# 人工智能基础 实验一

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### 【实验目的】

在给出的代码框架上完成吃豆人游戏的决策过程, 需要完成静态目标下的广度优先搜索与 A\* 搜索算法实现 寻找食物,在此基础上更进一步在多 agent 环境中实现 MaxMin 算法与 $\alpha-eta$ 剪枝,吃完所有食物同时避开鬼。

## 【实验内容】

本次实验有 2 个部分,分别是 Search 和 Multiagent。具体而言, Search 的目标是吃豆人仅仅是寻找食物; Multiagent 的目标是吃完所有食物,同时避开鬼。抽象而言,Search 实现的静态查找算法,Multiagent 的问题 是在有对手的情况下做出下一步决策使自己的利益最大化。Search 部分需要实现 BFS 算法和 A\*算法。Multiagent 部分需要实现 minimax 算法和 alpha-beta 剪枝。

#### 【实验过程】

一 、BFS 算法实现静态搜索食物。只需将给出的深度优先搜索代码中的栈结构改为普通队列结构。 伪代码如下所示:

```
function BREADTH-FIRST-SEARCH(problem) returns a solution, or failure
  node \leftarrow a \text{ node with STATE} = problem.INITIAL-STATE, PATH-COST = 0
  if problem.GOAL-TEST(node.STATE) then return SOLUTION(node)
  frontier -- a FIFO queue with node as the only element
  explored +- an empty set
  loop do
     if EMPTY?(frontier) then return failure
     node ←- POP(frontier) /* chooses the shallowest node in frontier */
     add node.STATE to explored
     for each action in problem.ACTIONS(node.STATE) do
         child -- CHILD-NODE(problem, node, action)
         if child.STATE is not in explored or frontier then
            if problem.GOAL-TEST(child.STATE) then return SOLUTION(child)
            frontier -- INSERT(child, frontier)
```

图 3.11 图的宽度优先搜索

将其写为 python 代码:

```
def myBreadthFirstSearch(problem):
   # YOUR CODE HERE
   visited = {} #存储访问过的节点
   frontier = util.Queue() #队列结构存储待访问节点
   frontier.push((problem.getStartState(), None))
   while not frontier.isEmpty(): #还有待访问节点时继续
      #取出下一步访问的节点,判断是否为目标节点,返回或扩展
      state, prev state = frontier.pop()
      if problem.isGoalState(state): #找到目标节点, 返回
         solution = [state]
         while prev state != None:
            solution.append(prev state)
            prev state = visited[prev state]
         return solution[::-1]
      if state not in visited:
                               #在BFS下,拓展该节点
         visited[state] = prev state
         for next state, step cost in problem.getChildren(state):
            frontier.push((next_state, state))
   return []
```

二、实现  $A^*$  静态搜索算法。和BFS类似,存储待访问节点的数据结构为优先队列,权值为 $g_n + h_n$ ,g 存储 从起始节点开始到当前待访问而未访问节点的实际消耗,在将某个节点插入优先队列的时刻生成。从优先队列取 出数据时每个节点都已经有 $g_n$ 域。

```
def myAStarSearch (problem, heuristic): #预估函数 h 已经从外部给出,调用即可
   # YOUR CODE HERE
   visited = {} #已访问节点列表
   frontier = util.PriorityQueue() #优先队列存储待访问节点
  frontier.__init__()
   #优先队列结构:同时插入状态与权值,权值为 g+h,初始节点 g=0
   frontier.push(((problem.getStartState(),0), (None,0)),
                             0 + heuristic(problem.getStartState()))
   while not frontier.isEmpty():
      (state,g), (prev_state,prev_g) = frontier.pop()
      #与 BFS 类似,从优先队列中取出下个待访问的节点,判断是否为目标,返回或扩展它
      if problem.isGoalState(state):
         solution = [state]
         while prev state != None:
            solution.append(prev_state)
            prev state = visited[prev state]
         return solution[::-1]
      #扩展节点,同时将 gn 值赋予即将插入优先队列的待访问节点
      if state not in visited:
         visited[state] = prev state
         for next_state, step_cost in problem.getChildren(state):
            next_g = g + step_cost
            frontier.push(((next_state,next_g), (state,g)),
                           next g + heuristic(next state))
   return []
```

三、极小极大算法实现多 agent 环境中的动态决策。伪代码如下所示:

```
function MINIMAX-DECISION(state) returns an action return arg max_a \in ACTIONS(s) MIN-VALUE(RESULT(state, a))

function MAX-VALUE(state) returns a utility value if Terminal-Test(state) then return Utility(state) v \leftarrow -\infty for each a in ACTIONS(state) do v \leftarrow MAX(v, MIN-VALUE(RESULT(s, a))) return v

function MIN-VALUE(state) returns a utility value if Terminal-Test(state) then return Utility(state) v \leftarrow \infty for each a in ACTIONS(state) do v \leftarrow MIN(v, MAX-VALUE(RESULT(s, a))) return v
```

