

CS440

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Book: Data & Communication, 10th Ed.

William Stallings

- Digital signal has defined levels (F3.1)

- Sin wave $v(t) = A \sin(2\pi ft + \phi)$

f : freq
 t : time

A : amplitude, max value of amplitude the $v(t)$ can take.

$$v(t) = A \sin(2\pi + 2\pi ft + \phi)$$

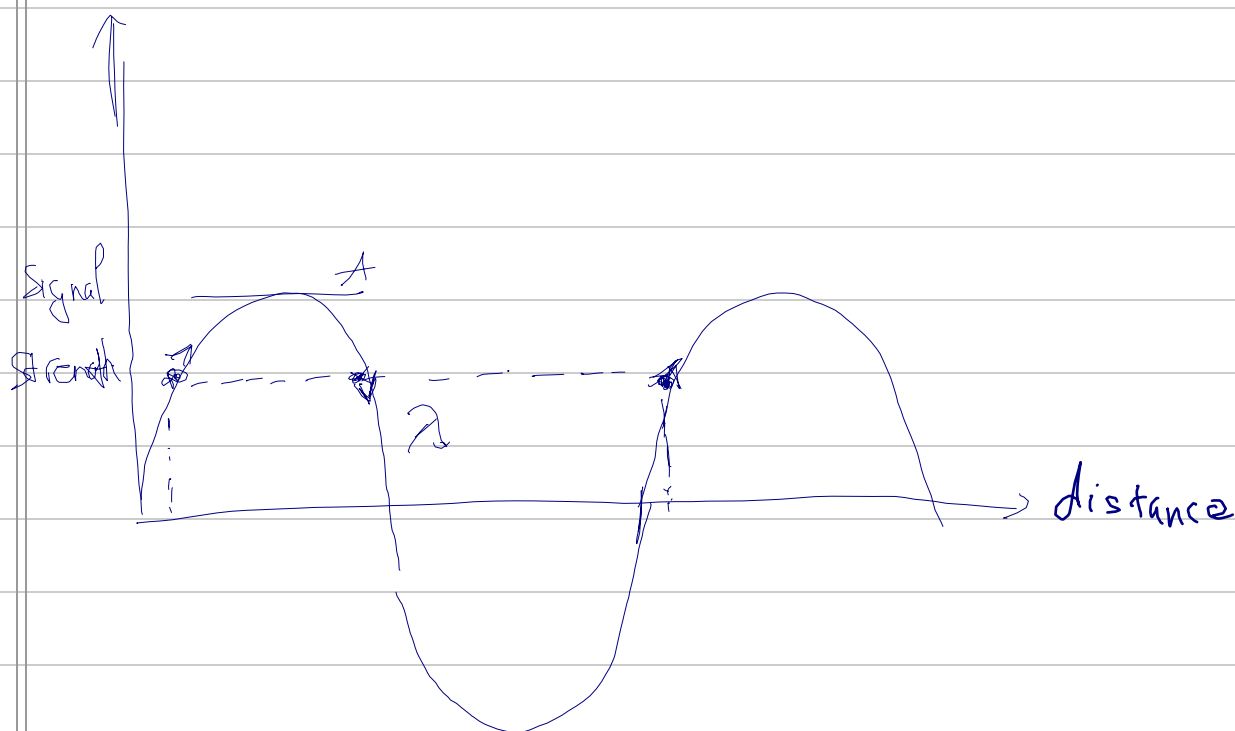
$$= A \sin\left(2\pi f\left(t + \frac{1}{f}\right) + \phi\right)$$

