medicine Storage to Medicine Storage
   collected panadol.
   moving from Medicine Storage to room 1
   scanned patient id: P1.
   successfully delivered panadol to room 1 ✓
   moving from room 1 to Medicine Storage
   collected Arinac.
   moving from Medicine Storage to room 2
   scanned patient id: P2.
   successfully delivered Arinac to room 2 ✓
   moving from room 2 to Medicine Storage
   collected Softin.
   moving from Medicine Storage to room 3
   scanned patient id: P3.
   successfully delivered Softin to room 3 ✓

```

Q6

```

import random

class Environment:
    def __init__(self):
        self.rooms={}
        self.status={}

    def initialize(self):
        charr='a'
        print("+++++++ initial state of rooms ++++++\n")
        for i in range(3):

```

```

self.rooms[i] = {}
self.status[i]={}
for j in range(3):
    self.rooms[i][j]= charr
    if self.rooms[i][j] in ('a', 'b', 'd', 'f', 'g', 'h'):
        self.status[i][j]='safe'
    else:
        self.status[i][j]='fire'
print(charr + ' ' + self.status[i][j]+ '\n')

    charr=chr(ord(charr)+1)
def displayEnvironment(self):
    print("+++++++____ Displaying Environment ____+++++\n")
    for i in range(3):
        for j in range(3):
            print('\n',self.status[i][j], self.rooms[i][j] , end=' ')
        print()

def get_percept(self):
    return self.rooms, self.status

class Agent:
    def __init__(self):
        pass
    def put_out_fire(self, env):
        for i in range(3):
            for j in range(3):
                if env.status[i][j]=='fire':
                    print(f'fire in room {env.rooms[i][j]} 🔥! extinguishing fire
now 🧯')
                    env.status[i][j]='safe'
                else:
                    print(f'no fire in room {env.rooms[i][j]} ✅')
            env.displayEnvironment()

def runAgent(agent, env):
    env.initialize()
    agent.put_out_fire(env)

env= Environment()

```

```
agent=Agent()  
runAgent(agent,env)
```

```
▶ ++++++ initial state of rooms ++++++  
⇒ a safe  
  b safe  
  c fire  
  d safe  
  e fire  
  f safe  
  g safe  
  h safe  
  i fire  
  
no fire in room a ✓  
+++++__ Displaying Environment __+++++  
  
safe a,safe b,fire c,  
safe d,fire e,safe f,  
safe g,safe h,fire i,  
no fire in room b ✓  
+++++__ Displaying Environment __+++++  
  
safe a,safe b,fire c,  
safe d,fire e,safe f,  
safe g,safe h,fire i,  
fire in room c 🔥 ! extinguishing fire now 🧯  
+++++__ Displaying Environment __+++++  
  
safe a,safe b,safe c,  
safe d,fire e,safe f,  
safe g,safe h,fire i,  
no fire in room d ✓  
+++++__ Displaying Environment __+++++
```