图 5.3 极小极大值决策算法

本次实验中还需要实现同时返回下一步最佳的状态,只需要在 child 中找出 max 或 min 的同时将对应的状态记录下来即可。代码如下所示:

```
class MyMinimaxAgent():
   def __init__(self, depth):
      self.depth = depth
   #用于选择使用 MAX 方案还是 MIN 方案
   def minimax(self, state, depth):
      if state.isMe():
          return self.maxv(state,depth)
      return self.minv(state,depth)
   #MAX 节点操作
   def maxv(self, state, depth):
      beststate = None
      bestv = -float('inf')
      if state.isTerminated():
          return None, state.evaluateScore()
      if depth == 0:
          return state, state.evaluateScore()
      for child in state.getChildren():#MAX 行动一次 depth-1
          st,sc = self.minimax(child, depth-1)
          if sc >= bestv:
             bestv = sc
             beststate = child
      return beststate, bestv
   #MIN 节点的操作
   def minv(self,state,depth):
      beststate = None
      bestv = float('inf')
      if state.isTerminated():
          return None, state.evaluateScore()
      for child in state.getChildren():#MIN 行动一次 depth 不变
          st,sc = self.minimax(child, depth)
          if sc <= bestv:</pre>
             bestv = sc
             beststate = child
      return beststate,bestv
   #外部调用的接口,输入当前状态返回下一步的最佳行动状态
   def getNextState(self, state):
      best_state, _ = self.minimax(state, self.depth)
      return best state
```

四、在极小极大算法的基础上实现  $\alpha-\beta$ 剪枝。类似 MAXMIN 算法,在其上增加每个节点的上下限  $\alpha-\beta$ 。 伪代码实现如下所示:

```
function ALPHA-BETA-SEARCH(state) returns an action
   v \leftarrow \text{MAX-VALUE}(state, -\infty, +\infty)
   return the action in ACTIONS(state) with value v
function MAX-VALUE(state, \alpha, \beta) returns a utility value
  if TERMINAL-TEST(state) then return UTILITY(state)
  for each a in ACTIONS(state) do
      v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(s, a), \alpha, \beta))
      if v \geq \beta then return v
      \alpha \leftarrow MAX(\alpha, v)
  return v
function MIN-VALUE(state, \alpha, \beta) returns a utility value
  if TERMINAL-TEST(state) then return UTILITY(state)
  for each ain ACTIONS(state) do
      v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(s,a), \alpha, \beta))
     if v \leq \alpha then return v
     \beta \leftarrow MIN(\beta, v)
   return v
```