$$= A \sin(2\pi f(t + T) + \phi) \Rightarrow T = \frac{1}{f}$$

$$= A \sin(\omega t + \phi)$$

\uparrow
phase

$\omega = 2\pi f$



C440

May 28th

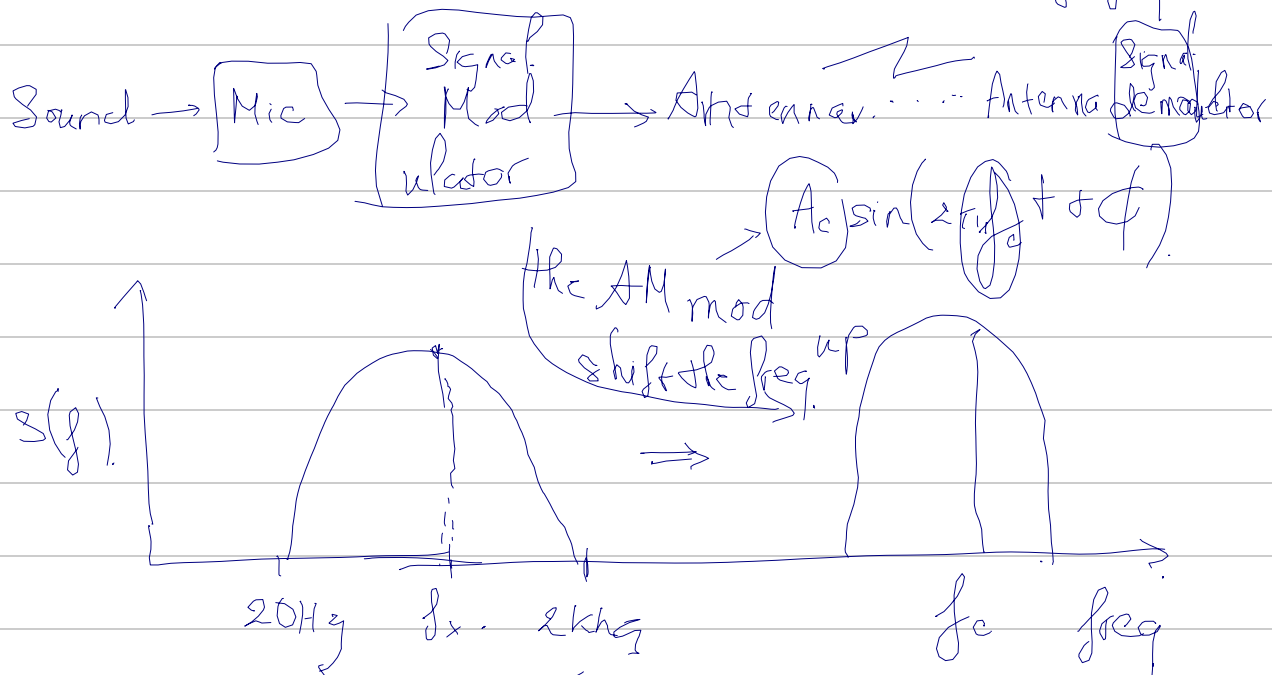
2015

Digital transceiver: converts from 1 digital logic to another logic (voltage, etc.), or act as a repeater.
(Fig 3.13)

Analog signal.

Analog data (1) singing thru mic in the concert
(2) the radio tower mod/demod.

LPF: truncate the high freq.



humanly hearable

- reduce noise

- small antenna

Method 1

8V

$f = 3.5\text{kHz}$ ① Amplitude, same freq, same phase

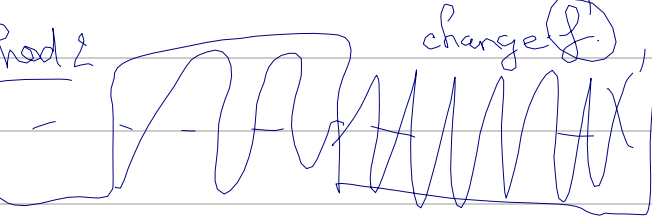
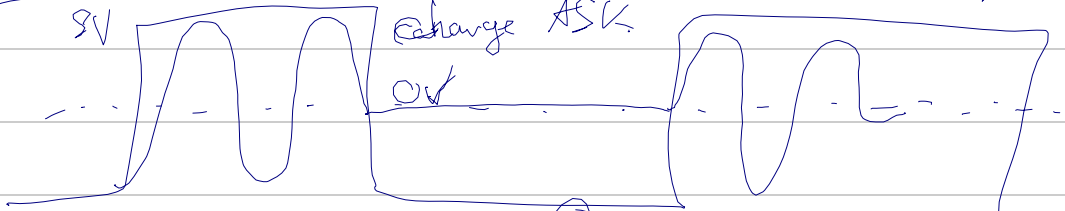
change ASK

0V

Method 2

change f

same amplitude, same phase



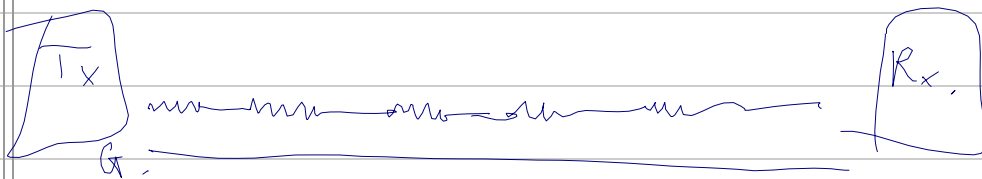
Method 3 phase is changed, same amplitude, same freq.