图 5.7 α-β搜索算法

```
将其实现为 python 代码,如下所示:
class MyAlphaBetaAgent():
   def __init__ (self, depth):
      self.depth = depth
   #外部调用接口,输入当前状态返回最佳后继状态
   def getNextState(self, state):
      # YOUR CODE HERE
      best_state, _ = self.alpha_beta_cut(state, self.depth,
                                           -float('inf'), float('inf'))
      return best state
   #用于选择调用 MAX 还是 MIN 方法
   def alpha beta cut(self, state, depth, alpha, beta):
      if state.isMe():
          return self.alpha_beta_cutmaxv(state,depth, alpha, beta)
      return self.alpha_beta_cutminv(state,depth, alpha, beta)
   def alpha beta cutmaxv(self, state, depth, alpha, beta):
      beststate = None
      bestv = -float('inf')
      if state.isTerminated():
          return None, state.evaluateScore()
      if depth == 0:
          return state, state.evaluateScore()
      for child in state.getChildren():
         st,sc = self.alpha_beta_cut(child, depth-1, alpha, beta)
          if sc > bestv:
             bestv = sc
             beststate = child
          if bestv > beta:
             return beststate,bestv
          alpha = max(alpha, bestv)
      return beststate,bestv
   def alpha beta cutminv(self, state, depth, alpha, beta):
      beststate = None
      bestv = float('inf')
      if state.isTerminated():
         return None, state.evaluateScore()
      for child in state.getChildren():
         st,sc = self.alpha_beta_cut(child, depth, alpha, beta)
         if sc < bestv:</pre>
            bestv = sc
            beststate = child
          if bestv < alpha:</pre>
             return beststate,bestv
         beta = min(beta, bestv)
      return beststate,bestv
```

```
运行 test. sh 测试文件,得到的结果如下所示。各测试结果均为 PASS,符合预期。
                                                   -GXH MINGW64 /d/OneDrive - mail.ustc.edu.cn/大三下/人工智能基础/LAB1
  ./test.sh
tarting on 5-27 at 13:15:37
        ## PASS: test_cases\q1\graph_backtrack.test

## solution: ['1:A->C', '0:C->G']

## expanded_states: ['A', 'D', 'C']

## PASS: test_cases\q1\graph_bfs.vs_dfs.test

## solution: ['2:A->D', '0:D->G']

## expanded_states: ['A', 'D']

## PASS: test_cases\q1\graph_infinite.test

## solution: ['A'->B', '1:B->C', '1:C->G']

## expanded_states: ['A', 'B', 'C']

## PASS: test_cases\q1\graph_manynaths.test

## solution: ['2:A->BB', '0:B2->C', '0:C->D', '2:D->E2', '0:E2->F', '0:F->G']

## PASS: test_cases\q1\graph_manynaths.test

## pacman layout: mediumMaze

## solution length: 130

## modes expanded. 146
 uestion q1: 4/4
  otal: 4/4
  our grades are NOT yet registered. To register your grades, make sure
o follow your instructor's guidelines to receive credit on your project.
[SearchAgent] using function depthFirstSearch
[SearchAgent] using problem type PositionSearchProblem
Path found with total cost of 130 in 0.0 seconds
Path found with total cost of 130 in 0.0 seconds
Path nodes expanded: 146
Path and emerges victorious! Score: 380
Path and emerges victo
         ### Question q2: 4/4 ###
inished at 13:15:41
 inished at 13:15:41
   uestion q2: 4/4
    our grades are NOT yet registered. To register your grades, make sure
o follow your instructor's guidelines to receive credit on your project.
 SearchAgent] using function bfs
SearchAgent] using problem type PositionSearchProblem
ath found with total cost of 68 in 0.0 seconds
earch nodes expanded: 269
acman emerges victorious! Score: 442
verage Score: 442.0
ion Rate: 1/1 (1.00)
ecord: Win
tarting on 5-27 at 13:15:44
    estion q3
  inished at 13:15:44
   uestion q3: 4/4
  our grades are NOT yet registered. To register your grades, make sure
o follow your instructor's guidelines to receive credit on your project.
[SearchAgent] using function astar and heuristic manhattanHeuristic [SearchAgent] using problem type PositionSearchProblem ath found with total cost of 68 in 0.0 seconds search nodes expanded: 221 acman emerges victorious! Score: 442 acman emerges victorious! Score: 442 oscores: 442.0 sin Rate: 1/1 (1.00) decord: Win Starting on 5-27 at 13:15:48
       **PASS: test_cases\q2\0-lecture-6-tree.test**

**PASS: test_cases\q2\1-1-minmax.test**

**PASS: test_cases\q2\1-1-minmax.test**

**PASS: test_cases\q2\1-2-minmax.test**

**PASS: test_cases\q2\1-3-minmax.test**

**PASS: test_cases\q2\1-3-minmax.test**

**PASS: test_cases\q2\1-4-minmax.test**

**PASS: test_cases\q2\1-6-minmax.test**

**PASS: test_cases\q2\1-6-minmax.test**

**PASS: test_cases\q2\1-6-minmax.test**

**PASS: test_cases\q2\1-1-minmax.test**

**PASS: test_cases\q2\1-1-minmax.test**

**PASS: test_cases\q2\1-1-vary-depth.test**

**PASS: test_cases\q2\1-1-vary-depth.test**

**PASS: test_cases\q2\1-2-1-vary-depth.test**

**PASS: test_cases\q2\1-2-1-vary-depth.test**

**PASS: test_cases\q2\1-2-3-vary-depth.test**

**PASS: test_cases\q2\1-2-3-vary-depth.test**

**PASS: test_cases\q2\1-2-3-vary-depth.test**

**PASS: test_cases\q2\1-2-4-vary-depth.test**

**PASS: test_cases\q2\1-2-4-vary-depth.test**

**PASS: test_cases\q2\1-2-4-vary-depth.test**

**PASS: test_cases\q2\1-2-4-vary-depth.test**

**PASS: test_cases\q2\1-4-two-ghost-3-1evel.test**

**PASS: test_cases\q2\1-4-two-ghost-3-1evel.test**

**PASS: test_cases\q2\1-1-check-depth-one-ghost.test**

**PASS: test_cases\q2\1-1-check-depth-one-ghost.test**

**PASS: test_cases\q2\1-1-check-depth-one-ghost.test**

**PASS: test_cases\q2\1-1-check-depth-one-ghost.test**

**PASS: test_cases\q2\1-2-check-depth-two-ghosts.test**

***PASS: test_cases\q2\1-2-check-depth-two-ghosts.test**

*********

***********
### Question q2: 5/5 ###
inished at 13:15:49
    estion q2: 5/5
Total: 5/5
    our grades are NOT yet registered. To register your grades, make sure
o follow your instructor's guidelines to receive credit on your project.
       ### Question q3: 5/5 ###
   uestion q3: 5/5
 otal: 5/5
  our grades are NOT yet registered. To register your grades, make sure
o follow your instructor's guidelines to receive credit on your project.
  acman emerges victorious! Score: 1433
verage Score: 1433.0
cores: 1433.0
in Rate: 1/1 (1.00)
ecord: Win
```