Asynchronous : example : internet

Synchronous example : TCP/IP

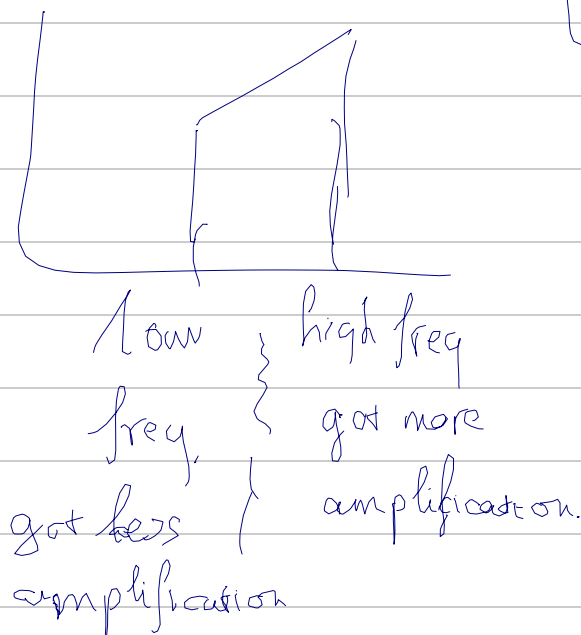
Attenuation:



Prob {
 - going thru a list of capacitors reduce signal strength
 - high freq becomes low freqs.
 - low — does not reach the Rx or lower than noise signal.

Sol use amplifier/equalizer

testing 123



white noise : multiple freqs combined.

stop at Categories of Noise.

pmp 2wfg

classmate, quizmzc.

quiz next of next week

Sun 11th

Sender



$n-k$ bit ($E = f(\text{data})$)

— generate checksum.



Receiver.



regenerate E & compare with
the sender's E

Parity Check:

Data

Parity (even) \rightarrow counting number of 1s in the data.

1101
↑ ↑ ↑

1

even - even : 0

odd - odd : 0

otherwise : 1

0011

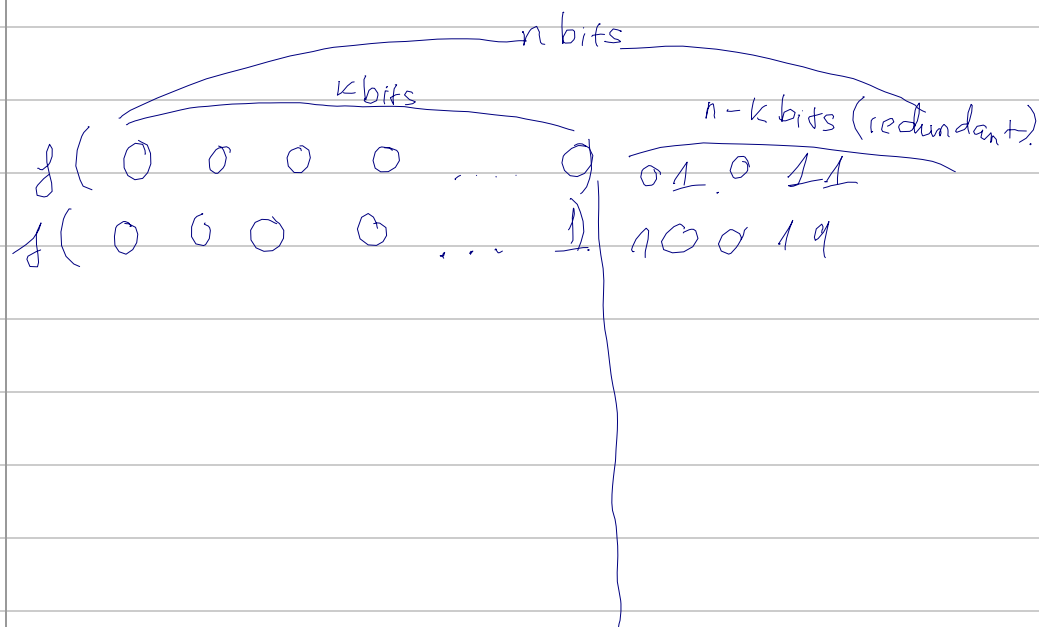
0

0000

0

Can't detect if 2-4-6-8 bit are inverted.

Data k -bit



Data

Redundant

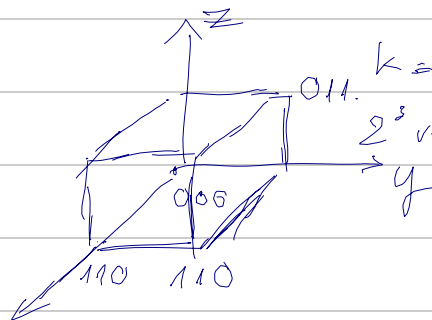
$$E = f(\text{data})$$

$$E' = f(\text{data}')$$

if $E \neq E'$ when $\text{Data} \neq \text{Data}'$

$\forall \text{ Data}$

$$k=3$$



$$k=3 \Rightarrow \text{if } k=3$$

2^3 vertices

each vertex is a msg.

2^k vertices.

$$\text{if } n \rightarrow 2^n \text{ vertices}$$

Error detection is always used but error correction is not widely used bec of its complexity in implementation & does not guarantee if the correction is 100% successful.

